

# The Limitations of Registers (cont'd)

Julien Stainer

Concurrent Algorithms  
Distributed Programming Laboratory  
`julien.stainer@epfl.ch`



ÉCOLE POLYTECHNIQUE  
FÉDÉRALE DE LAUSANNE



- ① Consensus from Stacks and Registers
- ② Immediate Snapshots
- ③ The Iterated Immediate Snapshot Model
- ④ Set Agreement in *IIS*
- ⑤  $k$ -Set Agreement from Registers

- 1 Consensus from Stacks and Registers
  - Problem Statement
  - The Case of Two Processes
  - The Case of Three Processes
- 2 Immediate Snapshots
- 3 The Iterated Immediate Snapshot Model
- 4 Set Agreement in *IIS*
- 5  $k$ -Set Agreement from Registers

Is it possible to **wait-free** implement a **consensus** object from **stacks** and **registers** in a system of **2** **processes**?

A **consensus** object offers an operation `PROPOSE( $v$ )` that returns a value. It fulfills the following properties:

**Termination** Any invocation of `PROPOSE` by a correct process terminates.

A **consensus** object offers an operation  $\text{PROPOSE}(v)$  that returns a value. It fulfills the following properties:

**Termination** Any invocation of  $\text{PROPOSE}$  by a correct process terminates.

**Agreement** At most one value is decided.

A **consensus** object offers an operation `PROPOSE( $v$ )` that returns a value. It fulfills the following properties:

**Termination** Any invocation of `PROPOSE` by a correct process terminates.

**Agreement** At most one value is decided.

**Validity** A decided value is a proposed value.

# Two Processes Consensus from a Stack and Registers

- 1: **initialization**
- 2:      $REG[0] \leftarrow \perp; REG[1] \leftarrow \perp$
- 3:      $S.push(\text{loser}); S.push(\text{winner})$
- 4: **operation**  $PROPOSE(v)$
- 5:      $REG[id] \leftarrow v$
- 6:     **if**  $S.pop() = \text{winner}$  **then**
- 7:         return  $v$
- 8:     **else**
- 9:         return  $REG[1 - id]$



- With 3 processes, the losers cannot easily know which value to adopt.

- With 3 processes, the losers cannot easily know which value to adopt.
- Even with several stacks and more registers, how to organize?

Is it possible to **wait-free** implement a **consensus** object from **stacks** and **registers** in a system of **3** **processes**?

- Suppose that there exists an algorithm solving 3 processes consensus from stacks and registers.

- Suppose that there exists an algorithm solving 3 processes consensus from stacks and registers.
- Show that there is a schedule in which a process takes an infinite number of steps but does not decide.

- Suppose that there exists an algorithm solving 3 processes consensus from stacks and registers.
- Show that there is a schedule in which a process takes an infinite number of steps but does not decide.
- This contradicts the termination property. Consequently, there is no such algorithm.

## Lemma 1

The initial configuration  $C(0, 1, 0)$  is bivalent.

## Lemma 1

The initial configuration  $C(0, 1, 0)$  is bivalent.

- Starting from  $C(0, 1, 0)$ , if  $p_1$  executes alone, it has to decide 0 because it cannot distinguish between this execution and the one starting from  $C(0, 0, 0)$  where it executes alone.



## Lemma 1

The initial configuration  $C(0, 1, 0)$  is bivalent.

- Starting from  $C(0, 1, 0)$ , if  $p_1$  executes alone, it has to decide 0 because it cannot distinguish between this execution and the one starting from  $C(0, 0, 0)$  where it executes alone.
- Starting from  $C(0, 1, 0)$ , if  $p_2$  executes alone, it has to decide 1 because it cannot distinguish between this execution and the one starting by  $C(1, 1, 1)$  where it executes alone.

## Lemma 1

The initial configuration  $C(0, 1, 0)$  is bivalent.

- Starting from  $C(0, 1, 0)$ , if  $p_1$  executes alone, it has to decide 0 because it cannot distinguish between this execution and the one starting from  $C(0, 0, 0)$  where it executes alone.
- Starting from  $C(0, 1, 0)$ , if  $p_2$  executes alone, it has to decide 1 because it cannot distinguish between this execution and the one starting by  $C(1, 1, 1)$  where it executes alone.
- Consequently,  $C(0, 1, 0)$  is bivalent.

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that
  - $\Sigma(C(0, 1, 0))$  is bivalent;

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that
  - $\Sigma(C(0, 1, 0))$  is bivalent;
  - $\forall i \in \{1, 2, 3\} : p_i(\Sigma(C(0, 1, 0)))$  is monovalent.

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that
  - $\Sigma(C(0, 1, 0))$  is bivalent;
  - $\forall i \in \{1, 2, 3\} : p_i(\Sigma(C(0, 1, 0)))$  is monovalent.
- Necessarily, there are two processes  $p_i$  and  $p_j$  such that  $p_i(\Sigma(C(0, 1, 0)))$  is 0-valent while  $p_j(\Sigma(C(0, 1, 0)))$  is 1-valent.

