Concurrent Algorithms (Overview)

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In short

This course is about the principles of robust concurrent computing

Today

Contraction

Motivation

Content

WARNING

- This course is different from the course : Distributed Algorithms
- shared memory vs message passing

It does make a lot of sense to take both

This course

Theoretical but no specific theoretical background is required

« Exercices throughout the semester

Mid term + Final exam + Bonus project

New York Times, 8 May 2004: Major chip manufacturers announced what is perceived as a major paradigm shift in computing:

Multiprocessors vs faster processors

Major chip manufacturers have announced a major paradigm shift:

Intel ... [has] decided to focus its development efforts on «dual core» processors ... with two engines instead of one, allowing for greater efficiency because the processor workload is essentially shared. Moore (65-75): the number of transistors on the same chip doubles every two years

But

Dennard (74): the frequency can double every year without doubling energy

The clock speed of a processor cannot be increased without overheating

But

More and more processors can fit in the same space

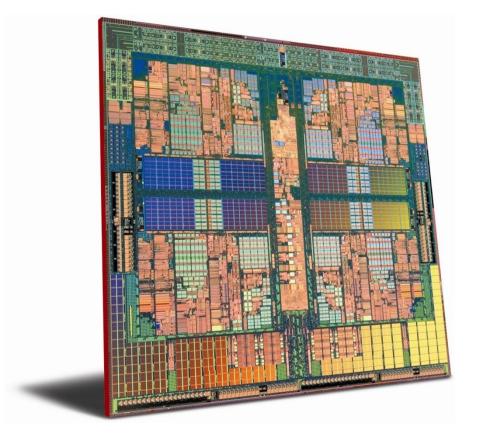
Multicores are almost everywhere

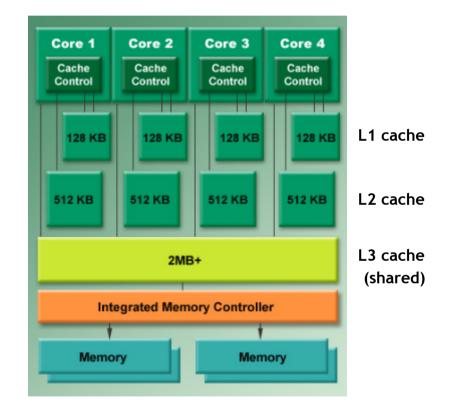
- **Dual-core** commonplace in laptops
- **Quad-core** in desktops
- **Dual quad-core** in servers
- All major chip manufacturers produce multicore CPUs
 - SUN Niagara (8 cores, 32 threads)
 - Intel Xeon (4 cores)
 - AMD Opteron (4 cores)

Multicores are almost everywhere

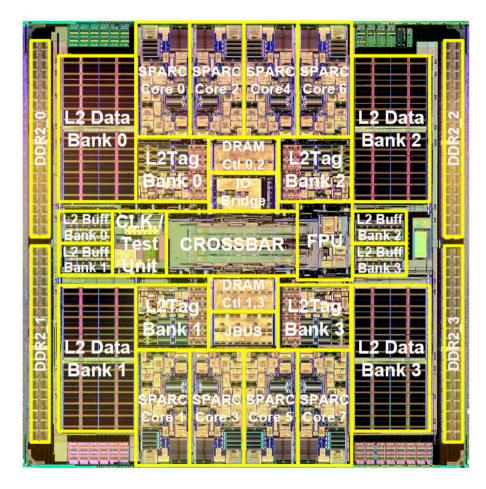
- **Quad-core** in laptops
- Octa-core in desktops
- 2*12 cores in servers
- All major chip manufacturers produce multicore CPUs
 - Oracle Sparc (32 cores, 256 threads)
 - Intel Xeon (12-16 cores)
 - AMD Opteron (12-16 cores)

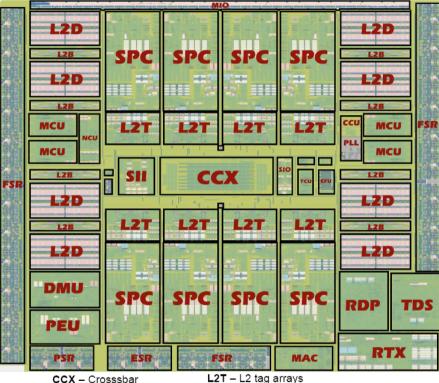
AMD Opteron (4 cores)





SUN's Niagara CPU2 (8 cores)





CCX – Crosssbar	L2T – L2 tag arrays
CCU – Clock control	MCU – Memory controller
DMU/PEU – PCI Express	MIO – Miscellaneous I/O
EFU – Efuse for redundancy	PSR – PCI Express SERDES
ESR – Ethernet SERDES	RDP/TDS/RTX/MAC – Ethernet
FSR – FBD SERDES	SII/SIO - I/O data path to and from memory
L2B – L2 write-back buffers	SPC – SPARC cores
L2D – L2 data arrays	TCU – Test and control unit

Multiprocessors

- Multiple hardware processors: each executes a series of processes (software constructs) modeling sequential programs
- Multicore architecture: multiple processors are placed on the same chip

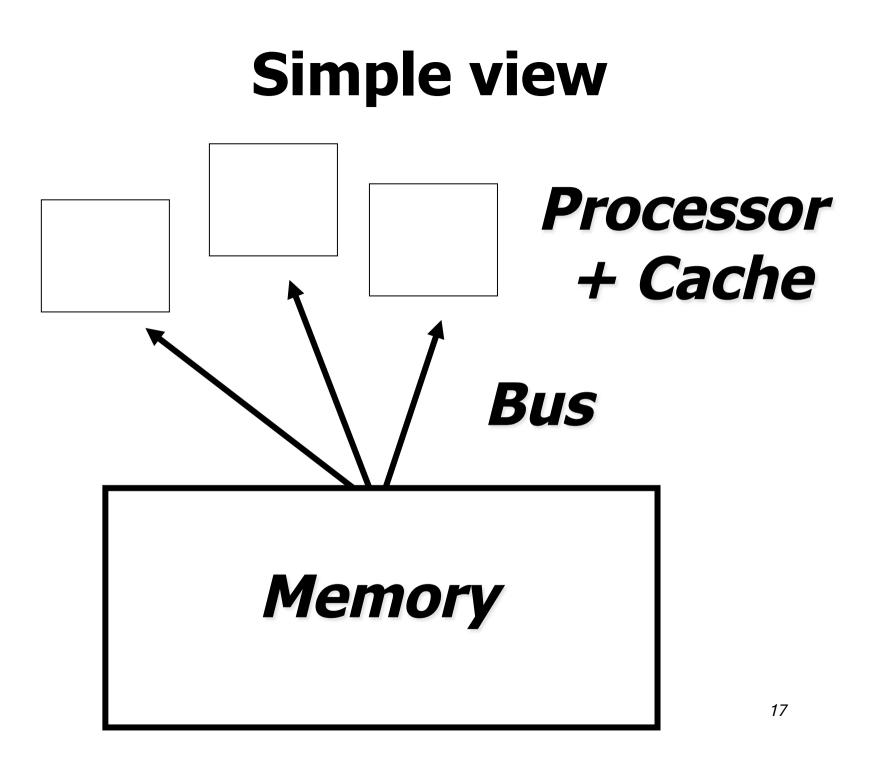
Principles of an architecture

Two fundamental components that *fall apart*: *processors* and *memory*

- The Interconnect links the processors with the memory:
- *I* SMP (symmetric): bus (a tiny Ethernet)
- *IVENTIFY* NUMA (network): point-to-point network

