

The Limitations of Registers

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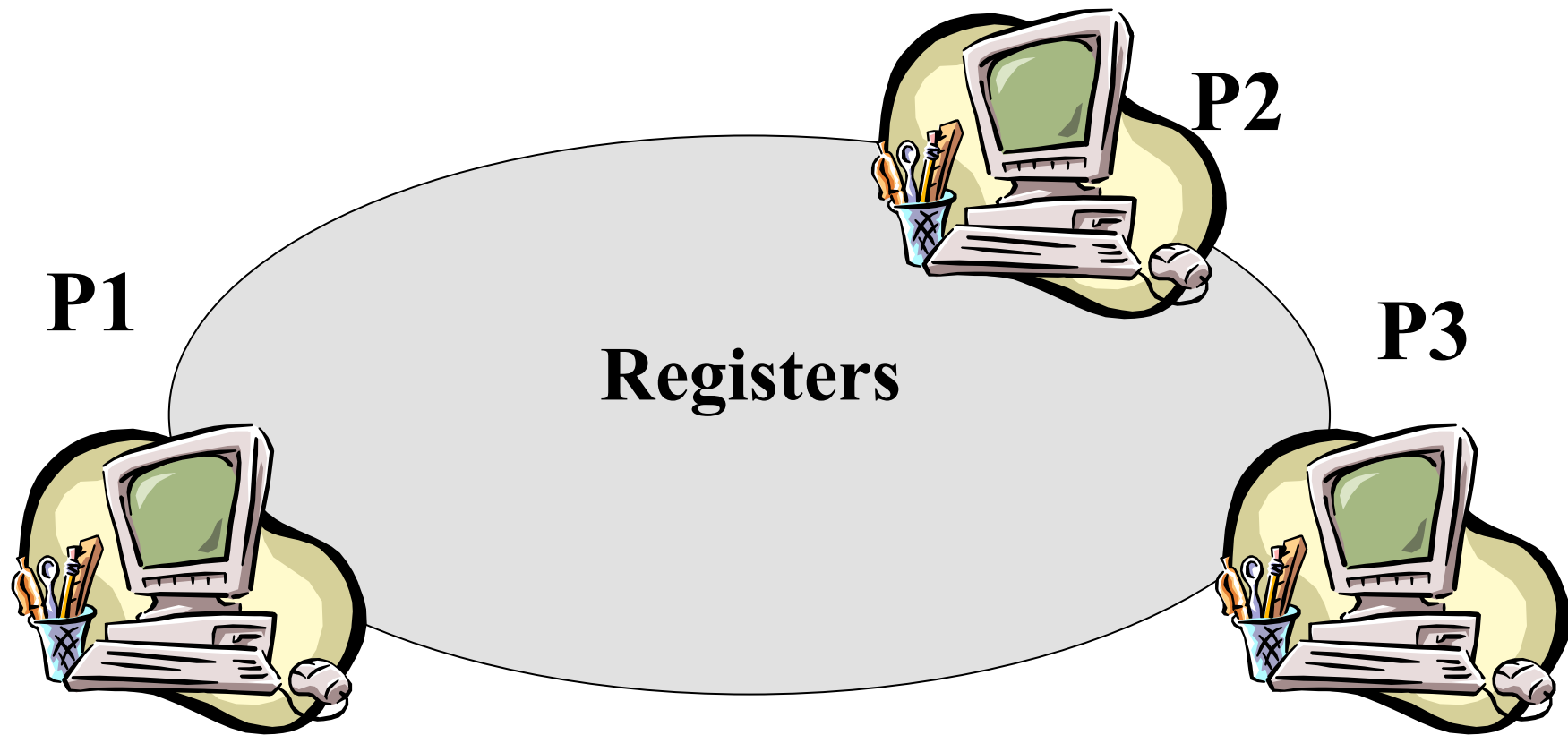