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that
  - $\Sigma(C(0, 1, 0))$  is bivalent;
  - $\forall i \in \{1, 2, 3\} : p_i(\Sigma(C(0, 1, 0)))$  is monovalent.
- Necessarily, there are two processes  $p_i$  and  $p_j$  such that  $p_i(\Sigma(C(0, 1, 0)))$  is 0-valent while  $p_j(\Sigma(C(0, 1, 0)))$  is 1-valent.
- Let  $op_i$  (resp.  $op_j$ ) be the next step executed by  $p_i$  (resp.  $p_j$ ) in  $\Sigma(C(0, 1, 0))$ .

# Maximal Schedule Leading to a Bivalent Configuration

- Consider a schedule  $\Sigma$  such that
  - $\Sigma(C(0, 1, 0))$  is bivalent;
  - $\forall i \in \{1, 2, 3\} : p_i(\Sigma(C(0, 1, 0)))$  is monovalent.
- Necessarily, there are two processes  $p_i$  and  $p_j$  such that  $p_i(\Sigma(C(0, 1, 0)))$  is 0-valent while  $p_j(\Sigma(C(0, 1, 0)))$  is 1-valent.
- Let  $op_i$  (resp.  $op_j$ ) be the next step executed by  $p_i$  (resp.  $p_j$ ) in  $\Sigma(C(0, 1, 0))$ .
- If  $op_i$  and  $op_j$  commute, then processes cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_j(p_i(\Sigma(C(0, 1, 0))))$  while one is 0-valent and the other is 1-valent. This is a contradiction.



- Since  $op_i$  and  $op_j$  do not commute, they are both invocations of operations on the same stack or register.

## Possible Values for $op_i$ and $op_j$

- Since  $op_i$  and  $op_j$  do not commute, they are both invocations of operations on the same stack or register.
- Two reads on the same register commute, so if  $op_i$  and  $op_j$  are both accesses to the same register, at least one of them is a write.

## Possible Values for $op_i$ and $op_j$

- Since  $op_i$  and  $op_j$  do not commute, they are both invocations of operations on the same stack or register.
- Two reads on the same register commute, so if  $op_i$  and  $op_j$  are both accesses to the same register, at least one of them is a write.
- If they are both writes to the same register, then  $p_i$  cannot distinguish between  $p_i(\Sigma(C(0, 1, 0)))$  and  $p_i(p_j(\Sigma(C(0, 1, 0))))$ , while one is 0-valent and the other 1-valent. This is a contradiction.

- If  $op_i$  is a write to a register and  $op_j$  a read to the same register, then  $p_i$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_i(\Sigma(C(0, 1, 0)))$  while the former is 1-valent and the latter is 0-valent. This is a contradiction.

- If  $op_i$  is a write to a register and  $op_j$  a read to the same register, then  $p_i$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_i(\Sigma(C(0, 1, 0)))$  while the former is 1-valent and the latter is 0-valent. This is a contradiction.
- Symmetric arguments apply when inverting the valence of  $p_i(\Sigma(C(0, 1, 0)))$  and  $p_j(\Sigma(C(0, 1, 0)))$  or when  $op_i$  and  $op_j$  are respectively a read and a write to the same register.

- If  $op_i$  is a write to a register and  $op_j$  a read to the same register, then  $p_i$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_i(\Sigma(C(0, 1, 0)))$  while the former is 1-valent and the latter is 0-valent. This is a contradiction.
- Symmetric arguments apply when inverting the valence of  $p_i(\Sigma(C(0, 1, 0)))$  and  $p_j(\Sigma(C(0, 1, 0)))$  or when  $op_i$  and  $op_j$  are respectively a read and a write to the same register.
- It follows that  $op_i$  and  $op_j$  are necessarily invocations of operations on the same stack.

- If both  $op_i$  and  $op_j$  are pop operations on the same stack, then  $p_k, k \in \{1, 2, 3\} \setminus \{i, j\}$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_j(p_i(\Sigma(C(0, 1, 0))))$  while one is 0-valent and the other 1-valent. This is a contradiction.

- If both  $op_i$  and  $op_j$  are pop operations on the same stack, then  $p_k, k \in \{1, 2, 3\} \setminus \{i, j\}$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_j(p_i(\Sigma(C(0, 1, 0))))$  while one is 0-valent and the other 1-valent. This is a contradiction.
- If  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack, then we have two cases:



- If both  $op_i$  and  $op_j$  are pop operations on the same stack, then  $p_k, k \in \{1, 2, 3\} \setminus \{i, j\}$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_j(p_i(\Sigma(C(0, 1, 0))))$  while one is 0-valent and the other 1-valent. This is a contradiction.
- If  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack, then we have two cases:
  - If in  $\Sigma(C(0, 1, 0))$  the stack is empty, then  $p_k$  cannot distinguish between  $p_j(p_i(\Sigma(C(0, 1, 0))))$  and  $p_j(\Sigma(C(0, 1, 0)))$  while the former is 0-valent and the latter is 1-valent. This is a contradiction.