Cycles

- The basic unit of time is the *cycle*: time to execute an instruction
- This changes with technology but the relative cost of instructions (local vs memory) does not



Hardware synchronization objects

- The basic unit of communication is the *read* and *write* to the memory (through the cache)
- More sophisticated objects are typically provided and, as we will see, necessary: C&S, T&S, LL/SC

The free ride is over

- Cannot rely on CPUs getting faster in every generation
- Utilizing more than one CPU core requires concurrency

The free ride is over

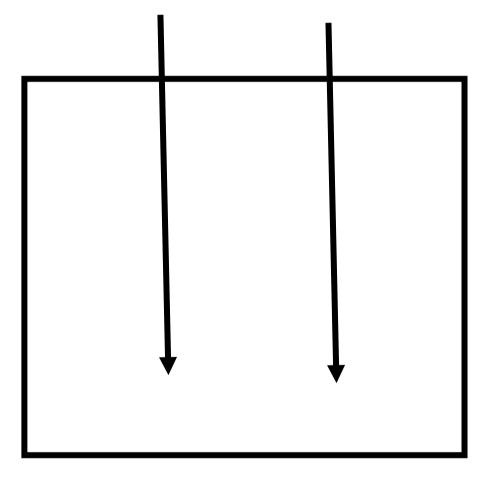
- One of the biggest software challenges: exploiting concurrency
 - Every programmer will have to deal with it
 - Concurrent programming is hard to get right

Speed will be achieved by having several processors work on independent parts of a task

But

the processors would occasionally need to pause and synchronize

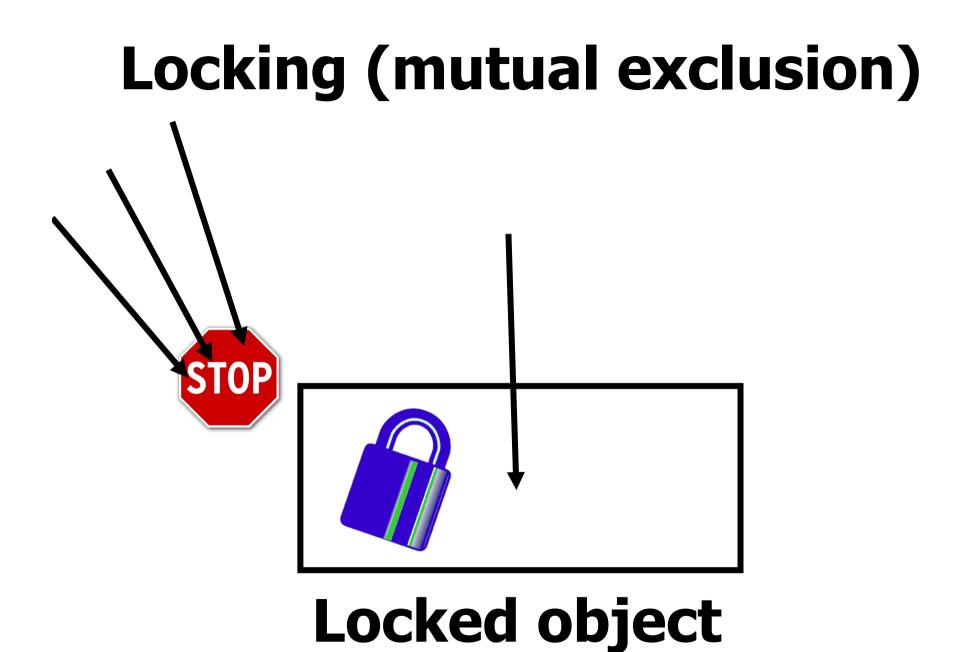
Concurrent processes



Shared object

Counter

```
public class Counter
private int c = 0;
public long getAndIncrement()
{
return c++;
}
```



Implicit use of a lock

```
public class SynchronizedCounter {
    private int c = 0;
    public synchronized void increment() {
        c++;
    }
    public synchronized void getAndincrement()
{
        return c++;
    }
    public synchronized int value() {
        return c;
    }
}
```

Locking with compare&swap()

- A Compare&Swap object maintains a value x, init to ⊥, and y;
- It provides one operation: c&s(old,new);
 - ✓ Sequential spec:
 - c&s(old,new)

{y := x; if x = old then x := new; return(y)}

Locking with compare&swap()

```
lock() {
repeat until
unlocked = this.c&s(unlocked,locked)
}
unlock() {
   this.c&s(locked,unlocked)
   }
```

Locking with test&set()

- A *Test&Set* object maintains binary values x, init to 0, and y;
- It provides one operation: t&s()

✓ Sequential spec:

✓ t&s() {y := x; x: = 1; return(y);}

Locking with test&set()

```
lock() {
repeat until (0 = this.t&s());
}
unlock() {
    this.setState(0);
    }
```

Locking with test&set()

```
lock() {
while (true)
 {
 repeat until (0 = this.getState());
 if 0 = (this.t&s()) return(true);
 }
unlock() {
         this.setState(0);
     }
```

Explicit use of a lock

```
Lock l = ...;
l.lock();
try {
// access the resource protected by this lock
} finally {
l.unlock();
}
```

Locking (mutual exclusion)

- *Difficult:* 50% of the bugs reported in Java come from the mis-use of « synchronized »
- *Fragile:* a process holding a lock prevents all others from progressing
- Slow: the act of locking itself impacts performance

Locked object

One process at a time

Processes are asynchronous

Page faults
Pre-emptions
Failures
Cache misses, ...

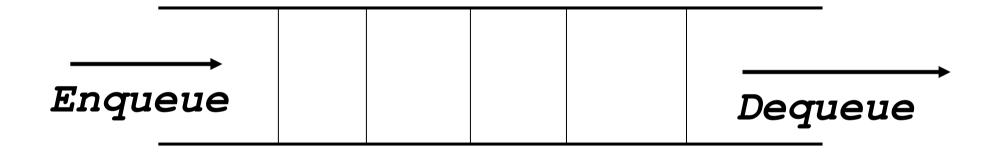
Processes are asynchronous

- A cache miss can delay a process by ten instructions
- A page fault by few millions
- An os preemption by hundreds of millions...