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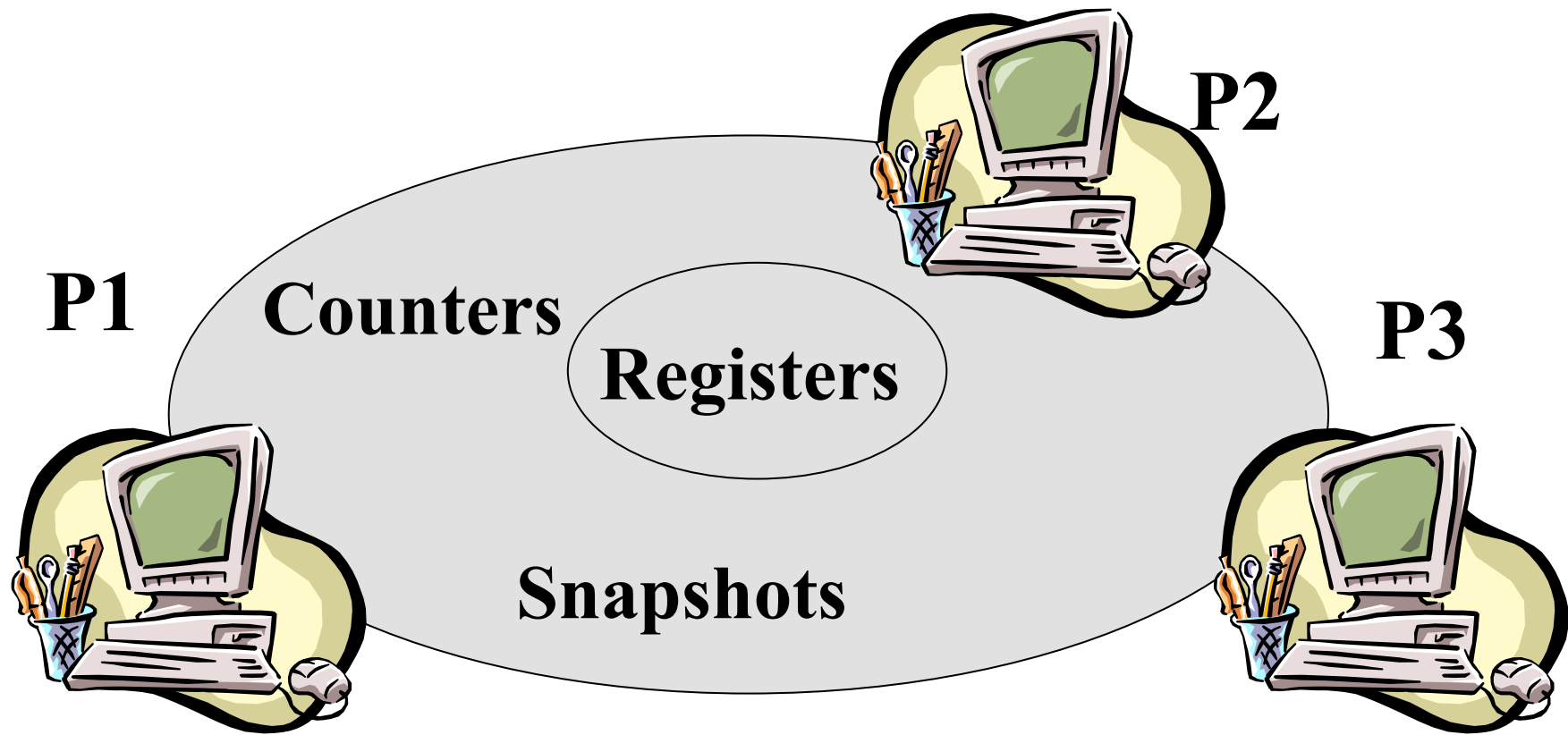
Registers