- If both  $op_i$  and  $op_j$  are pop operations on the same stack, then  $p_k, k \in \{1, 2, 3\} \setminus \{i, j\}$  cannot distinguish between  $p_i(p_j(\Sigma(C(0, 1, 0))))$  and  $p_j(p_i(\Sigma(C(0, 1, 0))))$  while one is 0-valent and the other 1-valent. This is a contradiction.
- If  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack, then we have two cases:
  - If in  $\Sigma(C(0, 1, 0))$  the stack is empty, then  $p_k$  cannot distinguish between  $p_j(p_i(\Sigma(C(0, 1, 0))))$  and  $p_j(\Sigma(C(0, 1, 0)))$  while the former is 0-valent and the latter is 1-valent. This is a contradiction.
  - If in  $\Sigma(C(0, 1, 0))$  the stack is not empty, then we need a further analysis.

In this case  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack that is not empty in  $\Sigma(C(0, 1, 0))$ .

- If  $p_i$  runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ , it necessarily eventually pops the item  $z$  that was on top of the stack in  $\Sigma(C(0, 1, 0))$  or it would not distinguish between the situation when it runs alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$  while it has to decide 0 in the first situation and 1 in the second.

In this case  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack that is not empty in  $\Sigma(C(0, 1, 0))$ .

- If  $p_i$  runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ , it necessarily eventually pops the item  $z$  that was on top of the stack in  $\Sigma(C(0, 1, 0))$  or it would not distinguish between the situation when it runs alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$  while it has to decide 0 in the first situation and 1 in the second.
- Let  $\Sigma_i$  be the schedule in which  $p_i$  executes solo from  $p_j(p_i(\Sigma(C(0, 1, 0))))$  until just after it pops the item  $z$ .

In this case  $op_i$  is a push operation and  $op_j$  a pop operation on the same stack that is not empty in  $\Sigma(C(0, 1, 0))$ .

- If  $p_i$  runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ , it necessarily eventually pops the item  $z$  that was on top of the stack in  $\Sigma(C(0, 1, 0))$  or it would not distinguish between the situation when it runs alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$  while it has to decide 0 in the first situation and 1 in the second.
- Let  $\Sigma_i$  be the schedule in which  $p_i$  executes solo from  $p_j(p_i(\Sigma(C(0, 1, 0))))$  until just after it pops the item  $z$ .
- Since until this pop operation  $p_i$  cannot distinguish if it started from  $p_j(p_i(\Sigma(C(0, 1, 0))))$  or  $p_i(p_j(\Sigma(C(0, 1, 0))))$ , it also takes the same steps while running alone from the later configuration. The only difference is the value it pops at the last step of  $\Sigma_i$ .

- $p_k$  cannot distinguish between  $\Sigma_i(p_j(p_i(\Sigma(C(0, 1, 0)))))$  and  $\Sigma_i(p_i(p_j(\Sigma(C(0, 1, 0)))))$  because the stack is in the same state in both configurations. The former configuration being 0-valent while the latter is 1-valent, this is a contradiction.

- $p_k$  cannot distinguish between  $\Sigma_i(p_j(p_i(\Sigma(C(0, 1, 0)))))$  and  $\Sigma_i(p_i(p_j(\Sigma(C(0, 1, 0)))))$  because the stack is in the same state in both configurations. The former configuration being 0-valent while the latter is 1-valent, this is a contradiction.
- The same reasoning applies if the roles of  $p_i$  and  $p_j$  swapped.

- If  $op_i$  and  $op_j$  are both push operations on the same stack, then, when running alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$ ,  $p_i$  necessarily eventually pops the item it pushed at  $op_i$  or it would not be able to distinguish this execution from the one when it runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ .



- If  $op_i$  and  $op_j$  are both push operations on the same stack, then, when running alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$ ,  $p_i$  necessarily eventually pops the item it pushed at  $op_i$  or it would not be able to distinguish this execution from the one when it runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ .
- Let  $\Sigma'_i$  be the schedule in which  $p_i$  executes alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$  until just after it pops the value pushed by  $op_i$ .

## Possible Values for $op_i$ and $op_j$

- If  $op_i$  and  $op_j$  are both push operations on the same stack, then, when running alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$ ,  $p_i$  necessarily eventually pops the item it pushed at  $op_i$  or it would not be able to distinguish this execution from the one when it runs alone from  $p_j(p_i(\Sigma(C(0, 1, 0))))$ .
- Let  $\Sigma'_i$  be the schedule in which  $p_i$  executes alone from  $p_i(p_j(\Sigma(C(0, 1, 0))))$  until just after it pops the value pushed by  $op_i$ .
- With the same reasoning, starting from  $\Sigma'_i(p_i(p_j(\Sigma(C(0, 1, 0))))$  or from  $\Sigma'_i(p_j(p_i(\Sigma(C(0, 1, 0))))$ ,  $p_j$  necessarily take the same steps until it eventually pops the value pushed by  $op_j$  (in the first situation) or by  $op_i$  (in the second one). Let us denote  $\Sigma'_j$  its steps until just after this pop.

- $p_k$  is not able to distinguish between  $\Sigma'_j(\Sigma'_i(p_i(p_j(\Sigma(C(0, 1, 0))))))$  and  $\Sigma'_j(\Sigma'_i(p_i(p_j(\Sigma(C(0, 1, 0))))))$ . This is a contradiction because the former is 1-valent while the latter is 0-valent.

