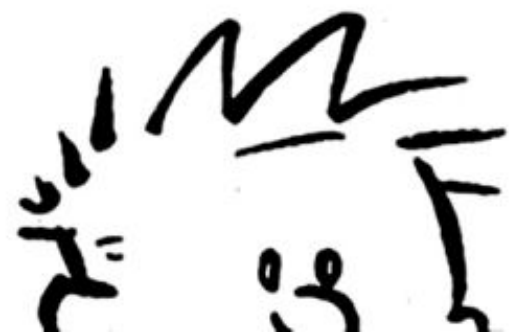


Role of Momentum in Byzantine Resilience of Distributed Learning

Nirupam Gupta

EPFL





“All models are wrong, but some are useful.”

— George Box ?

Machine Learning

Machine Learning

DATA

Machine Learning

DATA



Machine Learning

DATA



AMATEUR MACHINE

Machine Learning

DATA



AMATEUR MACHINE

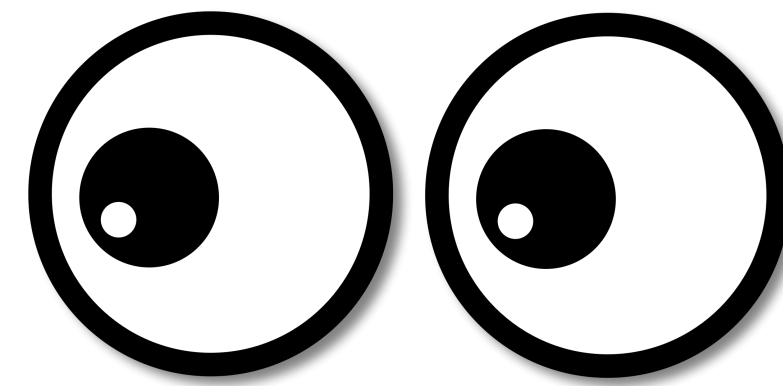


Machine Learning

DATA



AMATEUR MACHINE

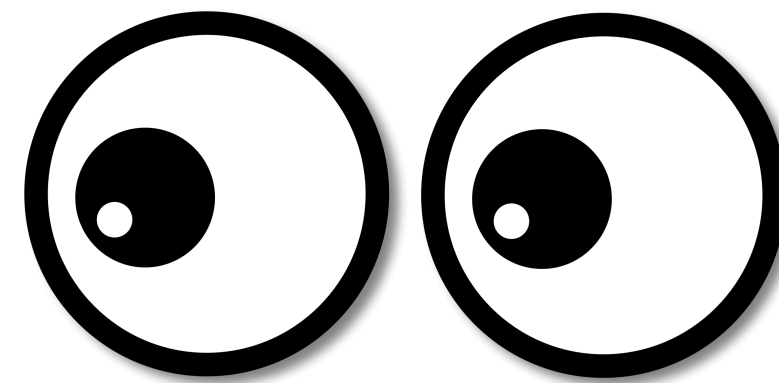


Machine Learning

DATA



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AMATEUR MACHINE



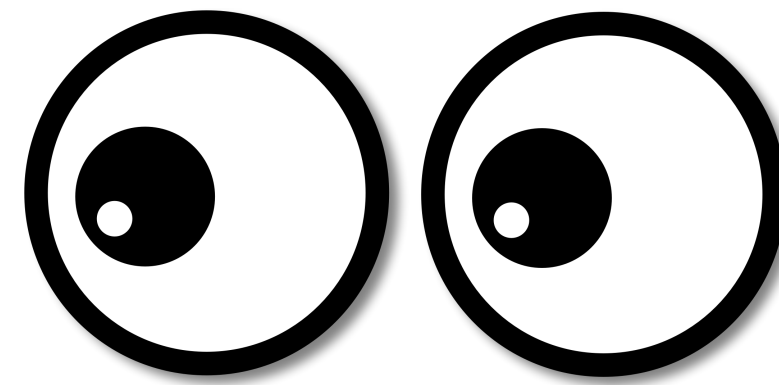
Machine Learning

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D

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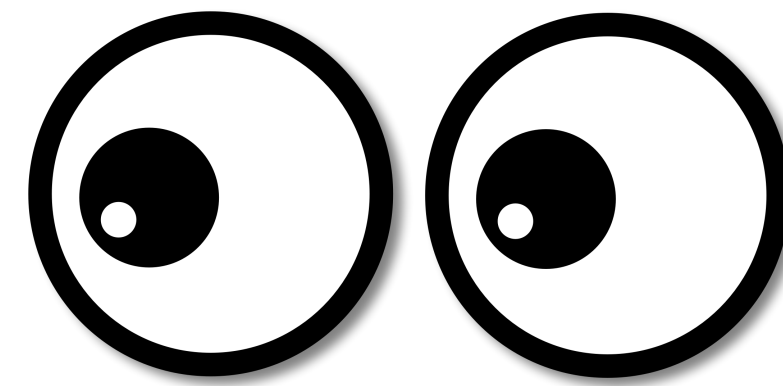
Machine Learning

DATA

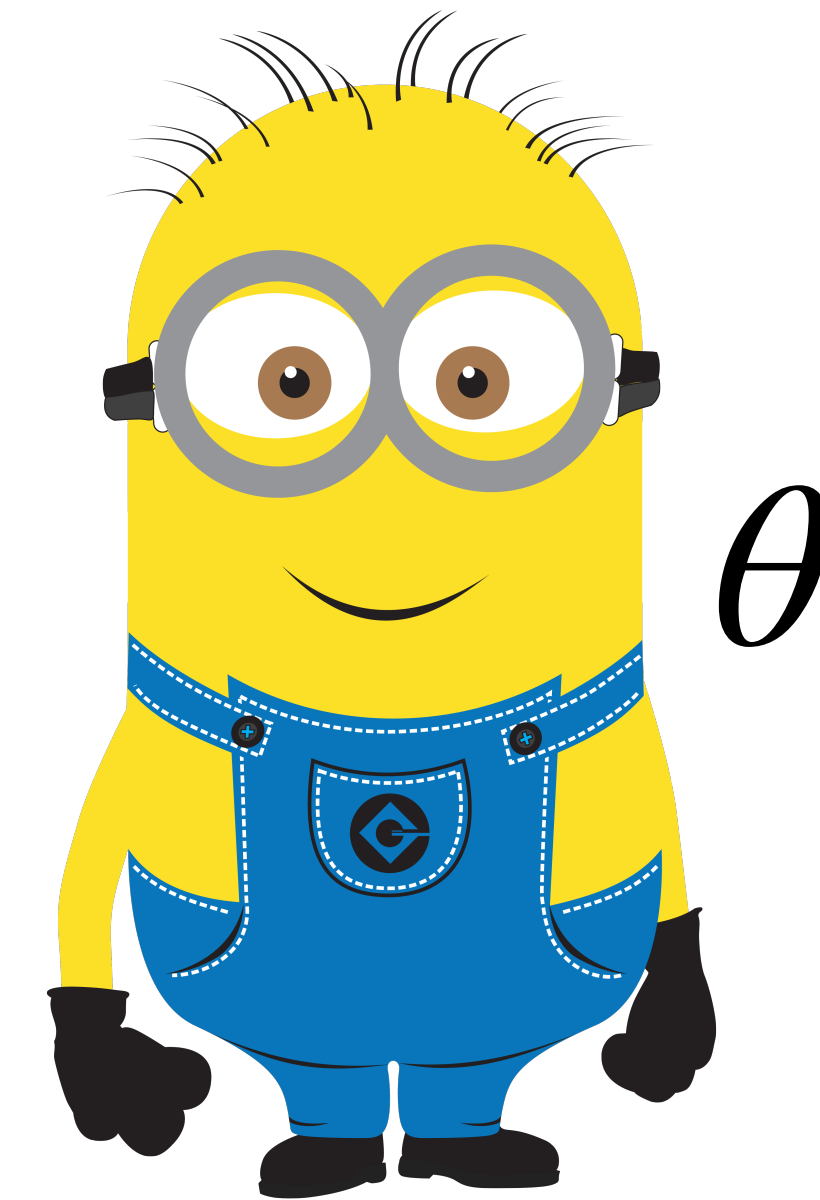


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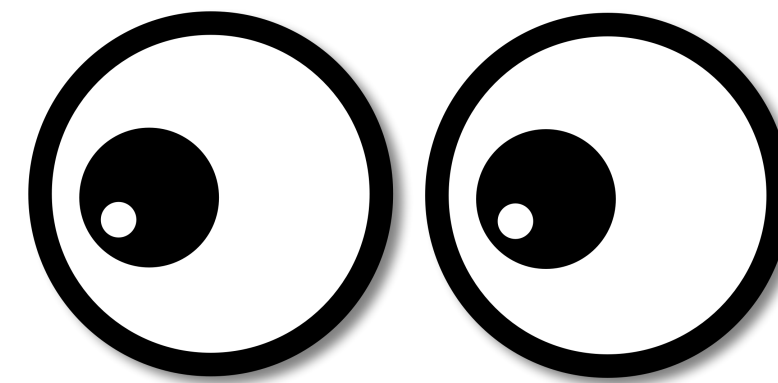
Machine Learning

DATA

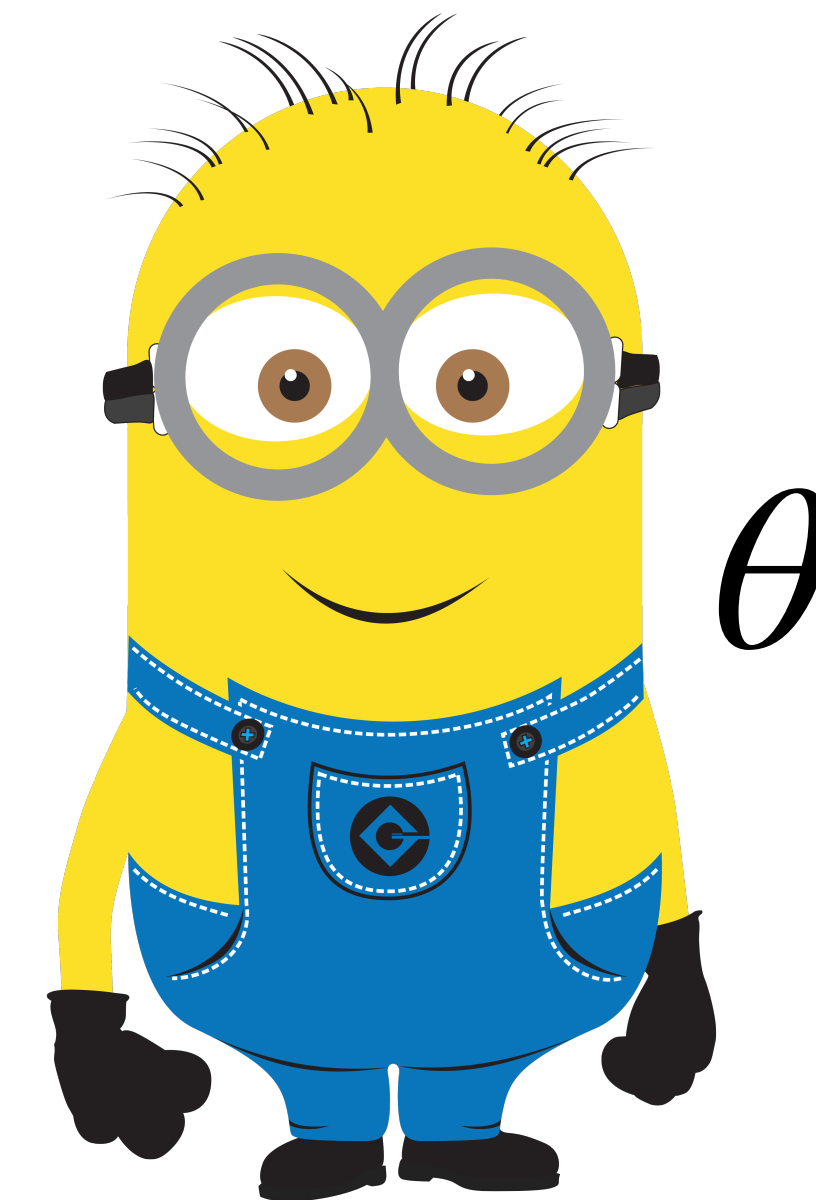
\mathcal{D}



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AMATEUR MACHINE



SOLVE

$$\theta^* \leftarrow \arg \min_{\theta} Q(\theta) := \mathbb{E}_{x \sim \mathcal{D}} q(\theta, x)$$

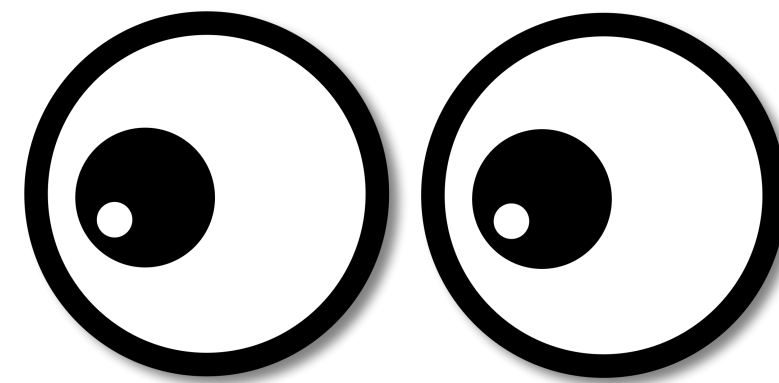
Machine Learning

DATA

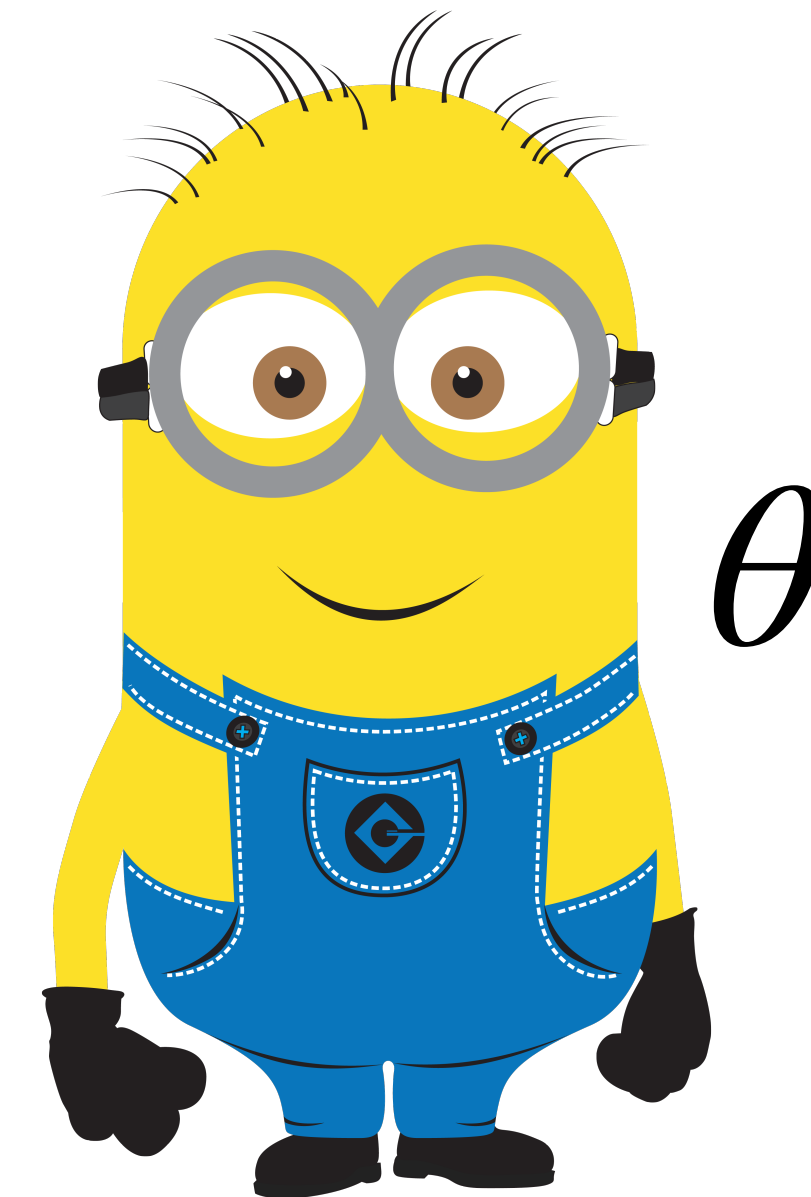
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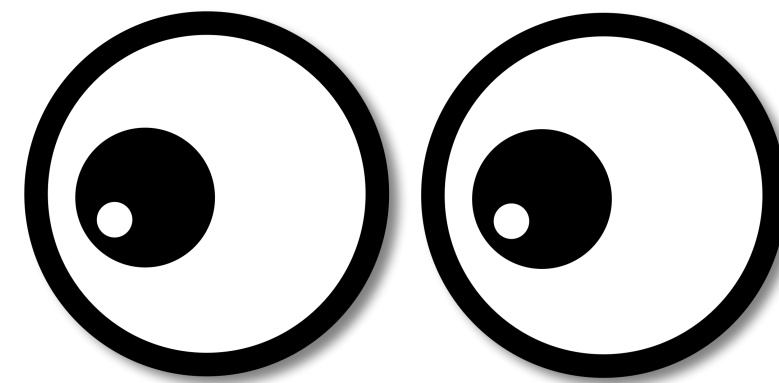
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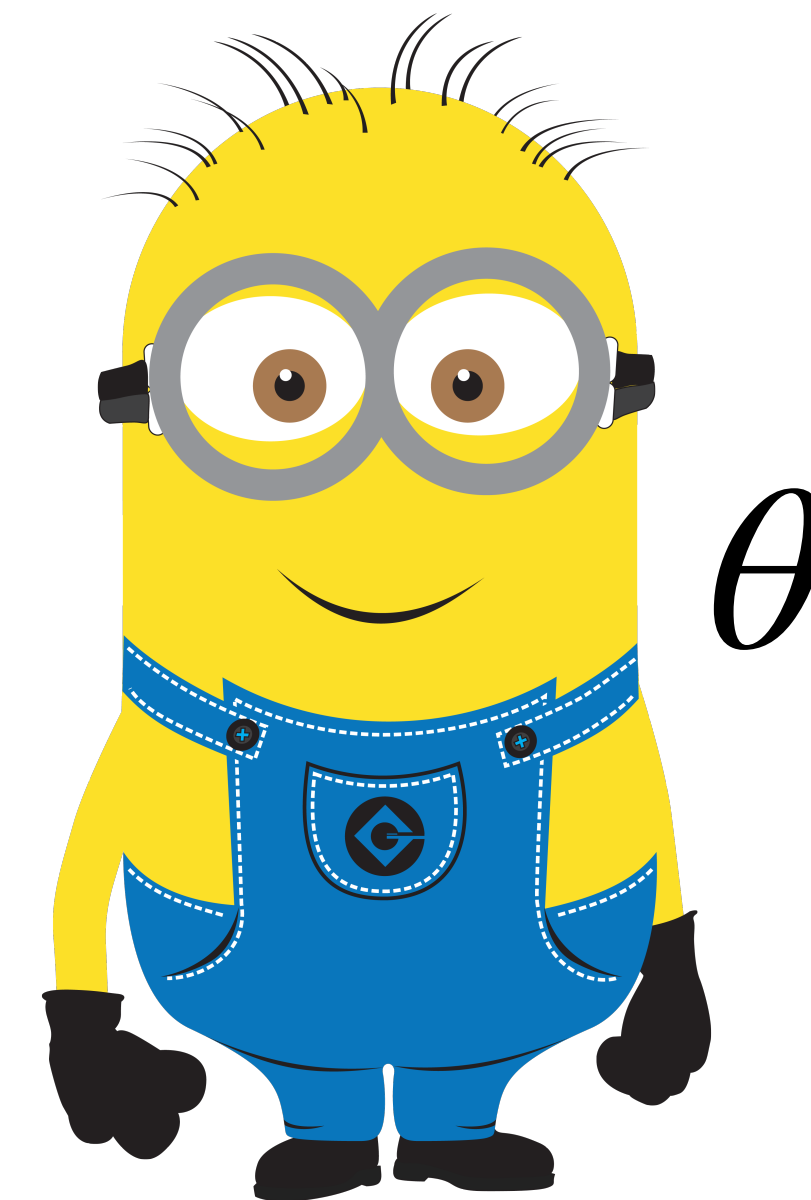
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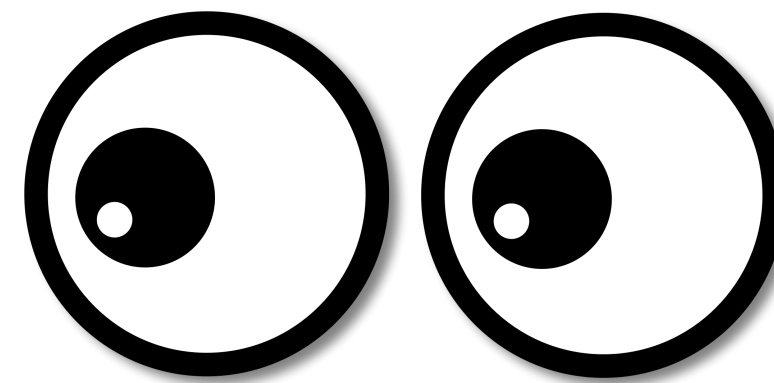
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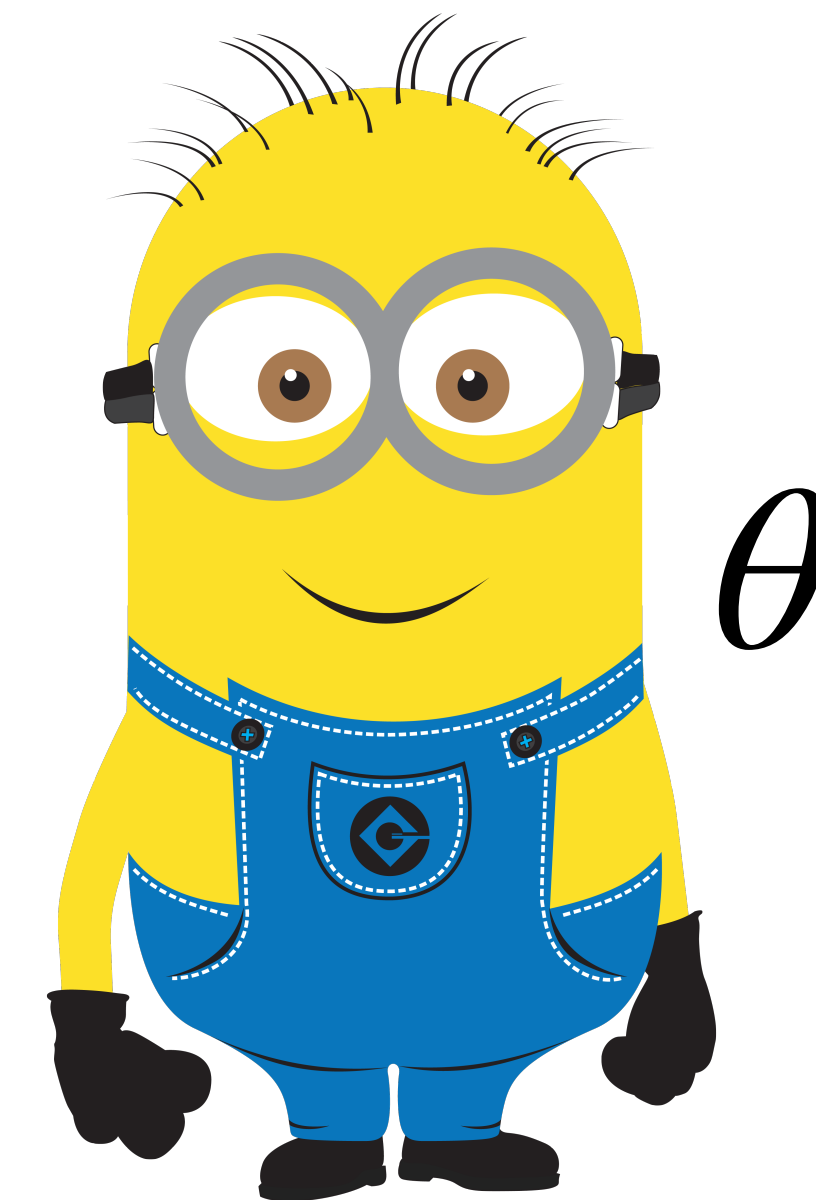


\mathcal{D}

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AMATEUR MACHINE



θ

Loss per data-point

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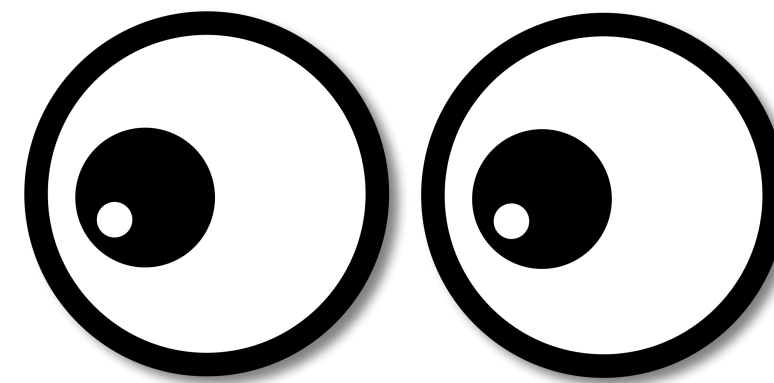
Machine Learning

