Transactional Memory

R. Guerraoui, EPFL

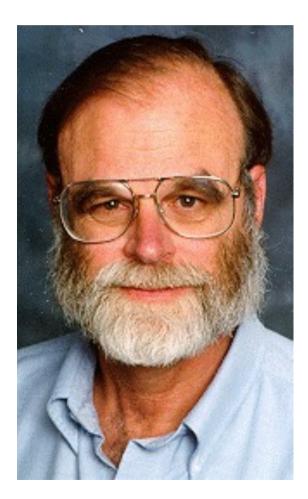
Locking is "history"

Lock-freedom is "difficult"



A synchronisation abstraction that is simple, robust and efficient

Transactions



Back to the sequential level

accessing object 1;accessing object 2;

Back to the sequential level

Semantics (serialisability)

Every transaction appears to execute at an indivisible point in time (linearizability of transactions)

The TM Topic has been a VERY HOT topic

Sun/Oracle, Intel, AMD, IBM, MSR

Fortress (Sun); X10 (IBM); Chapel (Cray)

The TM API (a simple view)

begin() returns ok

- *read()* returns a value or *abort write()* returns an *ok* or *abort*
- *commit()* returns *ok* or *abort abort()* returns *ok*

Two-phase locking

To write or read O, T requires a lock on O;
T waits if some T' acquired a lock on O

At the end, T releases all its locks

Two-phase locking (more details)

- For Every object O, with state s(O) (a *register*), is protected by a lock I(O) (a c&s)
- Every transaction has local variables wSet and wLog
- \checkmark Initially: I(O) = unlocked, wSet = wLog = \varnothing

Two-phase locking

Upon op = *read()* or *write(v)* on object O if $O \not\in WSet$ then wait until unlocked = I(O).c&s(unlocked,locked) wSet = wSet U OwLog = wLog U S(O).read()if op = read() then return S(O).read() S(O).write(v) return ok

Two-phase locking (cont'd)

Upon *commit()* cleanup() return ok

Upon *abort()* rollback() cleanup() return ok

Two-phase locking (cont'd)

Upon *rollback()* for all $O \in wSet \text{ do } S(O).write(wLog(O))$ wLog = \emptyset

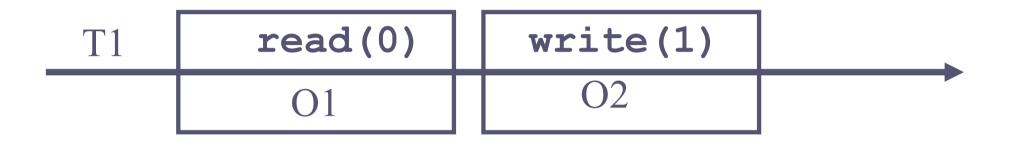
Upon *cleanup()* for all $O \in w$ Set do I(O).write(unlocked) wSet = \emptyset

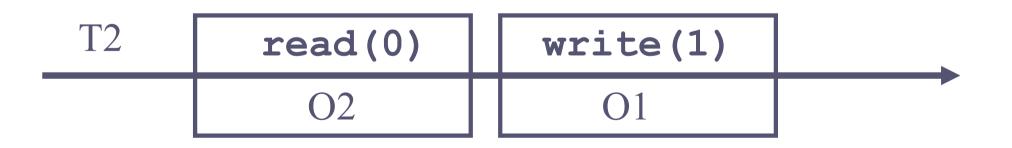
Why two phases? (what if?)

To write or read O, T requires a lock on O;
T waits if some T' acquired a lock on O

T releases the lock on O when T is done with O

Why two phases?





Two-phase locking (read-write lock)

To write O, T requires a write-lock on O;
T waits if some T' acquired a lock on O

To *read* O, T requires a *read-lock* on O;
T *waits* if some T' acquired a *write-lock* on O

Before committing, T releases all its locks

Two-phase locking - better dead than wait -

To write O, T requires a write-lock on O;
T aborts if some T' acquired a lock on O

To *read* O, T requires a *read-lock* on O;
 T *aborts* if some T' acquired a *write-lock* on O

Before committing, T releases all its locks

A transaction that aborts restarts again

Two-phase locking - better kill than wait -

To write O, T requires a write-lock on O;
T aborts T' if some T' acquired a lock on O

To read O, T requires a read-lock on O;
T aborts T' if some T' acquired a write-lock on O

Before committing, T releases all its locks

A transaction that is aborted restarts again

Two-phase locking - better kill than wait -

To write O, T requires a write-lock on O;
T aborts T' if some T' acquired a lock on O

To *read* O, T requires a *read-lock* on O;
T *waits* if some T' acquired a *write-lock* on O

Before committing, T releases all its locks

A transaction that is aborted restarts again

Visible Read (SXM, RSTM, TLRW)

- Write is mega killer: to write an object, a transaction aborts any live one which has read or written the object
- Visible but not so careful read: when a transaction reads an object, it says so

Visible Read

A visible read invalidates cache lines

For read-dominated workloads, this means a lot of traffic on the bus between processors

- This reduces the throughput

- Not a big deal with single-CPU, but with many core machines

Two-phase locking with invisible reads

To write O, T requires a write-lock on O;
T waits if some T' acquired a write-lock on O

To read O, T checks if all objects read remain valid - else T aborts

For a second second

Invisible reads (more details)

- Every object O, with state s(O) (register), is protected by a lock I(O) (c&s)
- Every transaction maintains, besides wSet and wLog:
- A local variable rset(O) for every object

