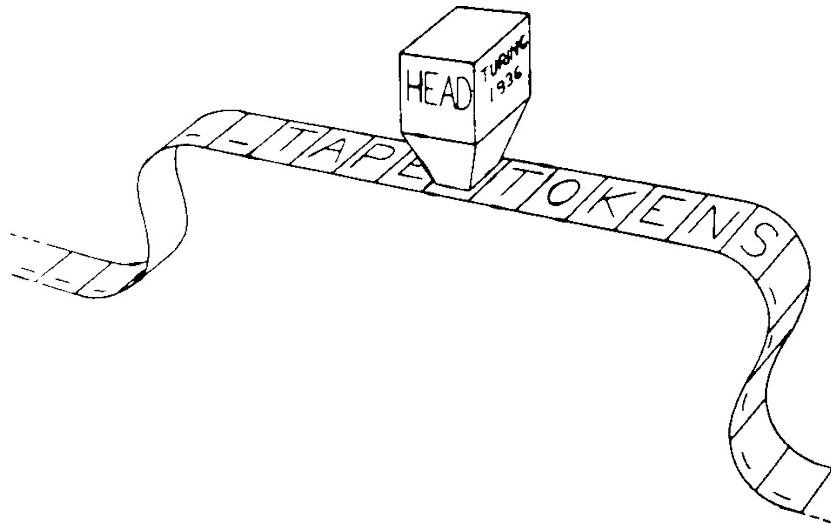


Classical Universality: Turing

Universality of Consensus

[Lamport-Schneider-Herlihy-CT]



Linearizable
(atomic)



Highly-available
(wait-free)

Act1: Universality

Turing

Act 2: Modern Universality

Turing + Lamport

Consensus

Processes propose each a value and **agree** on one

output = **propose**(input)