DATA

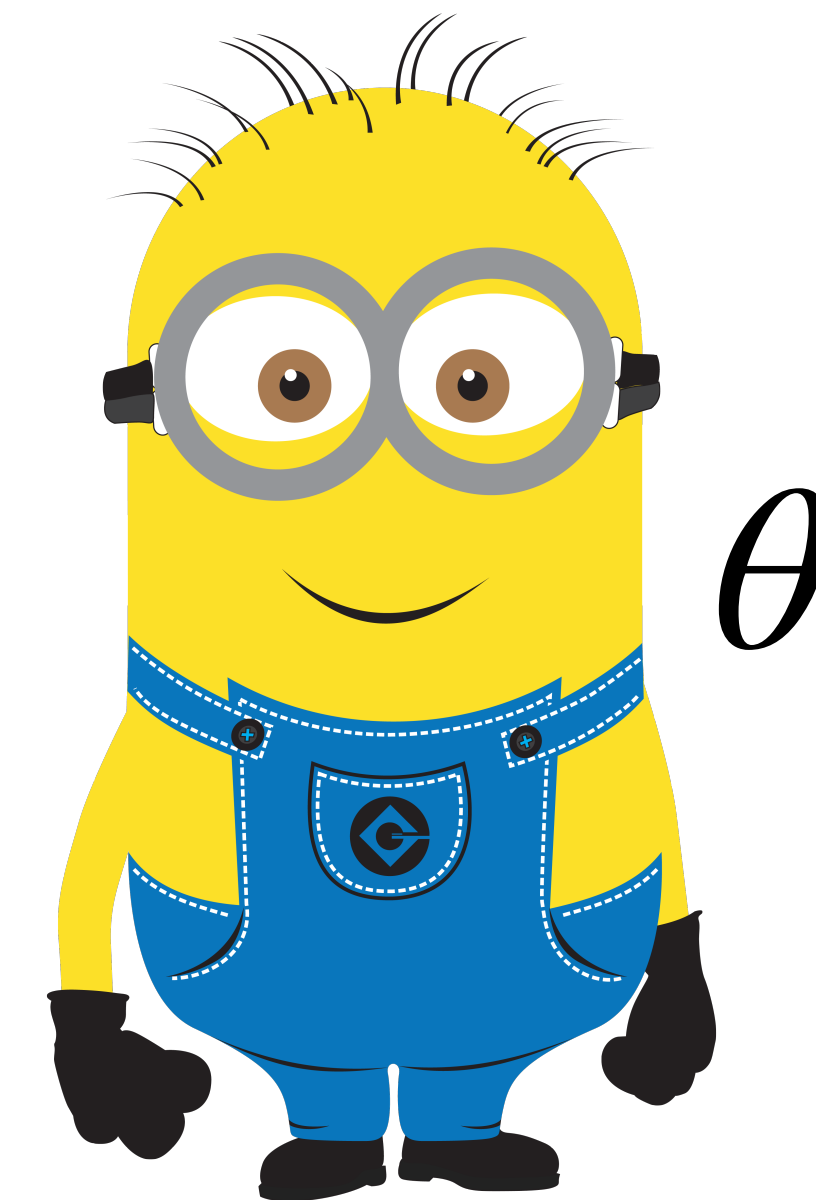


\mathcal{D}

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EXPERT MACHINE



Loss per data-point

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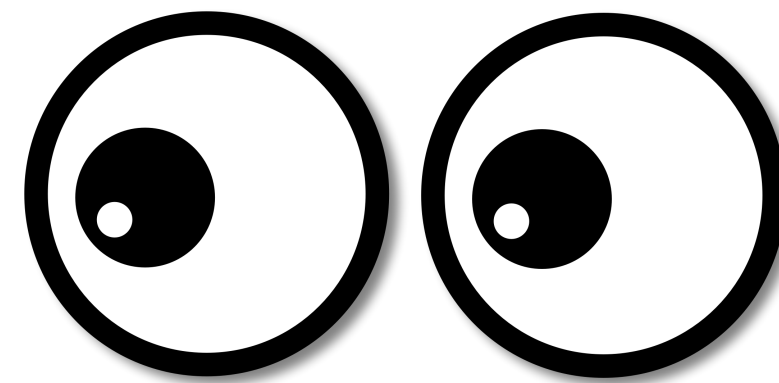
Machine Learning

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\mathcal{D}

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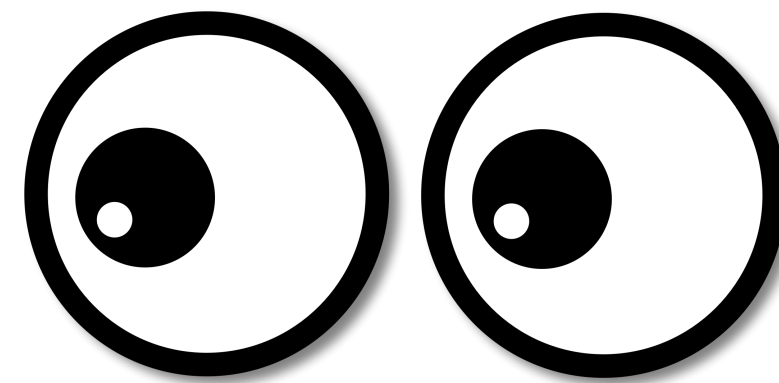
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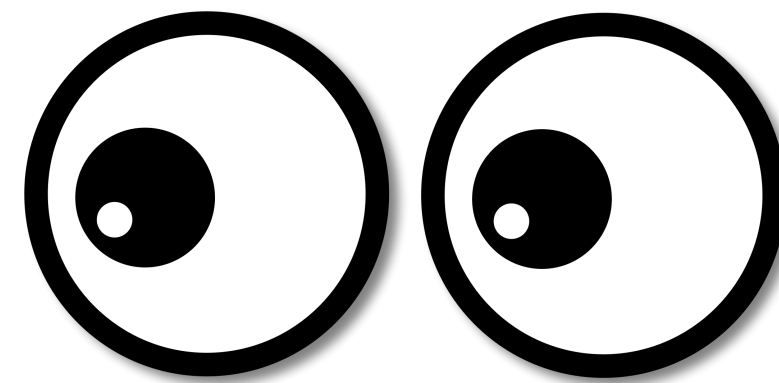
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EXPERT MACHINE

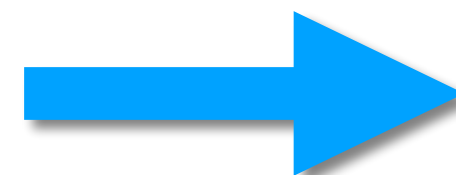


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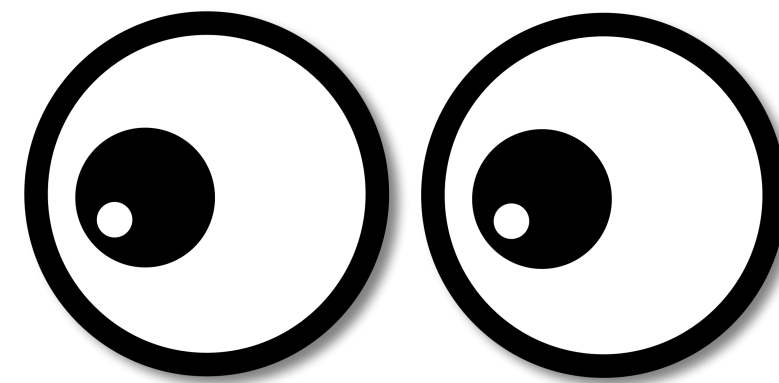
Machine Learning

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\mathcal{D}

WATCH & LEARN



EXPERT MACHINE



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Relax



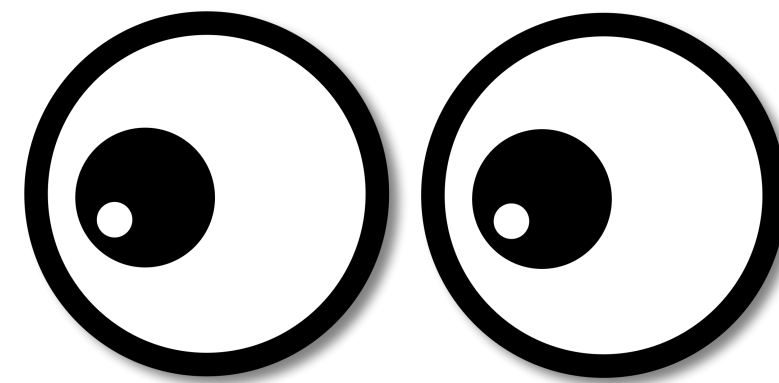
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\mathcal{D}

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EXPERT MACHINE



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Relax

MORE REASONABLE GOAL

$$\theta^* \in (\theta ; \nabla Q(\theta) = 0)$$

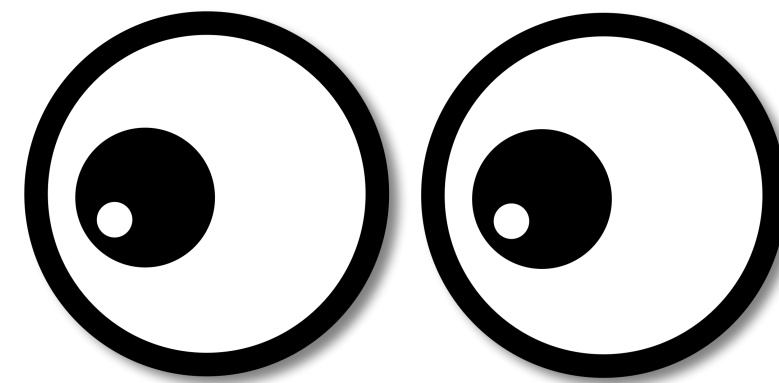
Machine Learning

DATA

\mathcal{D}



WATCH & LEARN



“EXPERT” MACHINE



θ^*

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MORE REASONABLE GOAL

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Distributed Learning



Distributed Learning

DATA IS GROWING



Distributed Learning

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Distributed Learning

DATA IS GROWING



SO ARE THE MODELS



Distributed Learning

DATA IS GROWING



SO ARE THE MODELS

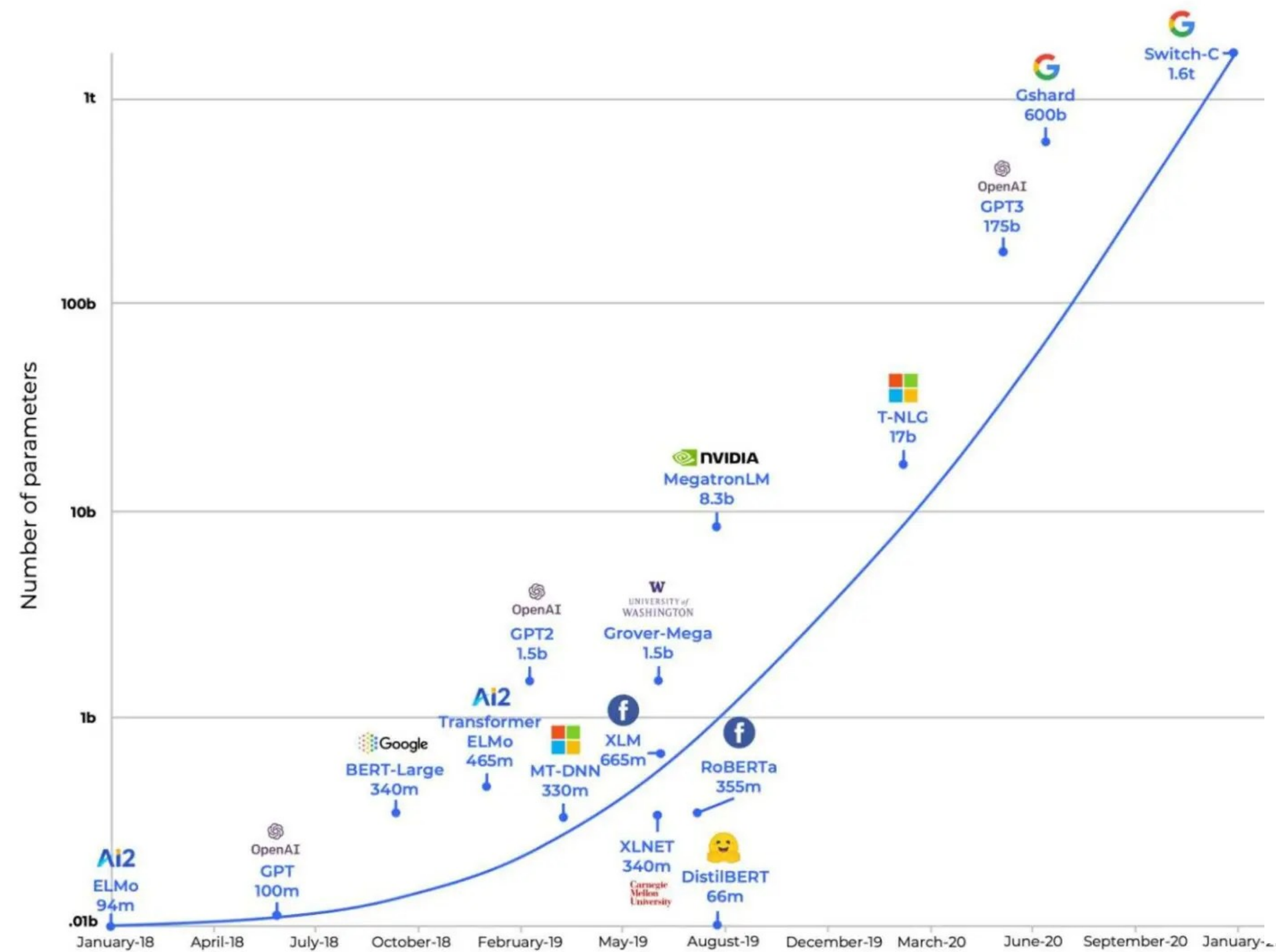


Distributed Learning

DATA IS GROWING



SO ARE THE MODELS



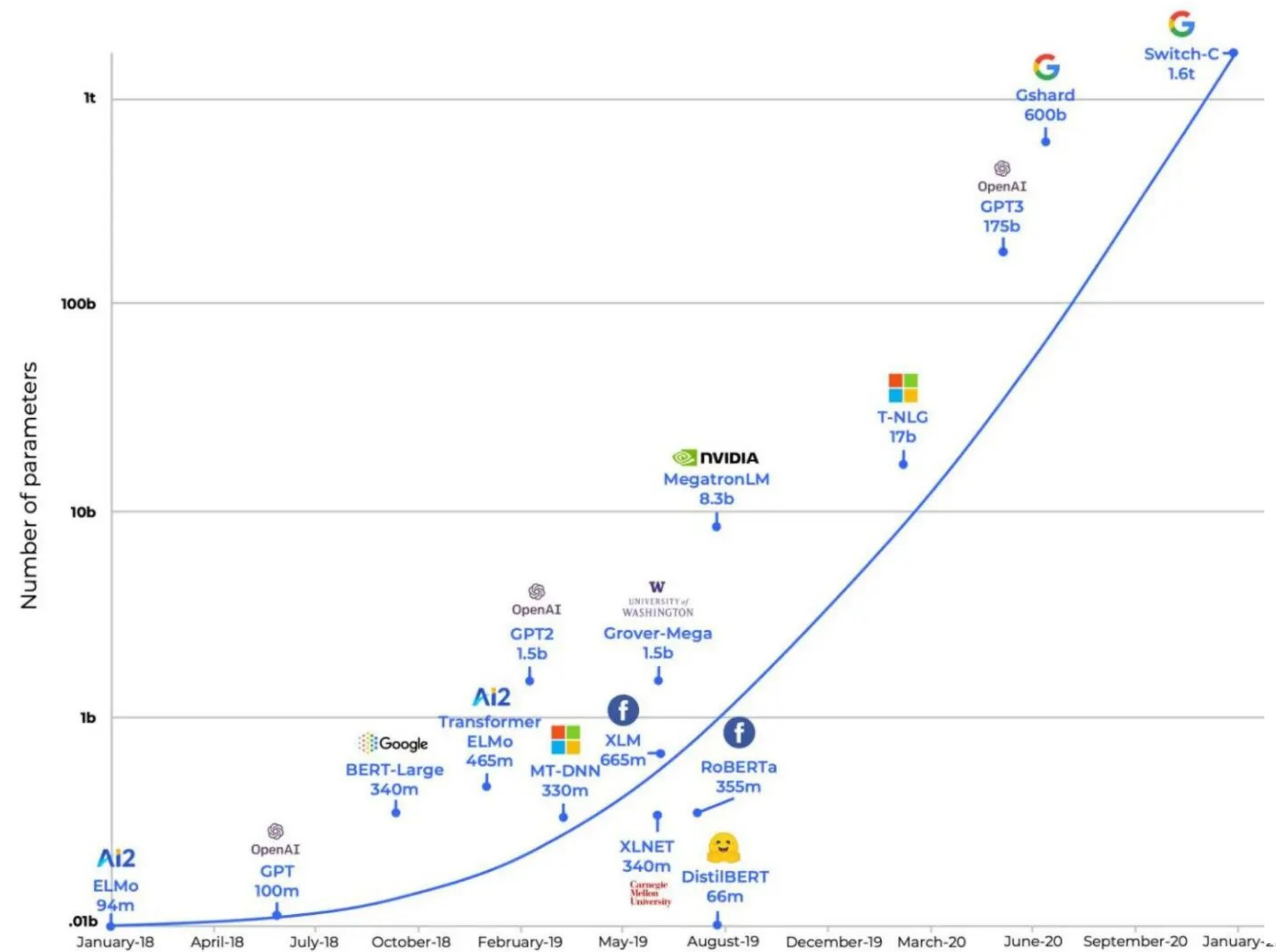
Distributed Learning

DATA IS GROWING



SO ARE THE MODELS

NEED MANY MACHINES TO TRAIN



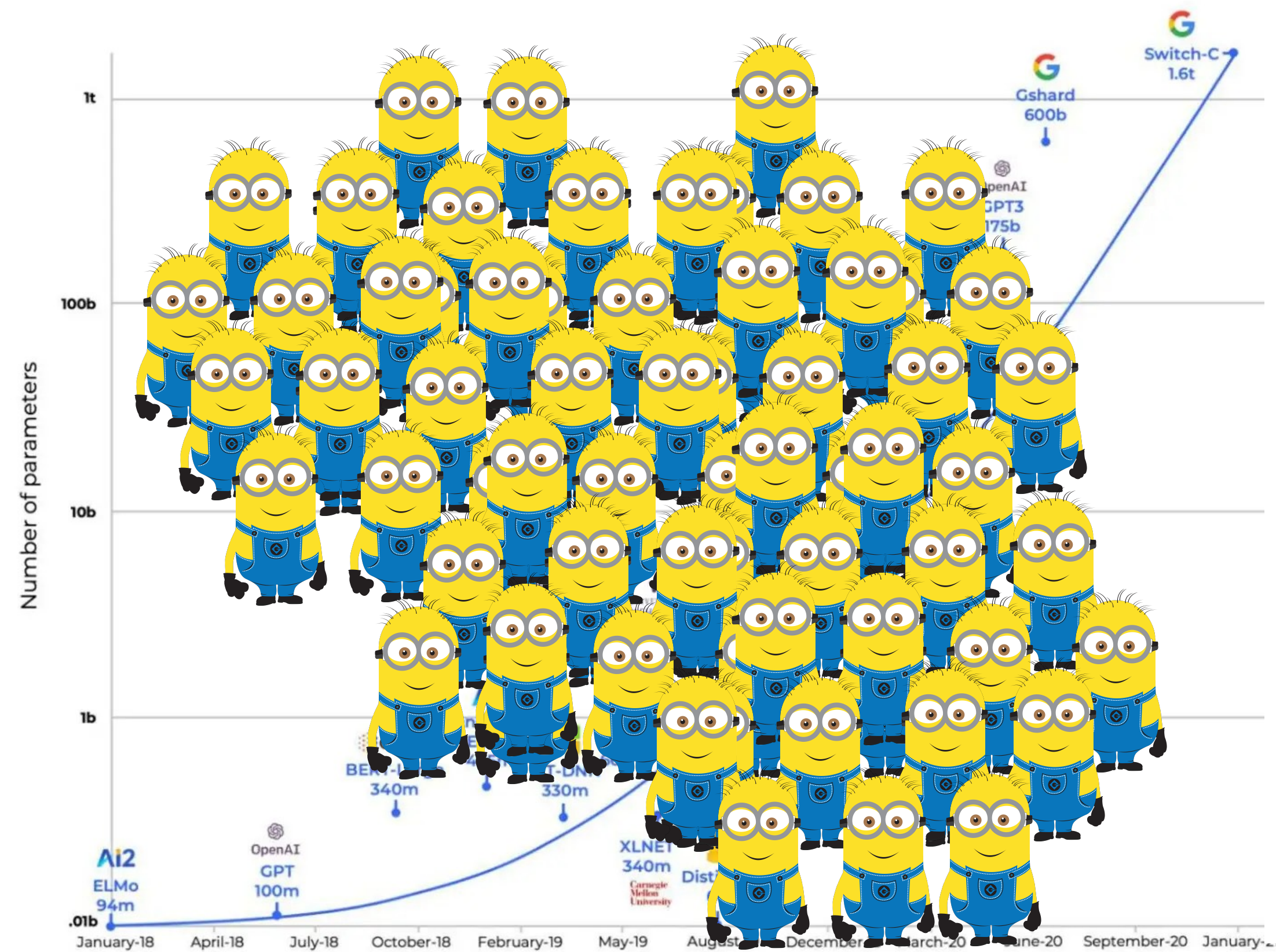
Distributed Learning

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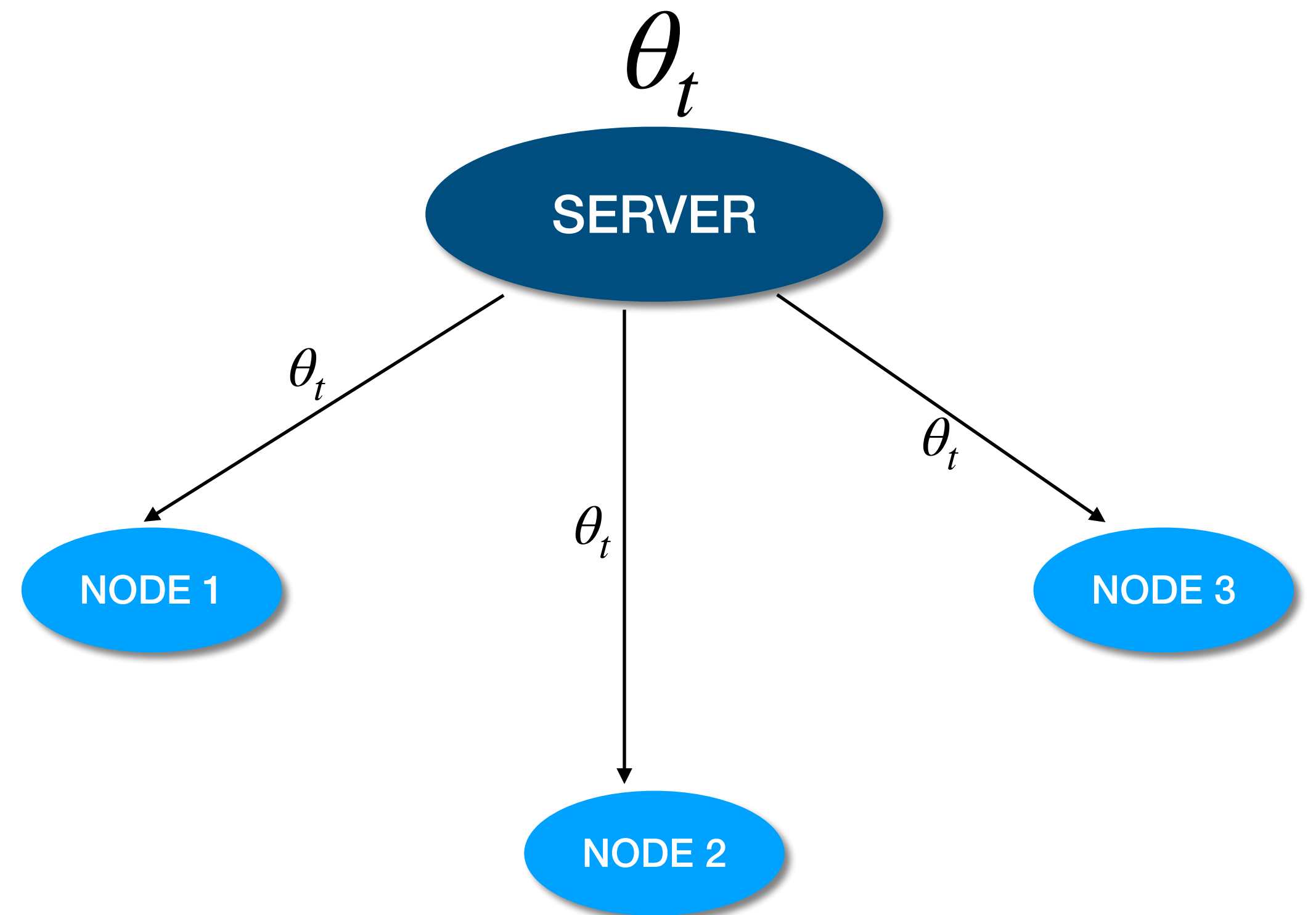
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Distributed SGD