Coarse grained locks => slow

Fine grained locks => errors

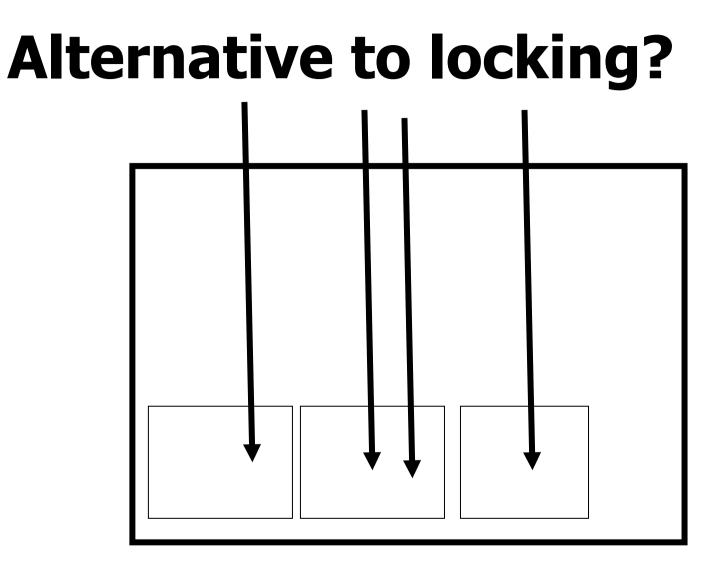
Double-ended queue



Processes are asynchronous

 Page faults, pre-emptions, failures, cache misses, ...

A process can be delayed by millions of instructions ...



Wait-free atomic objects

- Wait-freedom: every process that invokes an operation eventually returns from the invocation (robust ... unlike locking)
- Atomicity: every operation appears to execute instantaneously (as if the object was locked...)

In short

This course shows how to *wait-free* implement high-level *atomic* objects out of primitive base objects

Concurrent processes

Shared object

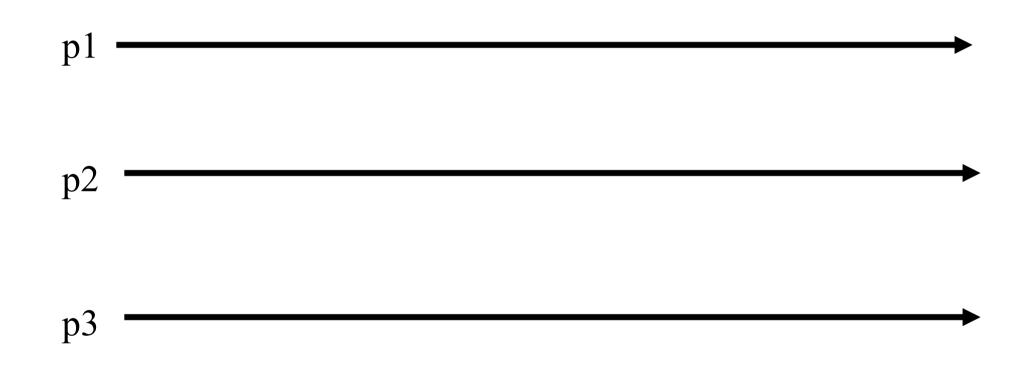
Roadmap

Model
 Processes and objects
 Atomicity and wait-freedom
 Examples
 Content

- We assume a finite set of processes
- Processes are denoted by p1,...pN or p, q, r
- Processes have unique identities and know each other (unless explicitly stated otherwise)

Processes are sequential units of computations

Inless explicitly stated otherwise, we make no assumption on process (relative) speed



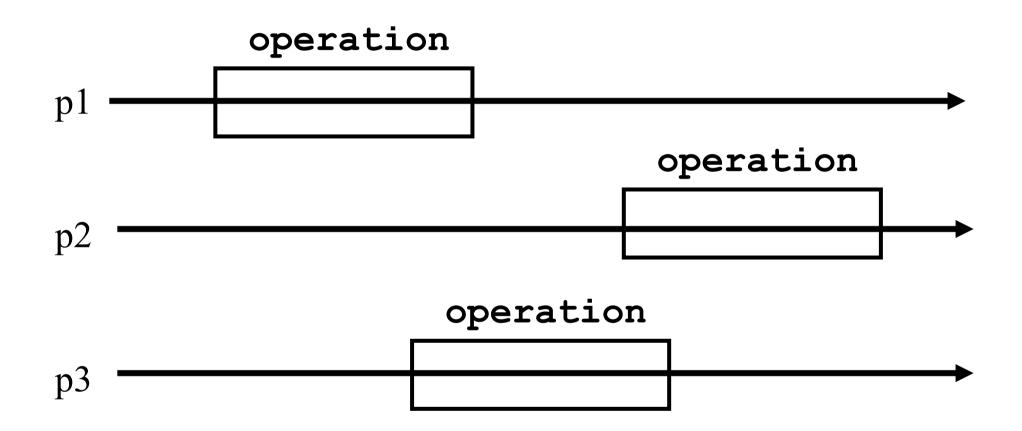
- A process either executes the algorithm assigned to it or crashes
- A process that crashes does not recover (in the context of the considered computation)
- A process that does not crash in a given execution (computation or run) is called correct (in that execution)

Processes p1 Vcrash p2 p3

On objects and processes

 Processes execute local computation or access shared objects through their operations

For Every operation is expected to return a reply

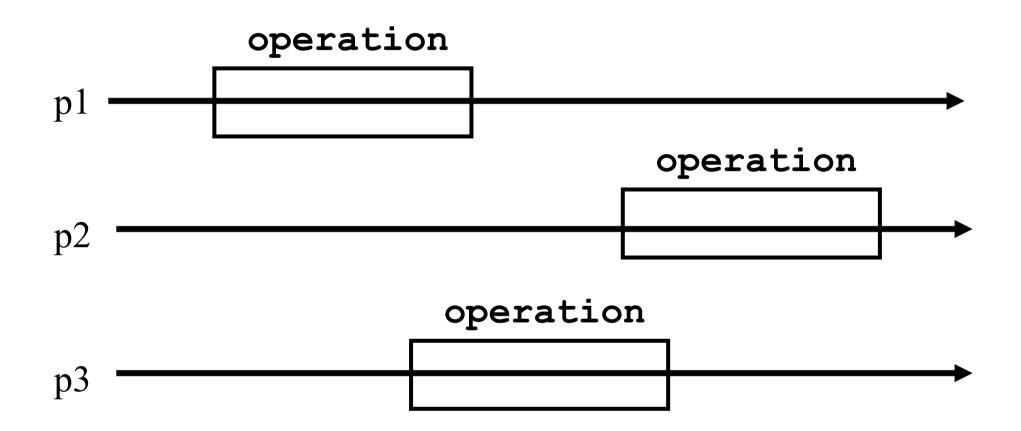


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On objects and processes

Sequentiality means here that, after invoking an operation op1 on some object O1, a process does not invoke a new operation (on the same or on some other object) until it receives the reply for op1

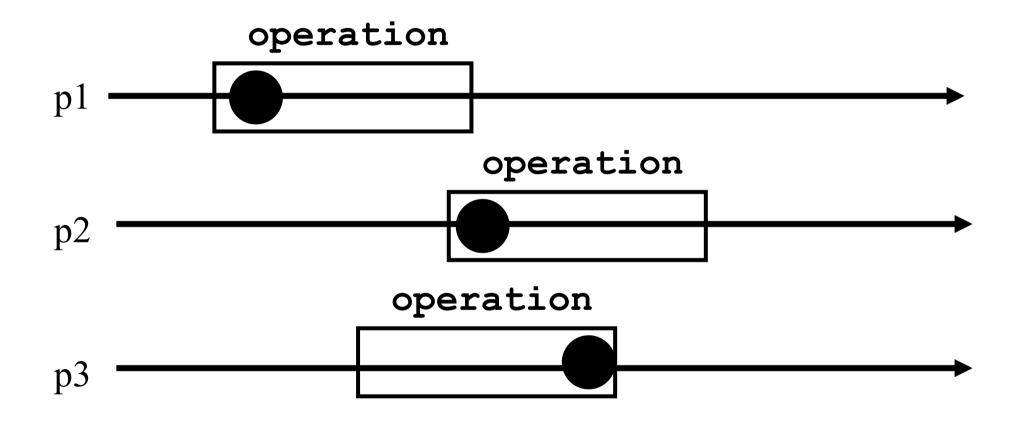
Remark. Sometimes we talk about operations when we should be talking about operation invocations



