Concurrent programming: From theory to practice

Concurrent Algorithms 2018

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Theoretical	Practical	Practical
(design)	(design)	(implementation)

Theoretical (design)

Practical (design) Practical (implementation)

- Impossibilities
- Upper/Lower bounds
- Techniques
- System models
- Correctness proofs





- Impossibilities
- Upper/Lower bounds
- Techniques
- System models
- Correctness proofs

- System models
 - shared memory
 - message passing
- Finite memory
- Practicality issues
 - re-usable objects
- Performance

Design

(pseudo-code)

Design (pseudo-code, prototype)



Outline

- CPU caches
- Cache coherence
- Placement of data
- Graph processing: Concurrent data structures

Outline

- CPU caches
- Cache coherence
- Placement of data
- Graph processing: Concurrent data structures







- Core freq: 2GHz = 0.5 ns / instr
- Core \rightarrow Disk = ~ms
- Core \rightarrow Memory = ~100ns
- Cache
 - Large = slow
 - Medium = medium
 - Small = fast



- Core freq: 2GHz = 0.5 ns / instr
- Core \rightarrow Disk = ~ms
- Core \rightarrow Memory = ~100ns
- Cache
 - Core \rightarrow L3 = ~20ns
 - Core \rightarrow L2 = ~7ns
 - Core \rightarrow L1 = ~1ns

Typical server configurations

- Intel Xeon
 - 12 cores @ 2.4GHz
 - L1: 32KB
 - L2: 256KB
 - L3: 40MB
 - Memory: 128GB



AMD Opteron

- 12 cores @ 2.4GHz
- L1: 64KB
- L2: 512KB
- L3: 20MB
- Memory: 128GB



Experiment

Throughput of accessing some memory, depending on the memory size

Outline

- CPU caches
- Cache coherence
- Placement of data
- Graph processing: Concurrent data structures

Until ~2004: single-cores



- Core freq: 3+GHz
- Core \rightarrow Disk
- Core \rightarrow Memory
- Cache
 - Core \rightarrow L3
 - Core \rightarrow L2
 - Core \rightarrow L1

After ~2004: multi-cores



Multi-cores with private caches



Cache coherence for consistency



Core 0 has X and Core 1

- wants to write on X
- wants to read X
- did Core 0 write or read X?

Cache coherence principles



- To perform a write
 - invalidate all readers, or
 - previous writer
- To perform a read
 - find the latest copy

Cache coherence with MESI

- A state diagram
- State (per cache line)
 - Modified: the only dirty copy
 - Exclusive: the only clean copy
 - Shared: a clean copy
 - Invalid: useless data



The ultimate goal for scalability

Possible states

- Modified: the only dirty copy
- Exclusive: the only clean copy
- Shared: a clean copy
- Invalid: useless data

Which state is our "favorite"?

The ultimate goal for scalability

- Possible states
 - Modified: the only dirty copy
 - Exclusive: the only clean copy

-Shared: a clean copy

- Invalid: useless data
- = threads can keep the data close (L1 cache)
- = faster

Experiment The effects of false sharing

Outline

- CPU caches
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Uniformity vs. non-uniformity

Typical desktop machine



= Uniform

• Typical server machine





















Experiment The effects of locality

Experiment The effects of locality


Outline

- CPU caches
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- Placement of data

Graph processing: Concurrent data structures

Graph processing

Relational view

d
d

Graph processing



Graphs keep the connections among entities materialized

Graph analytics

- Graphs have been studied in Math for centuries
 - Since Euler's "Seven Bridges of Königsberg", 1736
- Repeatedly traverse your graph and calculate math properties
- Classic graph problems
 - Graph isomorphism
 - Travelling salesman's problem
 - Max flow, min cut
 - ..
- More recent developments
 - Pagerank
 - Infomap



Graph queries

- Graph pattern matching
 - Query graphs to find sub-graphs that match a pattern e.g., triangle counting
- Essentially: SQL for graphs

Graph queries

- Graph pattern matching
 - Query graphs to find sub-graphs that match a pattern e.g., triangle counting
- Essentially: SQL for graphs
- Example: Friends of my friends SELECT p1, p3, COUNT(p2) MATCH (p1)-[:friend]->(p2)->[:friend]->(p3), ! (p1)-[:friend]->(p3)
 WHERE p1.country = p2.country GROUP BY p1, p3 ORDER BY COUNT(p2) DESC



Graph processing frequently involves both analytics and queries

Dissecting a graph processing system

with a focus on (concurrent) data structures

Architecture of a graph processing system



Architecture of a graph processing system



Tons of other data and metadata to store

tmp graph structure

"Vasilis", "Breaking bad", :likes "Rachid", "Dexter", :likes "Vasilis", "Dexter", :likes "Dexter", "Breaking bad", :similar "Breaking bad", "Dexter", :similar

graph structure



user-ids - internal ids

Vasilis $\rightarrow 0$ Rachid $\rightarrow 1$ Breaking bad $\rightarrow 2$ Dexter $\rightarrow 3$ $0 \rightarrow \text{Vasilis} \\ 1 \rightarrow \text{Rachid} \\ 2 \rightarrow \text{Breaking bad} \\ 3 \rightarrow \text{Dexter}$

labels

:likes, :people, :similar, ...