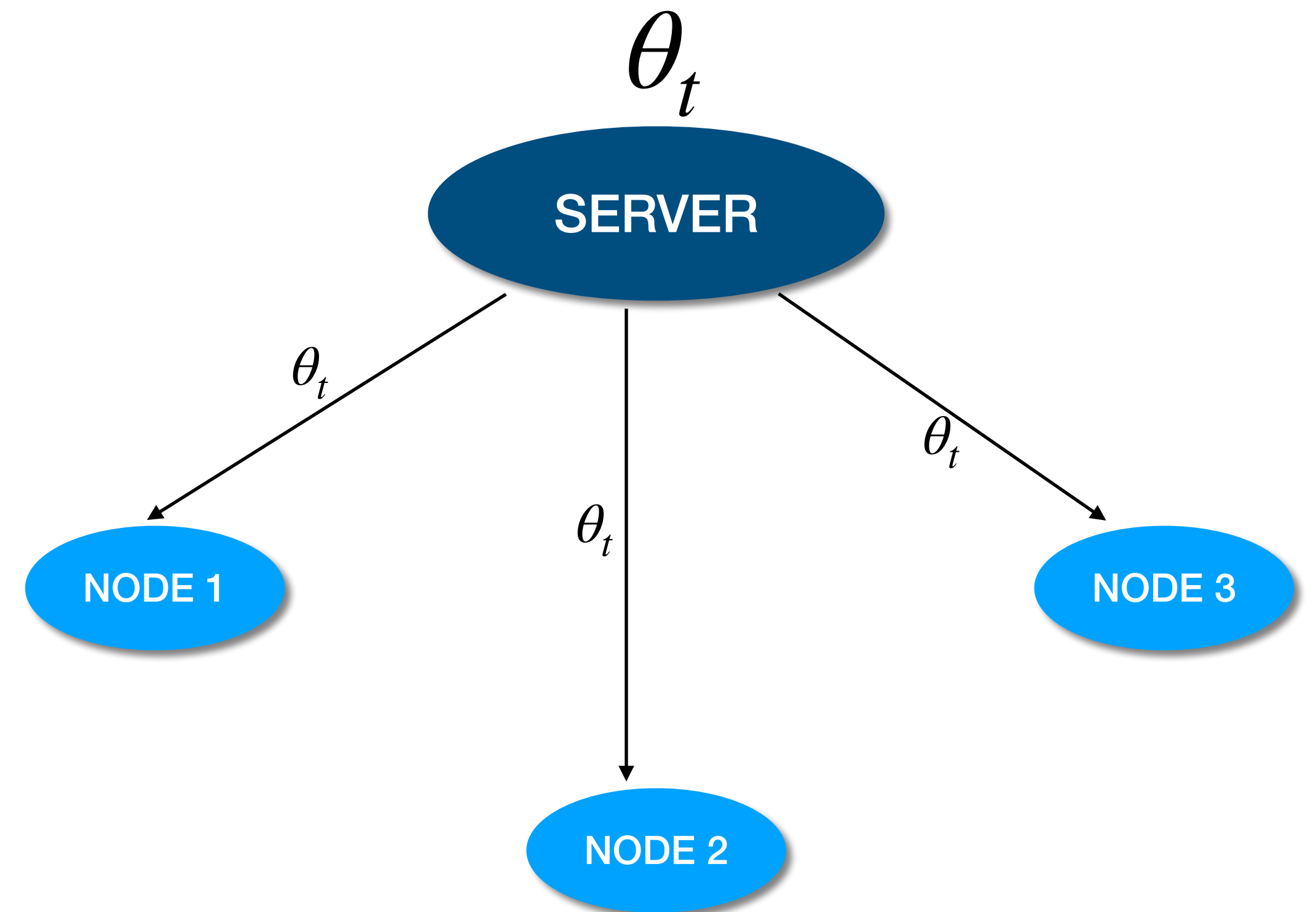
Divides the workload per machine by the total size of the system



Distributed SGD

Divides the workload per machine by the total size of the system

Nodes query *stochastic gradients* with bounded variance

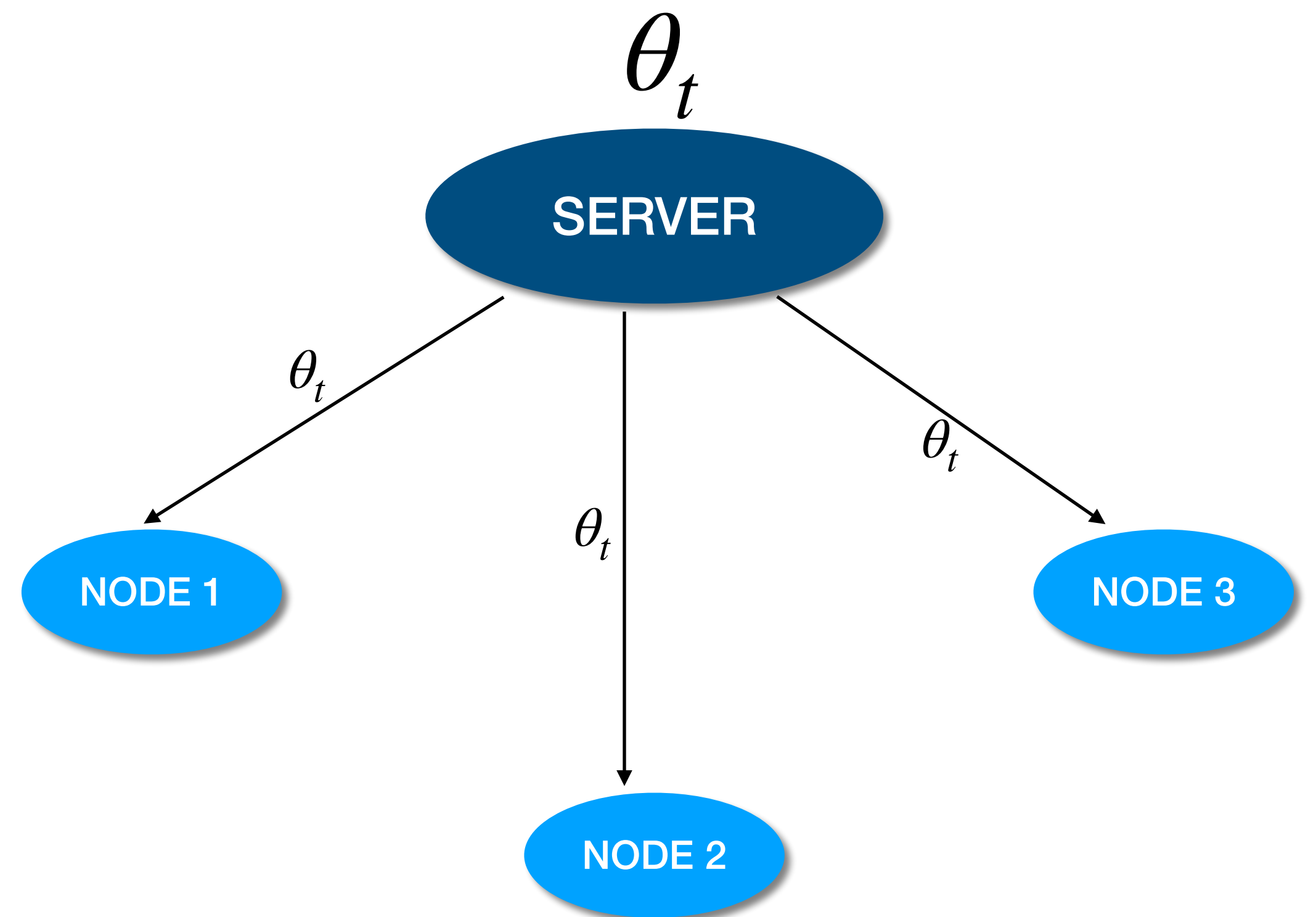


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$$g_t^i = \nabla Q(\theta_t) + u_t^i \quad ;$$

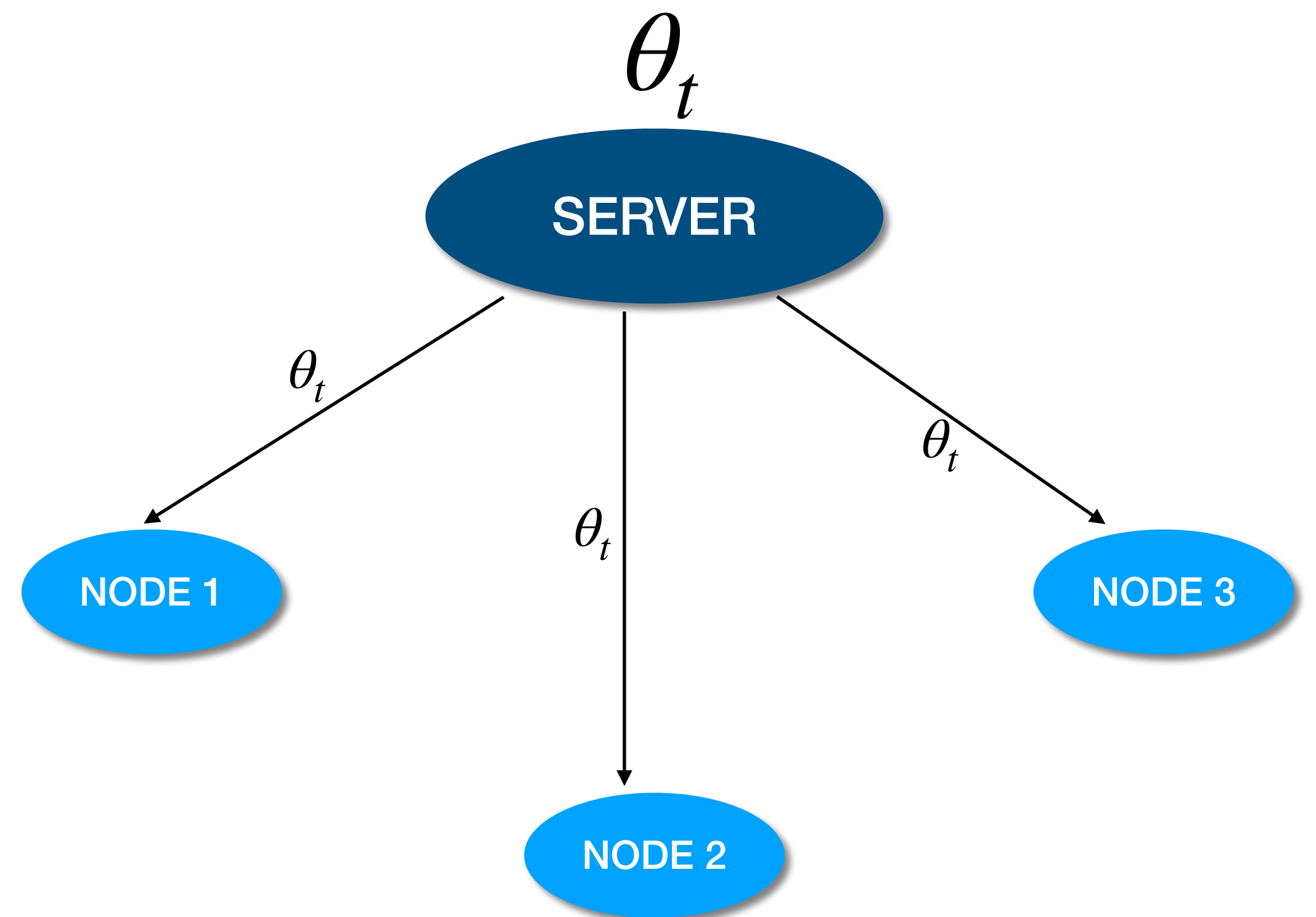


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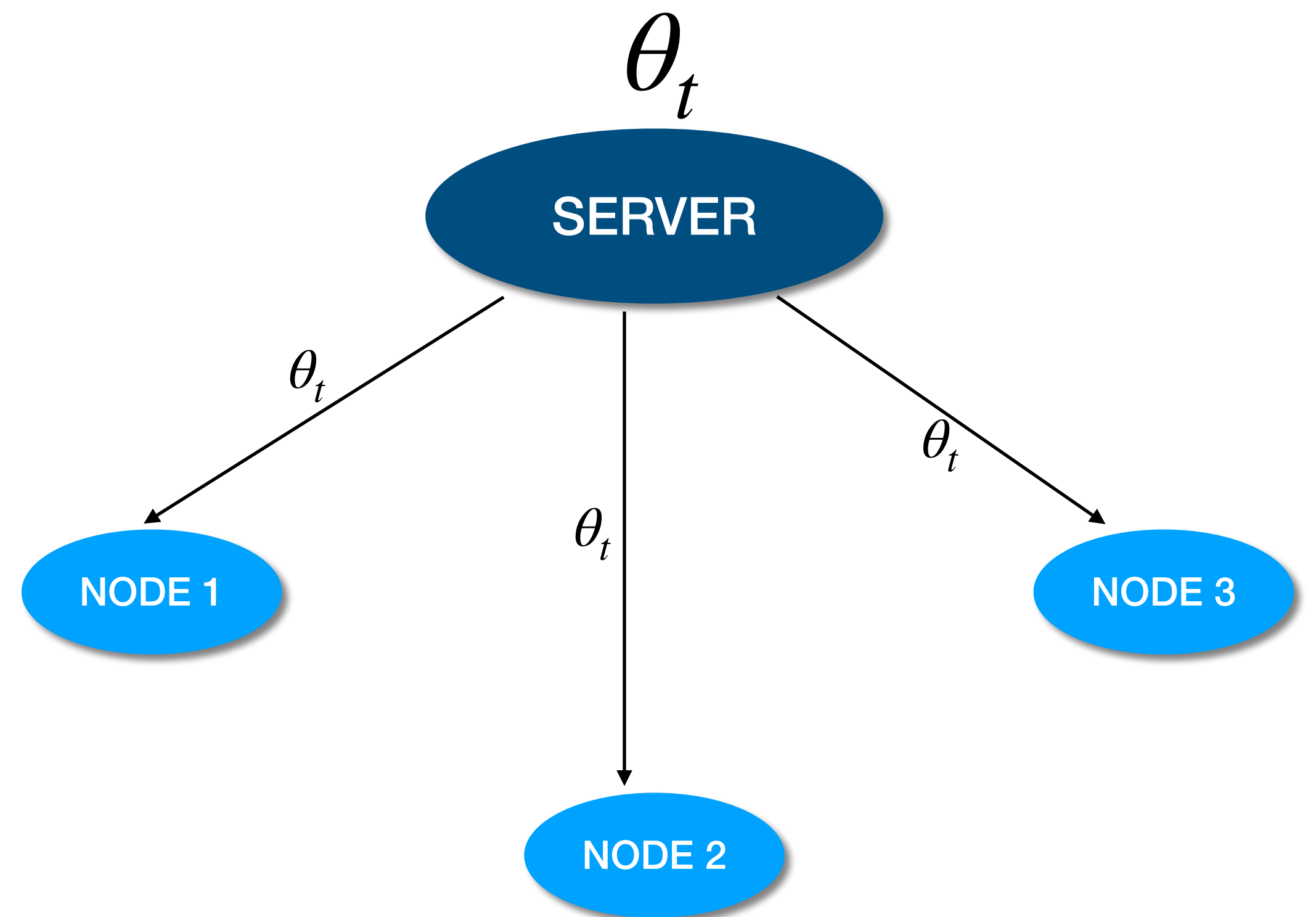


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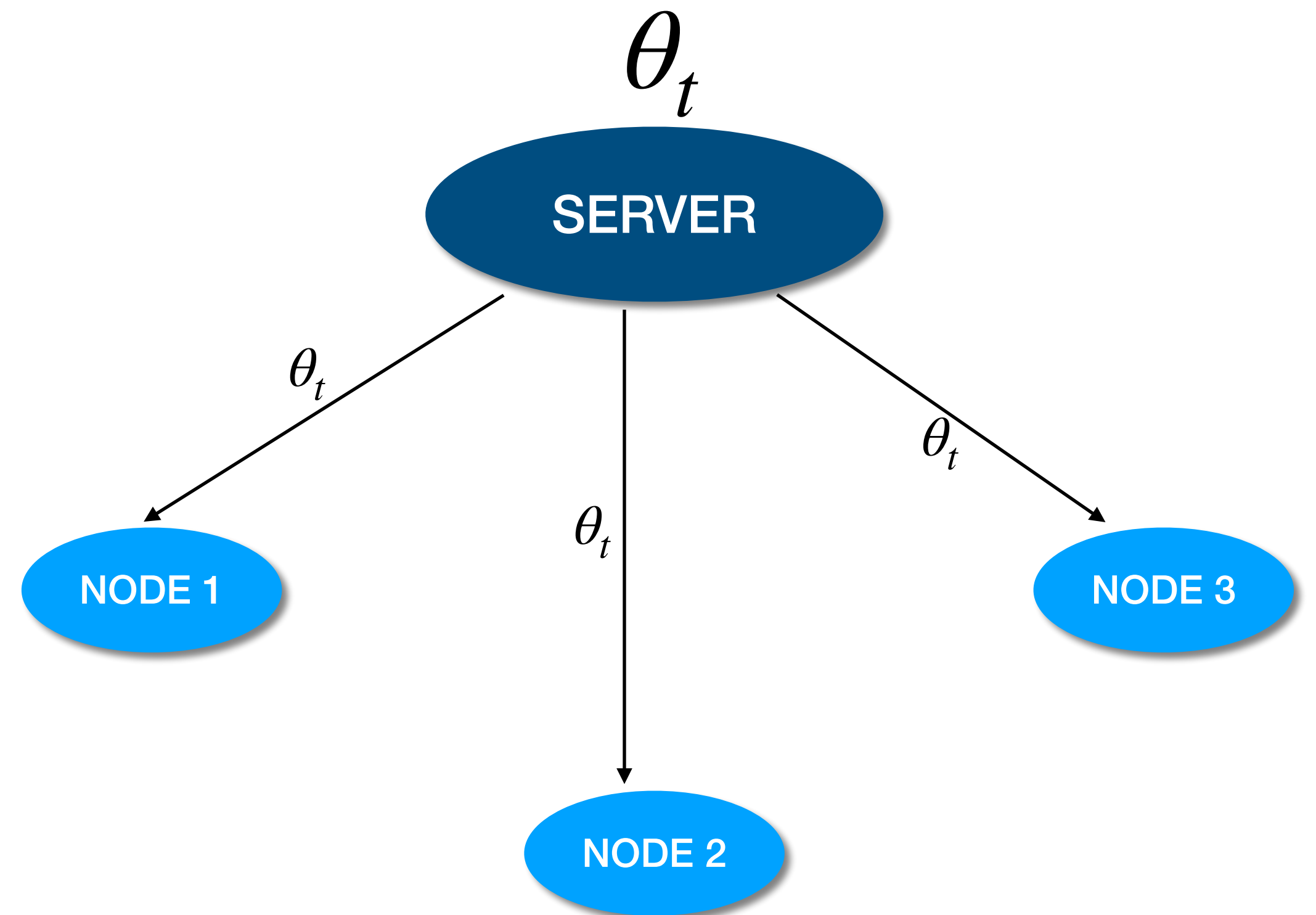
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True gradient



