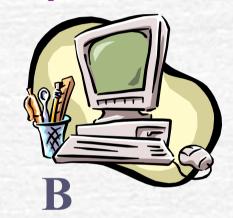
#### Distributed Systems

# Group Membership and View Synchronous Communication

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Who is there?

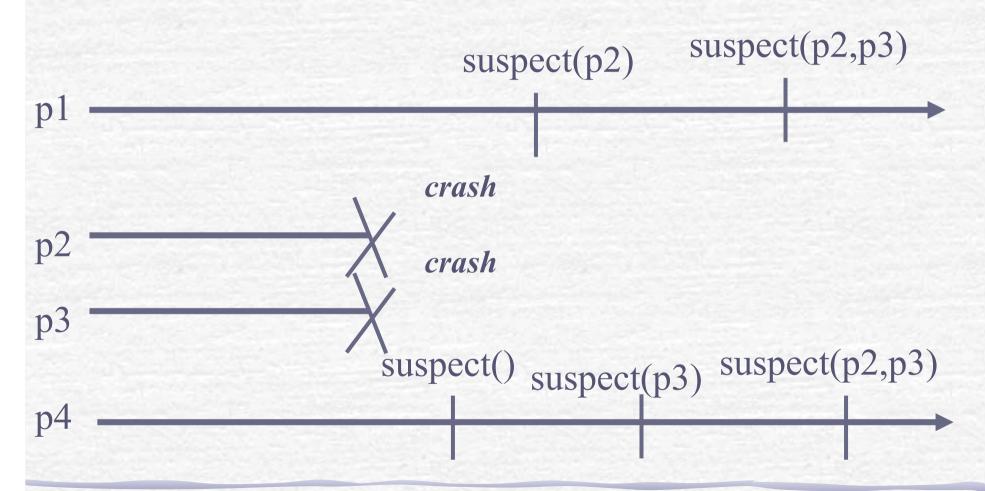


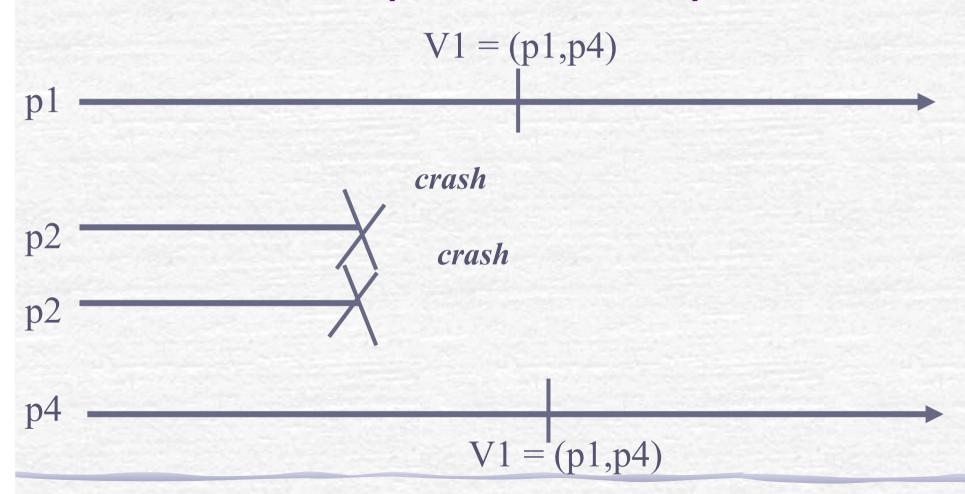


 In many distributed applications, processes need to know which processes are *participating* in the computation and which are not

 Failure detectors provide such information; however, that information is *not coordinated* (see next slide) even if the failure detector is perfect

#### Perfect Failure Detector





 To illustrate the concept, we focus here on a group membership abstraction to coordinate the information about *crashes*

 In general, a group membership abstraction can also typically be used to coordinate the processes joinning and leaving explicitly the set of processes (i.e., without crashes)

- Like with a failure detector, the processes are informed about failures; we say that the processes install views
- Like with a perfect failure detector, the processes have accurate knowledge about failures
- *Unlike* with a perfect failure detector, the information about failures are *coordinated*: the processes install the same sequence of views

- **Memb1.** Local Monotonicity: If a process installs view (j,M) after installing (k,N), then j > k and M < N
- **Memb2.** Agreement: No two processes install views (j,M) and (j,M') such that  $M \neq M'$
- **Memb3.** Completeness: If a process p crashes, then there is an integer j such that every correct process eventually installs view (j,M) such that  $p \notin M$
- **Memb4.** Accuracy: If some process installs a view (i,M) and  $p \notin M$ , then p has crashed

