Transactional Memory

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Locking is “history”

Lock-freedom is “difficult”
Wanted

A synchronisation abstraction that is simple, robust and efficient
Historical perspective

- Eswaran et al (CACM’76) Databases
- Papadimitriou (JACM’79) Theory
- Liskov/Sheifler (TOPLAS’82) Language
- Knight (ICFP’86) Architecture
- Herlihy/Moss (ISCA’93) Hardware
- Shavit/Touitou (PODC’95) Software
- Herlihy et al (PODC’03) Software – Dynamic
Back to the sequential level

- accessing object 1;
- accessing object 2;
Back to the sequential level

atomic {
    accessing object 1;
    accessing object 2;
}
Semantics (serialisability)

Every transaction appears to execute at an indivisible point in time (linearizability of transactions)
Double-ended queue

Enqueue  Dequeue
```java
class Queue {
    QNode head;
    QNode tail;
    public enq(Object x) {
        atomic {
            QNode q = new QNode(x);
            q.next = head;
            head = q;
        }
    }
    ...
}
```
Queue composition

Dequeue  Enqueue
class Queue {
    ...
    public transfer(Queue q) {
        atomic {
            Qnode n = this.dequeue();
            q.enqueue(n)
        }
    }
    ...
}
Simple example
(consistency invariant)

\[ 0 < x < y \]
Simple example
(transaction)

\[ T: x := x+1 \ ; \ y := y+1 \]
The illusion of a critical section

atomic {
    accessing object 1;
    accessing object 2;
}
“It is better for Intel to get involved in this [Transactional Memory] now so when we get to the point of having ... tons ... of cores we will have the answers”

Justin Rattner, Intel Chief Technology Officer
“...we need to explore new techniques like transactional memory that will allow us to get the full benefit of all those transistors and map that into higher and higher performance.”

Bill Gates
“...manual synchronization is intractable...transactions are the only plausible solution....”

Tim Sweeney, Epic Games
The TM Topic has been a VERY HOT topic

- Sun/Oracle, Intel, AMD, IBM, MSR
- Fortress (Sun); X10 (IBM); Chapel (Cray)
The TM API
(a simple view)

- \texttt{begin()} returns \textit{ok}
- \texttt{read()} returns a value or \textit{abort}
- \texttt{write()} returns an \textit{ok} or \textit{abort}
- \texttt{commit()} returns \textit{ok} or \textit{abort}
- \texttt{abort()} returns \textit{ok}
Two-phase locking

To **write** or **read** O, T requires a **lock** on O; T **waits** if some T' acquired a **lock** on O

At the end, T **releases** all its locks
Two-phase locking (more details)

Every object $O$, with state $s(O)$ (a register), is protected by a lock $l(O)$ (a c&s)

Every transaction has local variables $wSet$ and $wLog$

Initially: $l(O) = \text{unlocked}$, $wSet = wLog = \emptyset$
Two-phase locking

Upon op = \textit{read()} or \textit{write}(v) on object O
if O \notin wSet then
    wait until unlocked = l(O).c&s(unlocked,locked)
    wSet = wSet U O
    wLog = wLog U S(O).read()
if op = read() then return S(O).read()
S(O).write(v)
return ok
Two-phase locking (cont’d)

Upon *commit()*
cleanup()
return ok

Upon *abort()*
rollback()
cleanup()
return ok
Two-phase locking (cont’d)

Upon \textit{rollback()}
for all $O \in \text{wSet}$ do $\text{S(O).write(wLog(O))}$
$\text{wLog} = \emptyset$

Upon \textit{cleanup()}
for all $O \in \text{wSet}$ do $\text{l(O).write(unlocked)}$
$\text{wSet} = \emptyset$
Why two phases? (what if?)

To write or read O, T requires a lock on O; T waits if some T' acquired a lock on O

T releases the lock on O when T is done with O
Why two phases?

T1

read(0)  write(1)

O1  O2

T2

read(0)  write(1)

O2  O1
Two-phase locking (read-write lock)

- To **write** O, T requires a **write-lock** on O; T **waits** if some T’ acquired a **lock** on O

- To **read** O, T requires a **read-lock** on O; T **waits** if some T’ acquired a **write-lock** on O

- Before committing, T **releases** all its locks
Two-phase locking - better dead than wait -

To write O, T requires a write-lock on O; T aborts if some T’ acquired a lock on O

To read O, T requires a read-lock on O; T aborts if some T’ acquired a write-lock on O

Before committing, T releases all its locks
A transaction that aborts restarts again
Two-phase locking
- better kill than wait -

To write O, T requires a write-lock on O; T aborts T’ if some T’ acquired a lock on O

To read O, T requires a read-lock on O; T aborts T’ if some T’ acquired a write-lock on O

Before committing, T releases all its locks
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Two-phase locking - better kill than wait -

To **write** O, T requires a **write-lock on** O; T **aborts** T’ if some T’ acquired a **lock** on O

To **read** O, T requires a **read-lock on** O; T **waits** if some T’ acquired a **write-lock on** O

Before committing, T releases all its locks

A transaction that is aborted restarts again
Visible Read
(SXM, RSTM, TLRW)

*Write is mega killer:* to write an object, a transaction aborts any live one which has read or written the object.