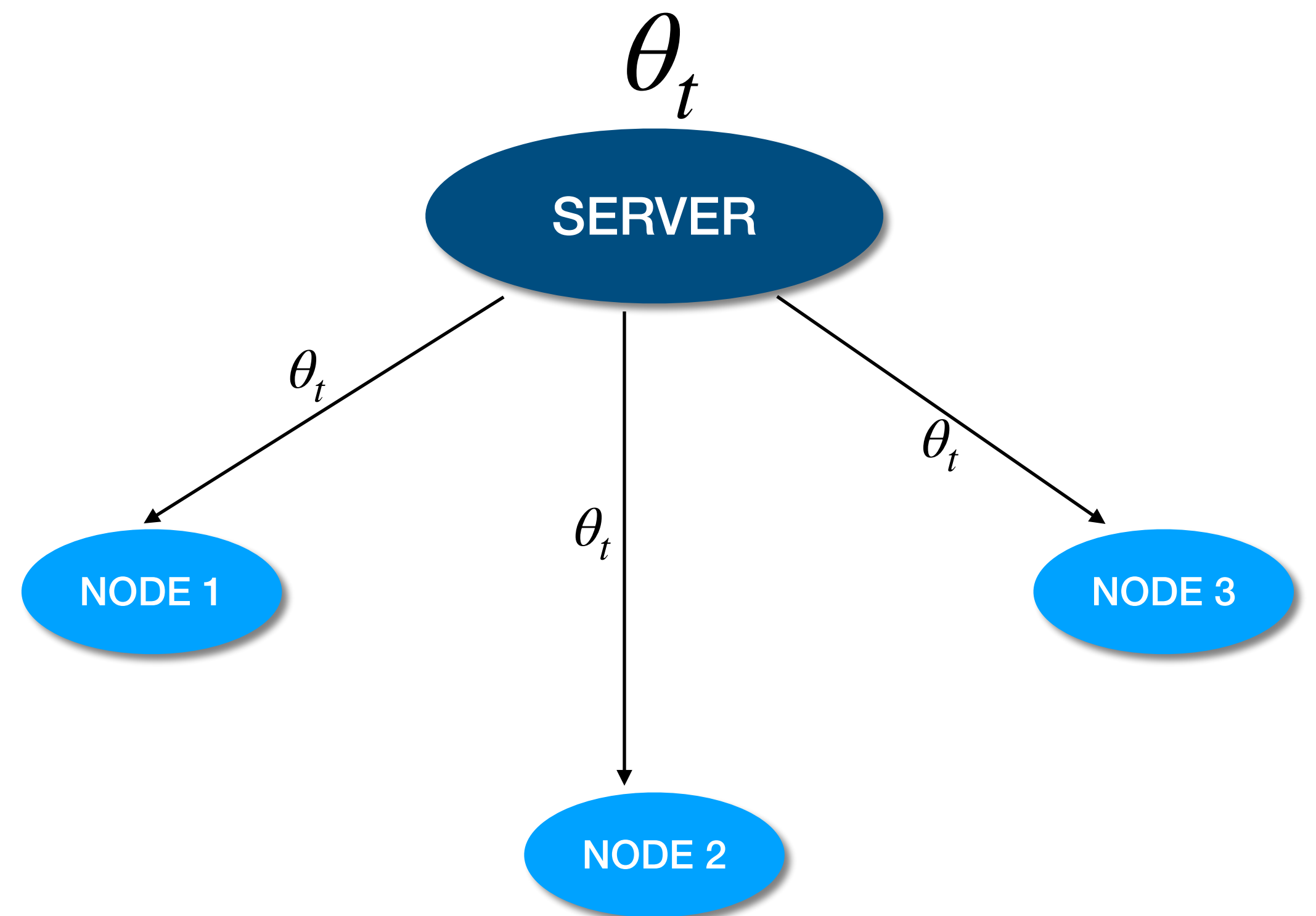
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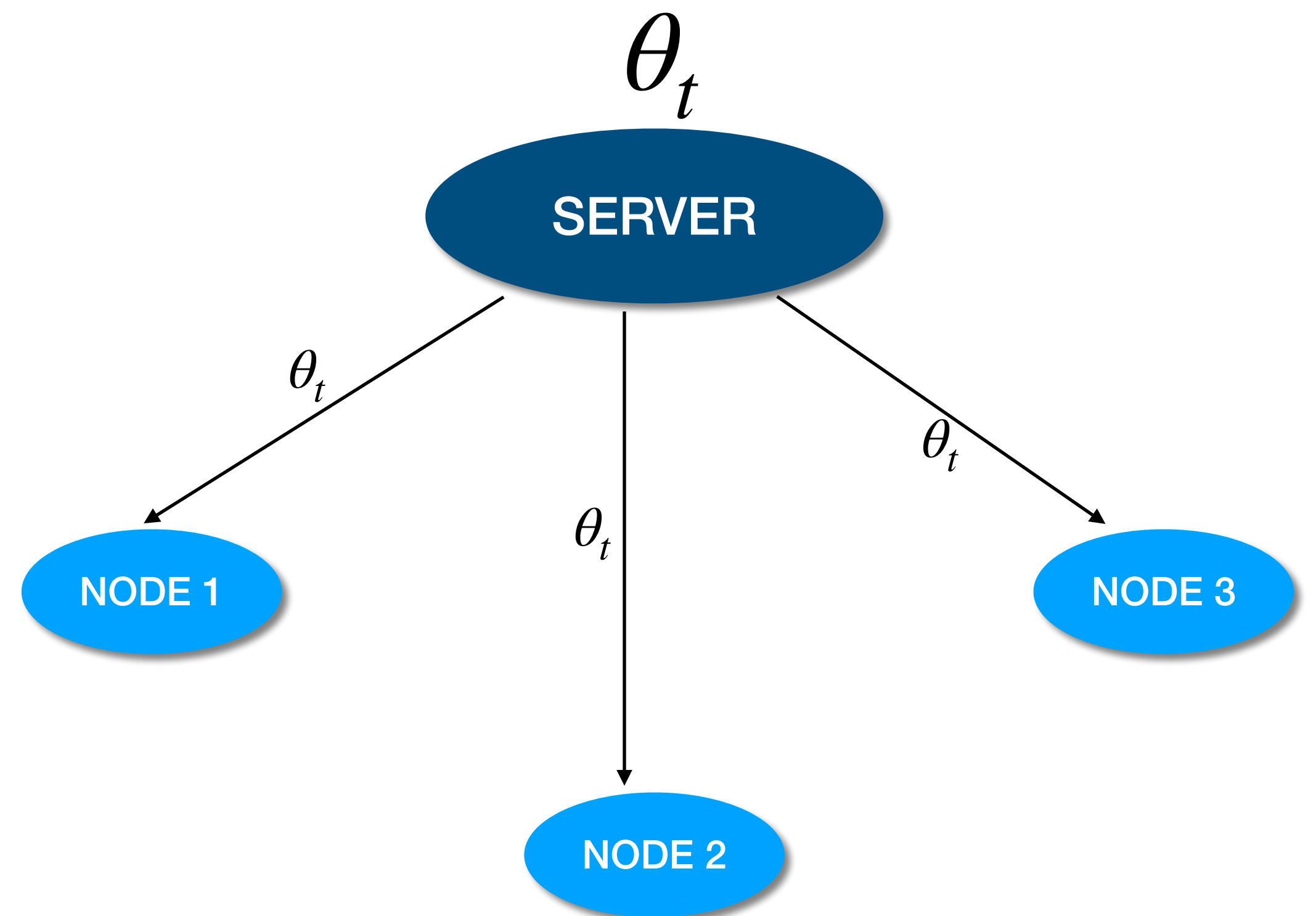
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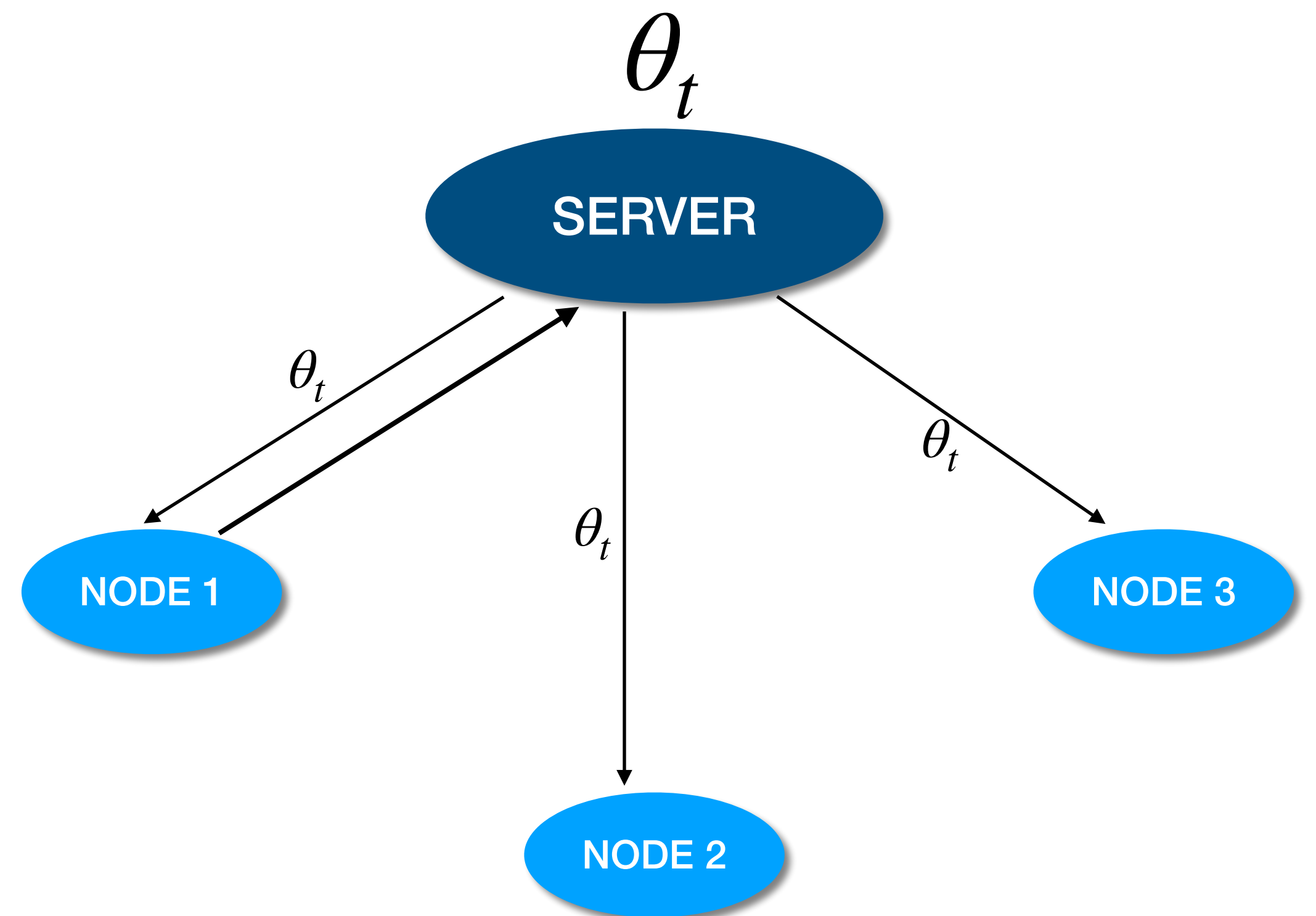
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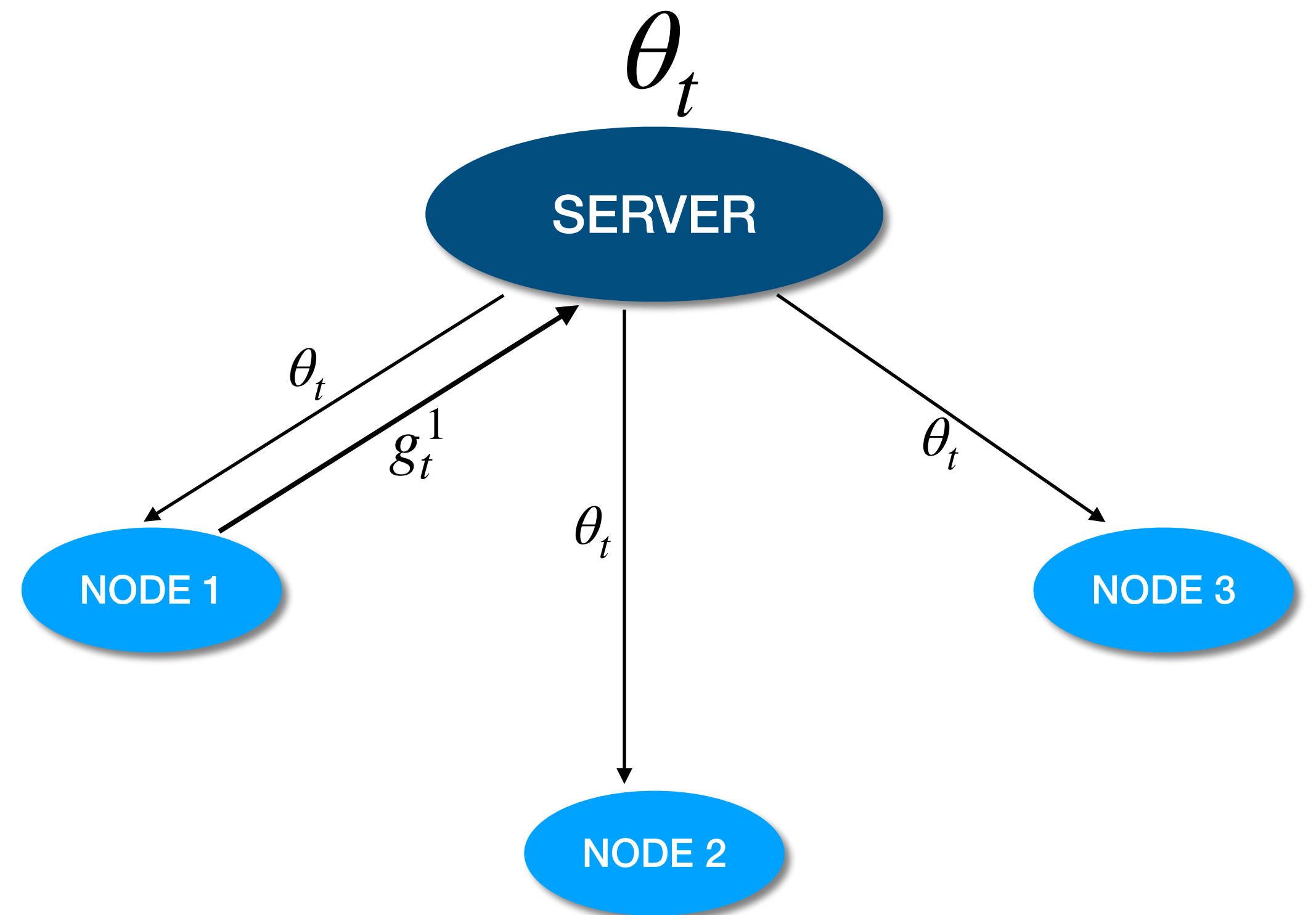
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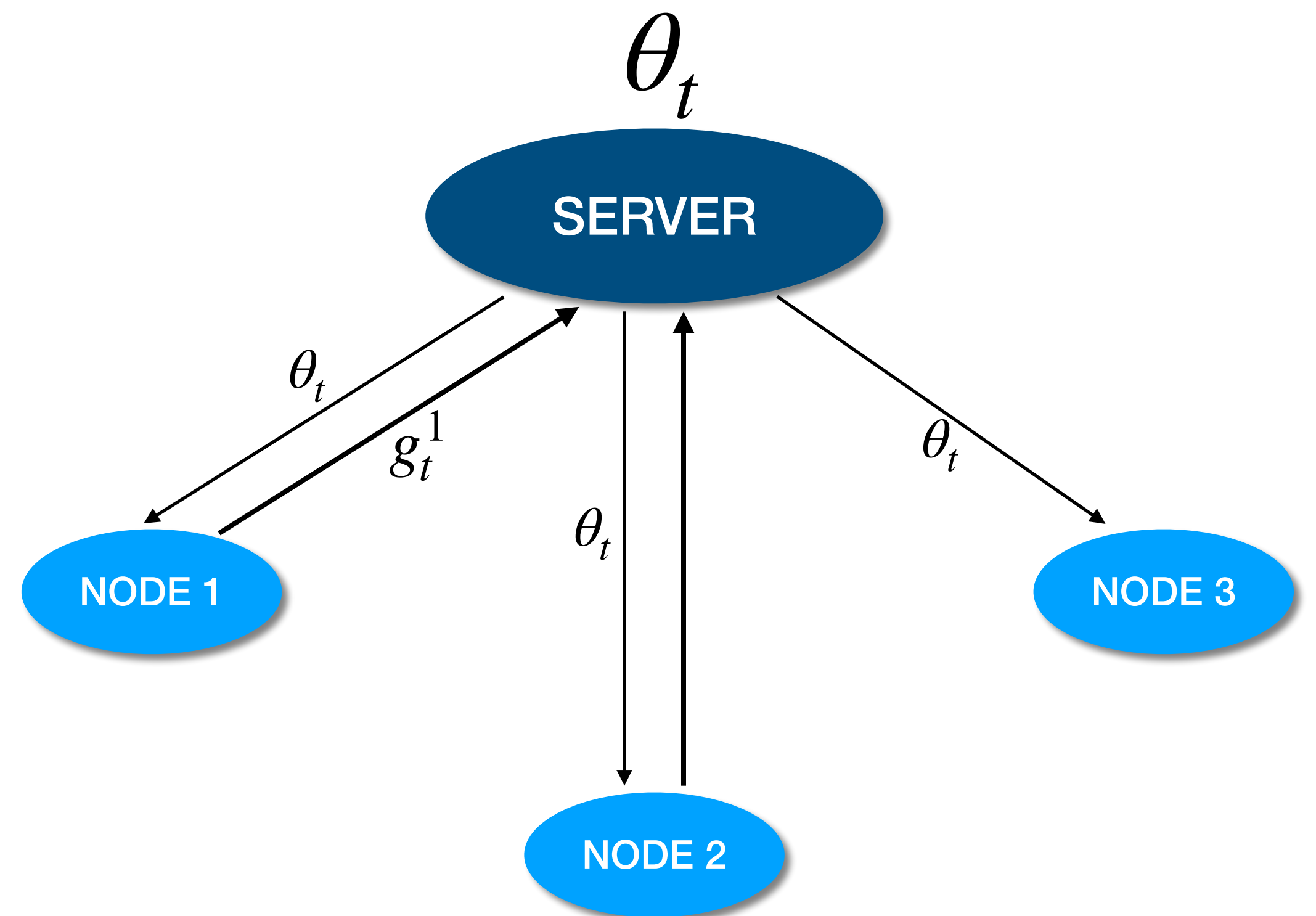
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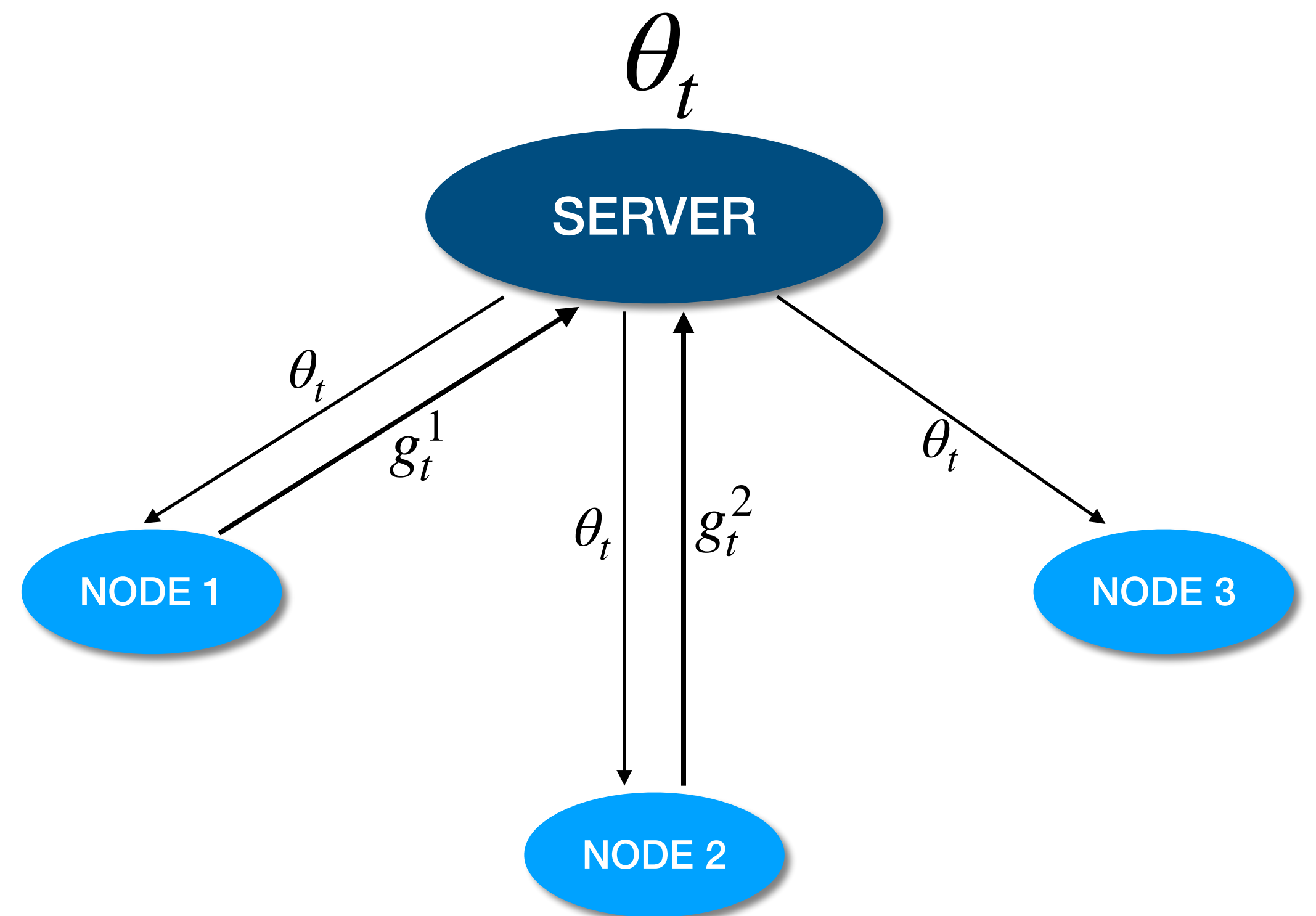
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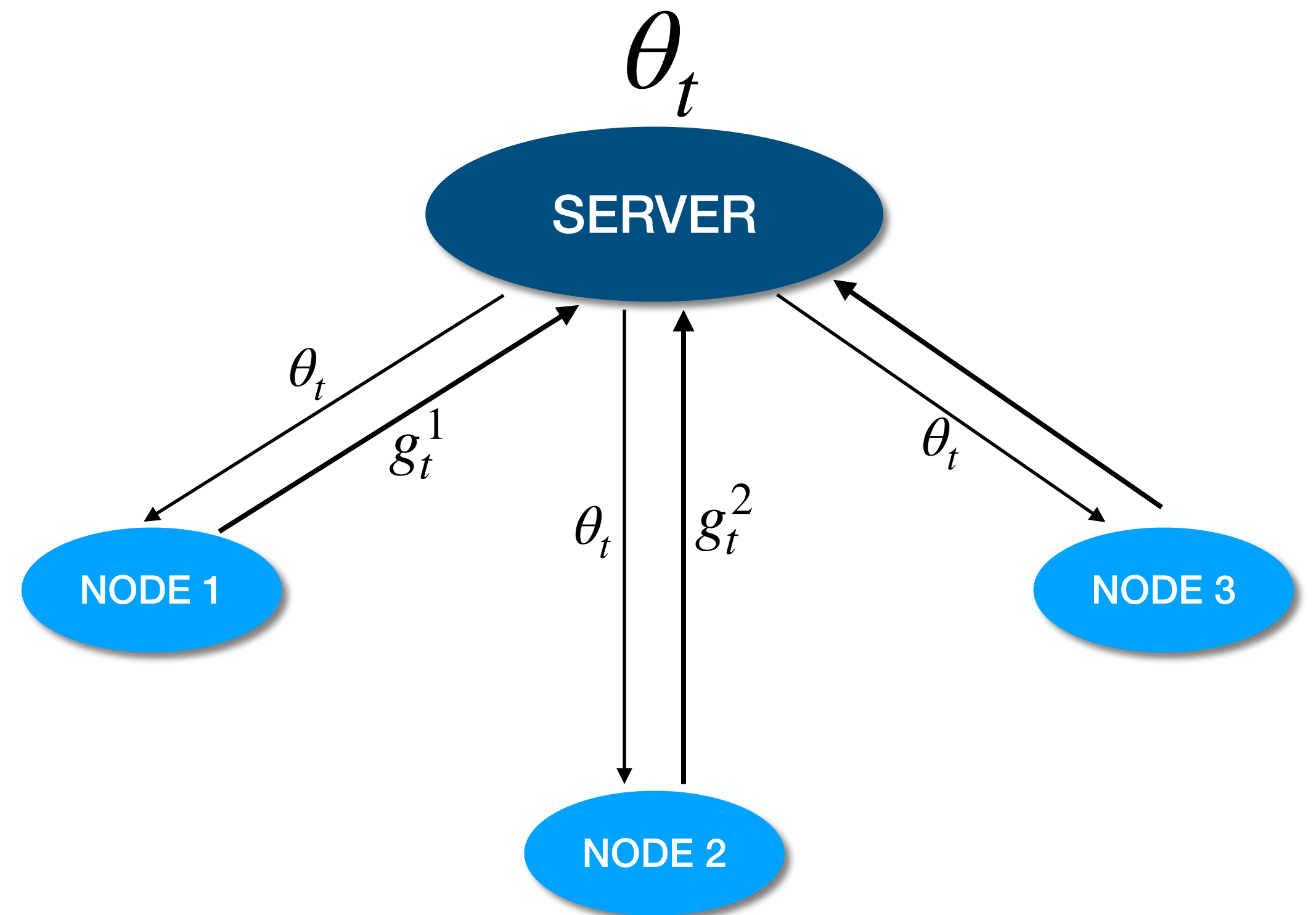
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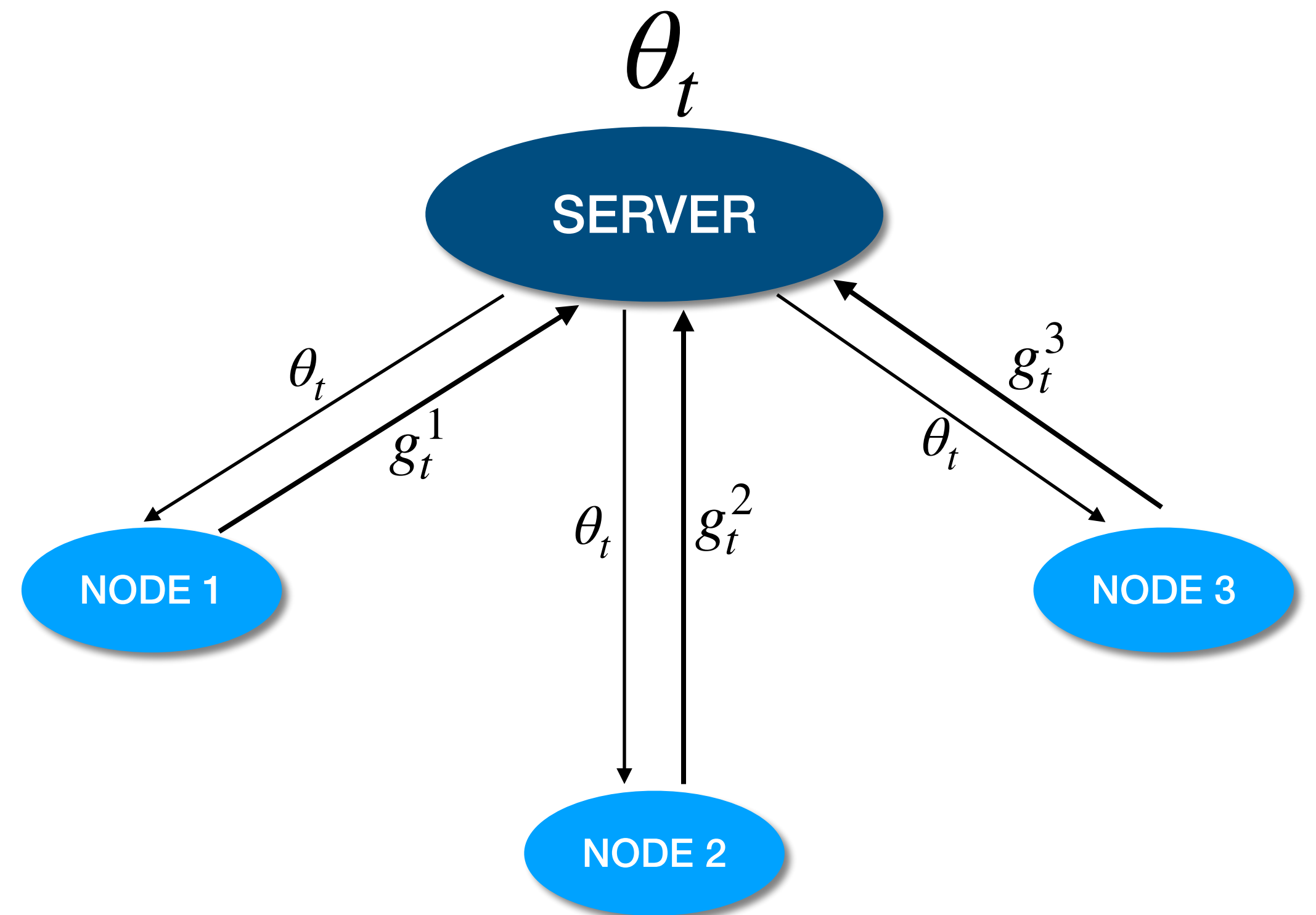
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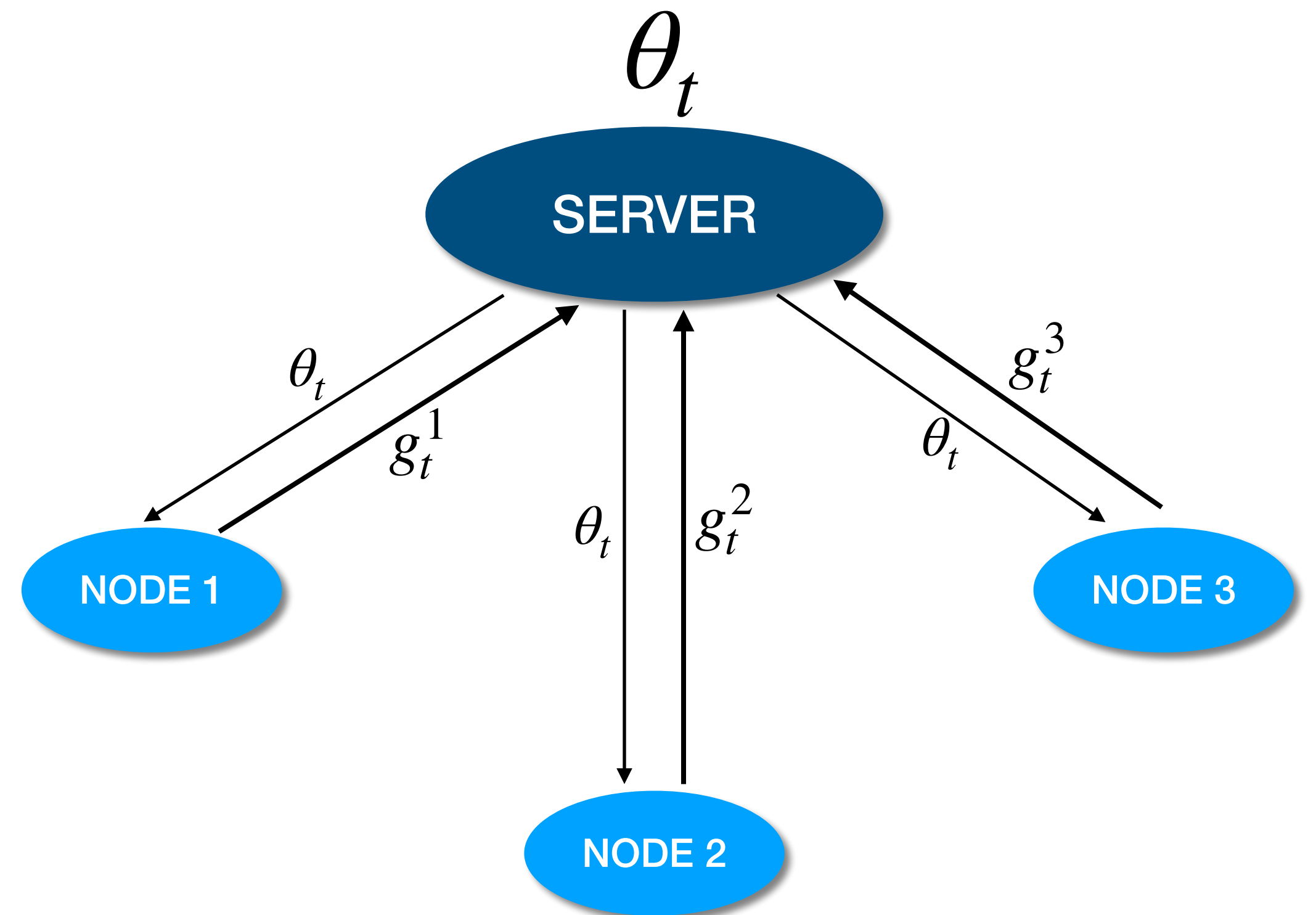
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True gradient