- Events
  - Indication: <membView, V>

- Properties:
  - Memb1, Memb2, Memb3, Memb4

#### Algorithm (gmp)

- Implements: groupMembership (gmp).
- **Uses:** 
  - PerfectFailureDetector (P).
  - UniformConsensus(Ucons).
- upon event < Init > do
  - r view := (0,S);
  - correct := S;
  - wait := true;

#### Algorithm (gmp – cont'd)

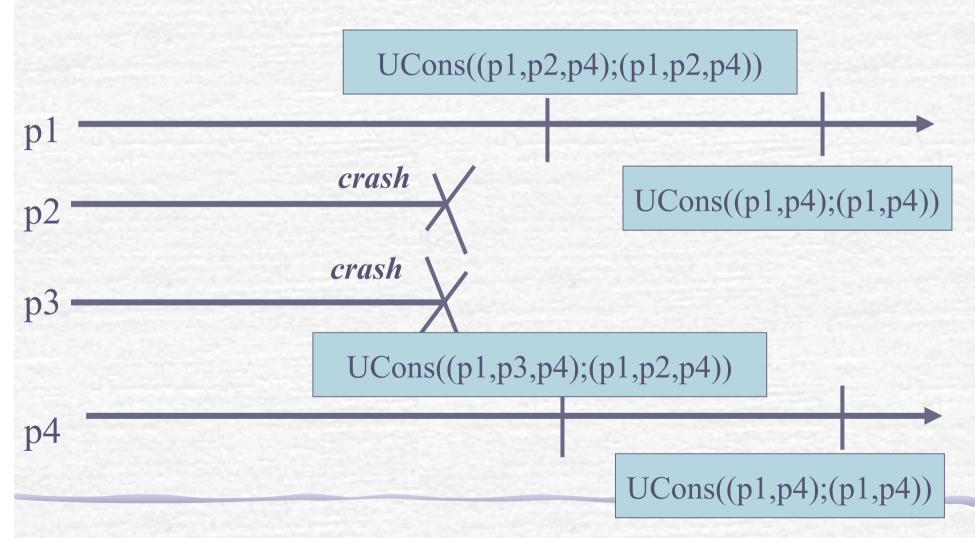
- upon event < crash, pi > do
  - correct := correct \ {pi};

- upon event (correct < view.memb) and (wait = false) do</li>
  - wait := true;
  - trigger<ucPropose,(view.id+1,correct) >;

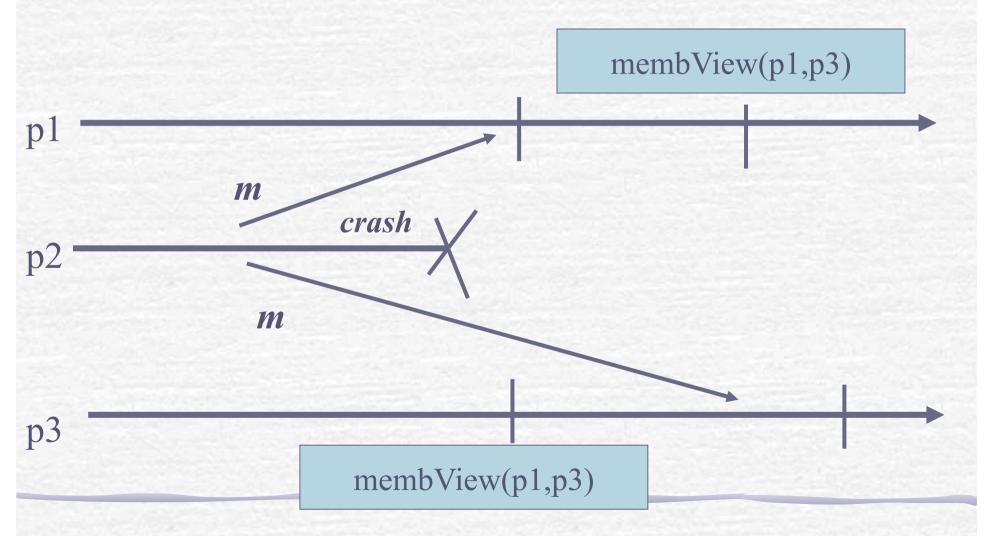
#### Algorithm (gmp - cont'd)