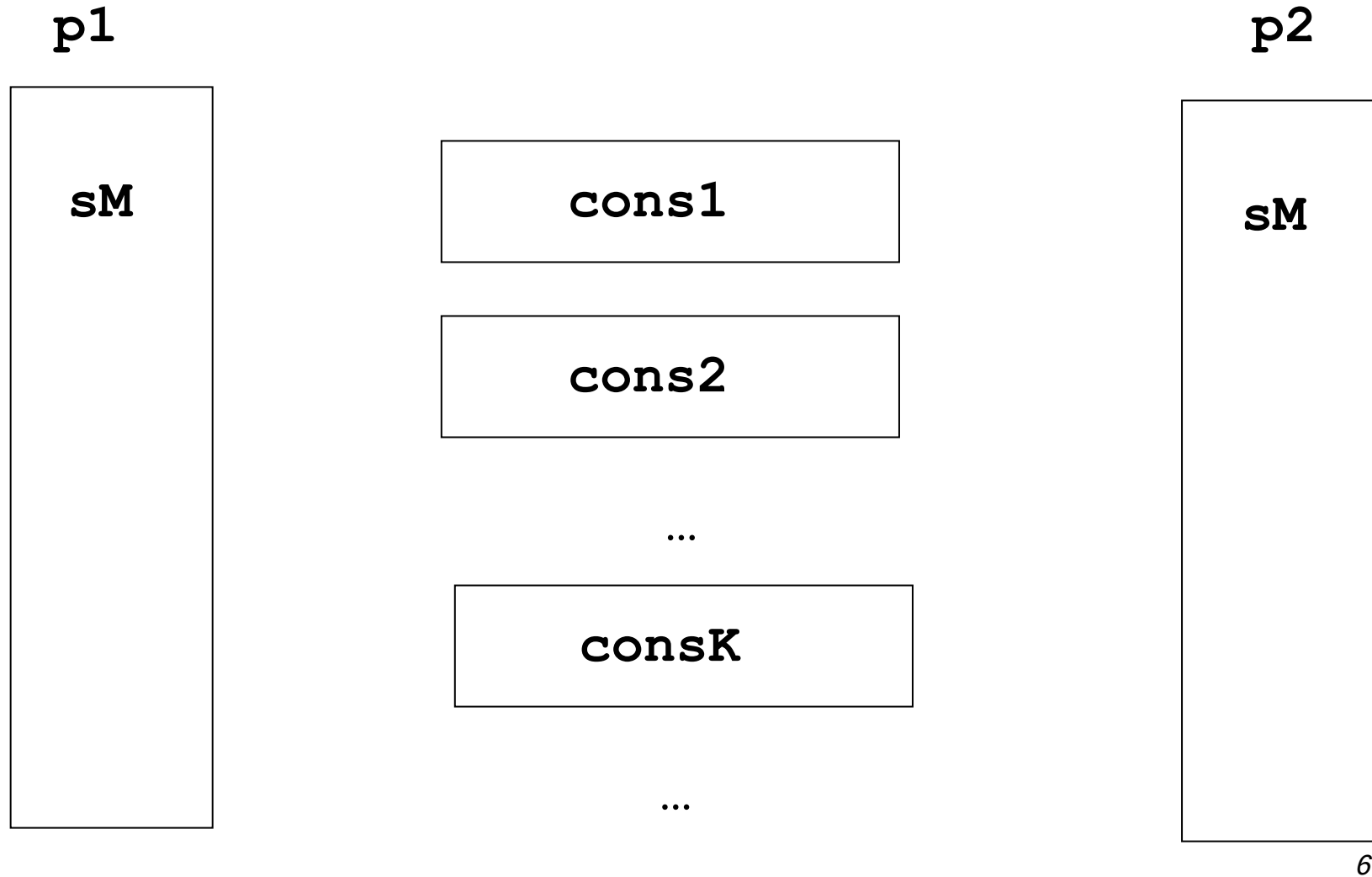
Universal Construction

Each process holds a copy of the simulated machine

Each process holds a list of commands for the machine

All processes share a list of consensus objects

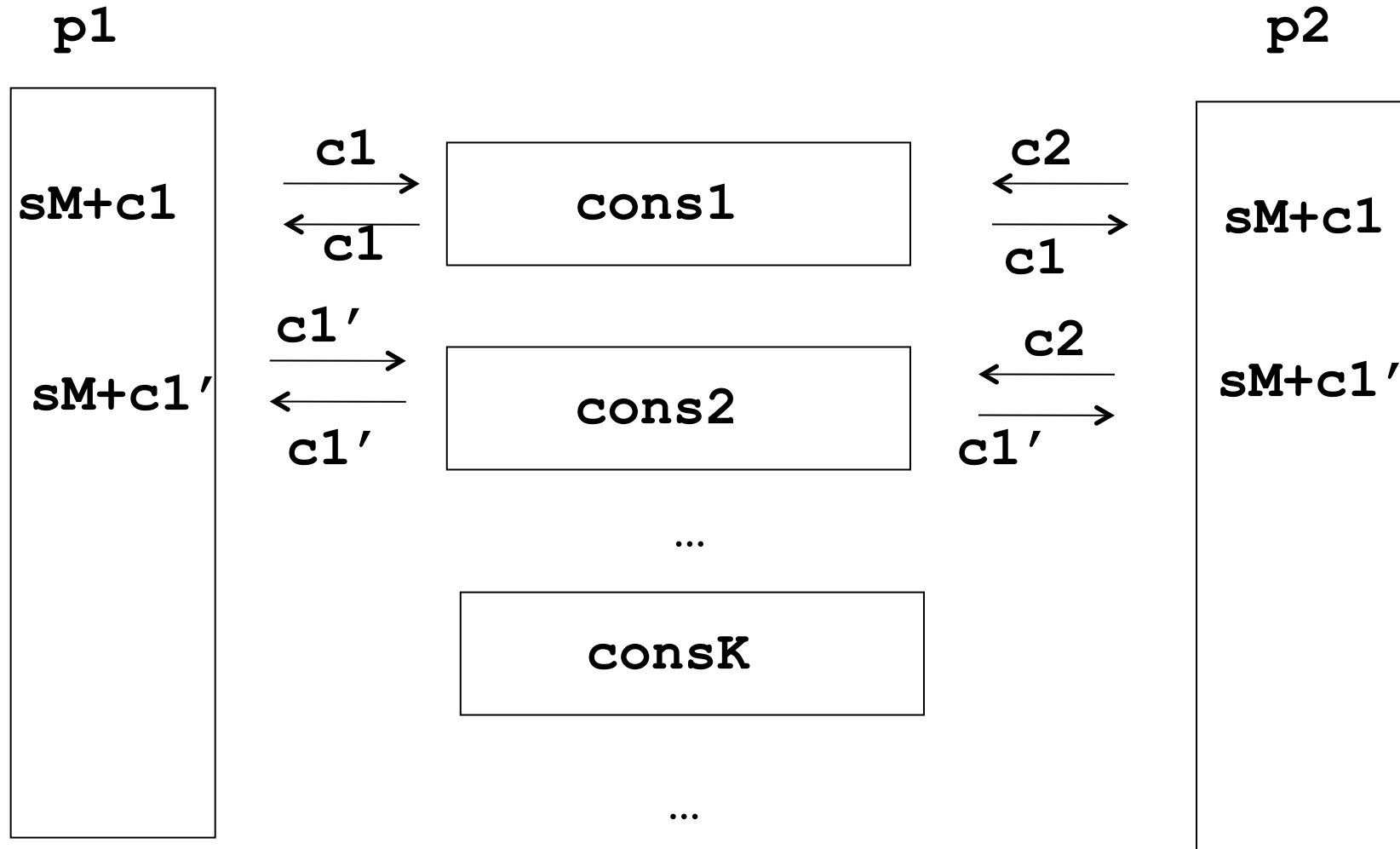
Universal Construction



Universal Construction

- `while(true)`
- `c = commands.next()`
- `cons = Consensus.next()`
- `c' = cons.propose(c)`
- `sM.perform(c')`

Universal Construction



What if consensus is not ensured?