Server averages the gradients, $\hat{g}_t = \frac{1}{n} \sum_i g_t^i$



Distributed SGD

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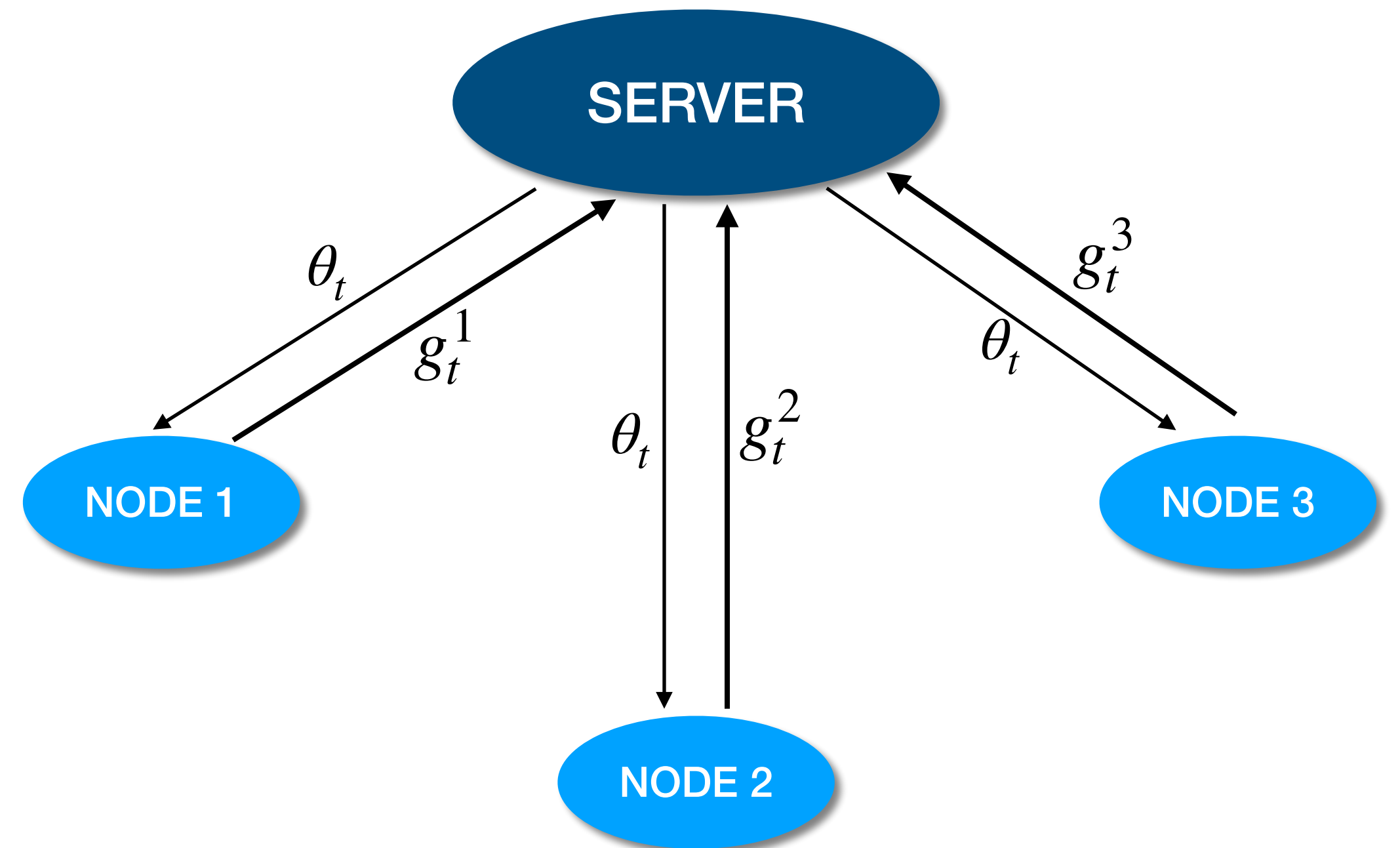
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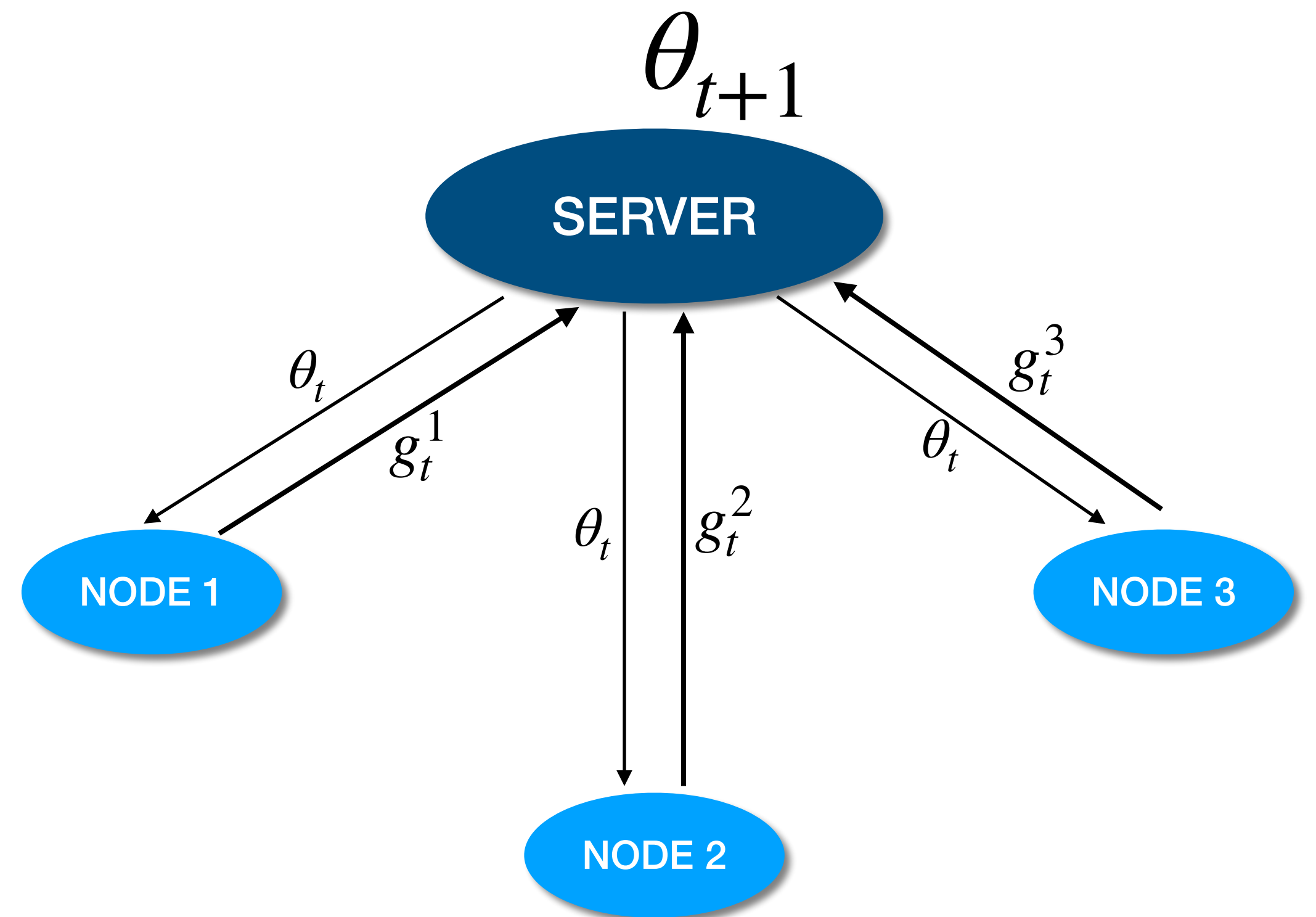
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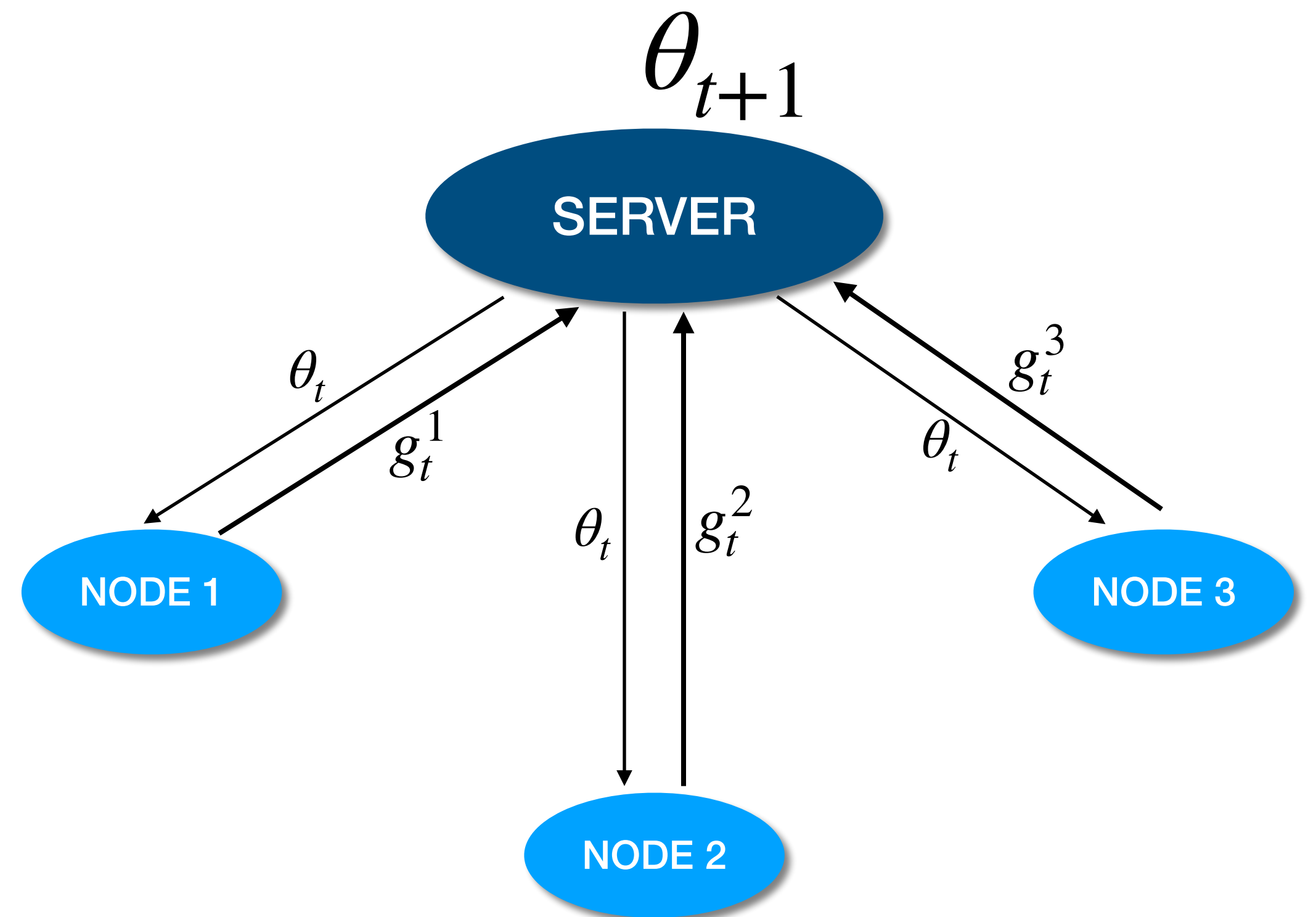
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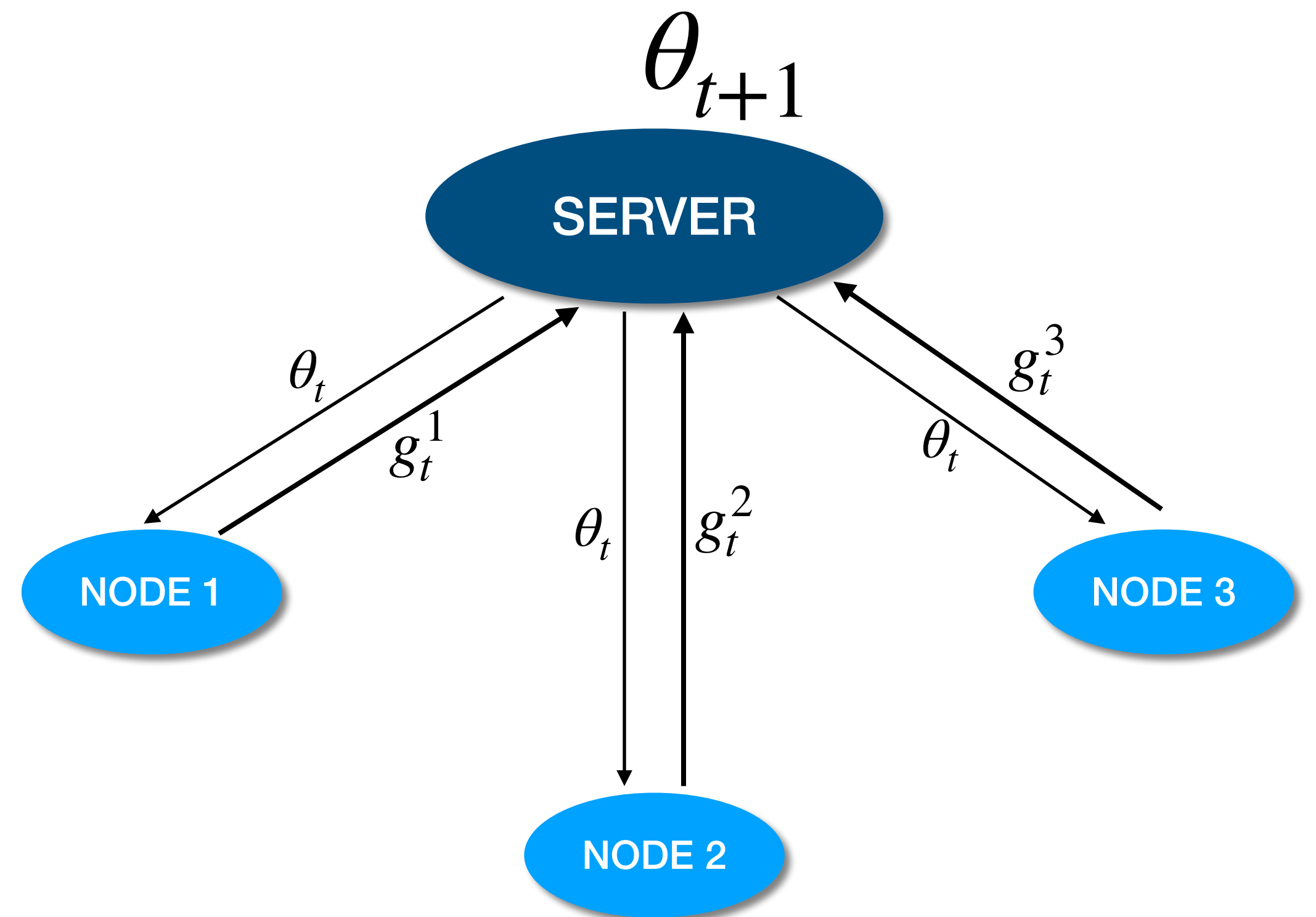
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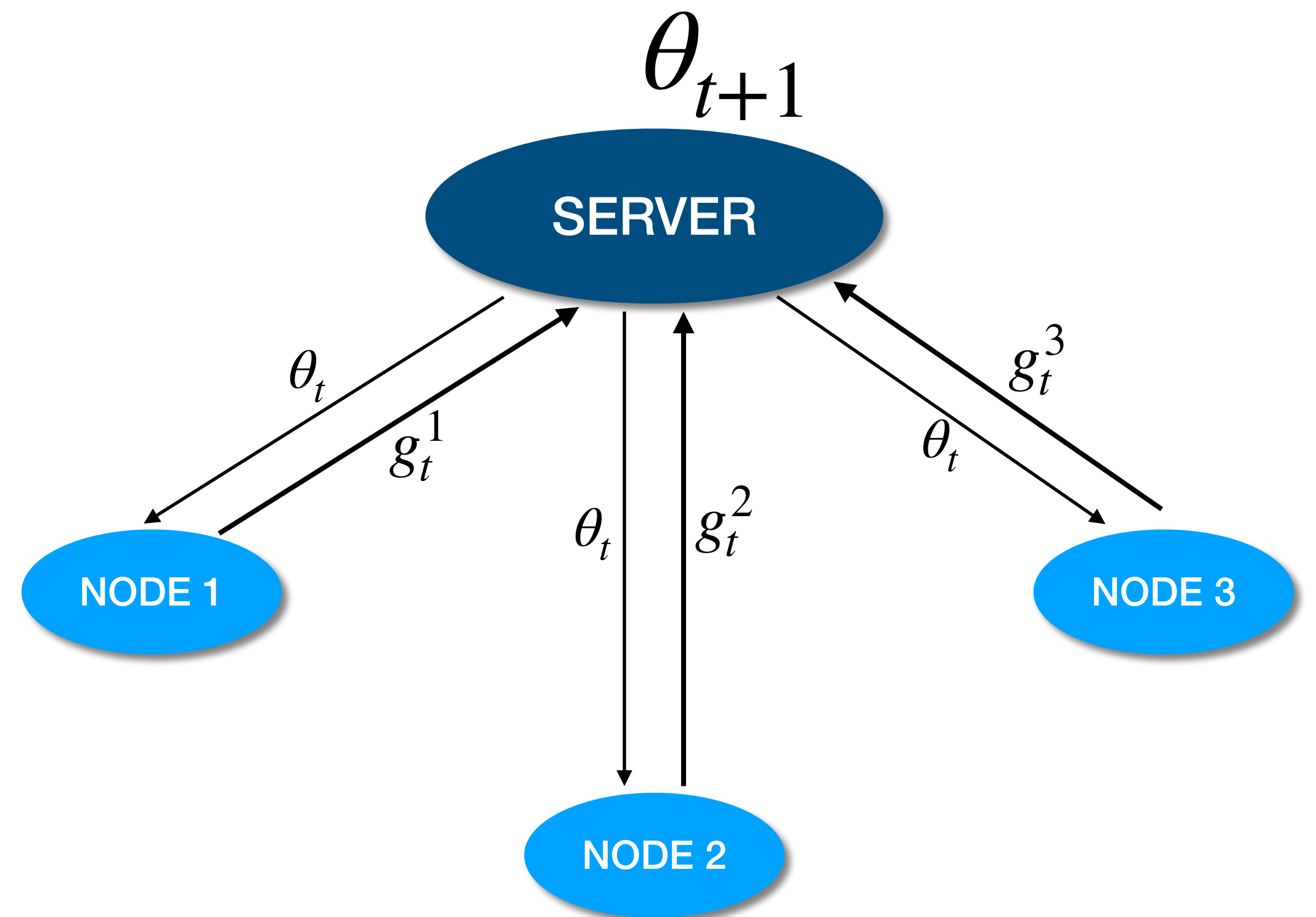
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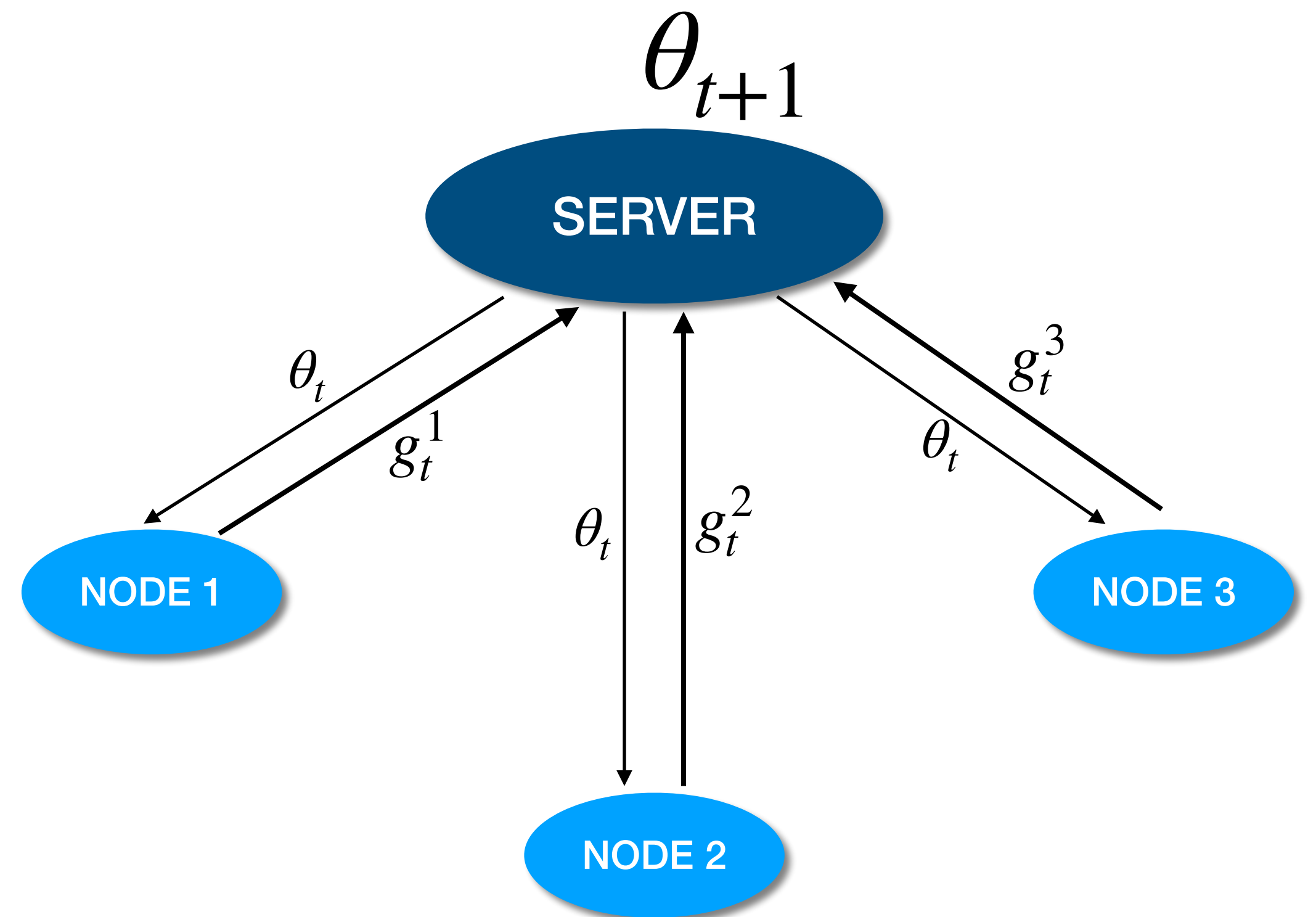
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Learning rate