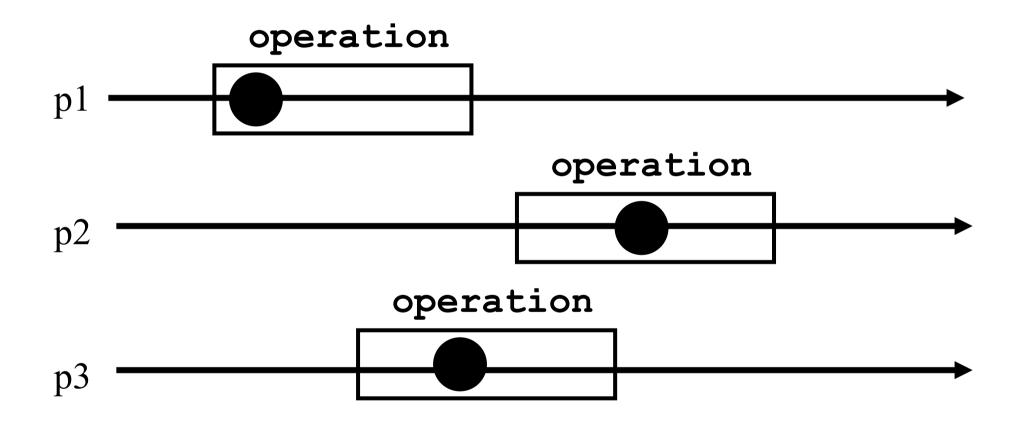
Atomicity

Every operation appears to execute at some indivisible point in time (called linearization point) between the invocation and reply time events

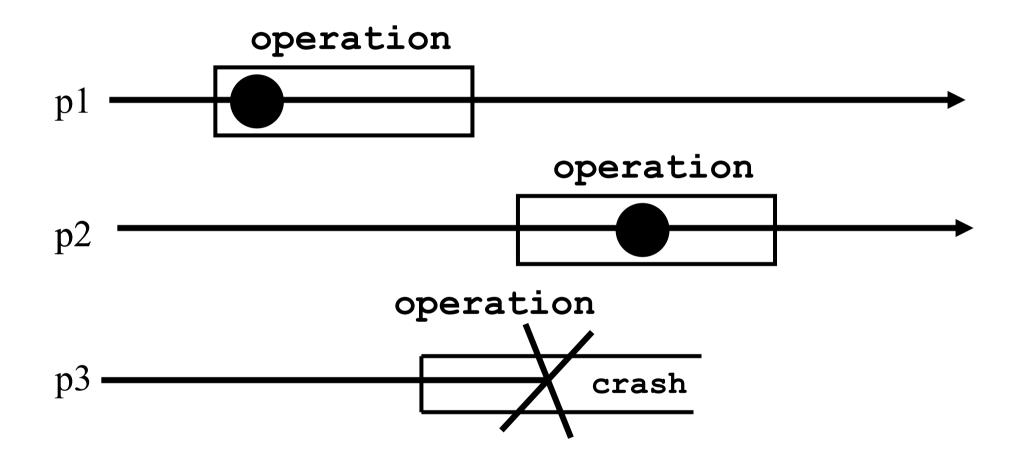
Atomicity



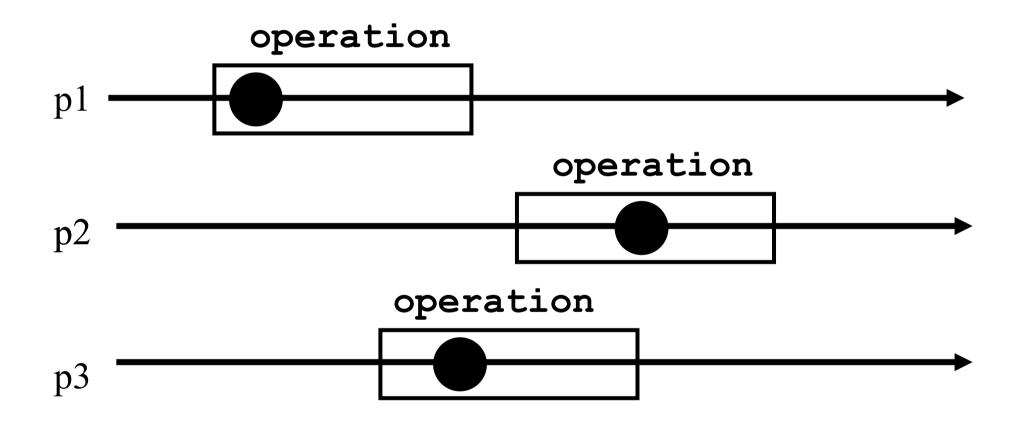
Atomicity



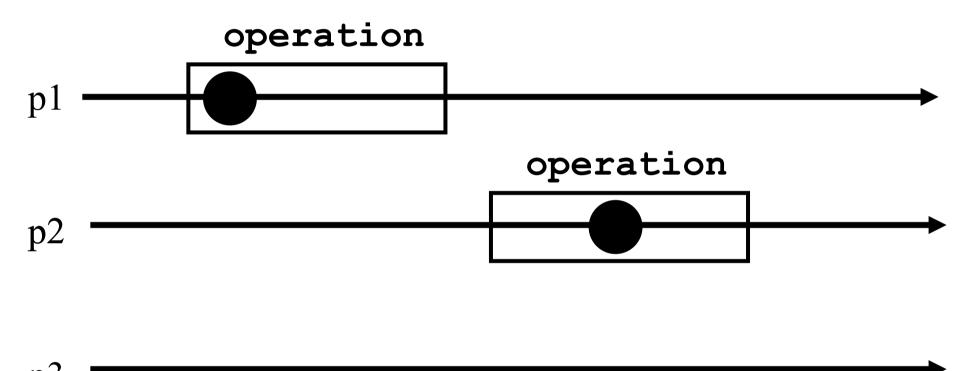
Atomicity (the crash case)