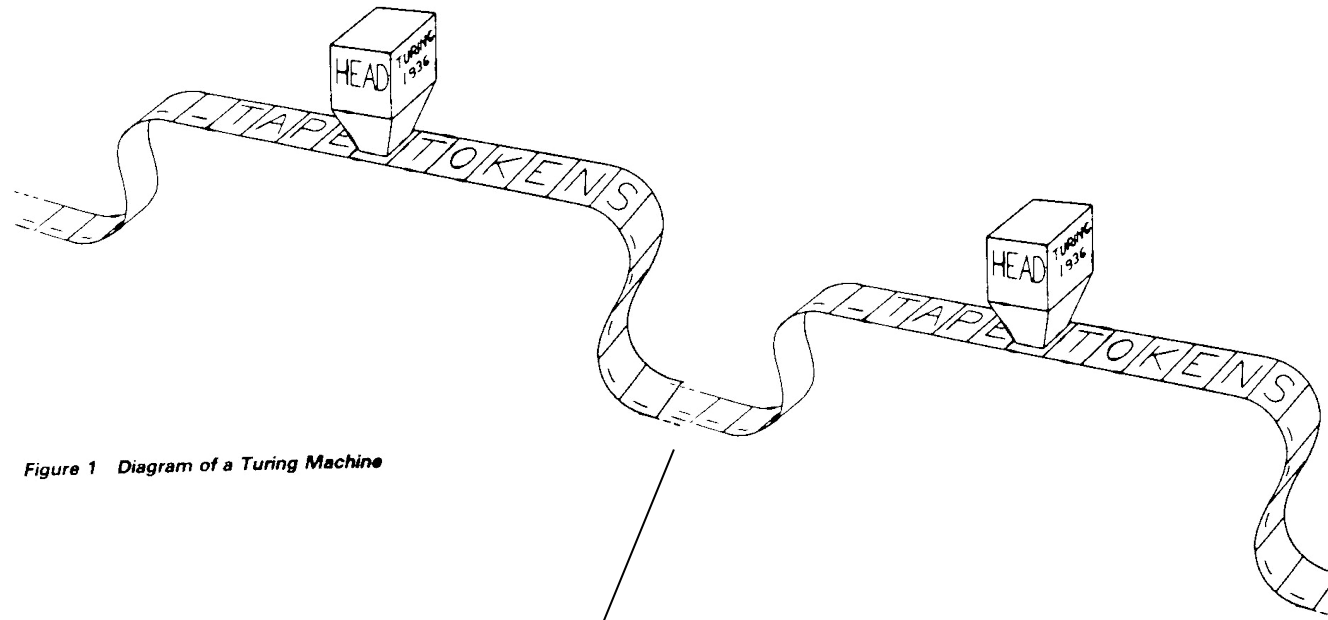
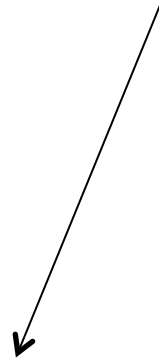


Figure 1 Diagram of a Turing Machine

Figure 1 Diagram of a Turing Machine

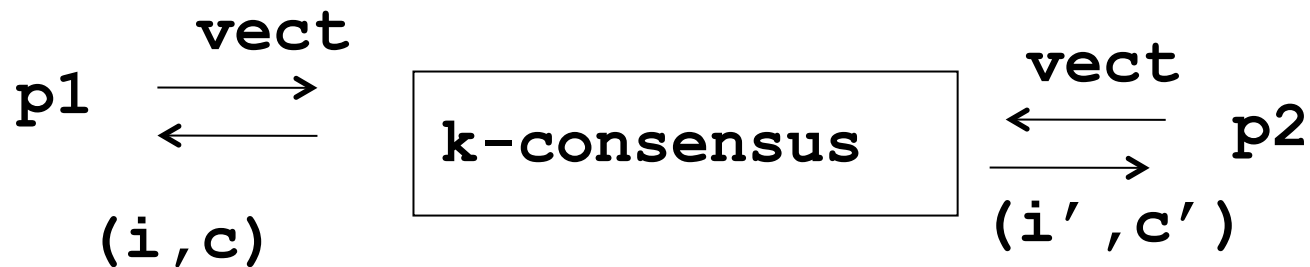


Consensus

K-Consensus

Every process proposes a vector of k values and returns a value at some position (Chauduri et al)

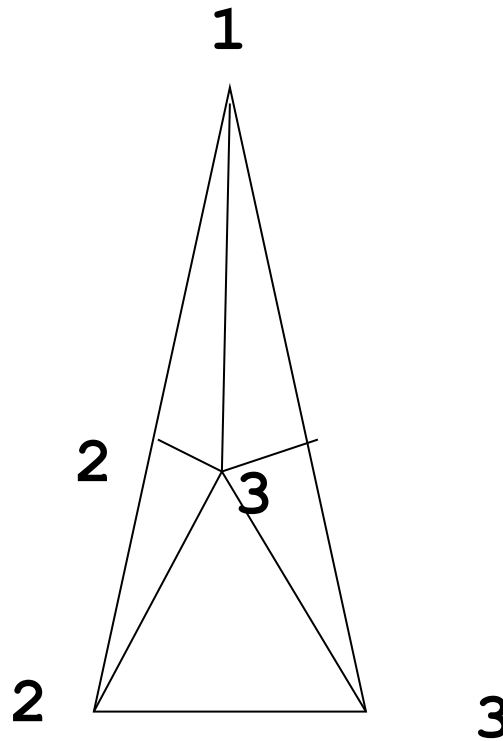
$(i,c) = \mathbf{propose}(kVect)$



K-Consensus

- ***Validity***: the value returned at any position has been proposed at that position
- ***Agreement***: no two values returned at the same position are different
- ***Termination***: every correct process that proposes eventually returns

$k+1$ -consensus is strictly weaker than k -consensus
in any system of more than $k+1$ processes
(Godel prize 2004 – HS,BG,SZ 93)



Sperner's Lemma: at least one triangle has three colors

What form of universality with K-consensus?