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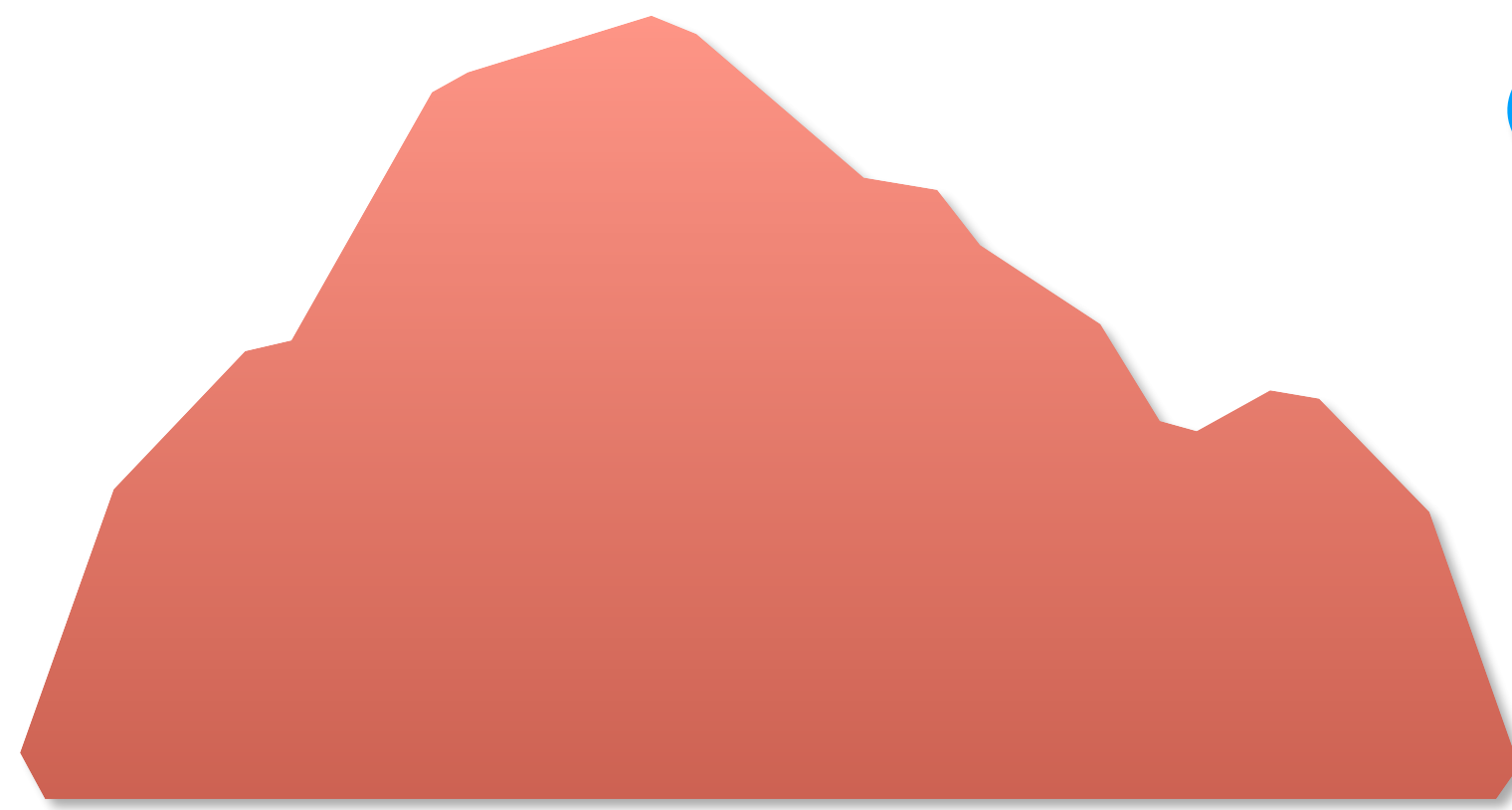
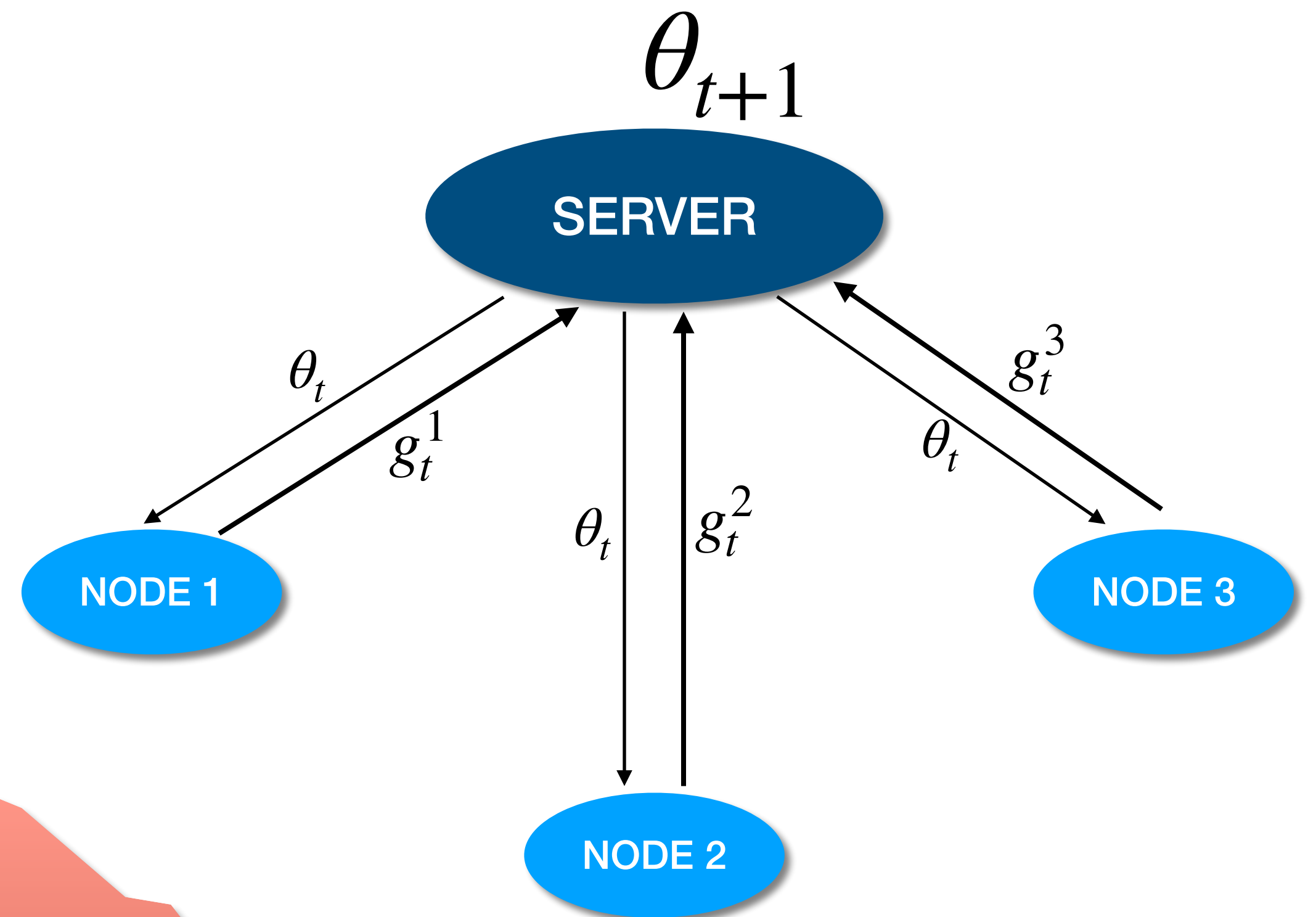
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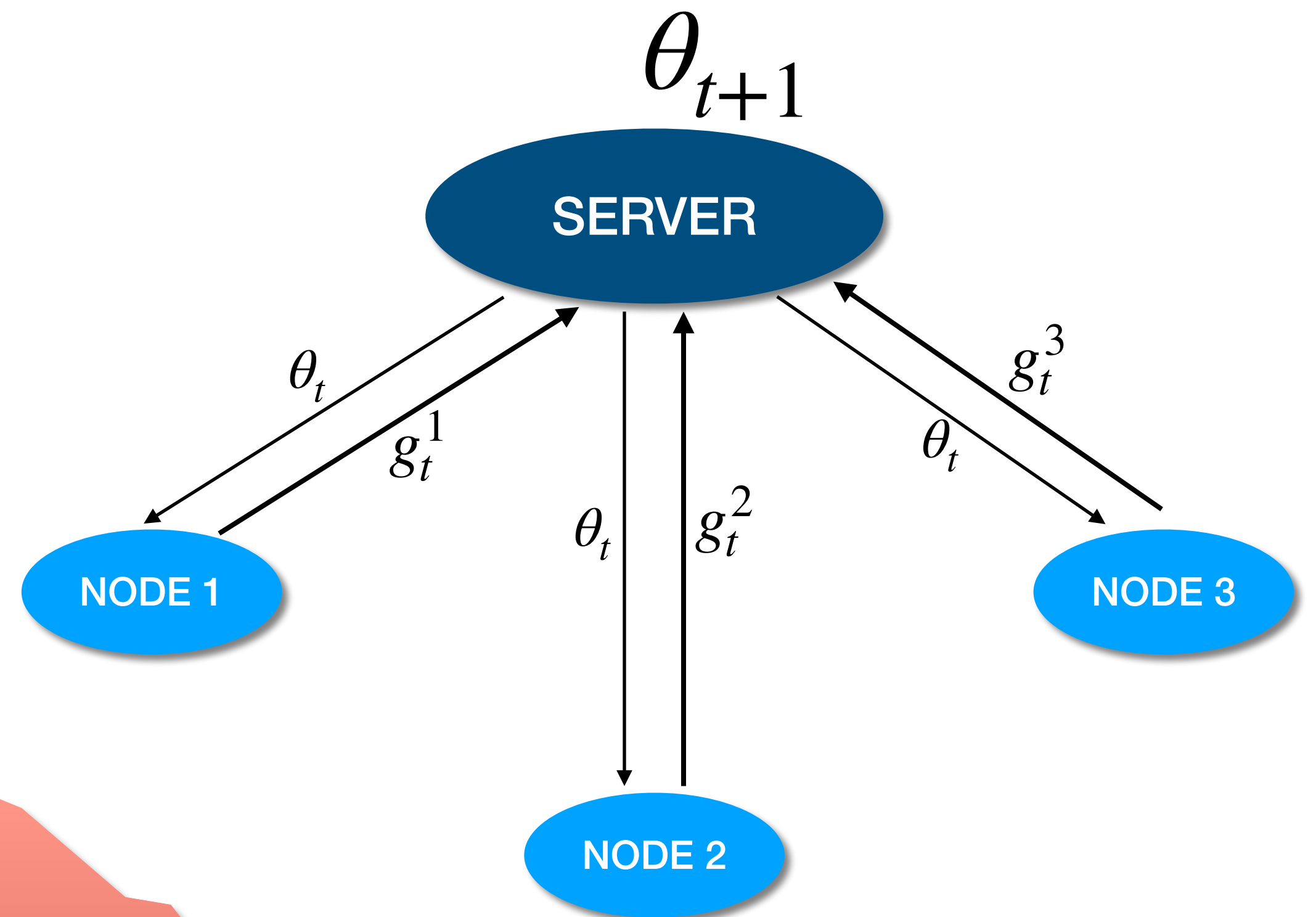
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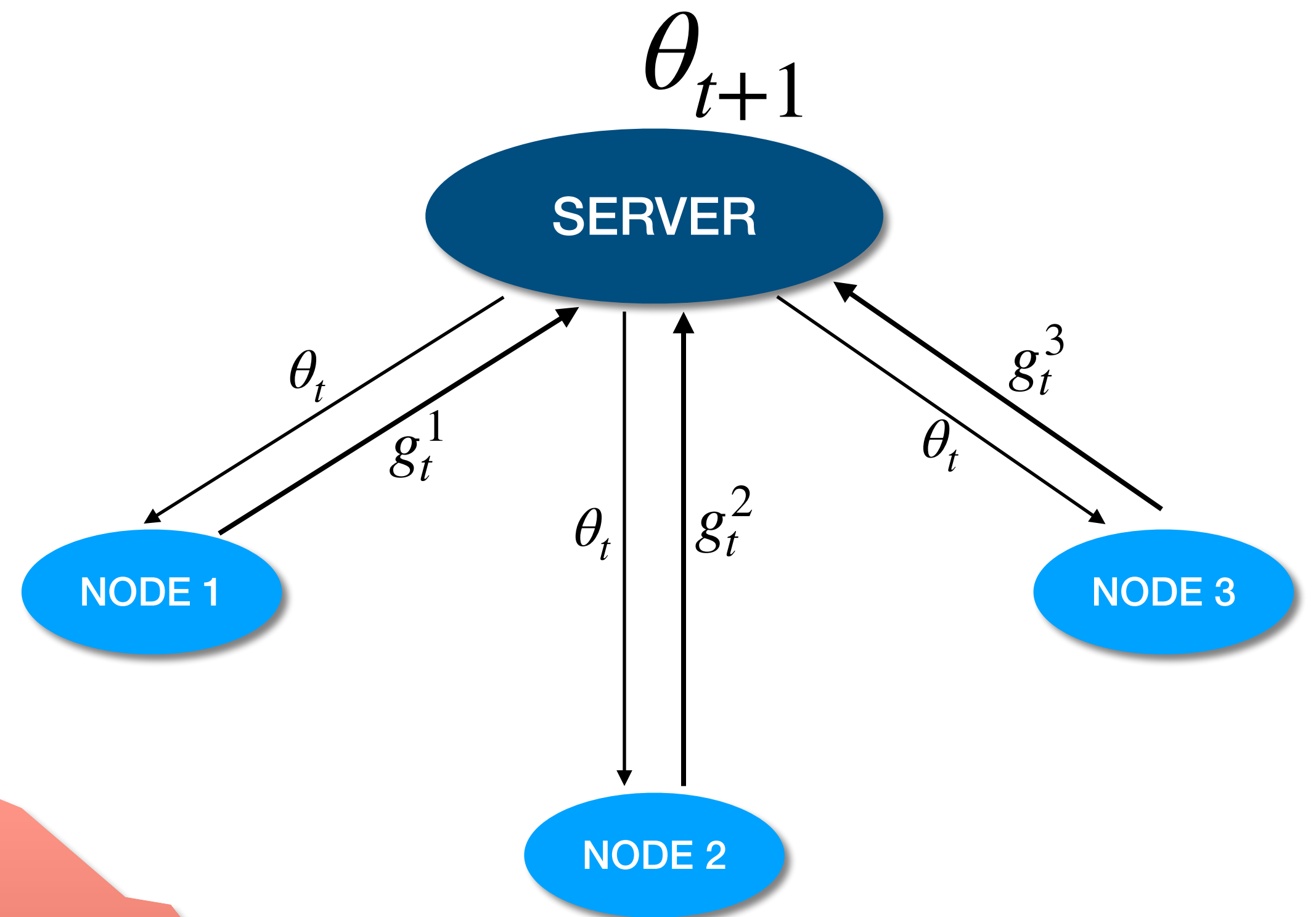
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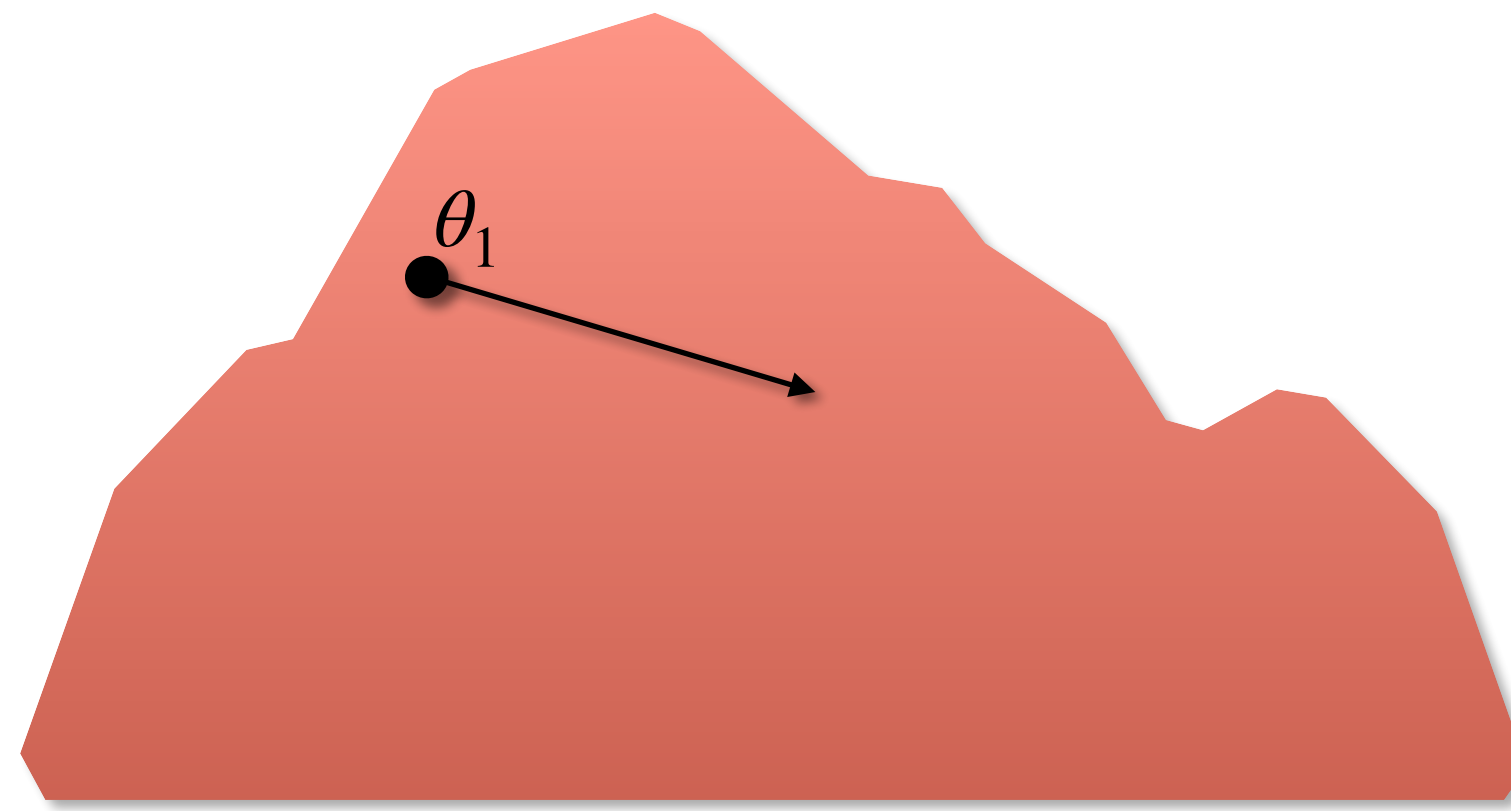
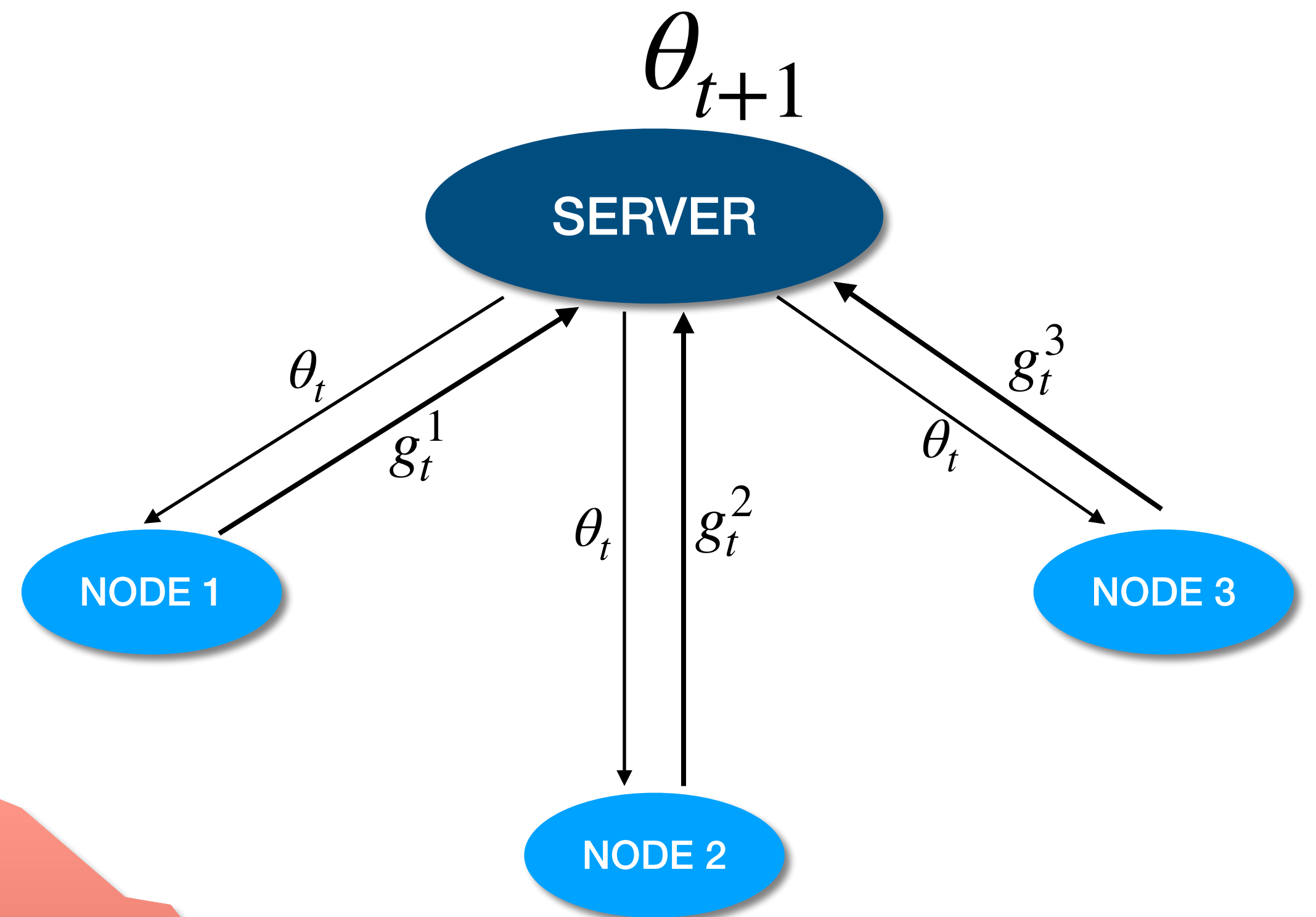