- **Question 1:** what objects can we implement with registers? **Counters** and **snapshots** (previous lecture)
- **Question 2:** what objects we cannot implement? (this lecture)

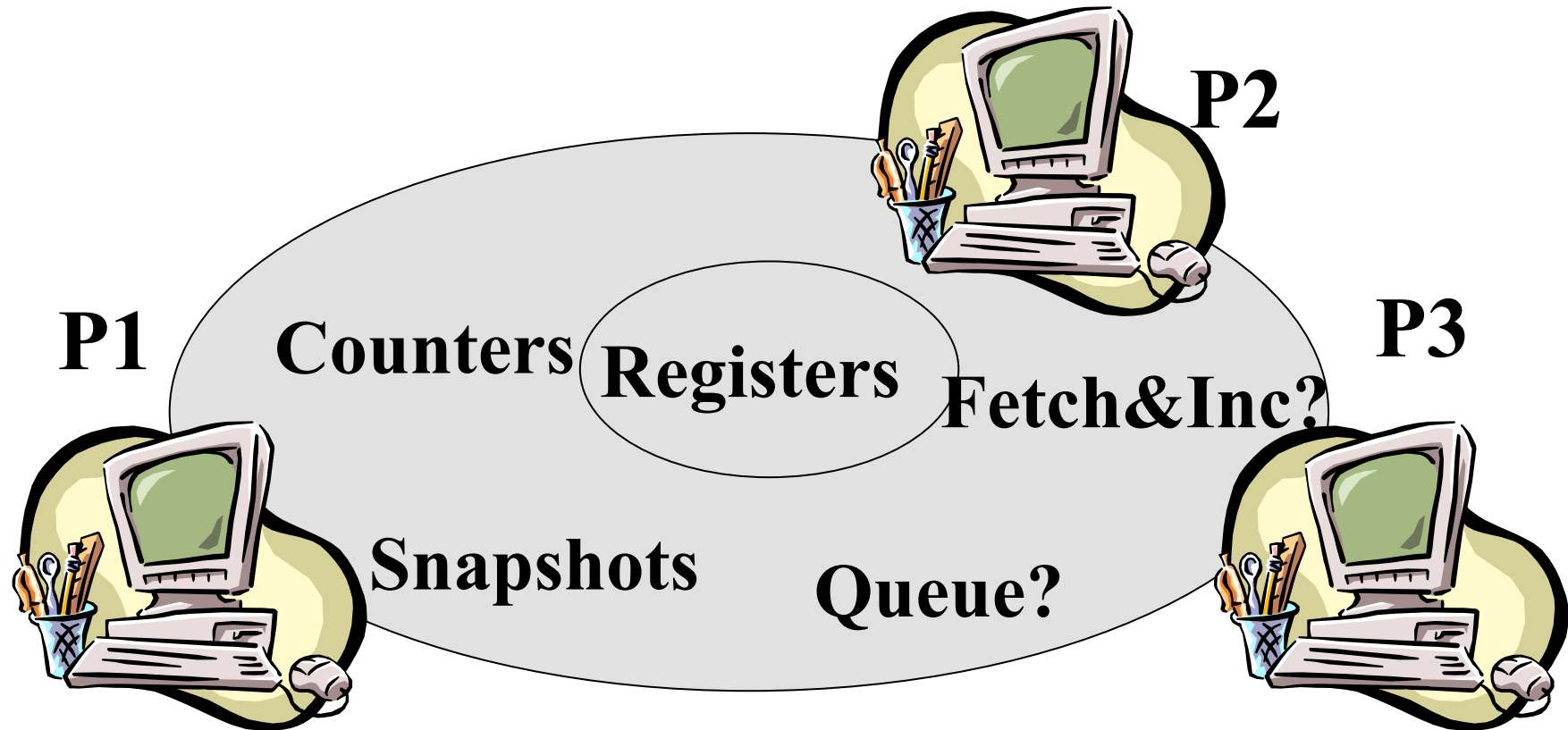
Shared memory model



Shared memory model



Shared memory model



Fetch&Inc

- **A counter that contains an integer**
- **Operation `fetch&inc()` increments the counter and returns the new value**

The consensus object

- One operation ***propose()*** which returns a value. When a propose operation returns, we say that the process decides
- No two processes decide differently
- Every decided value is a proposed value

The consensus object

- ***Proposition:***
 - ✓ ***Consensus*** can be implemented among two processes with ***Fetch&Inc*** and ***registers***
- **Proof (algorithm):** consider two processes **p0** and **p1** and two ***registers*** **R0** and **R1** and a ***Fetch&Inc C***.