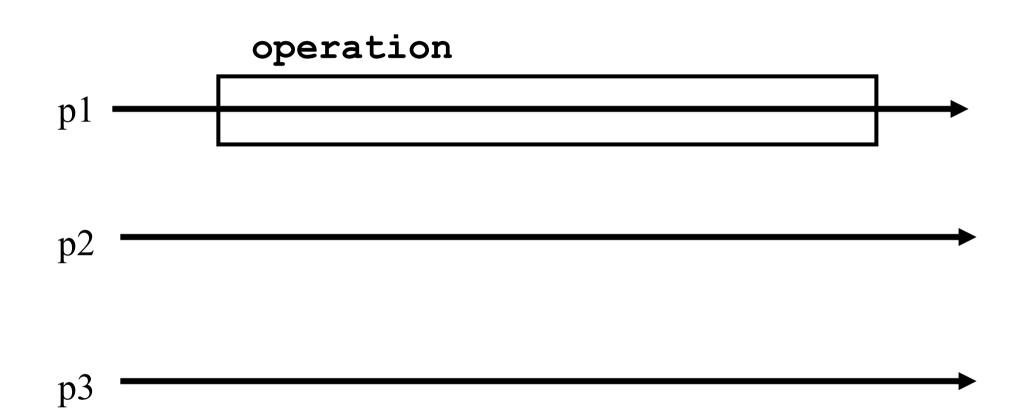
Atomicity (the crash case)



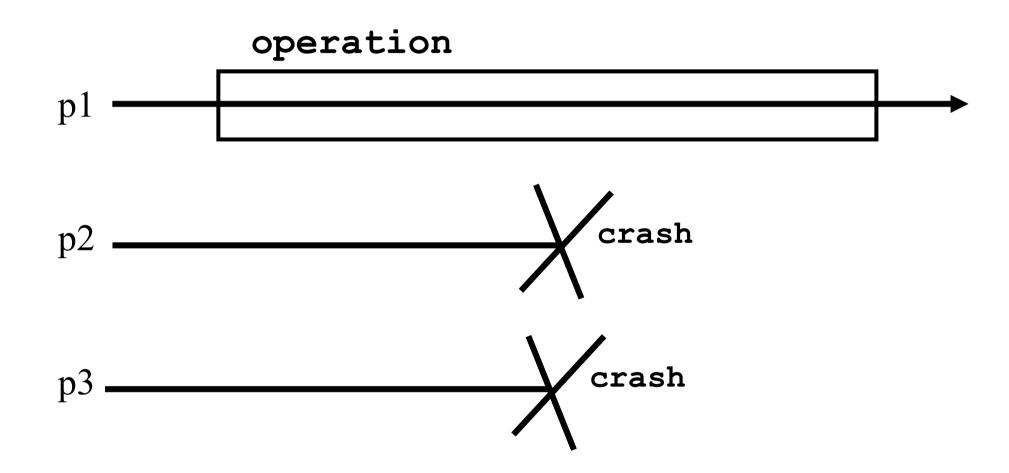
Atomicity (the crash case)



Any correct process that invokes an operation eventually gets a reply, no matter what happens to the other processes (crash or very slow)



- Wait-freedom conveys the robustness of the implementation
- With a wait-free implementation, a process gets replies despite the crash of the n-1 other processes
- Note that this precludes implementations based on locks (mutual exclusion)



Roadmap

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Motivation

 Most synchronization primitives (problems) can be precisely expressed as atomic objects (implementations)

Studying how to ensure robust synchronization boils down to studying wait-free atomic object implementations

Example 1

- The reader/writer synchronization problem corresponds to the *register* object
- Basically, the processes need to read or write a shared data structure such that the value read by a process at a time t, is the last value written before t

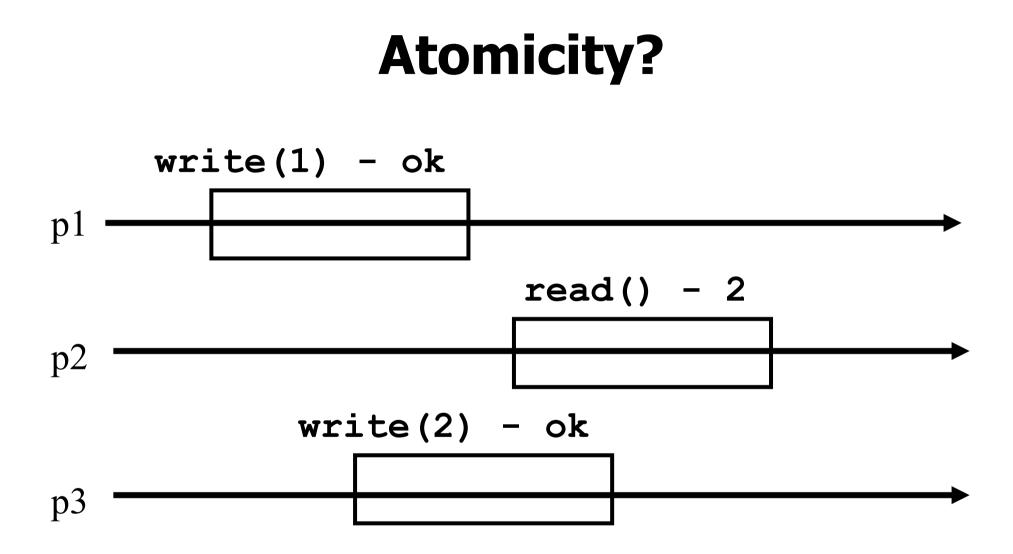
Register

A register has two operations: read() and write()

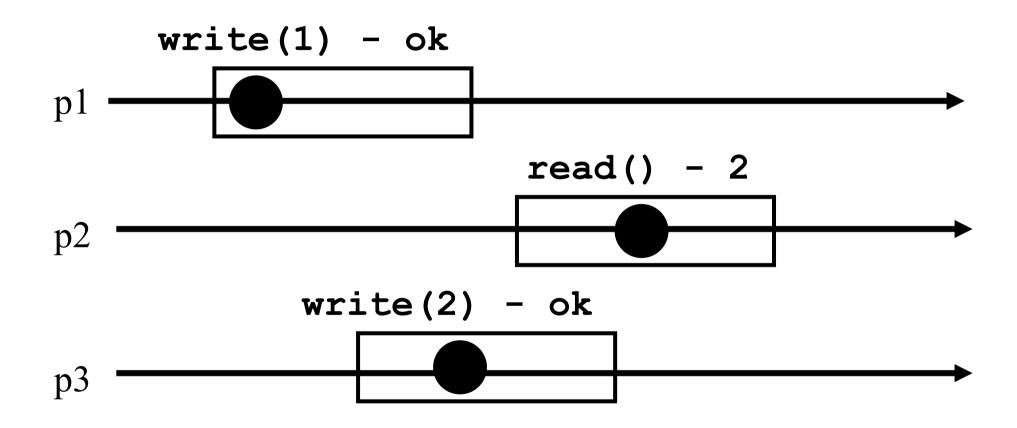
We assume that a *register* contains an integer for presentation simplicity, i.e., the value stored in the *register* is an integer, denoted by x (initially 0)