- $p_k$  is not able to distinguish between  $\Sigma'_j(\Sigma'_i(p_i(p_j(\Sigma(C(0, 1, 0))))))$  and  $\Sigma'_j(\Sigma'_i(p_i(p_j(\Sigma(C(0, 1, 0))))))$ . This is a contradiction because the former is 1-valent while the latter is 0-valent.
- In all cases we reach a contradiction. It follows that there exists a schedule such that a process takes an infinite number of steps without deciding, which concludes the proof.

It is impossible to wait-free  
implement consensus among 3  
processes from stacks and  
registers.

- 1 Consensus from Stacks and Registers
- 2 Immediate Snapshots
  - Immediate Snapshot Specification
  - Set-Linearizability
  - Immediate Snapshot Algorithm
- 3 The Iterated Immediate Snapshot Model
- 4 Set Agreement in *IIS*
- 5  $k$ -Set Agreement from Registers

An **immediate snapshot** object offers an operation `WRITE-SNAPSHOT( $v$ )` that can be invoked **at most once** by each process. It returns a set *view* of pairs  $(j, v_j)$  where  $j$  is a process identifier and  $v_j$  a value. If we denote by  $view_i$  the set returned to process  $i$ , we have the following properties:

**Termination** Any invocation of `WRITE-SNAPSHOT` by a correct process terminates.

An **immediate snapshot** object offers an operation  $\text{WRITE-SNAPSHOT}(v)$  that can be invoked **at most once** by each process. It returns a set *view* of pairs  $(j, v_j)$  where  $j$  is a process identifier and  $v_j$  a value. If we denote by  $\text{view}_i$  the set returned to process  $i$ , we have the following properties:

**Termination** Any invocation of  $\text{WRITE-SNAPSHOT}$  by a correct process terminates.

**Validity** If  $(j, v_j) \in \text{view}_i$ , then process  $j$  invoked  $\text{WRITE-SNAPSHOT}(v_j)$ .



An **immediate snapshot** object offers an operation  $\text{WRITE-SNAPSHOT}(v)$  that can be invoked **at most once** by each process. It returns a set *view* of pairs  $(j, v_j)$  where  $j$  is a process identifier and  $v_j$  a value. If we denote by  $\text{view}_i$  the set returned to process  $i$ , we have the following properties:

**Termination** Any invocation of  $\text{WRITE-SNAPSHOT}$  by a correct process terminates.

**Validity** If  $(j, v_j) \in \text{view}_i$ , then process  $j$  invoked  $\text{WRITE-SNAPSHOT}(v_j)$ .

**Self-Inclusion**  $(id, v_{id}) \in \text{view}_{id}$ .

An **immediate snapshot** object offers an operation  $\text{WRITE-SNAPSHOT}(v)$  that can be invoked **at most once** by each process. It returns a set *view* of pairs  $(j, v_j)$  where  $j$  is a process identifier and  $v_j$  a value. If we denote by  $\text{view}_i$  the set returned to process  $i$ , we have the following properties:

**Termination** Any invocation of  $\text{WRITE-SNAPSHOT}$  by a correct process terminates.

**Validity** If  $(j, v_j) \in \text{view}_i$ , then process  $j$  invoked  $\text{WRITE-SNAPSHOT}(v_j)$ .

**Self-Inclusion**  $(id, v_{id}) \in \text{view}_{id}$ .

**Containment**  $\forall i, j : \text{view}_i \subseteq \text{view}_j \vee \text{view}_j \subseteq \text{view}_i$ .

An **immediate snapshot** object offers an operation  $\text{WRITE-APSHOT}(v)$  that can be invoked **at most once** by each process. It returns a set *view* of pairs  $(j, v_j)$  where  $j$  is a process identifier and  $v_j$  a value. If we denote by  $\text{view}_i$  the set returned to process  $i$ , we have the following properties:

**Termination** Any invocation of  $\text{WRITE-APSHOT}$  by a correct process terminates.

**Validity** If  $(j, v_j) \in \text{view}_i$ , then process  $j$  invoked  $\text{WRITE-APSHOT}(v_j)$ .

**Self-Inclusion**  $(id, v_{id}) \in \text{view}_{id}$ .

**Containment**  $\forall i, j : \text{view}_i \subseteq \text{view}_j \vee \text{view}_j \subseteq \text{view}_i$ .

**Immediacy**  $\forall i, j : (j, v_j) \in \text{view}_i \implies \text{view}_j \subseteq \text{view}_i$ .

## Theorem

$$((i, v_i) \in view_j \wedge (j, v_j) \in view_i) \implies view_i = view_j$$

## Theorem

$$((i, v_i) \in view_j \wedge (j, v_j) \in view_i) \implies view_i = view_j$$

## Consequence

The calls to an immediate snapshot object can be **set-linearized** by ordering the processes according to the size of their views.