2-Consensus with Fetch&Inc

- Uses two registers R0 and R1, and a Fetch&Inc object C (with one fetch&inc() operation that returns its value)
- (NB. The value in C is initialized to 0)

- Process p_l:

- propose(v_l)
- R_l.write(v_l)
- val := C.fetch&inc()
- if(val = 1) then
- ✓ return(v_l)
- else return(R_{1-l}.read())

Impossibility [FLP85,LA87]

- ***Proposition:*** there is no *asynchronous deterministic* algorithm that implements *consensus* among two processes using only *registers*
- ***Corollary:*** there is no algorithm that implements *Fetch&Inc* among two processes using only *registers*

Queue

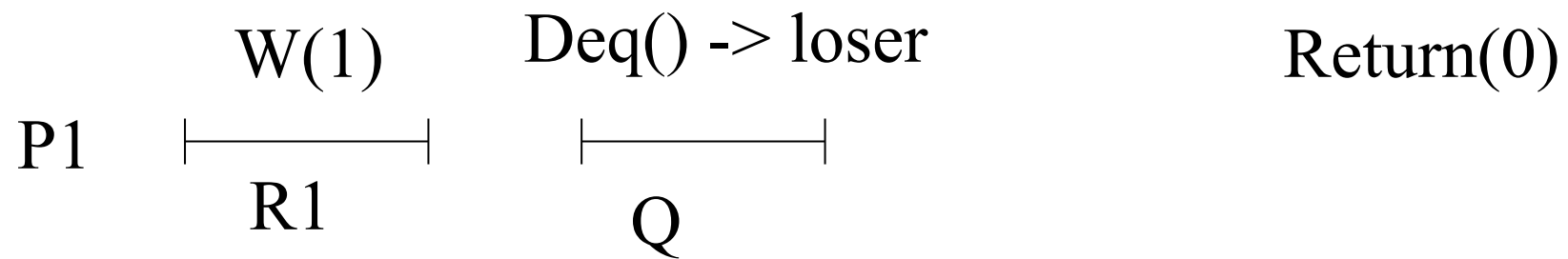
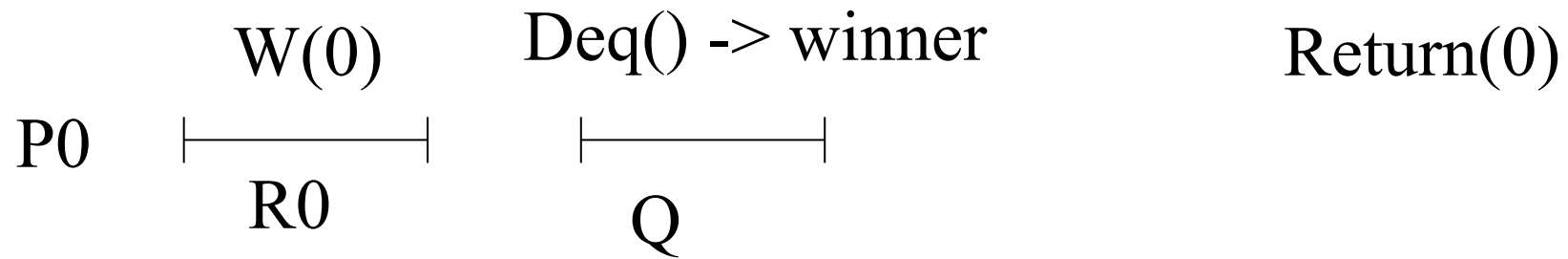
- **The queue is an object container with two operations: *enq()* and *deq()***
- **Can we implement a (atomic wait-free) *queue*?**