- upon event < ucDecided, (id, memb)> do
  - view := (id, memb);
  - wait := false;
  - trigger < membView, view>;

#### Algorithm (gmp)



#### Group Membership and Broadcast



• View synchronous broadcast is an abstraction that results from the combination of group membership and reliable broadcast

 View synchronous broadcast ensures that the delivery of messages is coordinated with the installation of views

Besides the properties of *group membership* (Memb1-Memb4) and reliable broadcast (RB1-RB4), the following property is ensured:

VS: A message is vsDelivered in the view where it is vsBroadcast

- Events
  - Request:
    - </pre

- Indication:
  - <vsDeliver, src, m>
  - <vsView, V>

If the application keeps *vsBroadcasting* messages, the *view synchrony* abstraction might never be able to *vsInstall* a new view; the abstraction would be impossible to implement

We introduce a specific event for the abstraction to **block** the application from **vsBroadcasting** messages; this only happens when a process crashes

- **Events** 
  - Request:
  - Indication:
    - </pr

#### Algorithm (vsc)

Implements: ViewSynchrony (vs).

#### **Uses:**

- GroupMembership (gmp).
- TerminatingReliableBroadcast(trb).
- BestEffortBroadcast(beb).

- upon event < Init > do
  - view := (0,S); nextView :=  $\bot$ ;
  - pending := delivered := trbDone := ∅;
  - flushing := blocked := false;

- upon event <vsBroadcast,m> and (blocked = false)
  do
  - delivered := delivered ∪ { m };
  - trigger <vsDeliver, self, m>;
  - trigger <bebBroadcast, [Data,view.id,m>;

- upon event<bebDeliver,src,[Data,vid,m]) do</pre>
  - If(view.id = vid) and (m ∉ delivered) and
    (blocked = false) then
    - delivered := delivered ∪ { m }
    - trigger <vsDeliver, src, m >;

- upon event < membView, V > do
  - addtoTail (pending, V);
- **upon** (pending  $\neq \emptyset$ ) and (flushing = false) **do** 
  - removeFromhead (pending);
  - flushing := true;
  - rtrigger <vsBlock>;

- Upon <vsBlockOk> do
  - blocked := true;
  - rtrbDone :=  $\emptyset$ ;
  - trigger <trbBroadcast, self, (view.id,delivered)>;

- Upon <trbDeliver, p, (vid, del)> do

  - forall m ∈ del and m ∉ delivered do
    - delivered := delivered ∪ { m };
  - trigger <vsDeliver, src, m >;

- **Upon** (trbDone = view.memb) and (blocked = true) do
  - view := nextView;
  - flushing := blocked := false;
  - r delivered :=  $\emptyset$ ;
  - trigger <vsView, view>;

# Consensus-Based View Synchrony

Instead of launching parallel instances of TRBs, plus a group membership, we use one consensus instance and parallel broadcasts for every view change

Roughly, the processes exchange the messages they have delivered when they detect a failure, and use consensus to agree on the membership and the message set

## Algorithm 2 (vsc)

Implements: ViewSynchrony (vs).

#### **Uses:**

- UniformConsensus (uc).
- BestEffortBroadcast(beb).
- PerfectFailureDetector(P).

```
upon event < Init > do
view := (0,S);
```

- correct := S;
- flushing := blocked := false;
- delivered := dset := ∅;

- upon event <vsBroadcast,m) and (blocked = false) do</pre>
  - delivered := delivered ∪ { m }
  - trigger <vsDeliver, self,m>;
  - trigger <bebBroadcast,[Data,view.id,m] >;

- upon event<bebDeliver,src,[Data,vid,m]) do</pre>
  - fif (view.id = vid) and (m ∉ delivered) and (blocked = false) then
    - delivered := delivered ∪ { m };
  - trigger <vsDeliver, src, m >;

- upon event < crash, p > do
  - correct := correct \ { p };
  - if flushing = false then
    - flushing := true;
    - trigger <vsBlock>;

- Upon <vsBlockOk> do
  - blocked := true;
  - rtrigger <bebBroadcast, [DSET,view.id,delivered] >;

- Upon <bebDeliver, src, [DSET,vid,del] > do
  - dset:= dset ∪ (src,del);
  - f if forall p ∈ correct, (p,mset) ∈ dset then
    trigger <ucPropose, view.id+1, correct, dset >;