With consensus

We implement a highly-available state machine



With k-consensus

We implement k state machines of which ***at least one*** is highly-available

Generalized Universality

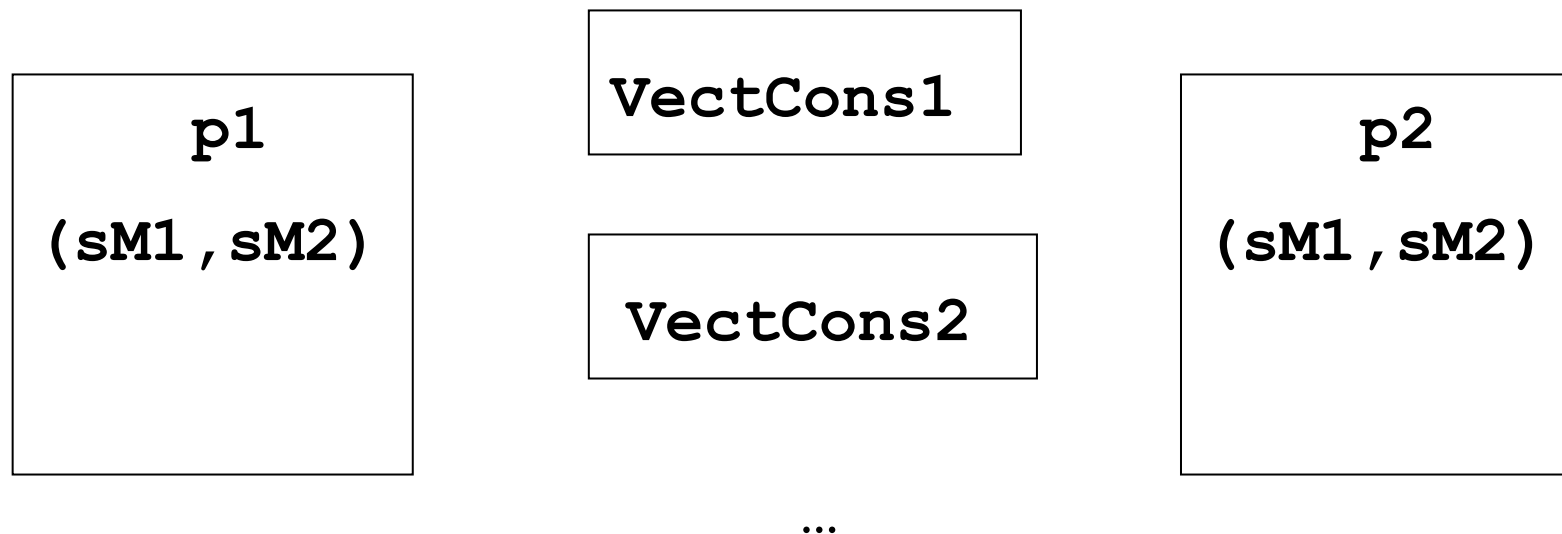
Act1: Universality
Turing

Act 2: Modern Universality
Turing + Lamport

Act 3: Generalized Universality

Generalized Universality

Each process holds a copy of each of the machines $sM(i)$ - and a lists of commands for each