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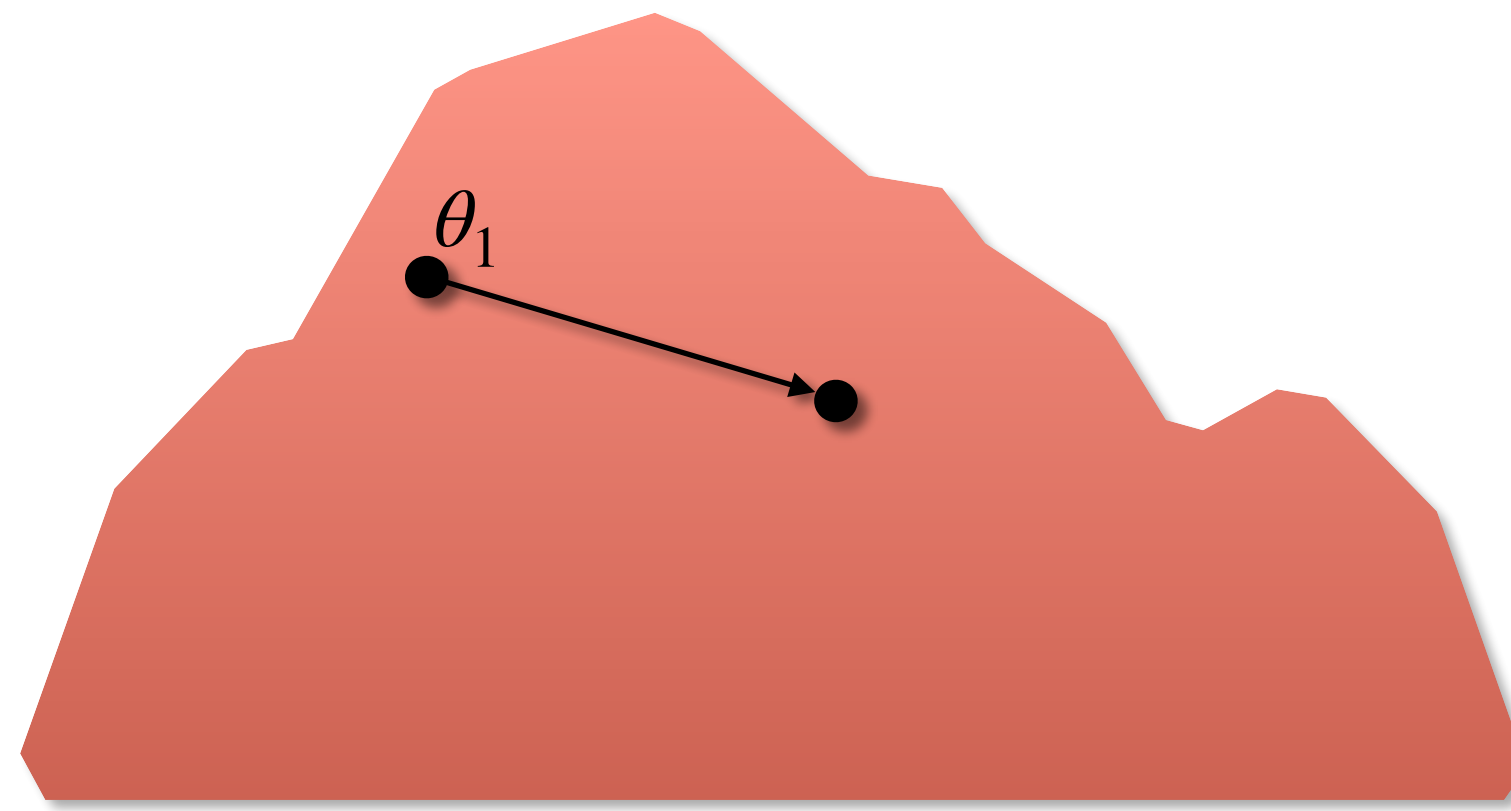
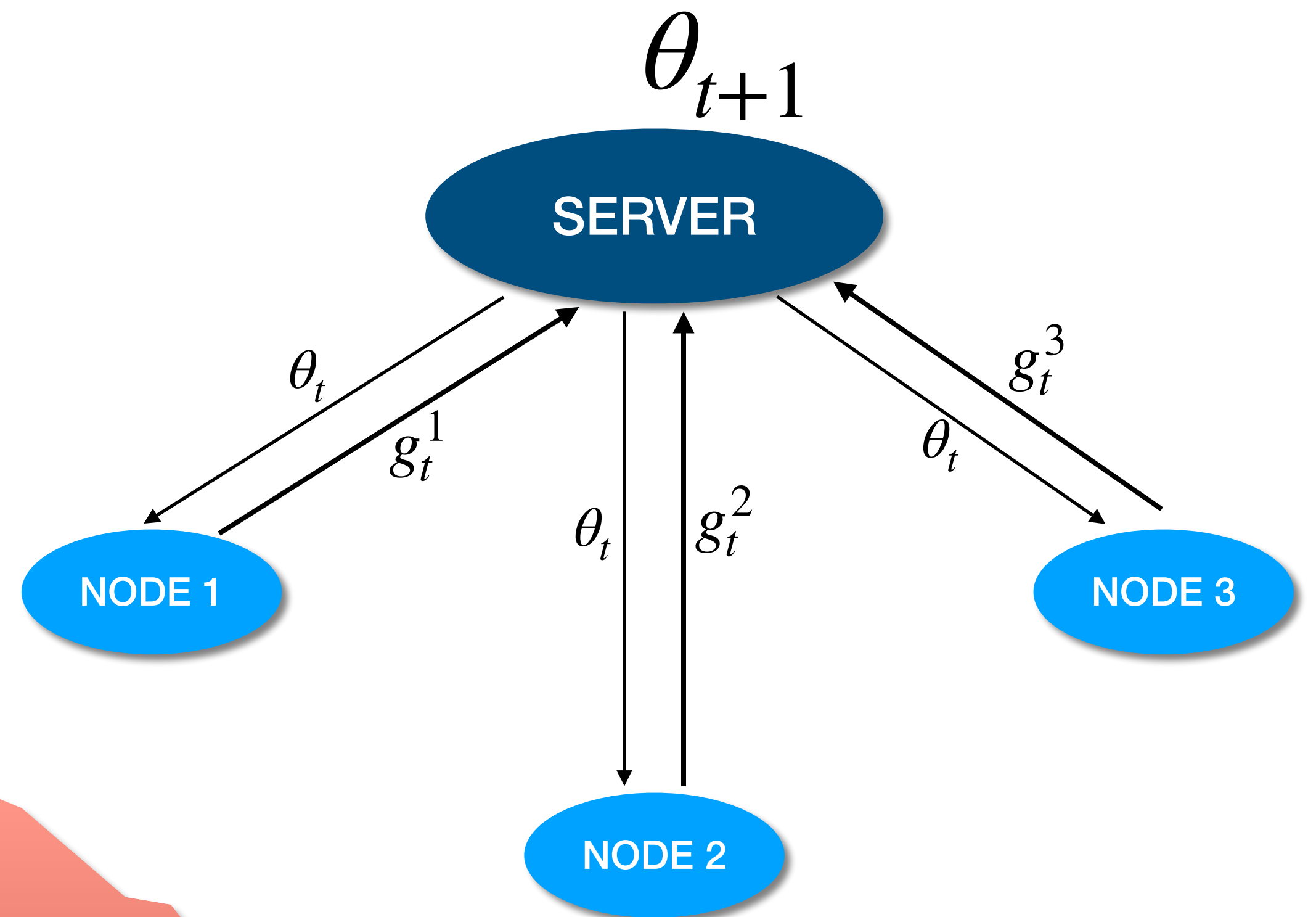
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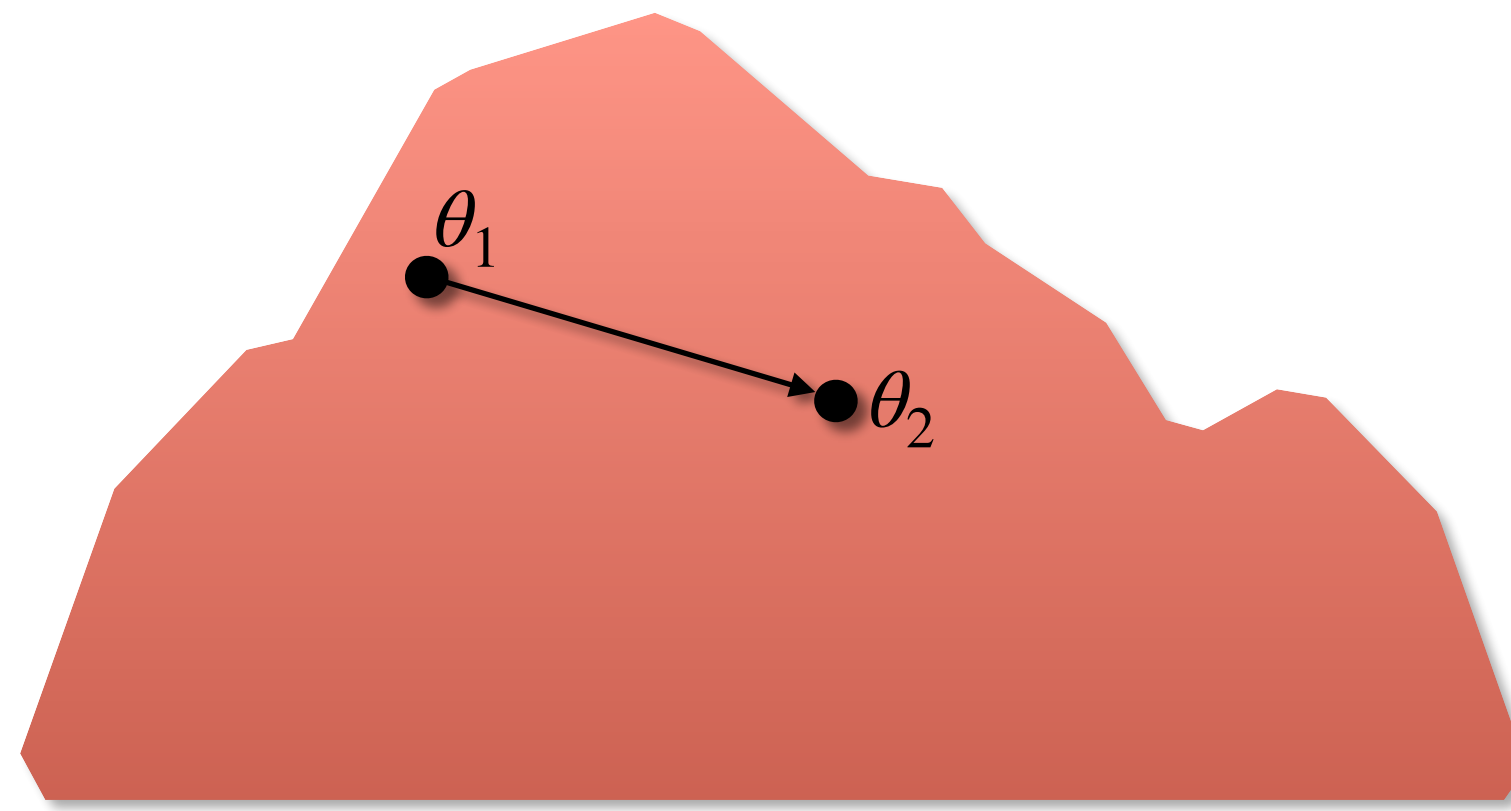
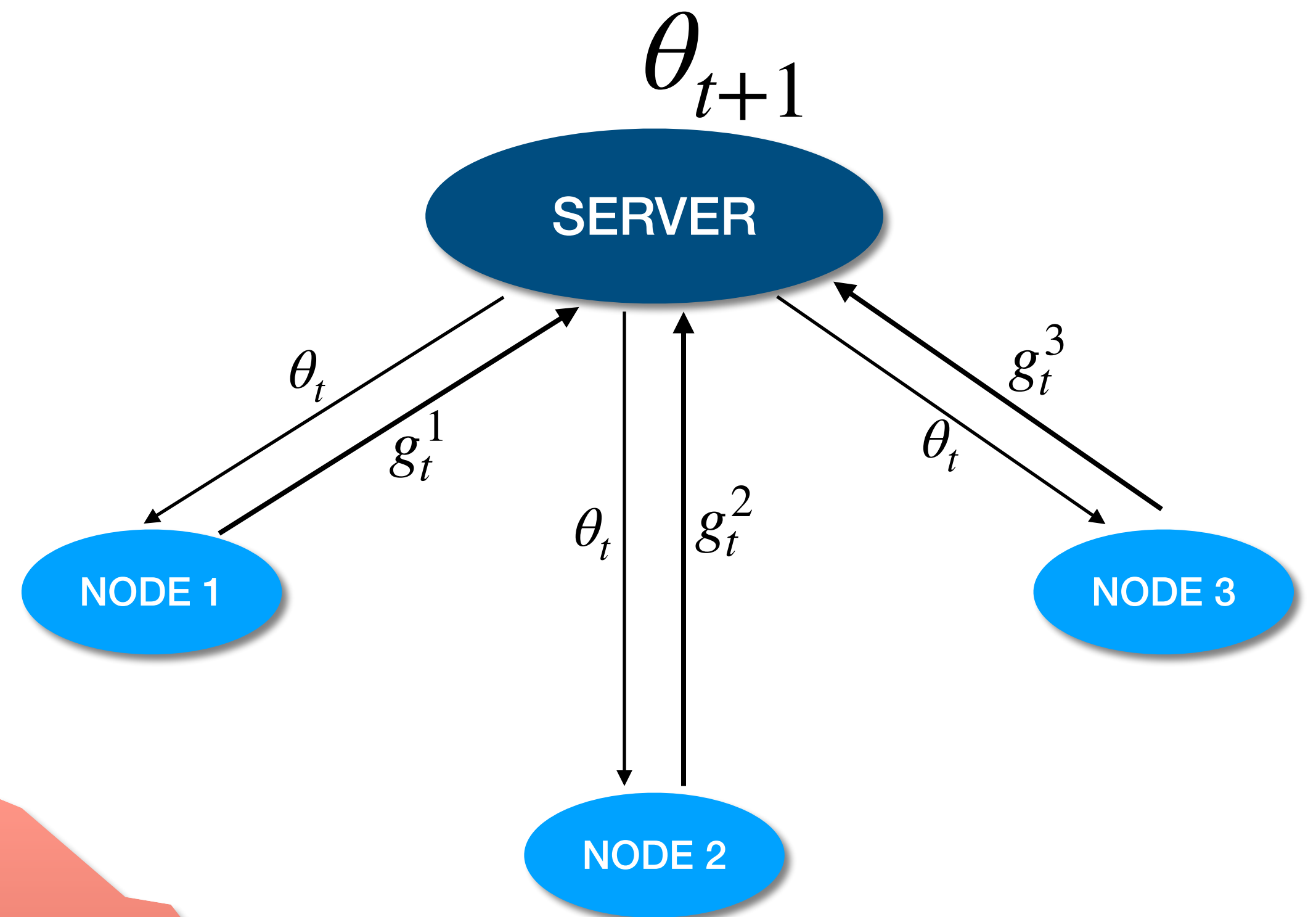
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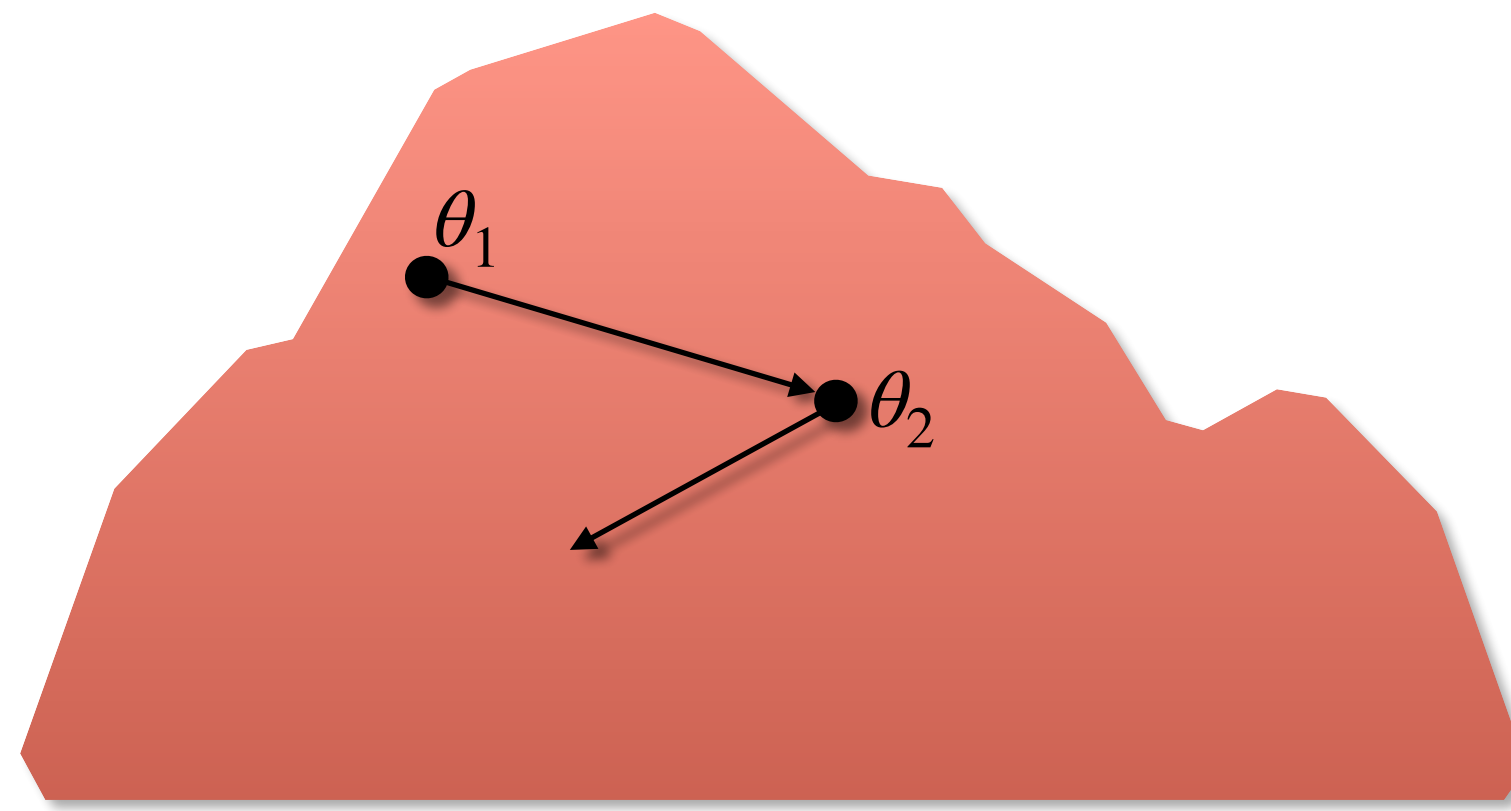
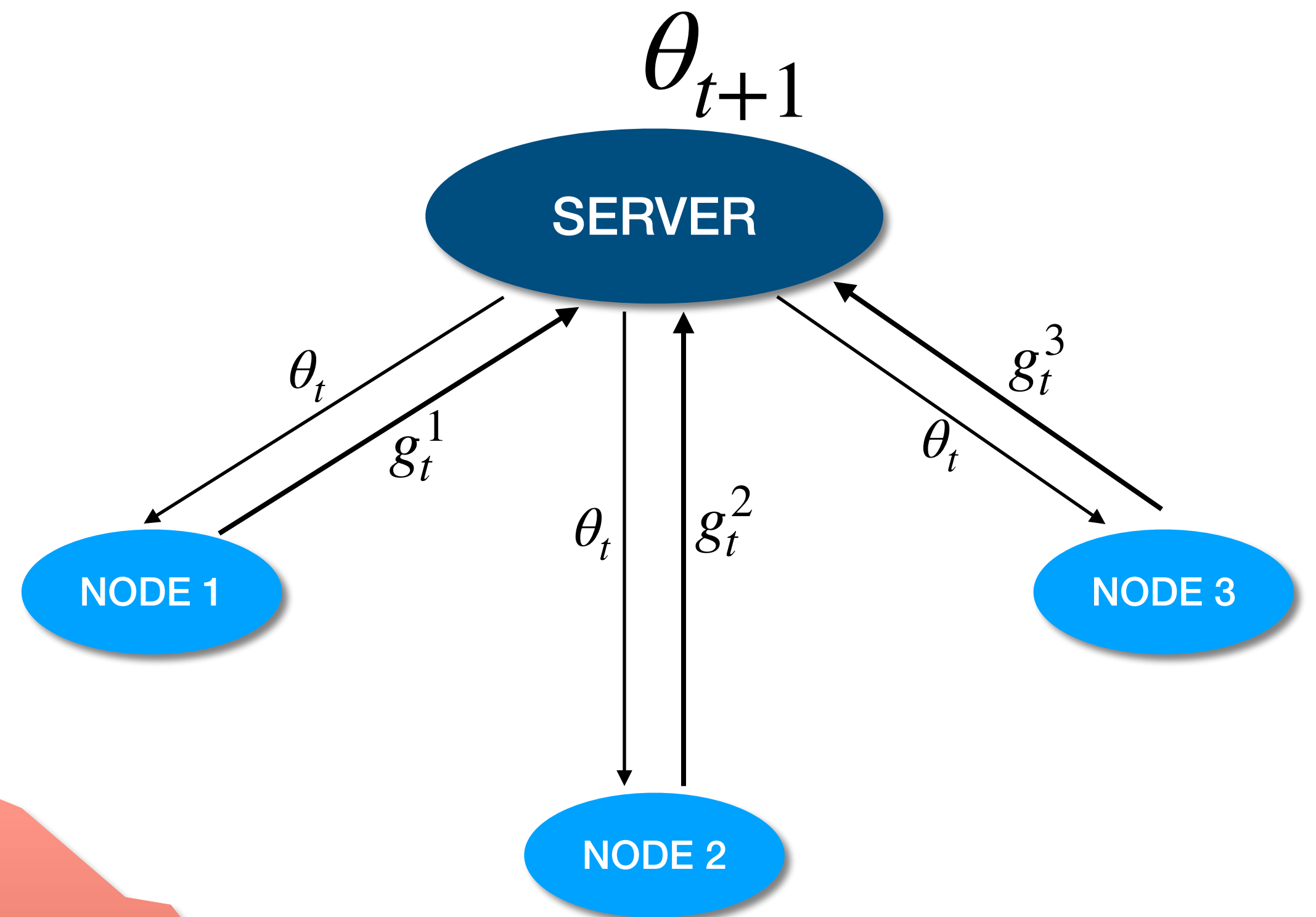
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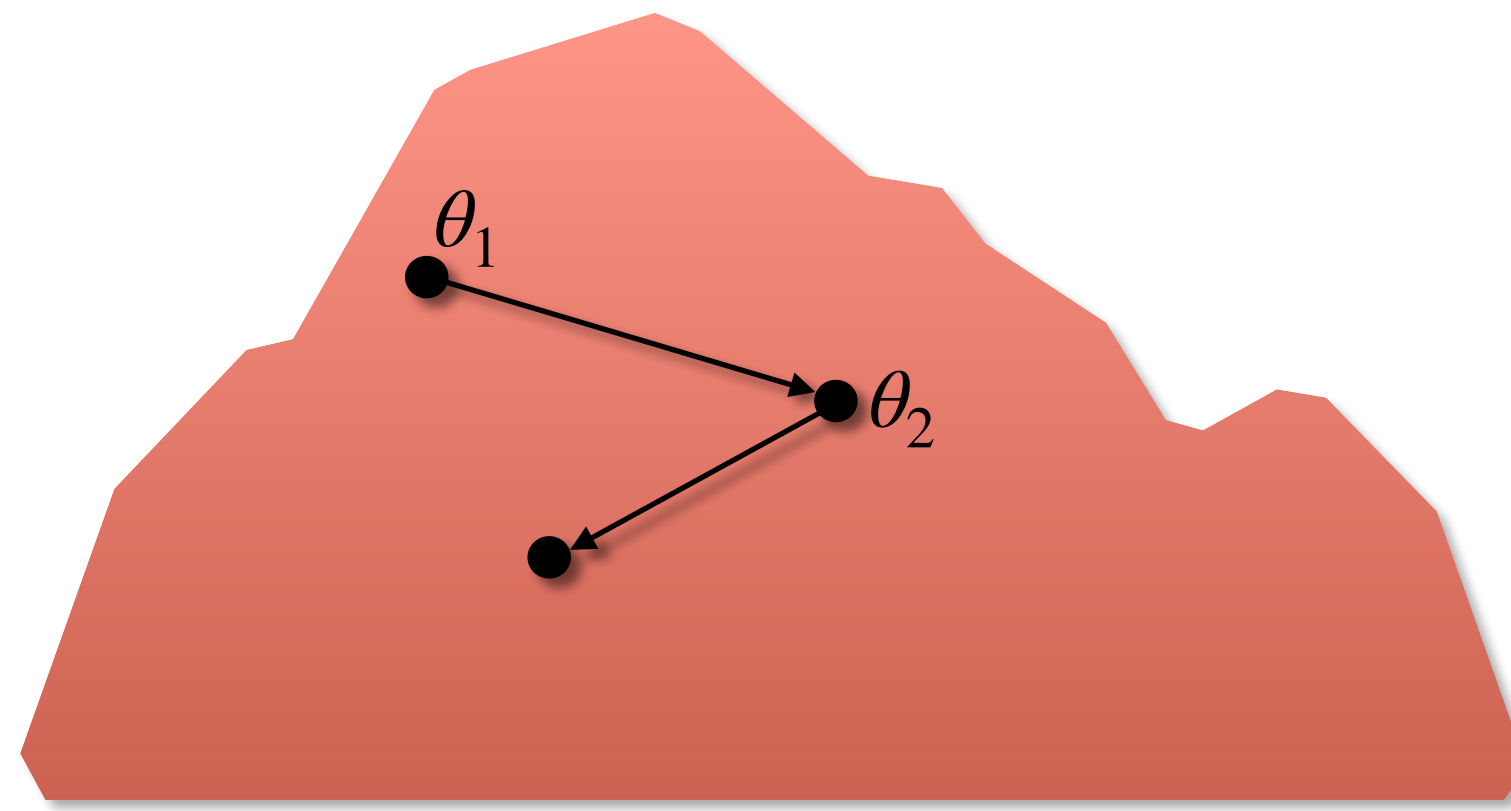
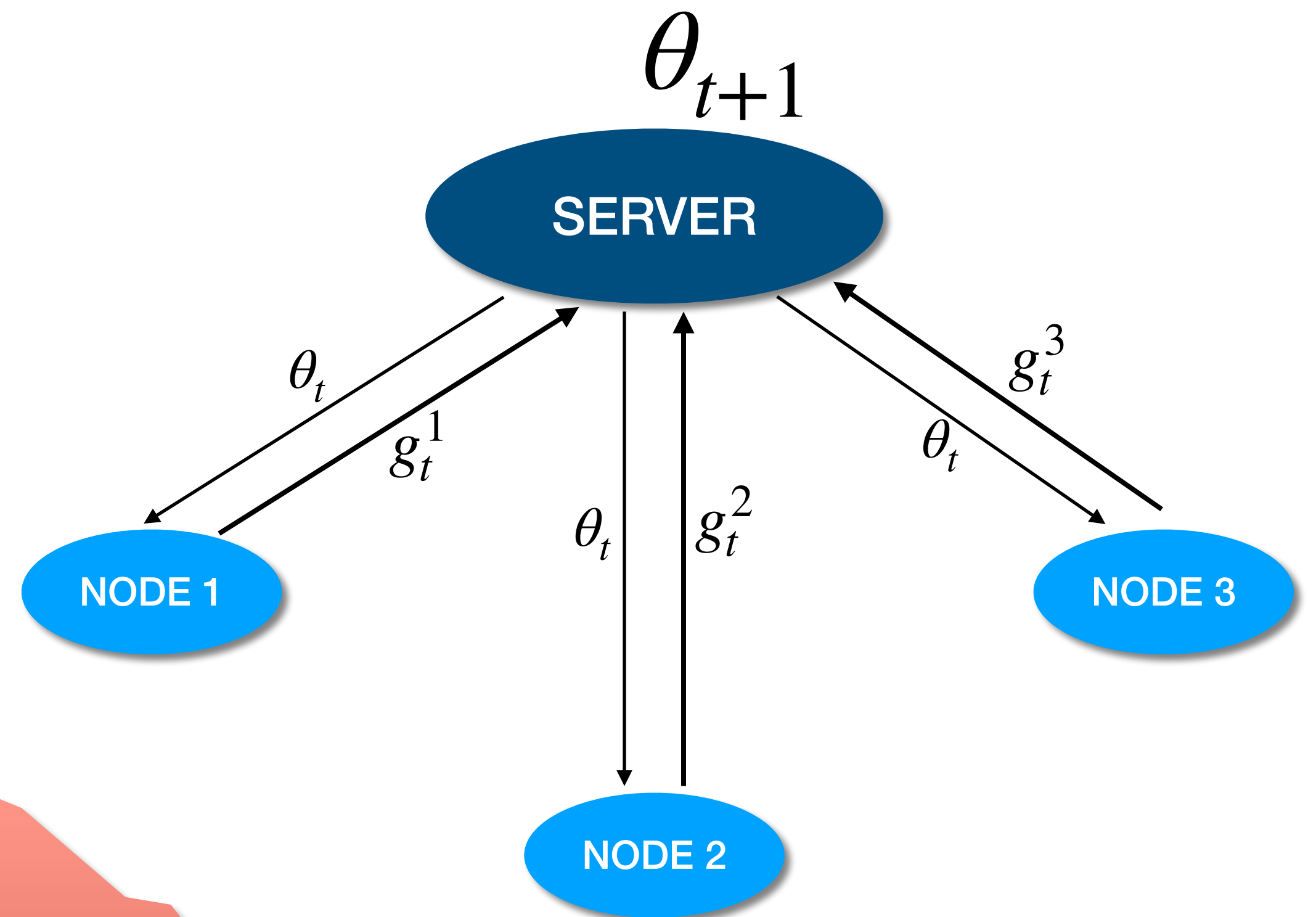