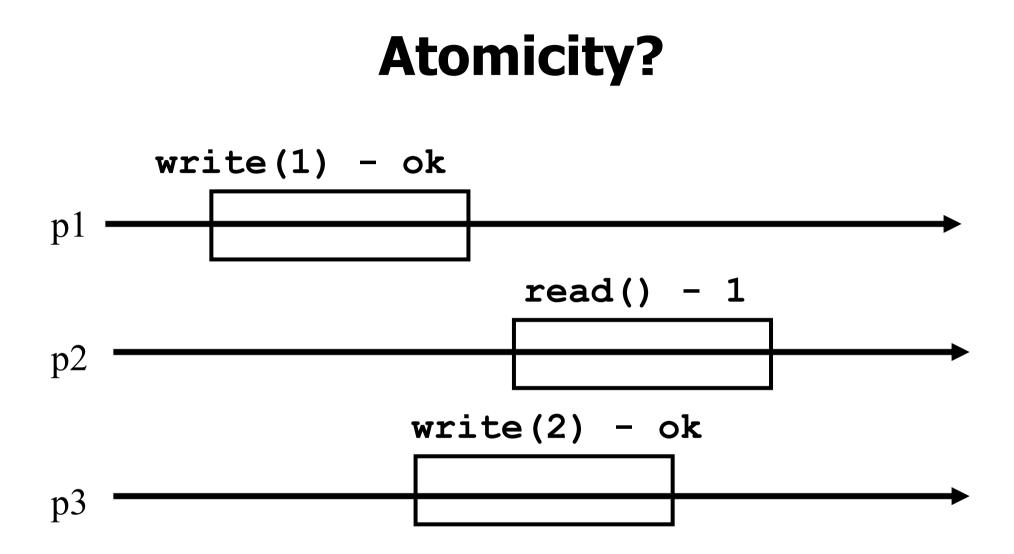
Sequential specification

Sequential specification read() return(x) write(v) *✓* X <- V; return(ok)

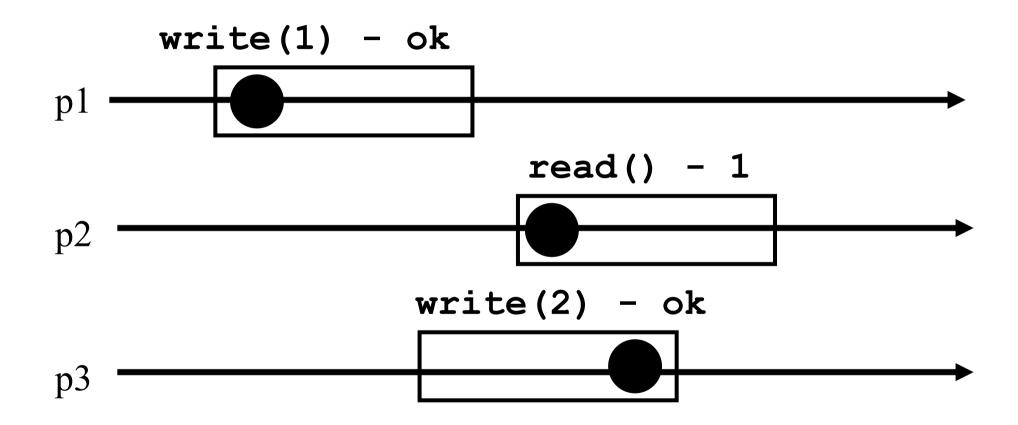


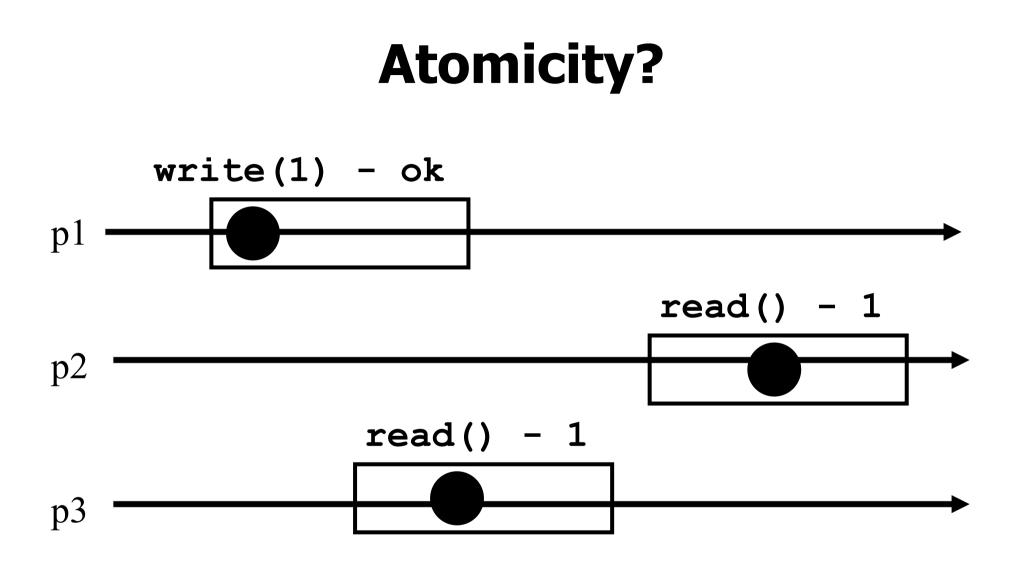
Atomicity?