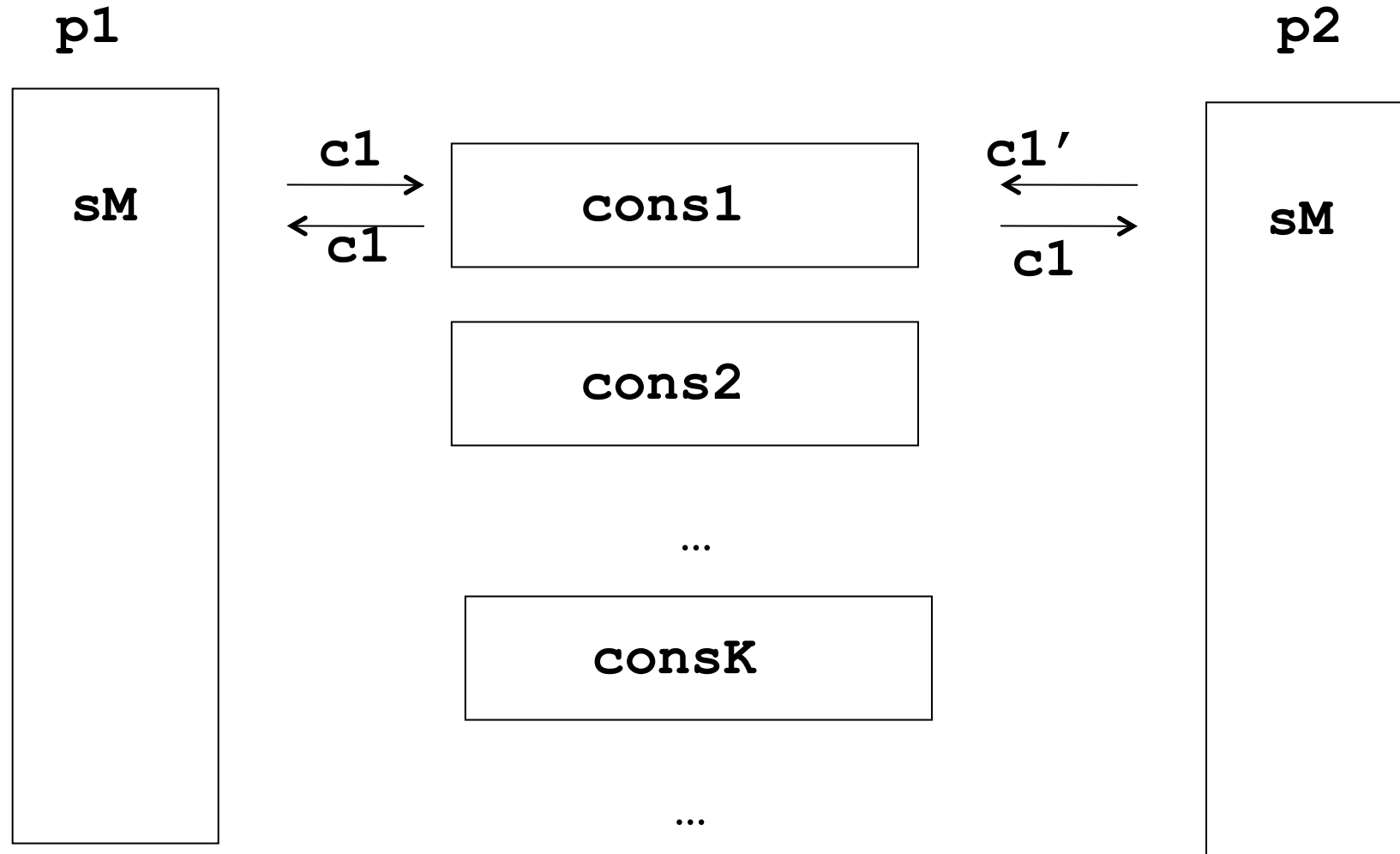
The processes share a list of k-vector consensus objects

Universal Construction

- while(true)
- c = commands.next()
- cons = consensus.next()

- c' = cons.propose(c)
- sM.perform(c')

Universal Construction



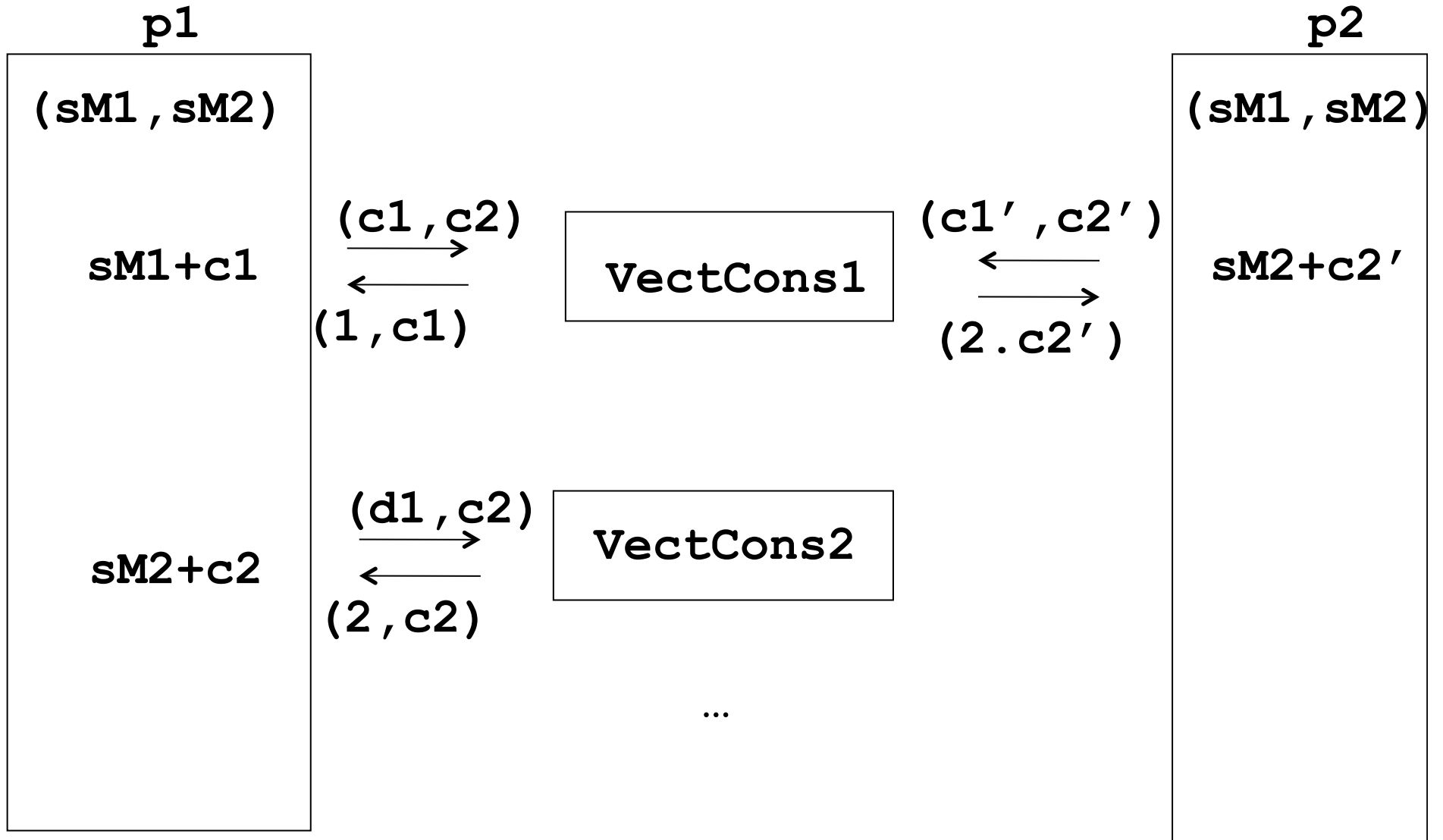
Generalized Universality?

