

# Register implementations out of faulty base registers

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# Failure modes

- Responsive: once  $\perp$ , forever  $\perp$
- Non-responsive: no reply

$t$  denotes the number of base objects that can fail

NB. In the asynchronous model, it is impossible to distinguish a non-responsive from a slow object

# Algorithms

- (1) Implements a SWMR *register* out of  $t+1$  SWMR base responsive failure-prone *registers*
- (2) Implements a SWSR *register* out of  $2t+1$  SWSR base non-responsive failure-prone *registers*

# Responsive model

- Write( $v$ )

- For  $j = 1$  to  $(t+1)$  do

- Reg[ $j$ ].write( $v$ );

- return(ok)

- Read()

- For  $j = t+1$  to  $1$  do

- $v :=$  Reg[ $j$ ].read();

- if  $v \neq \perp$  then return( $v$ )

# Non-responsive model

- Init:  $seq := 1$
- Write( $v$ )
  - $w\_seq := w\_seq + 1;$
  - For  $j = 1$  to  $(2t+1)$  do **||**:
    - $Reg[j].write(w\_seq, v);$
  - « wait until a majority of oks are returned »
  - return(ok)

# Non-responsive model

- Init:  $(sn, val) := (-1, \perp)$ ;
- Read()
  - For  $j = 1$  to  $(2t+1)$  do **||**:
  - $(s, v) := \text{Reg}[j].\text{read}()$ ;
  - $(sn, val) := (s, v)$  with the highest  $s$  from majority, including  $(sn, val)$
  - return  $(val)$