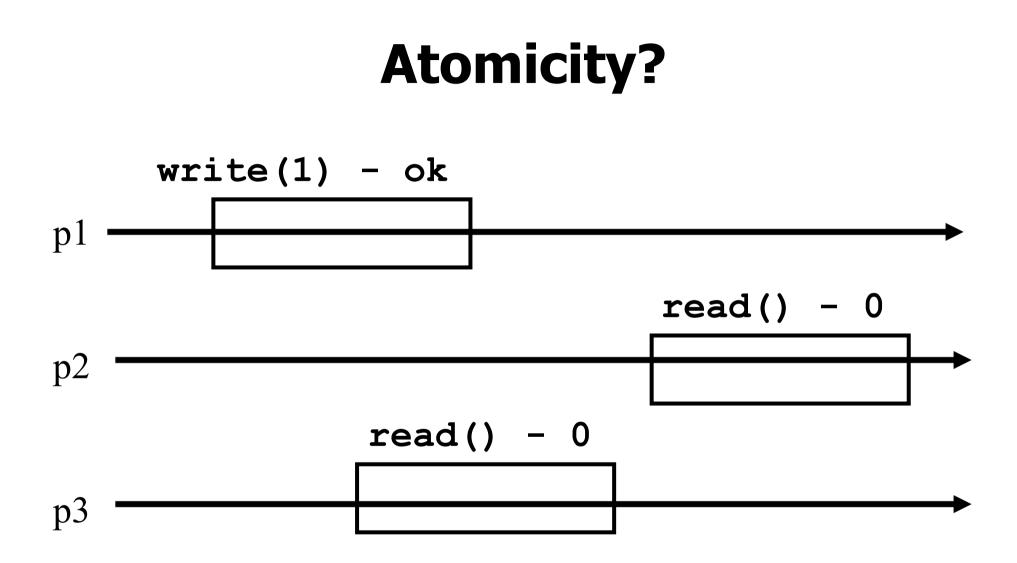


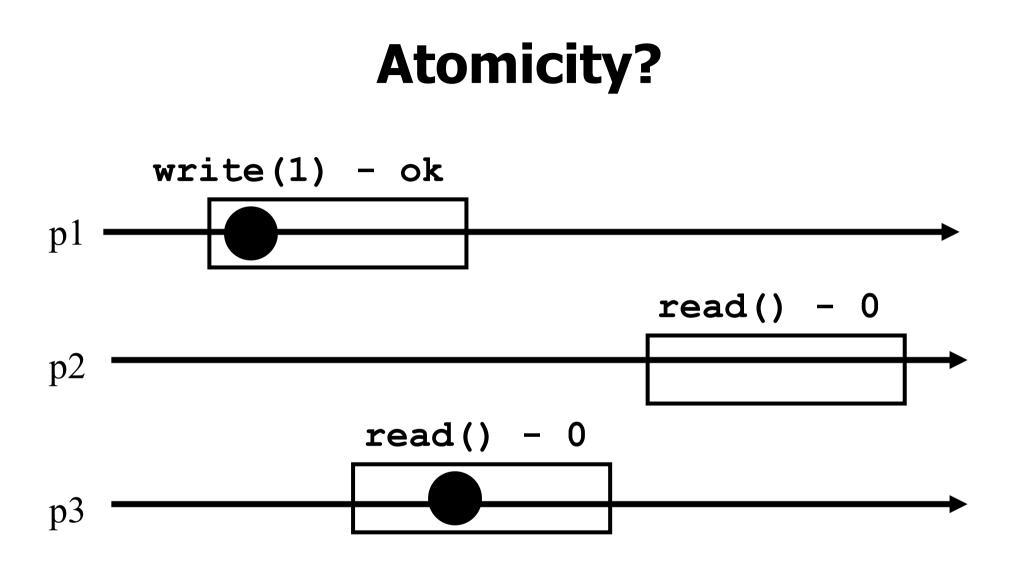
Atomicity?

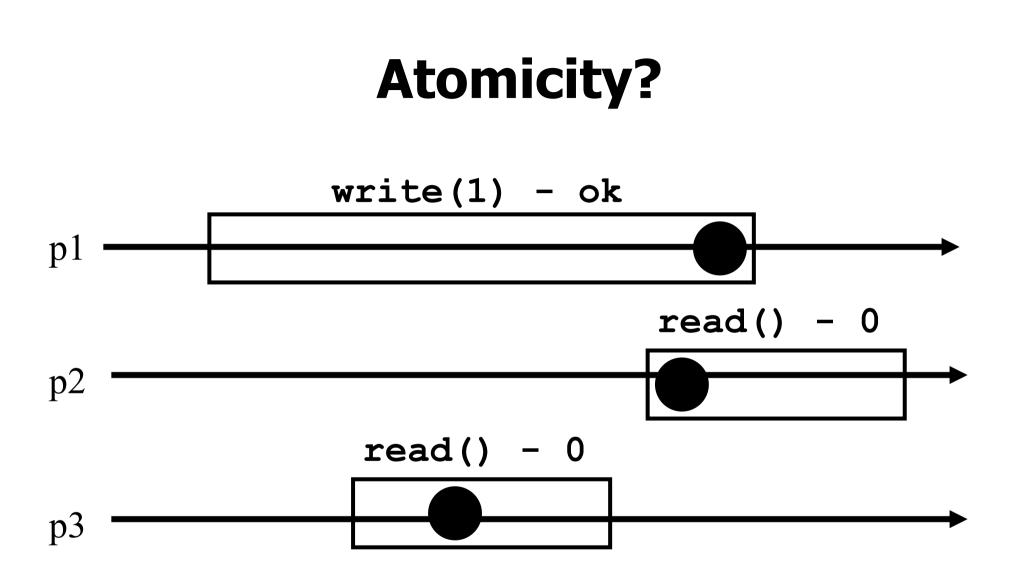


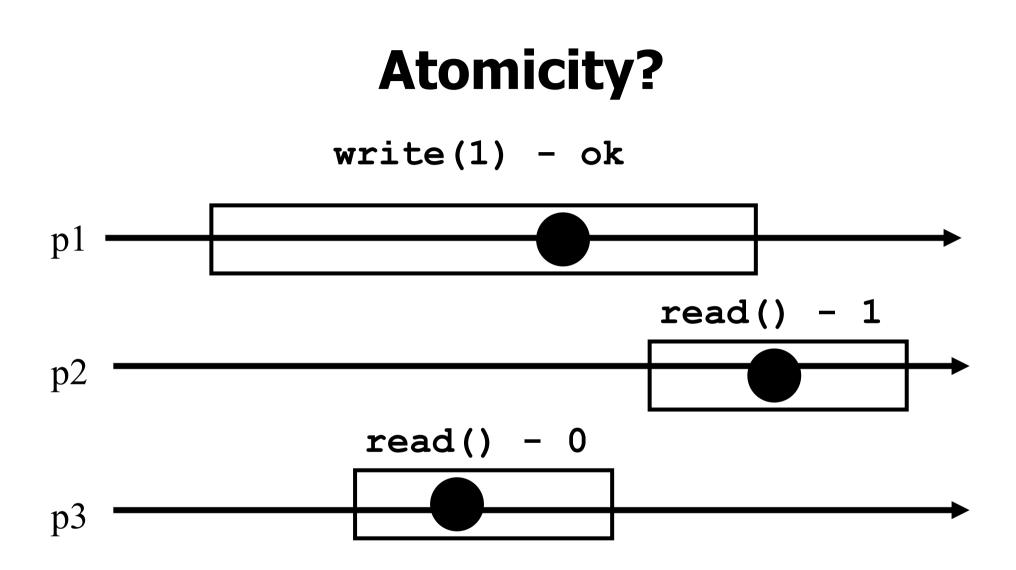


Atomicity? write(1) - ok p1 read() - 1p2 read() - 0p3



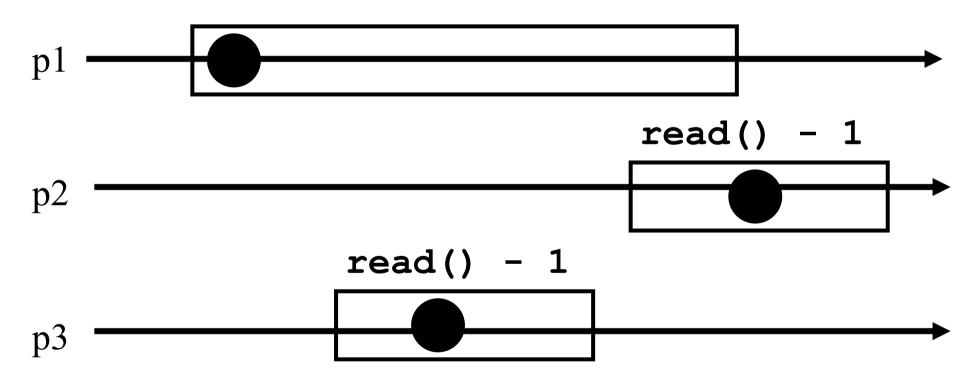






Atomicity?

write(1) - ok



Example 2

- The producer/consumer synchronization problem corresponds to the *queue* object
- Producer processes create items that need to be used by consumer processes
- An item cannot be consumed by two processes and the first item produced is the first consumed

Queue

A queue has two operations: enqueue() and dequeue()

We assume that a *queue internally* maintains a list x which exports operation *appends()* to put an item at the end of the list and *remove()* to remove an element from the head of the list

