#### Atomic register algorithms

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## Overview of this lecture

- (1) From regular to atomic
- (2) A 1-1 atomic fail-stop algorithm
- (3) A 1-N atomic fail-stop algorithm
- (4) A N-N atomic fail-stop algorithm
- (5) From fail-stop to fail-silent

# Fail-stop algorithms

- We first assume a fail-stop model; more precisely:
  - any number of processes can fail by crashing (no recovery)
  - channels are reliable
  - failure detection is perfect

# The simple algorithm

- Consider our fail-stop *regular* register algorithm
  - very process has a local copy of the register value
  - every process reads locally
  - the writer writes globally, i.e., at all (noncrashed) processes

# The simple algorithm

- Write(v) at pi
  - send [W,v] to all
  - for every pj, wait until either:
    - received [ack] or
    - suspected [pj]
  - Return ok

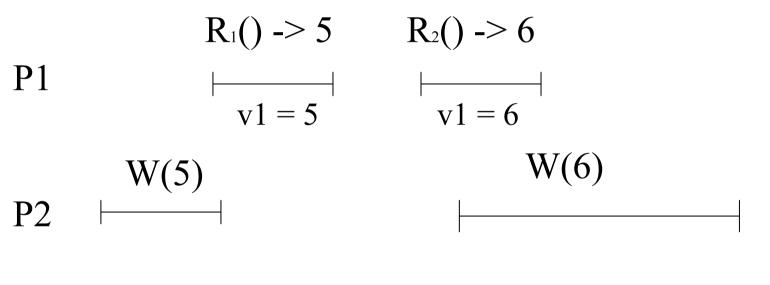
🗸 At pi:

when receive [W,v] from pj vi := v

send [ack] to pj

- Read() at pi
  - Return vi

#### Atomicity?



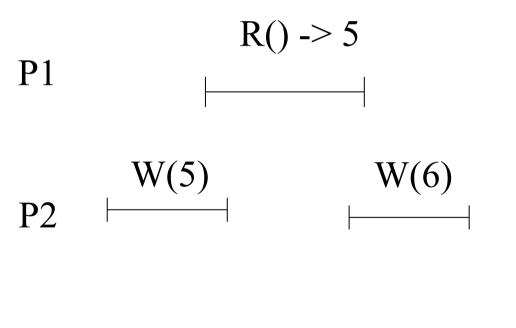
P3

#### Linearization?

# Fixing the pb: read-globally

- r Read() at pi
  - send [W,vi] to all
  - for every pj, wait until either:
    - receive [ack] or
    - suspect [pj]
  - Return vi

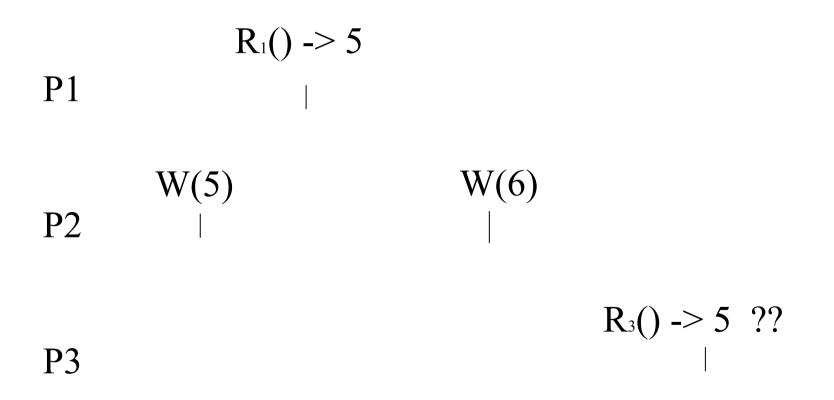
#### Still a problem



P3

R() -> 5

#### Linearization?



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# A fail-stop 1-1 atomic algorithm

- write(v) at p1
  - send [W,v] to p2
  - Wait until either:
    - receive [ack]from p2 or
    - suspect [p2]
  - Return ok