One by one:

$$view_1 = \{(1, v_1)\} \subsetneq view_2 = \{(1, v_1), (2, v_2)\} \subsetneq view_3 = \{(1, v_1), (2, v_2), (3, v_3)\}$$

Two then one:

$$view_1 = view_2 = \{(1, v_1), (2, v_2)\} \subsetneq view_3 = \{(1, v_1), (2, v_2), (3, v_3)\}$$

Three together:

$$view_1 = view_2 = view_3 = \{(1, v_1), (2, v_2), (3, v_3)\}$$

- 1: **initialization**
- 2:      $REG[1, \dots, n][1, \dots, n] \leftarrow [[\perp, \dots, \perp], \dots, [\perp, \dots, \perp]]$
- 3: **operation** WRITE-SNAPSHOT( $v$ )
- 4:     return REC\_WRITE-SNAPSHOT( $n, v$ )
- 5: **operation** REC\_WRITE-SNAPSHOT( $x, v$ )
- 6:      $REG[x][id] \leftarrow v$
- 7:     **for**  $i \in \{1, \dots, n\}$  **do**  $scan[j] \leftarrow REG[x][j]$  **end for**
- 8:      $view \leftarrow \{(j, scan[j]) \mid scan[j] \neq \perp\}$
- 9:     **if**  $|view| = x$  **then**
- 10:         return  $view$
- 11:     **else**
- 12:         return REC\_WRITE-SNAPSHOT( $x - 1, v$ )

- 1 Consensus from Stacks and Registers
- 2 Immediate Snapshots
- 3 The Iterated Immediate Snapshot Model**  
Computation Model  
Equivalence Theorem
- 4 Set Agreement in *IIS*
- 5  $k$ -Set Agreement from Registers



# The Iterated Immediate Snapshot Model

- Processes execute a sequence of asynchronous rounds.

# The Iterated Immediate Snapshot Model

- Processes execute a sequence of asynchronous rounds.
- During each round, a process that has not crashed invokes `WRITE-SNAPSHOT( $s$ )` to write its current state in the immediate snapshot object  $IS[r]$  associated to the round, and to collect the states of other processes.

# The Iterated Immediate Snapshot Model

- Processes execute a sequence of asynchronous rounds.
- During each round, a process that has not crashed invokes `WRITE-SNAPSHOT( $s$ )` to write its current state in the immediate snapshot object  $IS[r]$  associated to the round, and to collect the states of other processes.
- It then updates its state to include the knowledge it has gained on the state of other processes and proceeds to the next round.

# The Iterated Immediate Snapshot Model

- Processes execute a sequence of asynchronous rounds.
- During each round, a process that has not crashed invokes `WRITE-SNAPSHOT( $s$ )` to write its current state in the immediate snapshot object  $IS[r]$  associated to the round, and to collect the states of other processes.
- It then updates its state to include the knowledge it has gained on the state of other processes and proceeds to the next round.
- After a predetermined number of rounds  $R$ , a process that does not crash decides a value by applying a deterministic function `DECIDE` of its final state.

# The Iterated Immediate Snapshot Model

1: **initialization**

2:  $s \leftarrow \{\langle 0, \text{input of the process} \rangle\}$

3:  $r \leftarrow 1$

4: **while**  $r \leq R$  **do**

5:  $view \leftarrow IS[r].\text{WRITE-SNAPSHOT}(s)$

6:  $s \leftarrow s \cup \{\langle r, view \rangle\}$

7:  $r \leftarrow r + 1$

8:  $\text{DECIDE}(s)$

## The Read/Write Wait-free Model vs. *IIS*

- As shown before, *IIS* can be simulated in the read/write wait-free model.

# The Read/Write Wait-free Model vs. $\mathcal{IIS}$

- As shown before,  $\mathcal{IIS}$  can be simulated in the read/write wait-free model.
- Any one-shot colorless task that can be solved in the read/write wait-free model can be solved in  $\mathcal{IIS}$ .

# The Read/Write Wait-free Model vs. *ILIS*

- As shown before, *ILIS* can be simulated in the read/write wait-free model.
- Any one-shot colorless task that can be solved in the read/write wait-free model can be solved in *ILIS*.
- One-shot tasks: processes decide and it stops (e.g. consensus), as opposed to long-lived objects like stacks or queues that keep a separate state in shared memory.



# The Read/Write Wait-free Model vs. *IIS*

- As shown before, *IIS* can be simulated in the read/write wait-free model.
- Any one-shot colorless task that can be solved in the read/write wait-free model can be solved in *IIS*.
- One-shot tasks: processes decide and it stops (e.g. consensus), as opposed to long-lived objects like stacks or queues that keep a separate state in shared memory.
- Colorless tasks: in any execution, if a process decides, its decision value can be adopted by any other process as its own (e.g. consensus,  $k$ -set agreement but not renaming).

# The Read/Write Wait-free Model vs. *IIS*

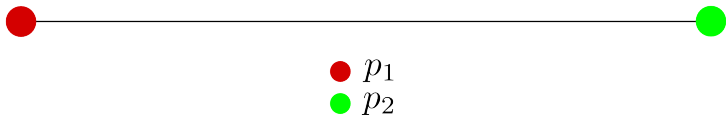
- As shown before, *IIS* can be simulated in the read/write wait-free model.
- Any one-shot colorless task that can be solved in the read/write wait-free model can be solved in *IIS*.
- One-shot tasks: processes decide and it stops (e.g. consensus), as opposed to long-lived objects like stacks or queues that keep a separate state in shared memory.
- Colorless tasks: in any execution, if a process decides, its decision value can be adopted by any other process as its own (e.g. consensus,  $k$ -set agreement but not renaming).