Upon *write(v)* on object O if O $\not\in$ wSet then wait until unlocked = I(O).c&s(unlocked,locked) wSet = wSet U OwLog = wLog U S(O).read()(*,ts) = S(O).read()S(O).write(v,ts) return ok

Upon *read()* on object O (v,ts) = S(O).read()if $O \in wSet$ then return v if I(O) = locked or not validate() then abort() if rset(O) = 0 then rset(O) = ts return v

Upon *validate()* for all O s.t rset(O) > 0 do (v,ts) = S(O).read()if ts \neq rset(O) or $(O \notin wset and I(O) = locked)$ then return false else return true

Upon *commit()* if not validate() then abort() for all $O \in$ wset do (v,ts) = S(O).read()S(O).write(v,ts+1)cleanup()

Upon *rollback()* for all $O \in wSet \text{ do } S(O).write(wLog(O))$ wLog = \emptyset

Upon *cleanup()* for all $O \in$ wset do I(O).write(unlocked) wset = \emptyset rset(O) = 0 for all O

DSTM (SUN)

To write O, T requires a write-lock on O;
T aborts T' if some T' acquired a write-lock on O

- To read O, T checks if all objects read remain valid else T abort
- Before committing, T releases all its locks



Killer write (ownership)

Careful read (validation)

More efficient algorithm?

Apologizing versus asking permission

- *Killer write*
- Optimistic read
 - validity check only at commit time



Invariant: 0 < x < yInitially: x := 1; y := 2



T1: x := x+1 ; y:= y+1

T2: z := 1 / (y - x)

Infinite loop

T1: x := 3; y:= 6

T2: a := y; b:= x; repeat b:= b + 1 until a = b



Serializability

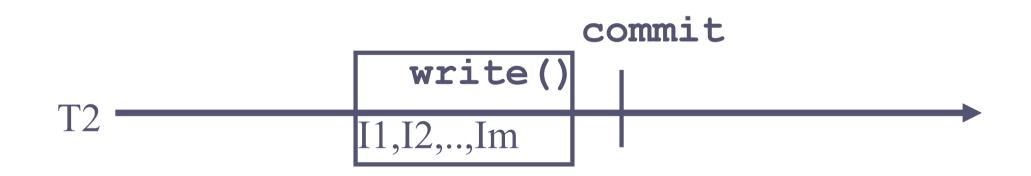
Consistent memory view

Trade-off

The read is either *visible* or *careful*







Read invisibility

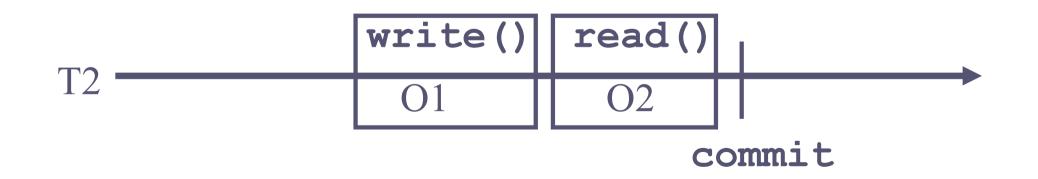
The fact that the read is invisible means T1 cannot inform T2, which would in turn abort T1 if it accessed similar objects (SXM, RSTM)

NB. Another way out is the use of multiversions: T2 would not have written "on" T1

Aborting is a fatality



abort



Conditional progress - obstruction-freedom -

A correct transaction that eventually does not encounter *contention* eventually commits

Obstruction-freedom seems reasonable and is indeed possible

DSTM

- To write O, T requires a write-lock on O (use C&S); T aborts T' if some T' acquired a write-lock on O (use C&S)
- To read O, T checks if all objects read remain valid else abort (use C&S)
- Before committing, T releases all its locks (use C&S)



- If a transaction T wants to write an object O owned by another transaction T', T calls a contention manager
- The contention manager can decide to wait, retry or abort T'

Contention managers

- Aggressive: always aborts the victim
- **Backoff**: wait for some time (exponential backoff) and then abort the victim
- Karma: priority = cumulative number of shared objects accessed – work estimate. Abort the victim when number of retries exceeds difference in priorities.
- **Polka**: Karma + backoff waiting

Greedy contention manager

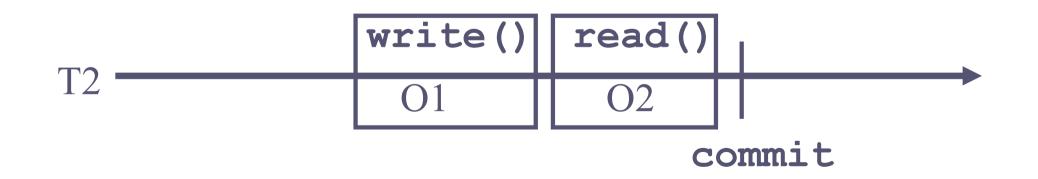
State

- Priority (based on start time)
- Waiting flag (set while waiting)
- *Wait* if other has
 - Higher priority AND not waiting
- Abort other if
 - Lower priority OR waiting

Aborting is a fatality



abort



Concluding remarks

TM does not always replace locks: it hides them

Memory transactions look like db transactions but are different

The garbage-collection analogy

- In the early times, the programmers had to take care of allocating and de-allocating memory
- Garbage collectors do it for you: they are now incorporated in Java and other languages
- Hardware support was initially expected, but now software solutions are very effective

