Byzantine Failures

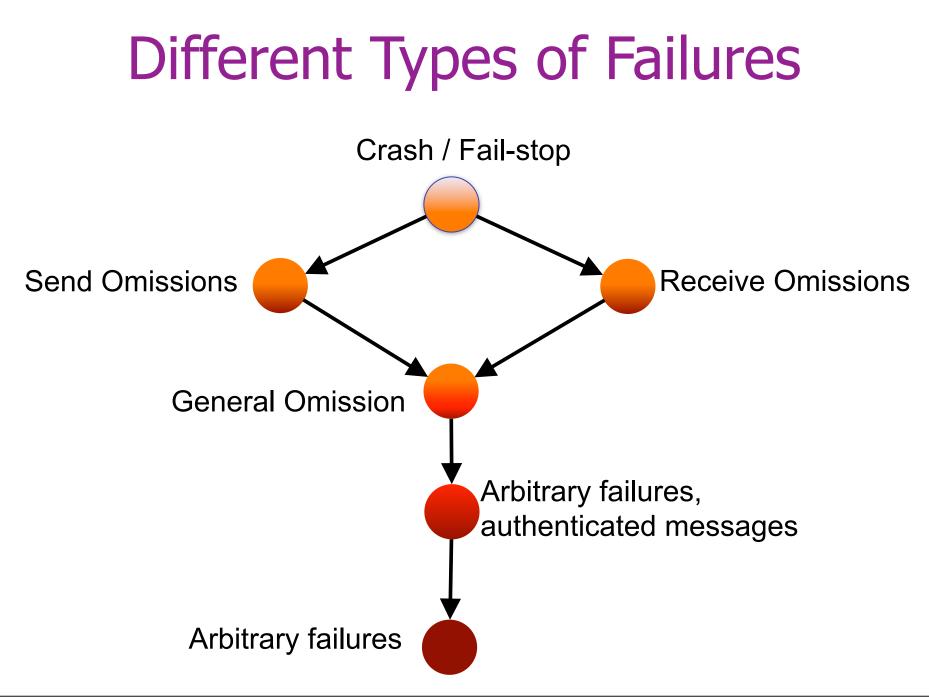
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Arbitrary "Byzantine" Failures

- Some subset of the processes may fail:
 - Send fake messages
 - Not send any messages
 - Try to disrupt the computation

Why Byzantine Fault Tolerance?

- Does this happen in the real world?
 - Malfunctioning hardware
 - Buggy software
 - Compromised system due to hackers
- Assumptions are vulnerabilities
- Is the cost worth it?
 - Hardware is always getting cheaper
 - Protocols are getting more and more efficient.

Byzantine Fault Tolerance

- Seen in the fail-stop model:
 - <u>Question</u>: "How do you build a reliable service?"
 - <u>Answer</u>: State machine replication solves the problem of crash failures.
- This week:
 - What if we want to build a service that can tolerate buggy software, hackers, etc... How do we build a service that tolerates arbitrary failures?

Consensus

- Key building block for state machine replication.
 - Agreement: not two processes decide on different values.
 - Validity: every decision is the initial value of some process.
 - Termination: every correct process eventually decides.

Validity

- (Strong) Validity: If all correct processes start with the same initial value v, then value v is the only decision value of correct processes.
- (Weak) Validity: If there are no failures, then every decision is the initial value of some process.

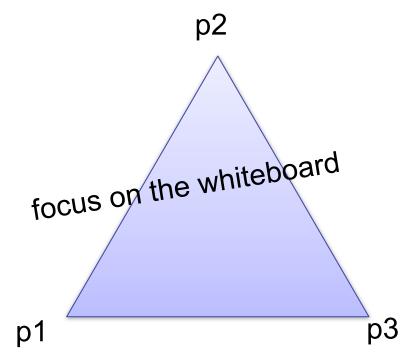
Achieving Fault Tolerance

- How many arbitrary failures can we tolerate?
 - Assume a system of n processes.
 - For crash failures:
 - If failure-detector P, then n-1 failures.
 - If failure-detector <>P, then < n/2 failures.
 - For arbitrary failures:
 - If failure-detector P, then < n/3 failures.

Number of Possible Failures

Lemma 1: In a system with n=3 and 1 failure, there is no algorithm that solves consensus.

Assume there exists some such protocol A.



Another look on why n>3t

- read-write register
- t faulty, liveness => n-t responses
- W set: n-t responses
- R set: n-t responses
- W and R have n-2t in common
 - -t may not be faulty
 - W and R have n-3t in common
- => n>3t

Number of Possible Failures

Lemma 1: In a system with n processes & t = n/3 failures, there is no algorithm that solves consensus.