A one-shot colorless task can be solved in the read/write wait-free model iff it can be solved in *IIS*.

- 1 Consensus from Stacks and Registers
- 2 Immediate Snapshots
- 3 The Iterated Immediate Snapshot Model
- 4 Set Agreement in *IIS*
- 5  $k$ -Set Agreement from Registers

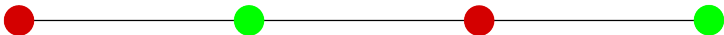
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.



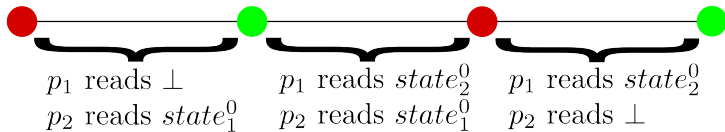
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.



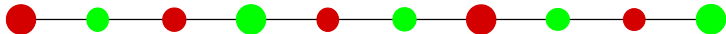
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.



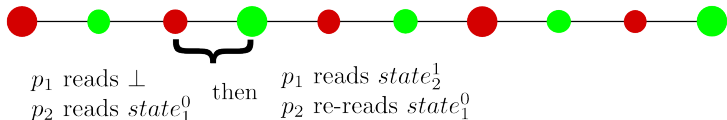
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.



# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

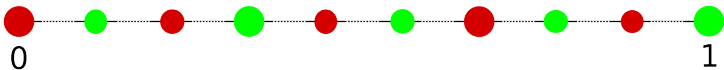
- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.





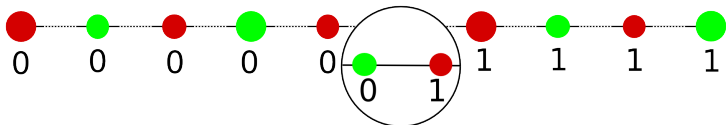
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.
- The processes have to decide in a finite number of rounds  $R$ , the subdivision is consequently finite.



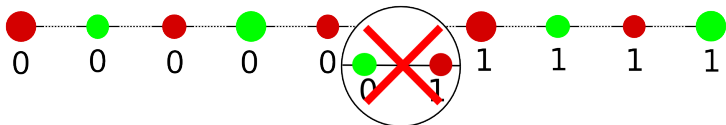
# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.
- The processes have to decide in a finite number of rounds  $R$ , the subdivision is consequently finite.
- The states can be tagged with the corresponding decided values.



# Solving Consensus is impossible in $\mathcal{IIS}$ with Two Processes

- The possible executions of an algorithm in  $\mathcal{IIS}$  between two processes can be seen as a subdivision of the initial configuration.
- The processes have to decide in a finite number of rounds  $R$ , the subdivision is consequently finite.
- The states can be tagged with the corresponding decided values.
- Impossibility result comes from Sperner's Lemma.



A  $k$ -set agreement object offers an operation  $\text{PROPOSE}(v)$  that returns a value. It fulfills the following properties:

**Termination** Any invocation of  $\text{PROPOSE}$  by a correct process terminates.

A  $k$ -set agreement object offers an operation  $\text{PROPOSE}(v)$  that returns a value. It fulfills the following properties:

**Termination** Any invocation of  $\text{PROPOSE}$  by a correct process terminates.

**Agreement** At most  $k$  different values are decided in the system.

A  $k$ -set agreement object offers an operation  $\text{PROPOSE}(v)$  that returns a value. It fulfills the following properties:

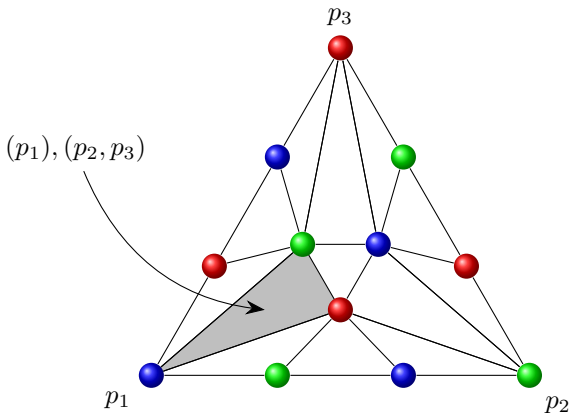
**Termination** Any invocation of  $\text{PROPOSE}$  by a correct process terminates.