Problem with safety

- while(true)
- for j = 1 to k: com(j) = commands(j).next()
- kVectC = kVectCons.next()

- (c,i) = kVectC.propose(com)
- sM(i).perform(c)

Problem with safety

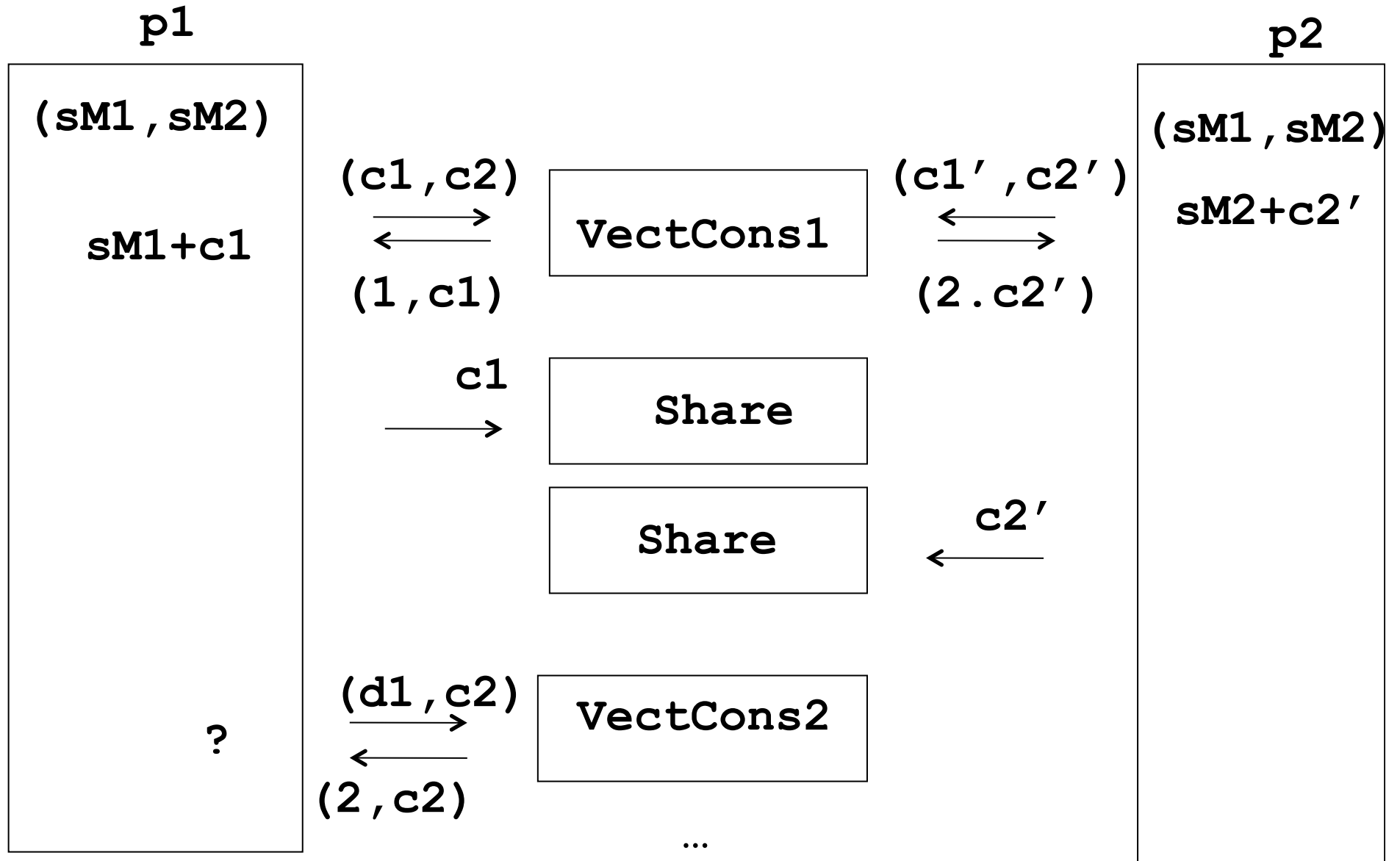


Generalized Universality

- while(true)
- for j = 1 to k: com(j) = commands(j).next()
- kVectC = kVectCons.next()