- Upon <ucDecided, id, memb, vsdset > do
  - forall (p,mset) ∈ vsdset: p ∈ memb do
  - forall (src,m) ∈ mset: m ∉ delivered do
    - delivered := delivered ∪ {m}
    - trigger <vsDeliver, src, m>;
  - view := (id, memb); flushing := blocked :=
    false; dset := delivered := ∅;
  - trigger <vsView, view>;

#### **Uniform View Synchrony**

We now combine the properties of

group membership (Memb1-Memb4) — which is already uniform

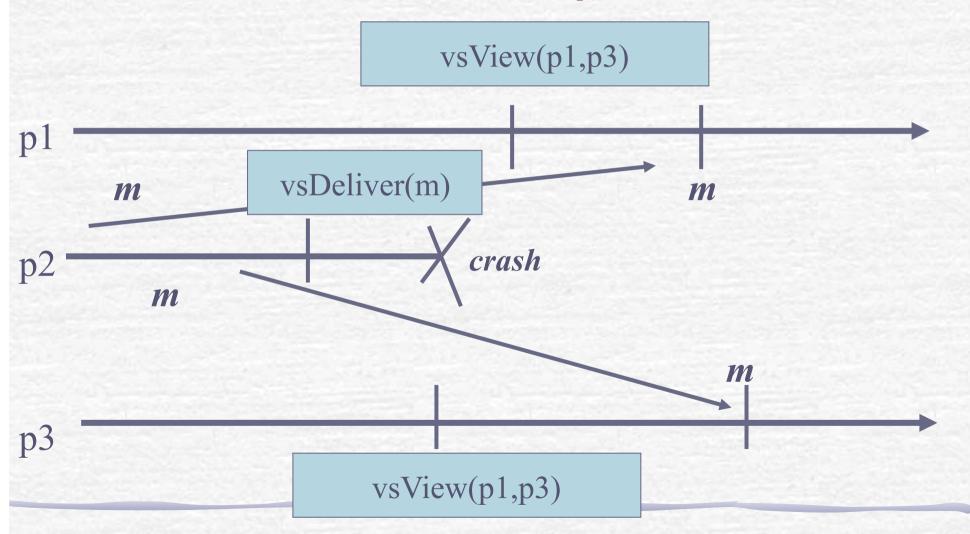
uniform reliable broadcast (RB1-RB4) — which we require to be uniform

**VS:** A message is **vsDelivered** in the view where it is **vsBroadcast** – which is already uniform

#### **Uniform View Synchrony**

Using uniform reliable broadcast instead of best effort broadcast in the previous algorithms does not ensure the uniformity of the message delivery

#### **Uniformity?**



## Algorithm 3 (uvsc)

- upon event < Init > do
  - view := (0,S);
  - correct := S;
  - flushing := blocked := false;
  - udelivered := delivered := dset := ∅;
  - for all m:  $ack(m) := \emptyset$ ;

- upon event <vsBroadcast,m) and (blocked = false)
  do</pre>
  - delivered := delivered ∪ {m};
  - rtrigger <bebBroadcast,[Data,view.id,m] >;

- upon event<bebDeliver,src,[Data,vid,m]) do</pre>
  - r if (view.id = vid) then
    - $\sigma$  ack(m) := ack(m)  $\cup$  {src};
  - r if m ∉ delivered then
    - delivered := delivered ∪ { m }
  - trigger <bebBroadcast, [Data,view.id,m] >;

- upon event (view ≤ ack(m)) and (m ∉ udelivered)
  do
  - rudelivered := udelivered ∪ { m }
  - rtrigger <vsDeliver, src(m), m >;

- upon event < crash, p > do
  - correct := correct \ { p };
  - if flushing = false then
    - flushing := true;
    - trigger <vsBlock>;

- Upon <vsBlockOk> do
  - blocked := true;
  - trigger <bebBroadcast,
    [DSET,view.id,delivered] >;
  - Upon <bebDeliver, src, [DSET,vid,del] > do
    - dset:= dset ∪ (src,del);
    - f forall p ∈ correct, (p,mset) ∈ dset
      then trigger < ucPropose, view.id+1,
      correct, dset >;

- Upon <ucDecided, id, memb, vsdset > do
  - rforall (p,mset) ∈ vs-dset: p ∈ memb do
  - forall (src,m) ∈ mset: m ∉ udelivered do
    - udelivered := udelivered ∪ {m}
    - trigger <vsDeliver, src, m>;
  - view := (id, memb); flushing := blocked := false; dset := delivered := udelivered := ∅;
  - trigger <vsView, view>;