**Agreement** At most  $k$  different values are decided in the system.

**Validity** All decided values are proposed values.

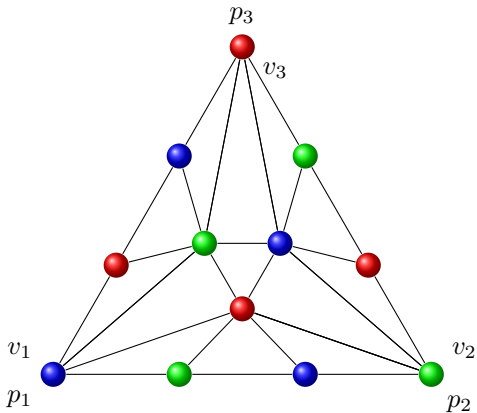
## 2-Set Agreement from Registers Among 3 Processes

The possible executions of an algorithm in  $\mathcal{IIS}$  between three processes can be seen as a subdivision of the initial configuration.



## 2-Set Agreement from Registers Among 3 Processes

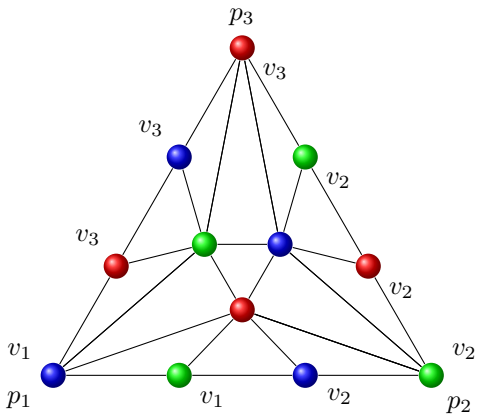
If a process runs alone, it has to decide its input.





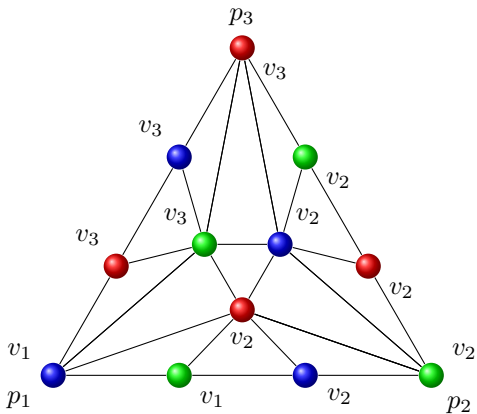
## 2-Set Agreement from Registers Among 3 Processes

If two processes run without seeing the third one, they have to decide on one of their two values.



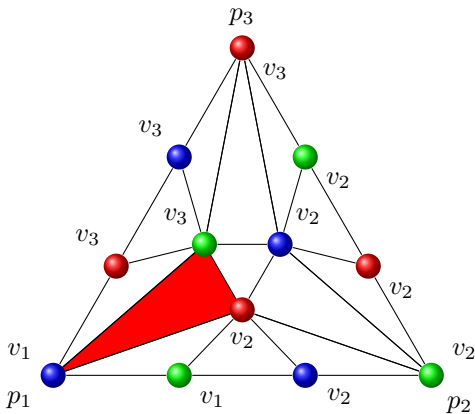
# 2-Set Agreement from Registers Among 3 Processes

By Sperner's Lemma, any completion of this type of coloring...



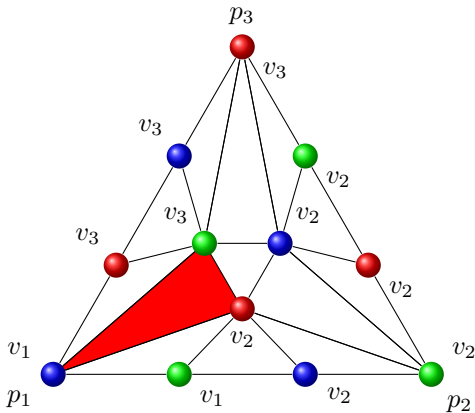
## 2-Set Agreement from Registers Among 3 Processes

By Sperner's Lemma, any completion of this type of coloring...  
has at least one configuration where processes decide on 3 different values.



## 2-Set Agreement from Registers Among 3 Processes

2-set agreement is consequently impossible in one round of  $IIS$  between 3 processes, but the same argument applies for any finite number  $R$  of rounds.



## $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of *LIS* is a triangulation of the initial ( $k$ -dimensional) configuration;

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of  $IIS$  is a triangulation of the initial ( $k$ -dimensional) configuration;
  - the possible final states have to be associated with decision values;



# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of  $ILS$  is a triangulation of the initial ( $k$ -dimensional) configuration;
  - the possible final states have to be associated with decision values;
  - the processes can only decide on values they have seen, these constraints impose that their decision in their final state forms a **Sperner's coloring** of the possible final states;

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of  $ILS$  is a triangulation of the initial ( $k$ -dimensional) configuration;
  - the possible final states have to be associated with decision values;
  - the processes can only decide on values they have seen, these constraints impose that their decision in their final state forms a **Sperner's coloring** of the possible final states;
  - Sperner's Lemma states that there is at least one final configuration that has the  $k + 1$  colors.

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of  $IIS$  is a triangulation of the initial ( $k$ -dimensional) configuration;
  - the possible final states have to be associated with decision values;
  - the processes can only decide on values they have seen, these constraints impose that their decision in their final state forms a **Sperner's coloring** of the possible final states;
  - Sperner's Lemma states that there is at least one final configuration that has the  $k + 1$  colors.
- Consequently,  $k$ -set agreement cannot be wait-free implemented in  $IIS$  in a system of  $k + 1$  processes.