- (c,i) = kVectC.propose(com)
- ***check other processes for any missing c'***
- sM(i).perform(c)
- ***inform other processes about c***

Generalized Universality



1st key idea (ensuring safety)



`write(c)`

if there is only `c`, `write(commit, c)`

if there is only `(commit, c)`, `return(commit, c)`

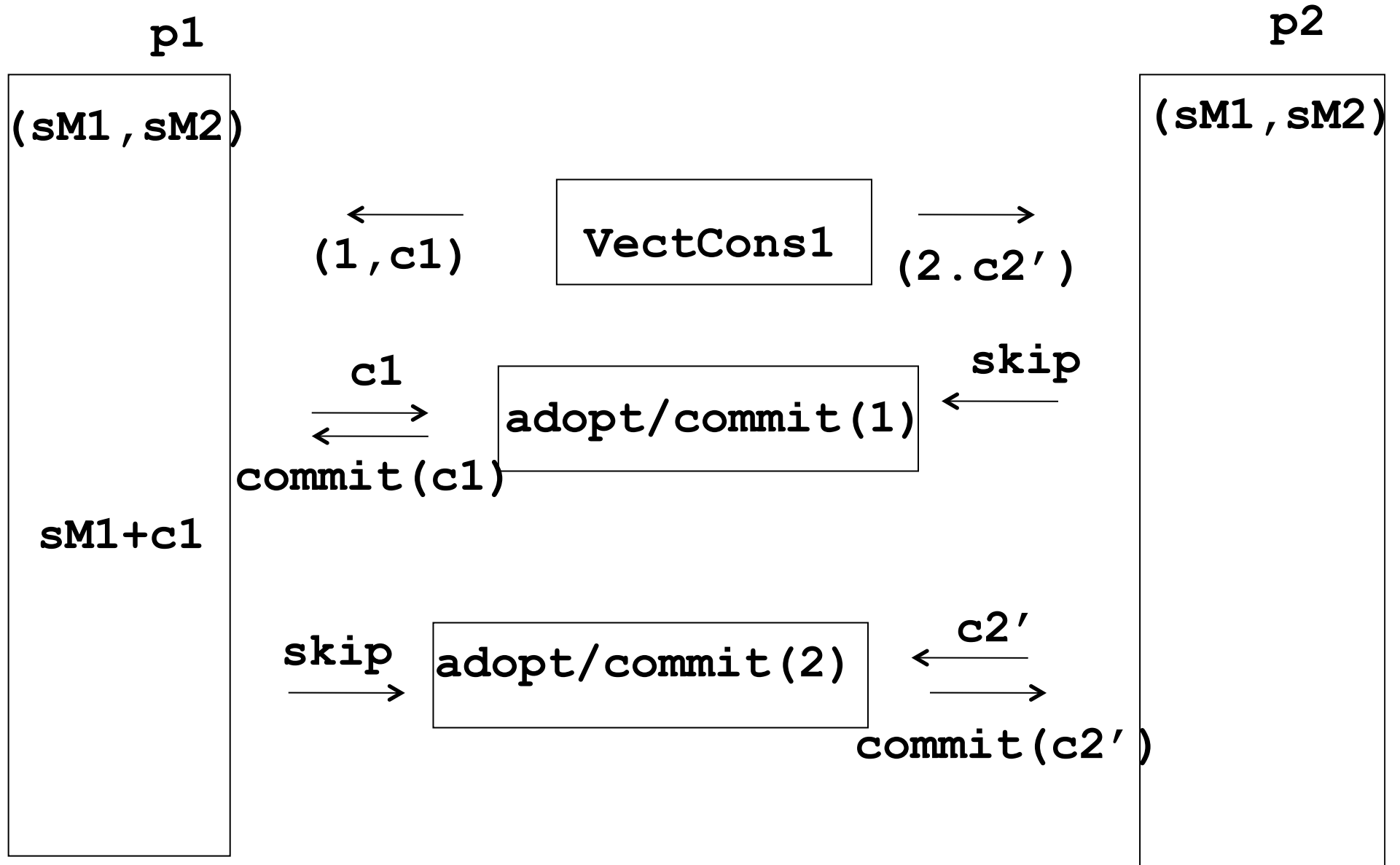
if there is `(commit, c')`, `return(adopt, c')`