At p2:

when receive [W,v] from p1

send [ack] to p2

Read() at p2
 Return v2

## A fail-stop 1-N algorithm

very process maintains a local value of the register as well as a sequence number

the writer, p1, maintains, in addition a timestamp ts1

any process can read in the register

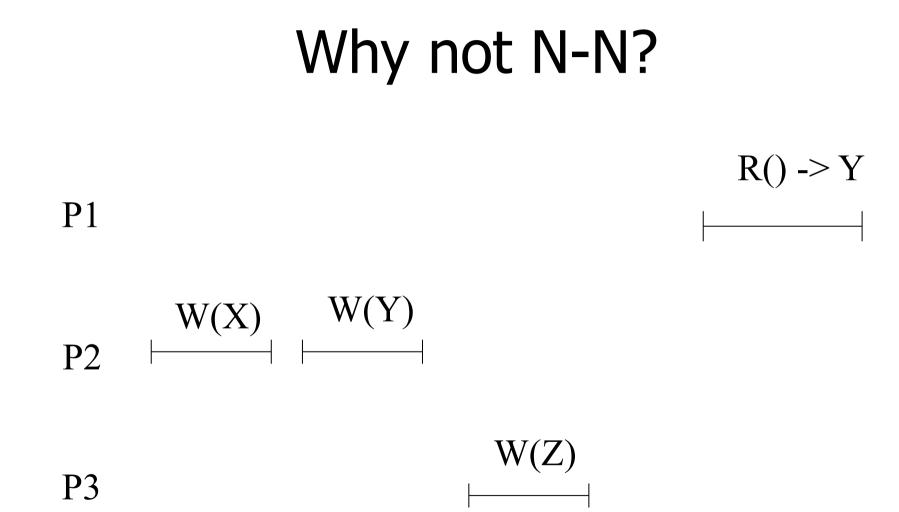
# A fail-stop 1-N algorithm

- Write(v) at p1
  - ts1++
  - send [W,ts1,v] to all
  - for every pi, wait until either:
    - receive [ack] or
    - suspect [pi]
  - Return ok

- Read() at pi
  - send [W,sni,vi] to all
  - for every pj, wait until either:
    - receive [ack] or
    - suspect [pj]
  - Return vi

# A 1-N algorithm (cont'd)

At pi
 When pi receive [W,ts,v] from pj
 if ts > sni then
 vi := v
 sni := ts
 send [ack] to pj



#### The Write() algorithm

- Write(v) at pi
  - ✓ send [W] to all
  - $\checkmark$  for every pj wait until
    - receive [W,snj] or
    - suspect pj
  - $\checkmark$  (sn,id) := (highest snj + 1,i)
  - ✓ send [W,(sn,id),v] to all
  - $\checkmark$  for every pj wait until
    - receive [W,(sn,id),ack] or
    - suspect pj
  - ✓ Return ok

- At pi
  - **T1**:
  - $\checkmark$  when receive [W] from pj
    - send [W,sn] to pj
  - **T2**:
  - ✓ when receive [W,(snj,idj),v] from pj
  - ✓ If (snj,idj) > (sn,id) then
    - vi := v
    - (sn,id) := (snj,idj)
  - ✓ send [W,(snj,idj),ack] to pj

## The Read() algorithm

- Read() at pi
  - ✓ send [R] to all
  - ✓ for every pj wait until
    - receive [R,(snj,idj),vj] or
    - suspect pj
  - $\checkmark$  v = vj with the highest (snj,idj)
  - ✓ (sn,id) = highest (snj,idj)
  - ✓ send [W,(sn,id),v] to all
  - $\checkmark$  for every pj wait until
    - receive [W,(sn,id),ack] or
    - suspect pj
  - ✓ Return v

- At pi
  - **T1**:
  - $\checkmark$  when receive [R] from pj
    - send [R,(sn,id),vi] to pj

#### **T2**:

- ✓ when receive [W,(snj,idj),v] from pj
- ✓ If (snj,idj) > (sn,id) then
  - vi := v
  - (sn,id) := (snj,idj)
- ✓ send [W,(snj,idj),ack] to pj

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#### From fail-stop to fail-silent

- We assume a majority of correct processes
- In the 1-N algorithm, the writer writes in a majority using a timestamp determined locally and the reader selects a value from a majority and then imposes this value on a majority
- In the N-N algorithm, the writers determines first the timestamp using a majority