Sequential specification

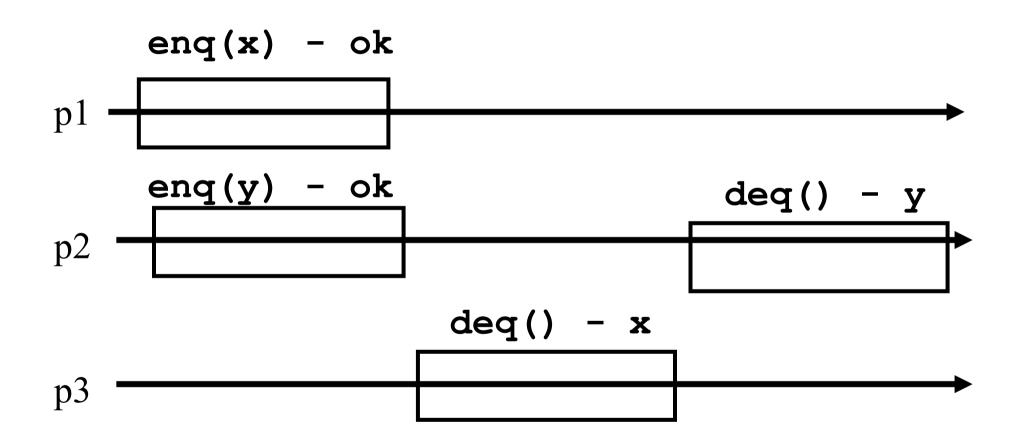
dequeue()

- if(x=0) then return(nil);
- else return(x.remove())

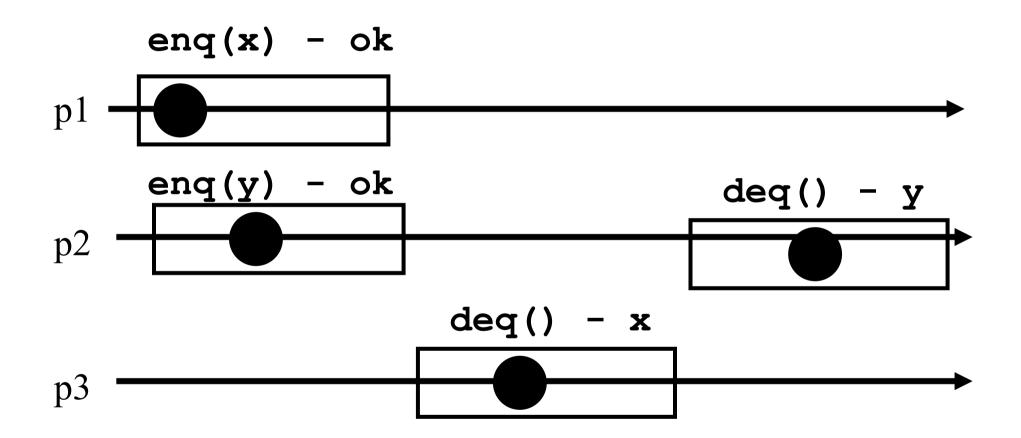
« enqueue(v)

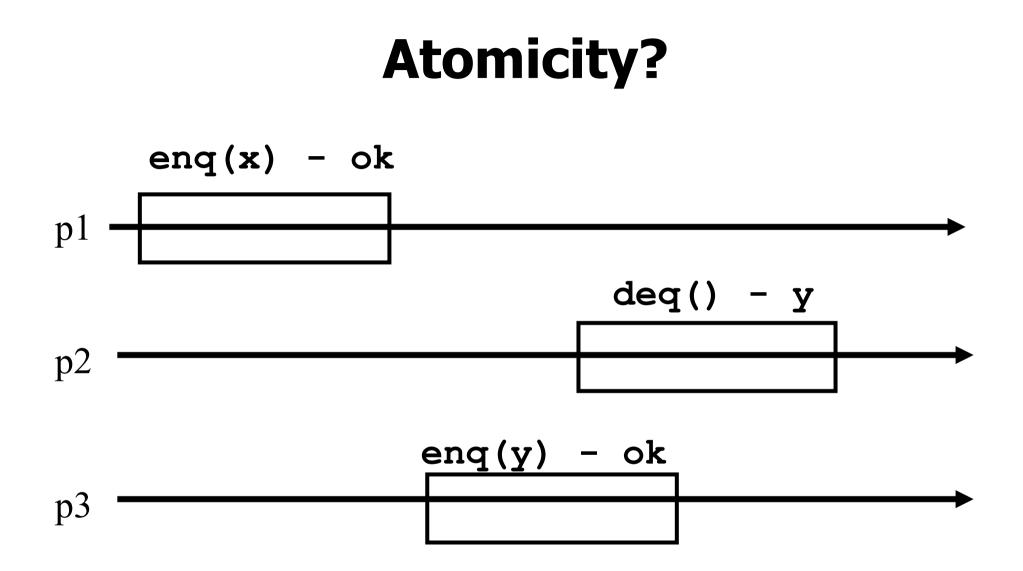
- r x.append(v);
- return(ok)

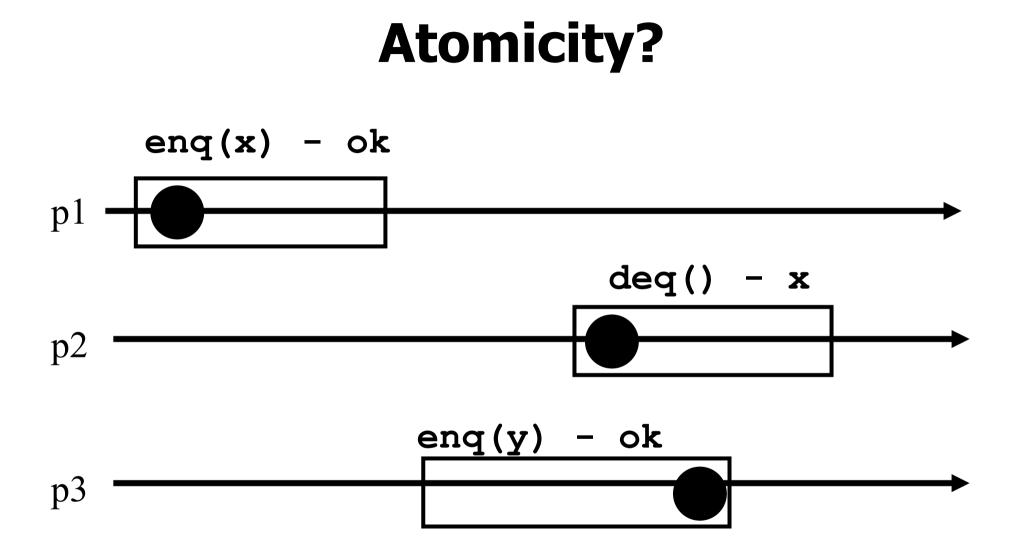
Atomicity?



Atomicity?







Roadmap

Model
 Processes and objects
 Atomicity and wait-freedom
 Examples
 Content

Content

- (1) Implementing *registers*
- (2) The power & limitation of *registers*
- (3) Universal objects & synchronization number
- (4) The power of *time* & failure detection
- (5) Tolerating *failure* prone objects
- (6) Anonymous implementations
- (7) Transaction memory

In short

This course shows how to wait-free implement high-level atomic objects out of basic objects

Remark. Unless explicitly stated otherwise, objects mean atomic objects and implementations are wait-free