else `return(adopt, c)`

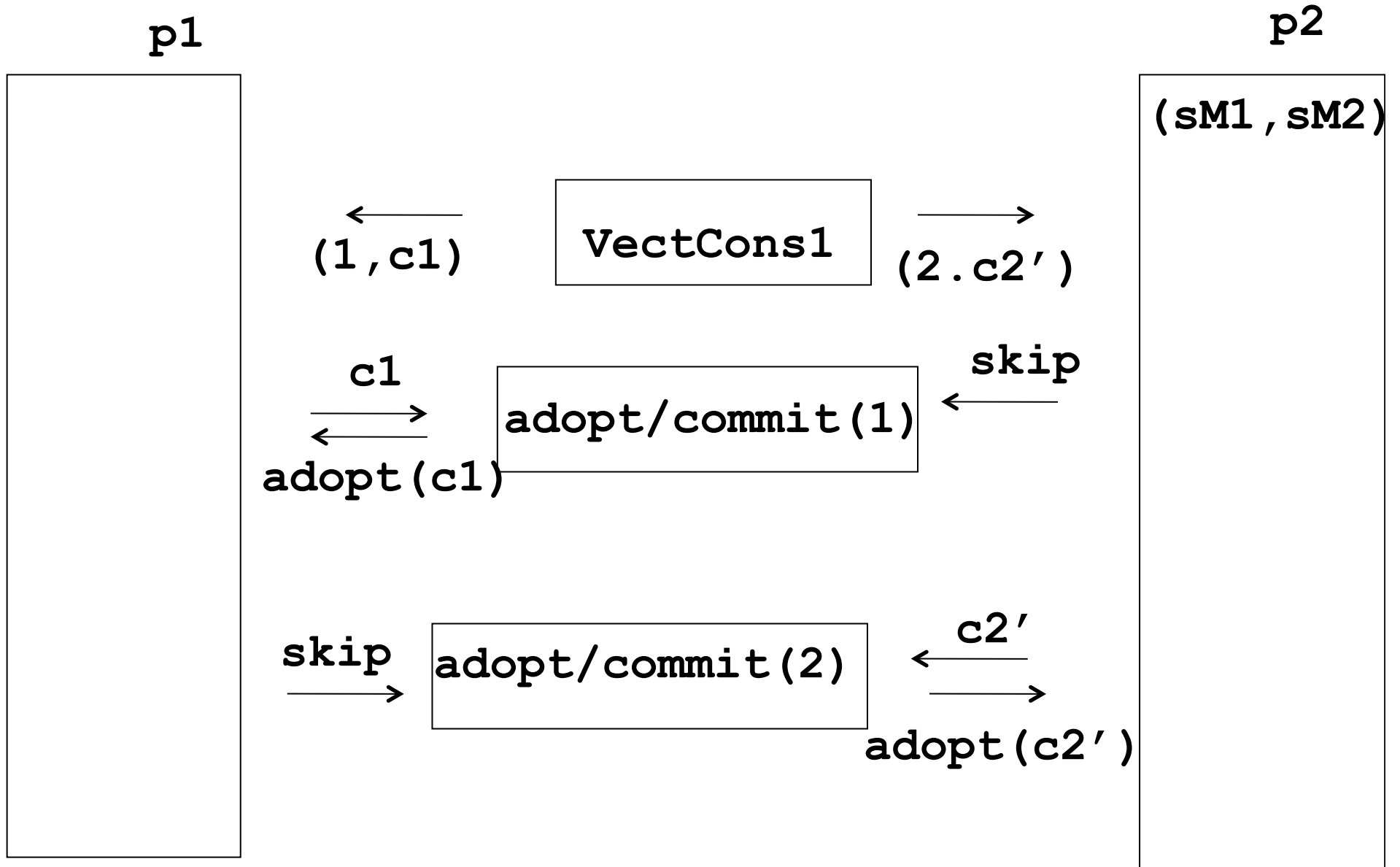
Adopt/commit

- ***Invariant (1)***: if a value v is committed then no other value is returned
- ***Invariant (2)***: if all processes propose the same command then the command is committed

Generalized Universality



Problem with liveness



2nd key idea (ensuring liveness)

Exploit success first



Can it be that no command is committed? i.e., if every `adopt/commit` box has one process proposes skip

Generalized universality (step 0)

- `newCom = commands.next()`
- `while(true)`
- `kVectC = kVectCons.next()`

Generalized universality (step 1)

- ...
- $(c,i) = \text{kVectC.propose}(\text{newCom})$
- ...

Generalized universality (step1-2)

- ...
- $(c,i) = \text{kVectC.propose}(\text{newCom})$
- $\text{vect}(i) = \text{commitment}(i,c)$
- ...

Generalized universality (step 1-2-2')

- ...
- $(c,i) = kVectC.propose(newCom)$
- $vect(i) = commitment(i,c)$
- for $j = 1$ to k except i :
 - $vect(j) = commitment(newCom(j))$
 - ...

Generalized universality (step 3)

...

for i = 1 to k

- if ok(vect(i)) then
 - sM(i).perform(vect(i))
 - newCom(i) = commands(i).next()
- else
 - newCom(i) = vect(i)

Generalized universality (step 3')

...

for $i = 1$ to k

- If $\text{older}(\text{newCom}(i), \text{vect}(i))$ then
 - $\text{sM}(i).\text{perform}(\text{newCom}(i))$
- If $\text{no}(\text{vect}(i))$ then $\text{newCom}(i) = \text{vect}(i)$
- else
- $\text{sM}(i).\text{perform}(\text{vect}(i))$
- If $\text{vect}(i) = \text{newCom}(i)$ then
 - $\text{newCom}(i) = \text{commands}(i).\text{next}()$
- $\text{add}(\text{newCom}(i), \text{vect}(i))$

Commitment

- ***Safety***: a process does not perform a command unless all others know the command
- ***Liveness***: at least one process executes a command in every round

NB. Every correct process executes at least one command every two rounds

Act1: Universality
Turing

Act 2: Modern Universality
Turing + Lamport

Act 3: Generalized Universality