2-Consensus with queues

Uses two registers R0 and R1, and a queue Q
Q is initialized to {winner, loser}

Process p_l :

```
propose(vl)  
  Rl.write(vl)  
  item := Q.dequeue()  
  if item = winner return(vl)  
  return(R{1-l}.read())
```



Correctness

Proof (algorithm):

- (wait-freedom) by the assumption of a wait-free register and a wait-free queue plus the fact that the algorithm does not contain any wait statement
- (validity) If p_I dequeues winner, it decides on its own proposed value. If p_I dequeues loser, then the other process p_J dequeued winner before. By the algorithm, p_J has previously written its input value in R_J . Thus, p_I decides on p_J 's proposed value;
- (agreement) if the two processes decide, they decide on the value written in the same register.

More consensus implementations

- A ***Test&Set*** object maintains binary values x , init to 0, and y ; it provides one operation: ***test&set()***
 - ✓ Sequential spec:
 - ✓ `test&set() {y := x; x := 1; return(y);}`
- A ***Compare&Swap*** object maintains a value x , init to \perp , and provides one operation: ***compare&swap(v,w)***
 - ✓ Sequential spec:
 - `c&s(old,new) {if x = old then x := new; return(x)}`

2-Consensus with Test&Set

- Uses two registers R0 and R1, and a Test&Set object T

-

- Process p_l :

- **propose(v_l)**

- **R_l.write(v_l)**

- **val := T.test&set()**

- **if(val = 0) then**

- **return(v_l)**

- **else return(R_{1-l}.read())**

✓

N-Consensus with C&S

- Uses a C&S object C

-

- Process p_i :

- **propose(vl)**

- **val := C.c&s(\perp , vl)**

- **if(val = \perp) then**

- ✓ **return(vl)**

- **else return(val)**

Impossibility [FLP85,LA87]

- **Proposition:** there is no *asynchronous deterministic* algorithm that implements *consensus* among two processes using only *registers*
- **Corollary:** there is no algorithm that implements a *queue (Fetch&Inc,...)* among two processes using only *registers*

Registers

- **Question 1:** what objects can we implement with registers? **Counters** and **snapshots** (previous lecture)
- **Question 2:** what objects we cannot implement? All objects that (together with **registers**) can implement **consensus** (this lecture)

Impossibility (Proof)

- **Proposition:** there is no algorithm that implements **consensus** among two processes using only **registers**
- Proof (by contradiction): consider two processes p_0 and p_1 and any number of **registers**, $R_1..R_k..$
Assume that a consensus algorithm A for p_0 and p_1 exists.

Elements of the model

- A ***configuration*** is a global state of the distributed system
- A new configuration is obtained by executing a ***step*** on a previous configuration: the step is the unit of execution

Elements of the model

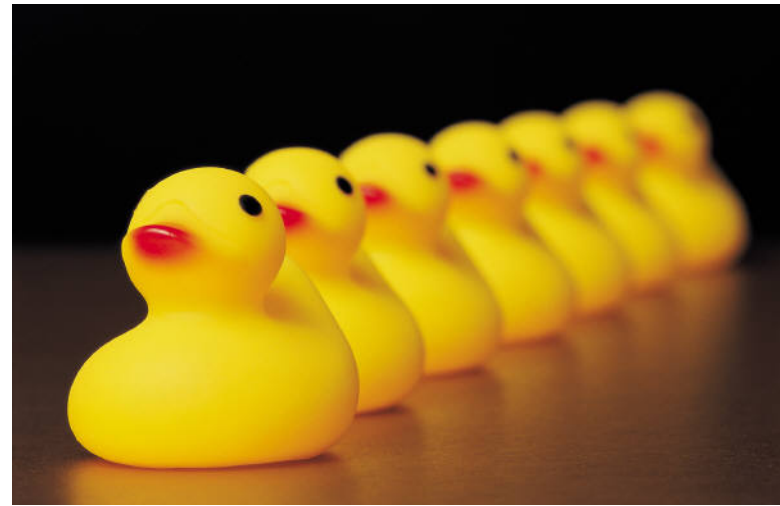
- **The adversary decides which process executes the next step and the algorithm deterministically decides the next configuration based on the current one**

What is distributed computing?

