

# Self-Stabilizing spanning tree

## 1 Algorithm

Consider a graph where the nodes  $\{p_0, \dots, p_{n-1}\}$  represents a set of  $n$  processes. Two nodes are connected if the corresponding processes can communicate. The node  $p_0$  is a distinguished process, and is referred to as the root. Process  $p_i$  communicates with its neighbour  $p_j$  by writing to a shared register  $r_{ij}$  and reading from  $r_{ji}$ . We say that the process  $p_i$  owns the registers in which  $p_i$  writes. That is,  $p_i$  owns  $r_{ij}$  for all neighbours  $p_j$  of  $p_i$ . Each register  $r_{ij}$  comprises two fields. The field  $r_{ij}.dis$  holds an integer value representing the distance from the root  $p_0$  to  $p_i$ . This integer value is bounded by some large constant  $K$ , and any assignment of a larger value to the distance field results in the assignment of  $K$ . The field  $r_{ij}.parent$  holds a binary value: if  $p_i$  considers that  $p_j$  is a parent, then  $r_{ij} = 1$ ; otherwise  $r_{ij} = 0$ .

Finally, each process  $p_i$  holds the following local variables: for each neighbour  $m$ , the variable  $lr_{mi}$  is of the same type as  $r_{mi}$ , and is used to store values read from that register; an integer-valued variable  $dist$ ; a boolean variable  $F$ .

It is assumed that each process  $p_i$  knows the list  $N_i$  of its neighbours, and that this list is ordered once and for all. Alg. 1 shows the pseudo-code of the spanning tree construction algorithm. Note that, the lines “for each  $j \in N_i$ ” mean that we take the successive neighbours of  $p_i$  in the predefined order.

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**Algorithm 1:** Self-stabilizing spanning tree construction

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1 case Node  $p_0$ 
2   while true do
3     foreach  $j \in N_0$  do
4        $r_{ij}.(parent, dis) \leftarrow (0, 0)$ 
5     end
6   end
7 case Node  $p_i \neq p_0$ 
8   while true do
9     foreach  $j \in N_i$  do
10       $lr_{mi} \leftarrow \text{read}(r_{mi})$ 
11    end
12     $F \leftarrow \text{false}$ 
13     $dist \leftarrow 1 + \min\{lr_{mi}.dis, m \in N_i\}$ 
14    foreach  $j \in N_i$  do
15      if  $F = \text{false}$  and  $lr_{ji}.dis = dist - 1$  then
16         $r_{ij}.(parent, dis) \leftarrow (1, dist)$ 
17         $F \leftarrow \text{true}$ 
18      else
19         $r_{ij}.(parent, dis) \leftarrow (0, dist)$ 
20    end
21  end
```

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*Question 1.* Consider a ring of  $n = 4$  processes. Assume that, initially, all processes are in the same state, and the registers contain the same values. Show that, if  $p_0$  executes the same code as the non-root processes, then it is possible to define an ordering of neighbours for each process, and an execution such that: (i) every process takes steps infinitely many times, (ii) the system does not converge. (*Hint: use the fact that opposite nodes “sees the same thing”*)

## 2 Solution

### 2.1 Answer 1

An easy answer (that I have not planned) stems from the fact that we consider a particular algorithm. Indeed, if the root executes the same code as the other processes, then the distance fields in the registers will keep increasing until it reaches the maximum value (staying there hereafter).

### 2.2 Answer 2

Another answer allows to show that there is no deterministic self-stabilizing algorithm which computes a spanning tree if every process executes the same code. Indeed, start from a configuration  $C_0$  in which all processes are in the same state, and all registers contains the same value. Let  $a, b, c, d$  be the processes in the ring (say counterclockwise). Consider the schedule  $S = (acbd)^\omega$ , that is, each time a process takes a step, the diametrically opposite process then takes a step.

Focus for example on the beginning of the execution. In the configuration  $C_0$ , every process sees the same thing (the registers around him contains the same values) as the diametrically opposite process. Thus, if activating the process  $a$  puts it in some state, then activating the process  $c$  right after puts  $c$  in exactly the same state. By continuing this strategy, every process takes infinitely many steps, and infinitely often we reach a configuration in which every process sees exactly the same thing as the opposite process (a symmetric configuration). This prevents the computation of a spanning tree since otherwise, we would get infinitely often a spanning tree with two roots. This argument can be generalized to show the impossibility of spanning tree with uniform algorithm in case of ring of processes of size not a prime number.

This kind of symmetry argument is ubiquitous in distributed computing. It says that, if the environment (the scheduler here) can maintain a form of symmetry in the system infinitely often, then one cannot solve any problem requiring a form of symmetry breaking (e.g. leader election, spanning tree, mutual exclusion, enumeration, etc.). Also, it is not limited to impossibility results in self-stabilization.

It is also interesting to find how we can circumvent this argument. The idea is that we must assume something on the environment which allows the possibility of symmetry breaking. For example, restricting to the case where the number of processes in the ring is a prime number, or considering stochastic scheduler (selecting the next process to activate in a random manner), and so on.