# $k$ -Set Agreement from Registers Among $k + 1$ Processes

- Using the same principles with  $k + 1$  processes:
  - starting from an initial configuration where  $k + 1$  different values are proposed;
  - the set of possible configurations after  $R$  iterations of  $IIS$  is a triangulation of the initial ( $k$ -dimensional) configuration;
  - the possible final states have to be associated with decision values;
  - the processes can only decide on values they have seen, these constraints impose that their decision in their final state forms a **Sperner's coloring** of the possible final states;
  - Sperner's Lemma states that there is at least one final configuration that has the  $k + 1$  colors.
- Consequently,  $k$ -set agreement cannot be wait-free implemented in  $IIS$  in a system of  $k + 1$  processes.
- It follows that  $k$ -set agreement cannot be wait-free implemented from registers in a system of  $k + 1$  processes.

- 1 Consensus from Stacks and Registers
- 2 Immediate Snapshots
- 3 The Iterated Immediate Snapshot Model
- 4 Set Agreement in *IIS*
- 5  $k$ -Set Agreement from Registers

## BG-Simulation

Any one-shot colorless task that we can solve with  $n$  processes and  $t$  crashes, we can solve it with  $t + 1$  processes and  $t$  crashes.

## BG-Simulation

Any one-shot colorless task that we can solve with  $n$  processes and  $t$  crashes, we can solve it with  $t + 1$  processes and  $t$  crashes.

## BG-Simulation

The study of decision tasks computability can be reduced to the  $n - 1$ -resilient case.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.



## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.
  - Use the BG-simulation with  $n$  simulators to simulate  $k + 1$  processes.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.
  - Use the BG-simulation with  $n$  simulators to simulate  $k + 1$  processes.
  - Simulate the protocol.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.
  - Use the BG-simulation with  $n$  simulators to simulate  $k + 1$  processes.
  - Simulate the protocol.
  - Decide any value decided by a simulated process.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.
  - Use the BG-simulation with  $n$  simulators to simulate  $k + 1$  processes.
  - Simulate the protocol.
  - Decide any value decided by a simulated process.
- This solves  $k$ -set agreement between our  $k + 1$  simulators.

## $k$ -Set Agreement is Impossible with $k$ crashes or more.

- $k$ -set agreement is impossible to solve among  $k + 1$  processes with  $k$  crashes.
- For any  $n > k$ , suppose we have a  $k$ -resilient algorithm for  $k$ -set agreement.
- We can then build a  $k$ -resilient algorithm for  $k + 1$  processes/simulators.
  - Use the BG-simulation with  $n$  simulators to simulate  $k + 1$  processes.
  - Simulate the protocol.
  - Decide any value decided by a simulated process.
- This solves  $k$ -set agreement between our  $k + 1$  simulators.
- Contradiction, so there is no such algorithm.

- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.







- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.
- The Iterated Immediate Snapshot model and the read/write wait-free model can compute the same tasks.

- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.
- The Iterated Immediate Snapshot model and the read/write wait-free model can compute the same tasks.
- The possible configurations after  $R$  rounds of *IIS* have a regular geometric structure.

- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.
- The Iterated Immediate Snapshot model and the read/write wait-free model can compute the same tasks.
- The possible configurations after  $R$  rounds of *IIS* have a regular geometric structure.
- Sperner's Lemma allows to prove that  $k$ -set agreement is impossible in a system of  $k + 1$  processes.

- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.
- The Iterated Immediate Snapshot model and the read/write wait-free model can compute the same tasks.
- The possible configurations after  $R$  rounds of *IIS* have a regular geometric structure.
- Sperner's Lemma allows to prove that  $k$ -set agreement is impossible in a system of  $k + 1$  processes.
- BG-simulation allows to simulate larger systems while preserving the number of crashes.

- Implementing a consensus object from stacks and registers is possible for 2 processes but not for 3.
- The Iterated Immediate Snapshot model and the read/write wait-free model can compute the same tasks.
- The possible configurations after  $R$  rounds of *IIS* have a regular geometric structure.
- Sperner's Lemma allows to prove that  $k$ -set agreement is impossible in a system of  $k + 1$  processes.
- BG-simulation allows to simulate larger systems while preserving the number of crashes.
- Combining the two results, we show that  $k$ -set agreement is impossible from registers in a system prone to  $k$  crashes or more.

-  Borowsky E. and Gafni E., Immediate atomic snapshots and fast renaming. *Proc. 12th ACM Symposium on Principles of Distributed Computing (PODC'93)*, pp. 41-51, 1993.
-  Borowsky E. and Gafni E., A simple algorithmically reasoned characterization of wait-free computations. *Proc. 16th ACM Symposium on Principles of Distributed Computing (PODC'97)*, pp. 189-198, 1997.
-  Herlihy M. and Shavit N., The topological structure of asynchronous computability. *Journal of the ACM*, 46(6):858-923, 1999.
-  Herlihy M.P., Kozlov D. N. and Rajsbaum S., *Distributed computing through combinatorial topology*. Morgan Kaufmann, 2014 (ISBN 978-0-12-404578-1).