A game



A game between an adversary and a set of processes



The adversary decides which process goes next



The processes take steps



Elements of the model

- The adversary decides which process executes the next step and the algorithm deterministically decides the next configuration based on the current one

Elements of the model

- ***Schedule:*** a sequence of steps represented by process ids
- The schedule is chosen by the system
- An asynchronous system is one with no constraint on the schedules: any sequence of process ids is a schedule

Consensus

- The algorithm must ensure that *agreement* and *validity* are satisfied in every schedule
- Every process that executes an infinite number of steps eventually decides

Impossibility (elements)

- (1) a (initial) **configuration** C is a set of (initial) values of p_0 and p_1 together with the values of the registers: $R_1..R_k,..$;
- (2) a **step** is an elementary action executed by some process p_i : it consists in reading or writing a value in a register and changing p_i 's state according to the algorithm A ;
- (3) a **schedule** S is a sequence of steps; $S(C)$ denotes the configuration that results from applying S to C .

Impossibility (elements)

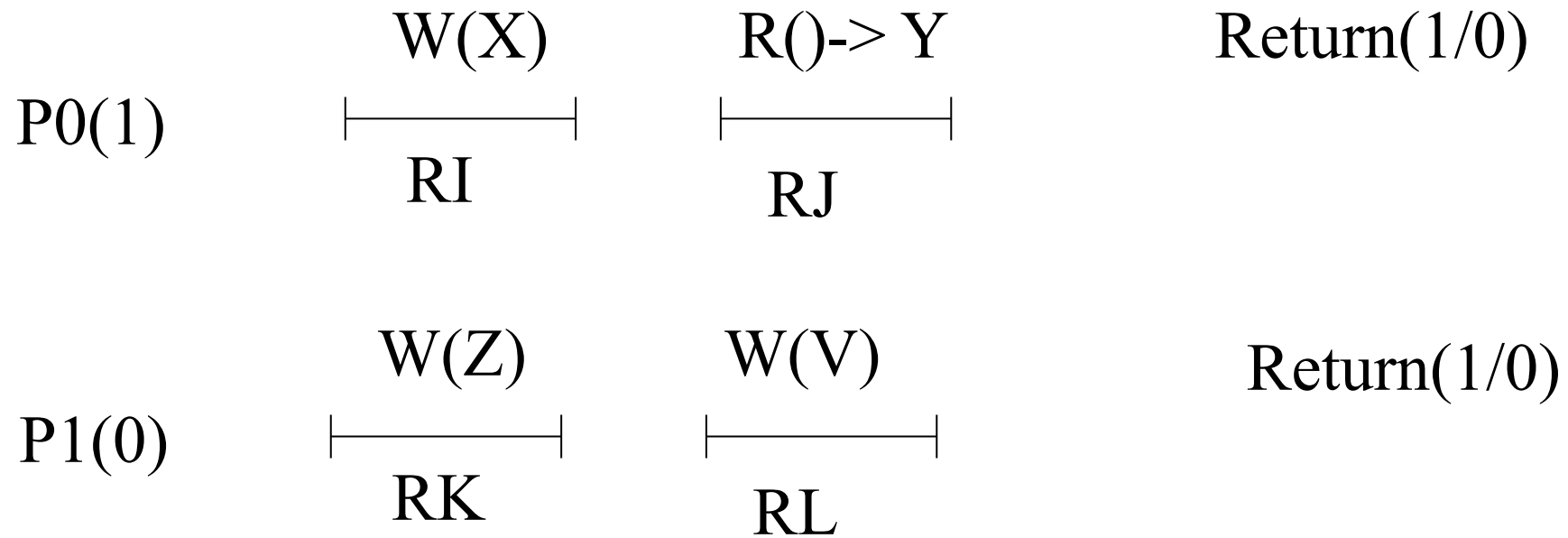
- Consider u to be 0 or 1; a configuration C is ***u-valent*** if, starting from C , no matter how the processes behave, no decision other than u is possible
- We say that the configuration is ***univalent***. Otherwise, the configuration is called ***bivalent***