Proof: By reduction. Given an algorithm A that solves consensus for system (3t,t) where n=3t, we show how to solve consensus in a system (3,1)where n=3 and t=1. Since we know this is impossible, we get a contradiction.

Number of Possible Failures

Lemma 1: In a system with n processes and = n/3 failures, there is no algorithm that solves consensus.

Proof: (Continued)

- Given algorithm A for (3t, t)-system.
- In (3,1) system, each process pi simulates t process in system (3t, t). It assigns its own value to each process that it is simulating, and outputs a decision if any of them decide.

Solving Consensus

• Assume synchronous rounds (i.e., failure detector P):

In every round, each correct process:

- 1. sends a message
- 2. receives all messages sent in that round
- 3. updates its state.

Solving Consensus

- Two variants:
 - 1. No signatures, no cryptography.
 - 2. Signatures: a process can sign a message such that every other process that receives the signed message can determine precisely who it came from.
 - Note: If a process forwards a signed message to someone else, they can check the signature too!

Solving Consensus

- Today:
 - 1. Algorithm Signed_Consensus: solves consensus when processes can sign messages.
 - 2. Algorithm Echo_Broadcast: provides some special reliable broadcast guarantees. NOT (today)
 - 3. Use Echo_Broadcast to solve consensus with no signatures. NOT (today)

- Each process pi begins with initial value vi.
- Each process maintains a set of candidate values VALUES.
- For any string x, process pi can generate a signature sign(x,i) that authenticates the fact that x came from pi.
 - No other process except pi can generate sign(x,i).
 - Every other process can verify that sign(x,i) is correct.

- In round 0, process pi:
 - 1. Adds its initial value vi to VALUES.
 - 2. Generates signature s=sign(vi).
 - 3. Sends [vi, s] to all in round 1.

- In each round $0 < r \le t+1$, process pi:
 - 1. Receives a set of message M.
 - 2. Each m in M is [v : s1 : s2 : s3 : ...]
 - Each sj is the signature of some process pj on the string [v : s1 : s2 : ... : s[j-1]].
 - If any signatures are invalid, then discard m.
 - 3. For each m in M:
 - If pi already signed m, then do nothing.
 - Otherwise, pi adds its signature s = sign(m)
 - Then in the next round, pi sends [m : s] to every process that has not already signed m.
 - Add v to set VALUES.

- At the end of round t+1:
 - Choose the minimum v in VALUES.
 - Decide(v).

• Proof: Termination

Every node decides after t+1 rounds.

- Proof: Weak Validity
 - Assume every process is correct. Then all messages sent contain values that were proposed by some process. So every value in VALUES was proposed by some value.

- Proof: Agreement
 - Let v be the minimum value decided by some correct process.
 - Let r be the first round in which any correct process adds v to VALUES.
 - Let pj be a correct process that adds v to VALUES in round r.

- Proof: Agreement
 - Case 1: r=0
 - v = vj is the initial value of process pj.
 - Since pj is correct, it sends [vj : sign(vj)] to every process in round 1.
 - Every process receives this message and adds v to VALUES.

- Proof: Agreement
 - Case 2: 1 < r < t+1
 - Process pj receives a message m containing value v.
 - Every process that has already sign m has already received value v.
 - Process pj signs m and in the next round sends it to every process that has not yet received v.
 - Since pj is correct, every process receives the signed m in the next round and extracts v, adding it to VALUES.

- Proof: Agreement
 - -Case 3: r = t+1
 - Process pj receives a message m containing value v.
 - Message m contains t+1 signatures.
 - Thus, one of the processes that signed m must have been correct!
 - But, by assumption, round r is the first round in which any process puts value v in VALUES.
 - Contradiction!! Case 3 can't happen.

- Proof: Agreement
 - Thus, we conclude that every process adds v to VALUES by the end of round t+1.
 - By assumption, v is the minimum value decided by any process.
 - Since each process decides the smallest value it has in VALUES, every process decides v.

Byzantine Agreement

- Summary:
 - In a synchronous model, in 2(t+1) rounds we can solve Byzantine agreement as long as t<n/3.
 - Note: consensus can be solved in t+1 rounds.
 But standard solutions use exponential message complexity! (See EIG trees.)

Byzantine Fault Tolerance

• Idea: use Byzantine Agreement to build a replicated state machine!

- Robust: tolerates arbitrary failures.
- But: how to do it efficiently? What about with <>P? Can we do Byzantine Paxos??