*Visible but not so careful read:* when a transaction reads an object, it says so.
Visible Read

A visible read invalidates cache lines

For read-dominated workloads, this means a lot of traffic on the bus between processors
- This reduces the throughput
- Not a big deal with single-CPU, but with many core machines (e.g. SPART T2 Niagara)
Two-phase locking with invisible reads

To write O, T requires a write-lock on O; T waits if some T’ acquired a write-lock on O

To read O, T checks if all objects read remain valid - else T aborts

Before committing, T checks if all objects read remain valid and releases all its locks
Invisible reads (more details)

- Every object $O$, with state $S(O)$ (register), is protected by a lock $l(O)$ (c&s).

- Every transaction maintains, besides $wSet$ and $wLog$:
  - a local variable $rset(O)$ for every object.
Invisible reads

Upon \text{write}(v) on object \text{O}
if \text{O} \notin \text{wSet} then
    wait until unlocked = \text{I(O).c&s(unlocked,locked)}
    \text{wSet} = \text{wSet} \cup \text{O}
    \text{wLog} = \text{wLog} \cup \text{S(O).read()}
    \text{(*,ts) = S(O).read()}
    \text{S(O).write(v,ts)}
return ok
Invisible reads

Upon \texttt{read()} on object O
\[(v,ts) = S(O).read()\]
if \(O \in \text{wSet}\) then return \(v\)
if \(l(O) = \text{locked}\) or not validate() then abort()
if \(rset(O) = 0\) then \(rset(O) = ts\)
return \(v\)
Invisible reads

Upon `validate()`

for all \( O \) s.t \( rset(O) > 0 \) do

\[(v,ts) = S(O).read()\]

if \( ts \neq rset(O) \) or

\((O \notin wset \text{ and } l(O) = \text{locked})\)

then return false

else return true
Invisible reads

Upon \textit{commit()}
if not validate() then abort()
for all \( O \in \text{wset} \) do
  \((v,ts) = S(O).read()\)
  \(S(O).write(v,ts+1)\)
cleanup()
Invisible reads

Upon \textit{rollback()}
for all $O \in \text{wSet}$ do $S(O).write(wLog(O))$
\[ wLog = \emptyset \]

Upon \textit{cleanup()}
for all $O \in \text{wset}$ do $l(O).write(unlocked)$
\[ wset = \emptyset \]
\[ rset(O) = 0 \text{ for all } O \]
DSTM (SUN)

- To write O, T requires a write-lock on O; T aborts T’ if some T’ acquired a write-lock on O.

- To read O, T checks if all objects read remain valid – else T abort.

- Before committing, T releases all its locks.
DSTM

- **Killer write** (ownership)
- **Careful read** (validation)
More efficient algorithm?

Apologizing versus asking permission

- **Killer write**
- **Optimistic read**
  - validity check only at commit time
Example

Invariant: 0 < x < y
Initially: x := 1; y := 2
Division by zero

T1: $x := x + 1$ ; $y := y + 1$

T2: $z := 1 / (y - x)$
Infinite loop

T1: x := 3; y := 6

T2: a := y; b := x;
    repeat b := b + 1 until a = b
Opacity

- Serializability
- Consistent memory view
Trade-off

The read is either visible or careful
Intuition

T1

\[
\text{read()}
\]

\[
O_1, O_2, \ldots, O_n
\]

T2

\[
\text{write()}
\]

\[
I_1, I_2, \ldots, I_m
\]

commit

read()

\[
I_k
\]
Read invisibility

The fact that the read is invisible means T1 cannot inform T2, which would in turn abort T1 if it accessed similar objects (SXM, RSTM)

NB. Another way out is the use of multiversions: T2 would not have written “on” T1
Conditional progress - obstruction-freedom -

A correct transaction that eventually does not encounter *contention* eventually commits.

*Obstruction-freedom* seems reasonable and is indeed possible.
DSTM

- To \textit{write} O, T requires a \textit{write-lock on} O (use C&S); T aborts T' if some T' acquired a \textit{write-lock} on O (use C&S)

- To \textit{read} O, T checks if all objects read remain valid - else abort (use C&S)

- Before committing, T releases all its locks (use C&S)
If a transaction T wants to write an object O owned by another transaction T’, T calls a *contention manager*

The contention manager can decide to wait, retry or abort T’
Contention managers

- **Aggressive**: always aborts the victim
- **Backoff**: wait for some time (exponential backoff) and then abort the victim
- **Karma**: priority = cumulative number of shared objects accessed – work estimate. Abort the victim when number of retries exceeds difference in priorities.
- **Polka**: Karma + backoff waiting
Greedy contention manager

State
- Priority (based on start time)
- Waiting flag (set while waiting)

Wait if other has
- Higher priority AND not waiting

Abort other if
- Lower priority OR waiting
Aborting is a fatality
Concluding remarks

TM does not always replace locks: it hides them

Memory transactions look like db transactions but are different
The garbage-collection analogy

In the early times, the programmers had to take care of allocating and de-allocating memory.

Garbage collectors do it for you: they are now incorporated in Java and other languages.

Hardware support was initially expected, but now software solutions are very effective.