	$W(X)$	$R() \rightarrow Y$	
$P0(0)$	-----	-----	$Return(0)$
	RI	RJ	

	$W(Z)$	$W(V)$	
$P1(0)$	-----	-----	$Return(0)$
	RK	RL	

	$W(X)$	$R() \rightarrow Y$	
P0(1)	-----	-----	Return(1)
	RI	RJ	

	$W(Z)$	$W(V)$	
P1(1)	-----	-----	Return(1)
	RK	RL	



Impossibility (structure)

- ***Lemma 1:*** there is at least one initial ***bivalent*** configuration
- ***Lemma 2:*** given any bivalent configuration C , there is an ***arbitrarily long schedule*** $S(C)$ that leads to another bivalent configuration

The conclusion

- Lemmas 1 and 2 imply that there is a configuration C and an *infinite* schedule S such that, for any prefix S' of S , $S'(C)$ is bivalent.
- In infinite schedule S , at least one process executes an infinite number of steps and does not decide
- A contradiction with the assumption that A implements consensus.

Lemma 1

The initial configuration $C(0,1)$ is bivalent

Proof: consider $C(0,0)$ and $p1$ not taking any step: $p0$ decides 0; $p0$ cannot distinguish $C(0,0)$ from $C(0,1)$ and can hence decide 0 starting from $C(0,1)$; similarly, if we consider $C(1,1)$ and $p0$ not taking any step, $p1$ eventually decides 1; $p1$ cannot distinguish $C(1,1)$ from $C(0,1)$ and can hence decide 1 starting from $C(0,1)$. Hence the bivalency.

Lemma 2

Given any bivalent configuration C , there is an arbitrarily long schedule S such that $S(C)$ is bivalent

Proof (by contradiction): let S be the schedule with the maximal length such as $D = S(C)$ is bivalent; $p_0(D)$ and $p_1(D)$ are both univalent: one of them is 0-valent (say $p_0(D)$) and the other is 1-valent (say $p_1(D)$)

Lemma 2

- Proof (cont'd): To go from D to $p_0(D)$ (vs $p_1(D)$) p_0 (vs p_1) accesses a register; the register must be the same in both cases; otherwise $p_1(p_0(D))$ is the same as $p_0(p_1(D))$: in contradiction with the very fact that $p_0(D)$ is 0-valent whereas $p_1(D)$ is 1-valent

Lemma 2

- Proof (cont'd): To go from D to $p_0(D)$, p_0 cannot read R ; otherwise R has the same state in D and in $p_0(D)$; in this case, the registers and p_1 have the same state in $p_1(p_0(D))$ and $p_1(D)$; if p_1 is the only one executing steps, then p_1 eventually decides 1 in both cases: a contradiction with the fact that $p_0(D)$ is 0-valent; the same argument applies to show that p_1 cannot read R to go from D to $p_1(D)$

Thus both p_0 and p_1 write in R to go from D to $p_0(D)$ (resp., $p_1(D)$). But then $p_0(p_1(D)) = p_0(D)$ (resp. $p_1(p_0(D)) = p_1(D)$) --- a contradiction.

The conclusion (bis)

Lemmas 1 and 2 imply that there is a configuration C and an *infinite* schedule S such that, for any prefix S' of S , $S'(C)$ is bivalent.

In infinite schedule S , at least one process executes an infinite number of steps and does not decide

A contradiction with the assumption that A implements consensus.