properties

"Vasilis", {people, male}, 33, Zurich "Rachid", {people, male}, ??, Lausanne

lifetime management

number_of_references: X





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• tmp graph structure

- append only
- dynamic schema

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 - \rightarrow segmented table

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 - Classic graph structures

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Classic graph structures 1. connectivity matrix





3. compressed source row (CSR)



tmp graph structure

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Mapping user ids to internal ids

- create once
- read-only after

tmp graph structure"Vasilis", "Breaking bad", :likes
"Rachid", "Dexter", :likes
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1 > Rachid
2 > Breaking bad

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 $3 \rightarrow \text{Dexter}$

Dexter \rightarrow 3

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• Mapping user ids to internal ids

- create once
- read-only after
- \rightarrow hash map, lock-free reads

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 - Mapping internal ids to user ids
 - create once
 - read-only after
 - fixed key range: [0, N}
 - \rightarrow (sequential) array

tmp graph structure

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Storing labels

- usually a small enumeration e.g., person, female, male
- storing strings is expensive "person" \rightarrow ~ 7 bytes
- comparing strings is expensive

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→ dictionary encoding, e.g.,

- person $\rightarrow 0$
- female \rightarrow 1
- male \rightarrow 2

Ofc, hash map to

- store those
- translate during runtime

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• Property

- one type per property, e.g., int
- 1:1 mapping with vertices/edges

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- Lifetime management (and other counters)
 - cache coherence: atomic counters can be expensive



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• Property

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- 1:1 mapping with vertices/edges
 → (sequential) arrays

 Lifetime management (and other counters)

- cache coherence: atomic counters can be expensive
- Two potential solutions
 - 1. approximate counters
 - 2. stripped counters

Thread local:

counter[0]

counter[1] co

counter[2]

increment(int by) { counter[my_thread_id] += by; }
int value() {
 int sum = 0;
 for (int i = 0; i < num_threads; i++) { sum += counter[i];
 for [int sum;</pre>



Score

Structure	# Usages
array / buffer	5
map	2



- Used for speeding up "queries"
 - Which vertices have label :person?
 - Which edges have value > 1000?



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- Buffer management
 - In "real" systems, resource management is very important
 - buffer pools
 - no order
 - insertions and deletions
 - no keys



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 - Which vertices have label :person?
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\rightarrow maps, trees

- Buffer management
 - In "real" systems, resource management is very important
 - buffer pools
 - no order
 - insertions and deletions
 - no keys
 - → Fixed num object pool: array
 - → Otherwise: list
 - → Variable-sized elements: heap



- producers create and share tasks
- consumers get and handle tasks
- insertions and deletions
- usually FIFO requirements



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 - set equality expensive
 - usually common groups
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- Giving unique ids (renaming)



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 - → 2-level **dictionary** encoding
 - {person, female} $\rightarrow 0$
 - {person, male} \rightarrow 1
- Giving unique ids (renaming) \rightarrow tree, map, set, counter, other₂?


Score

Structure	# Usages
array / buffer	6
map	5
tree / heap	2
set	1
queue	1



- 1. Mapping from keys to values
- 2. Atomic value aggregations e.g., COUNT, SUM, MAX
- insertion only



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- create a map of the small table
- insertion phase, followed by
- probing phase



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- Join

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- create a map of the small table
- insertion phase, followed by
- probing phase
- \rightarrow hash map, lock-free probing



• Distinct

• can be solved with sorting, or



• Distinct

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 \rightarrow hash set



Distinct

can be solved with sorting, or
 → hash set

• Limit (top k)

- can be solved with sorting, or
- different specialized structures



Distinct

can be solved with sorting, or
→ hash set

• Limit (top k)

- can be solved with sorting, or
- different specialized structures
- \rightarrow tree
- \rightarrow heap
- \rightarrow ~ list
- → array (e.g., 2 elements only)
- \rightarrow register (1 element only)

group by / join



Breadth-first search (BFS)

FIFO order

•

track visited vertices

0

3

2

group by / join

Vasilis, Breaking bad Rachid Dexter Vasilis, 2 Vasilis, 2

distinct





Breadth-first search (BFS)

- FIFO order
- track visited vertices

0

3

2

- \rightarrow queue
- \rightarrow set

•

group by / join

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Breadth-first search (BFS)

- FIFO order
- track visited vertices
- \rightarrow queue
- \rightarrow set

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Depth-first search (DFS)

- LIFO order
- track visited vertices



0

2

group by / join

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distinct







Breadth-first search (BFS)

- FIFO order
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- \rightarrow set

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Depth-first search (DFS)

- LIFO order
- track visited vertices
- \rightarrow stack
- \rightarrow set



0

2



Score

Structure	# Usages
array / buffer	7
map	6
set	4
tree / heap	3
queue	2
stack	1
list	1



Conclusions

- Both theory and practice are necessary for
 - Designing, and
 - Implementing fast / scalable data structures
- Hardware plays a huge role on implementations
 - How and which memory access patterns to use
- (Concurrent) Data structures
 - The backbone of every system
 - An "open" and challenging area or research

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