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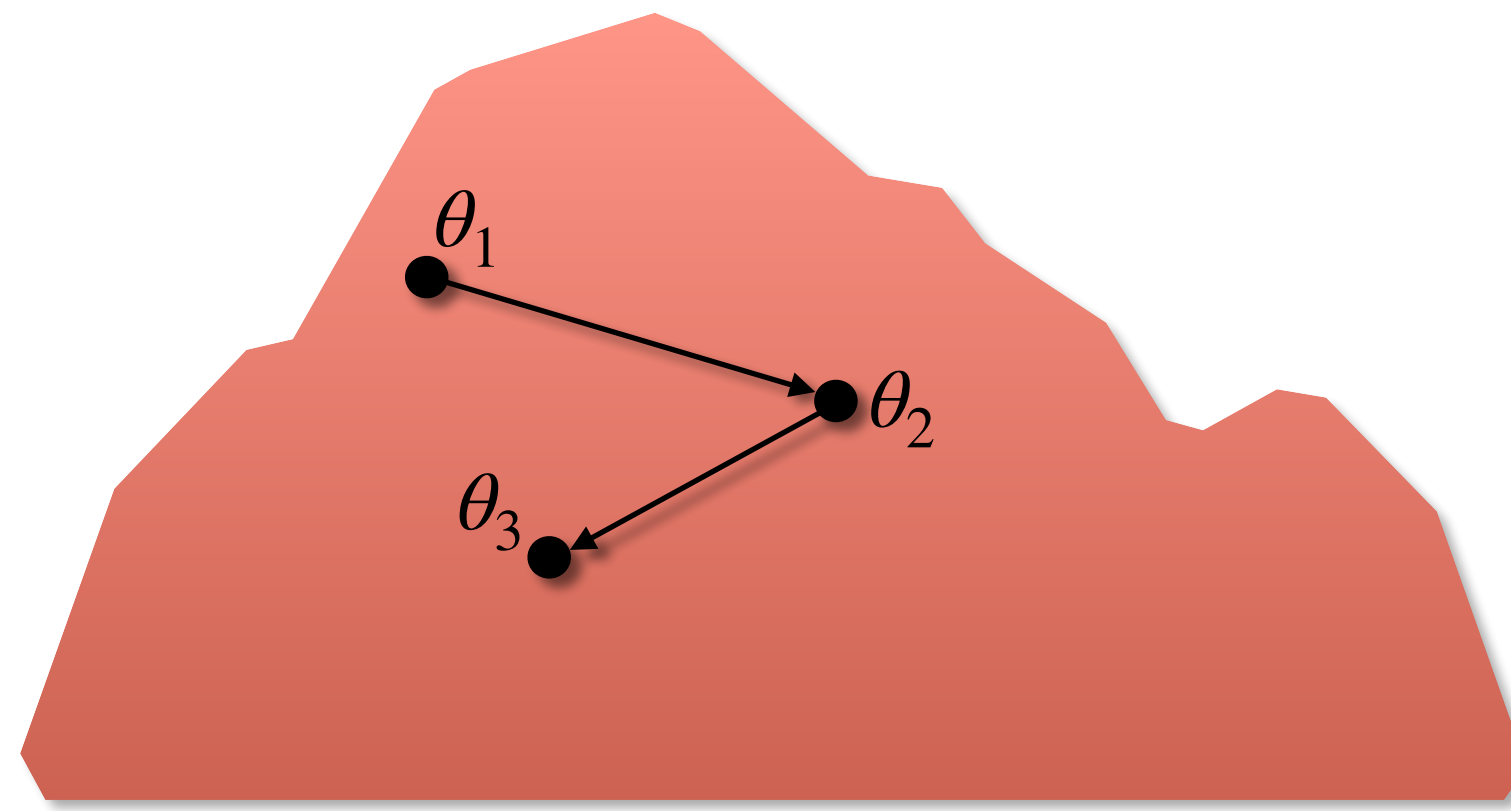
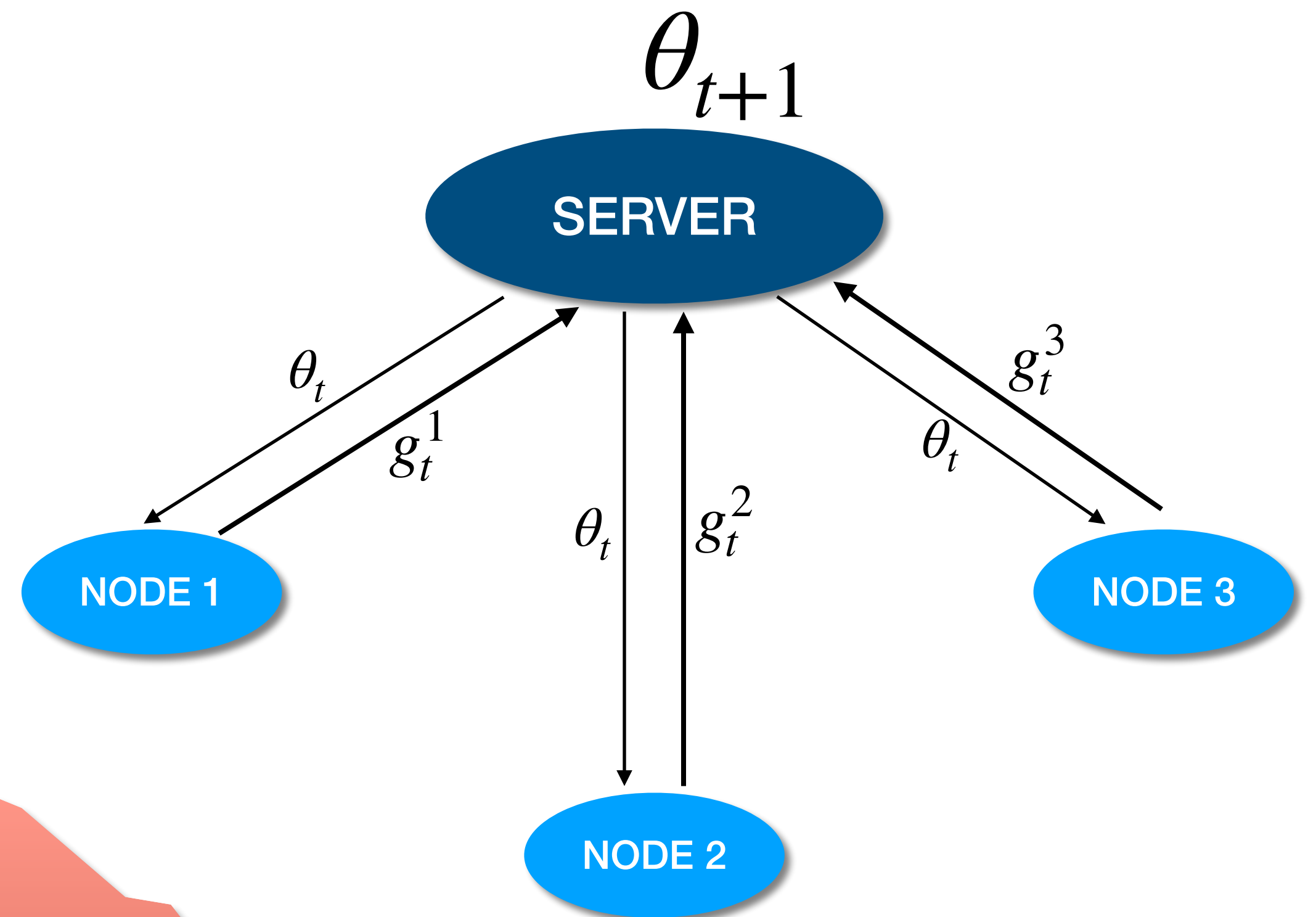
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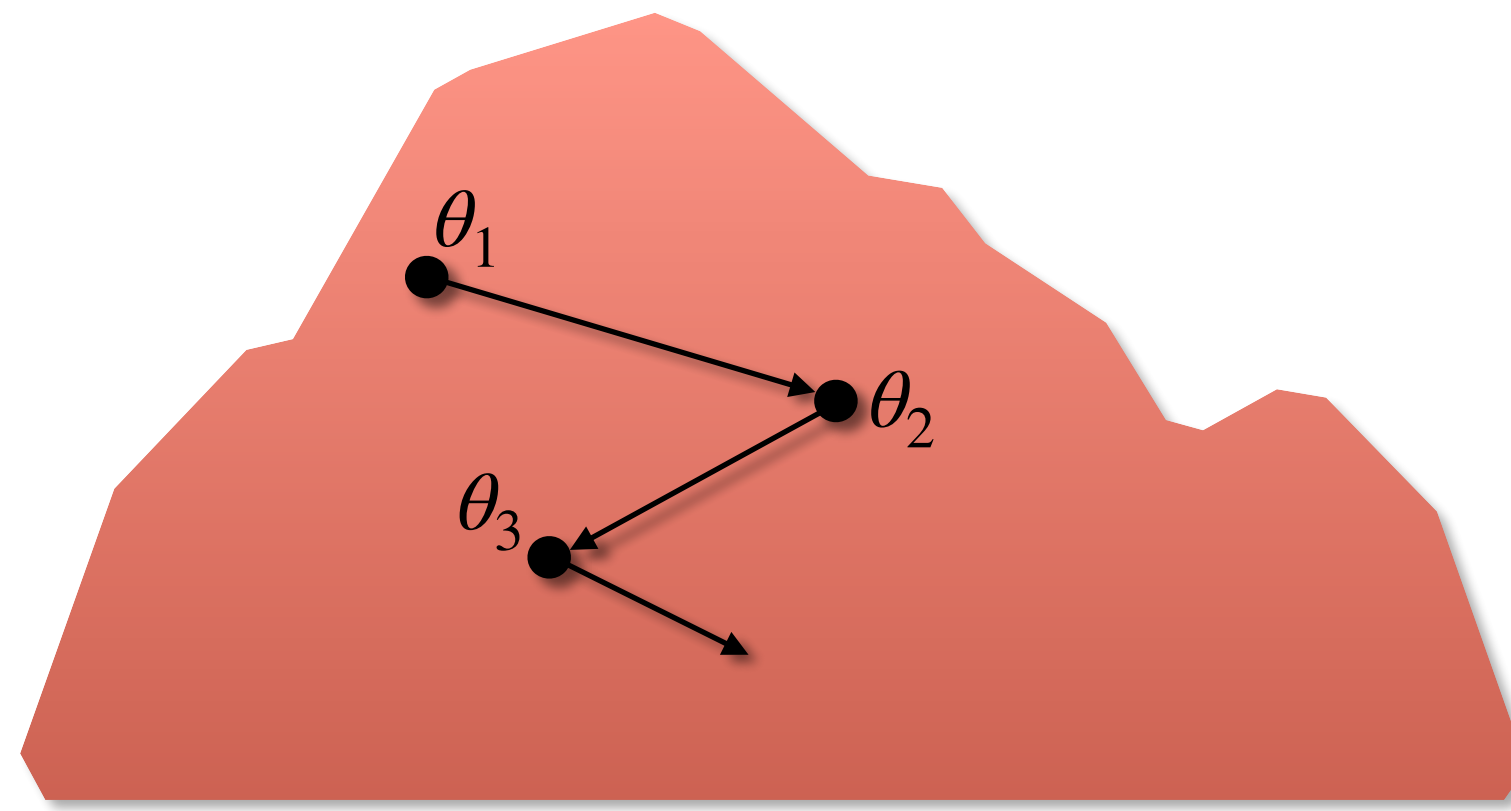
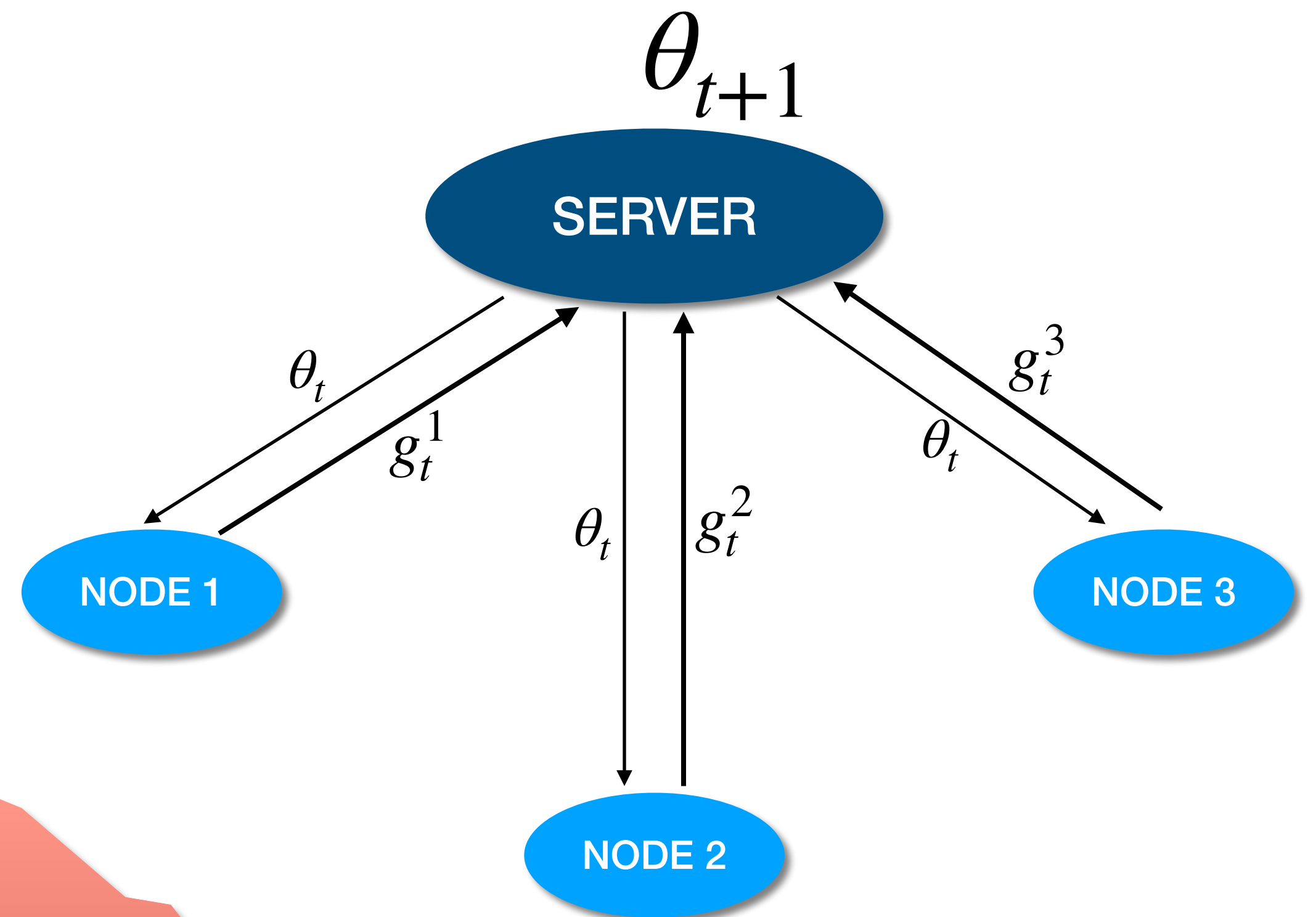
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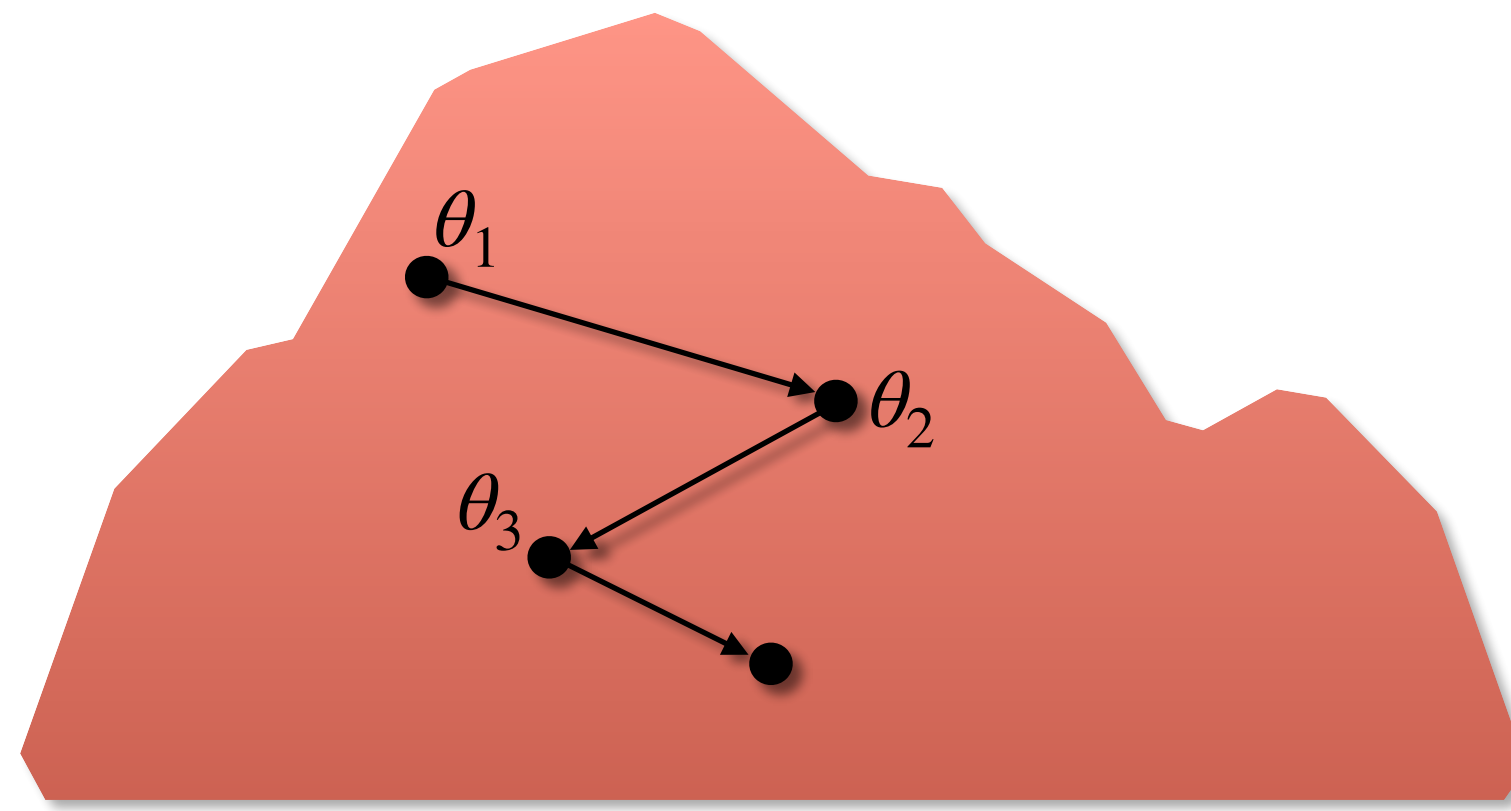
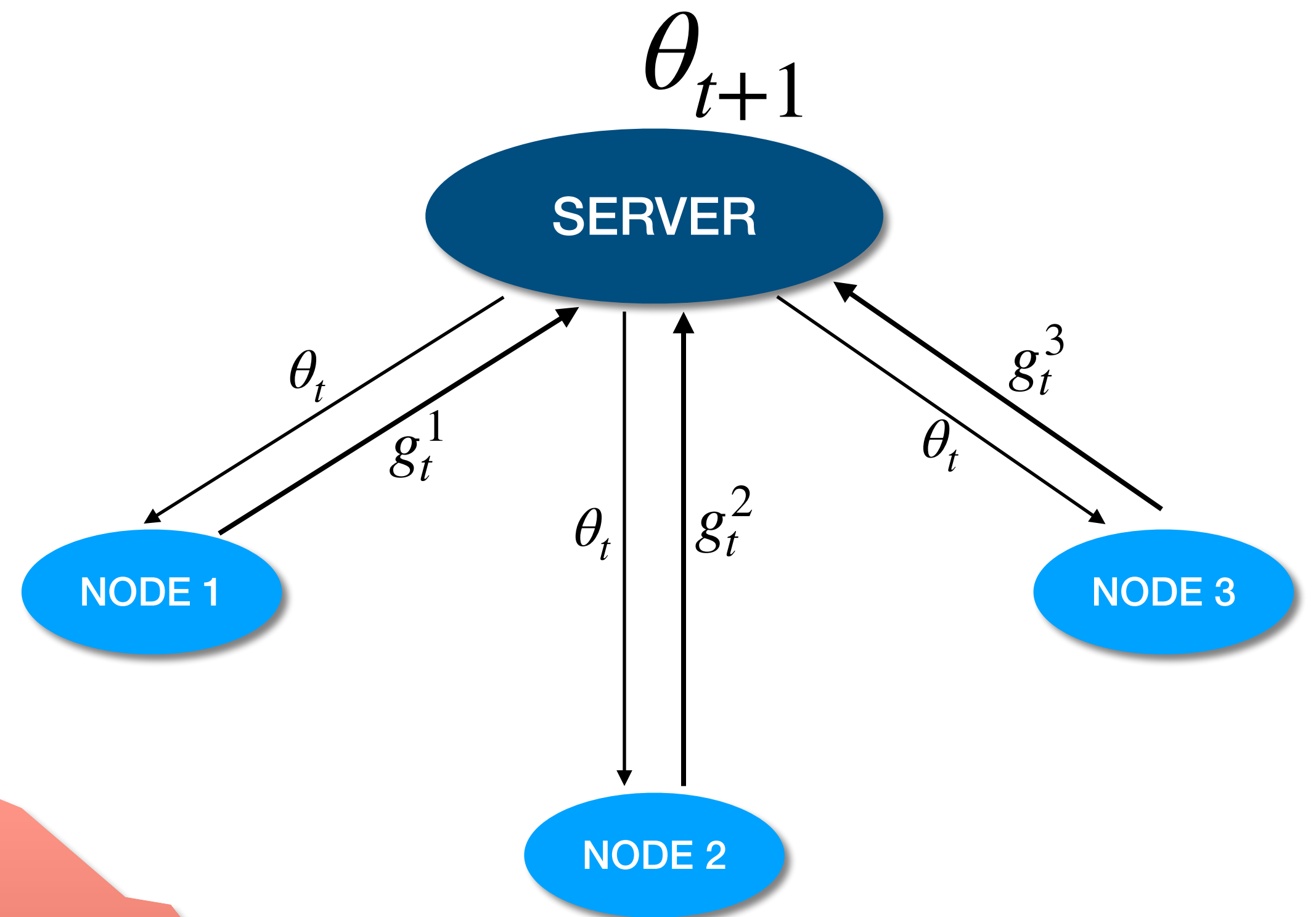
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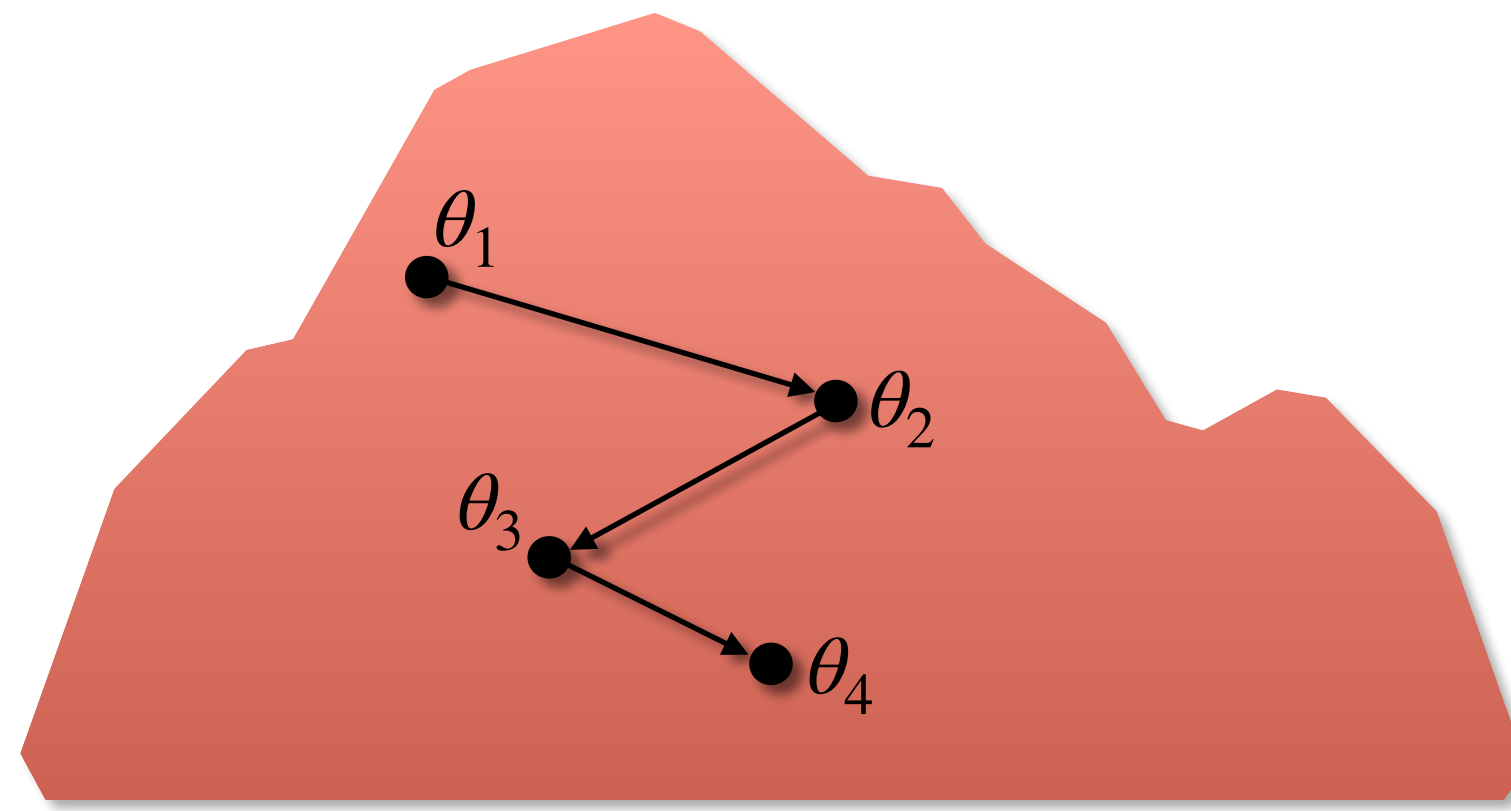
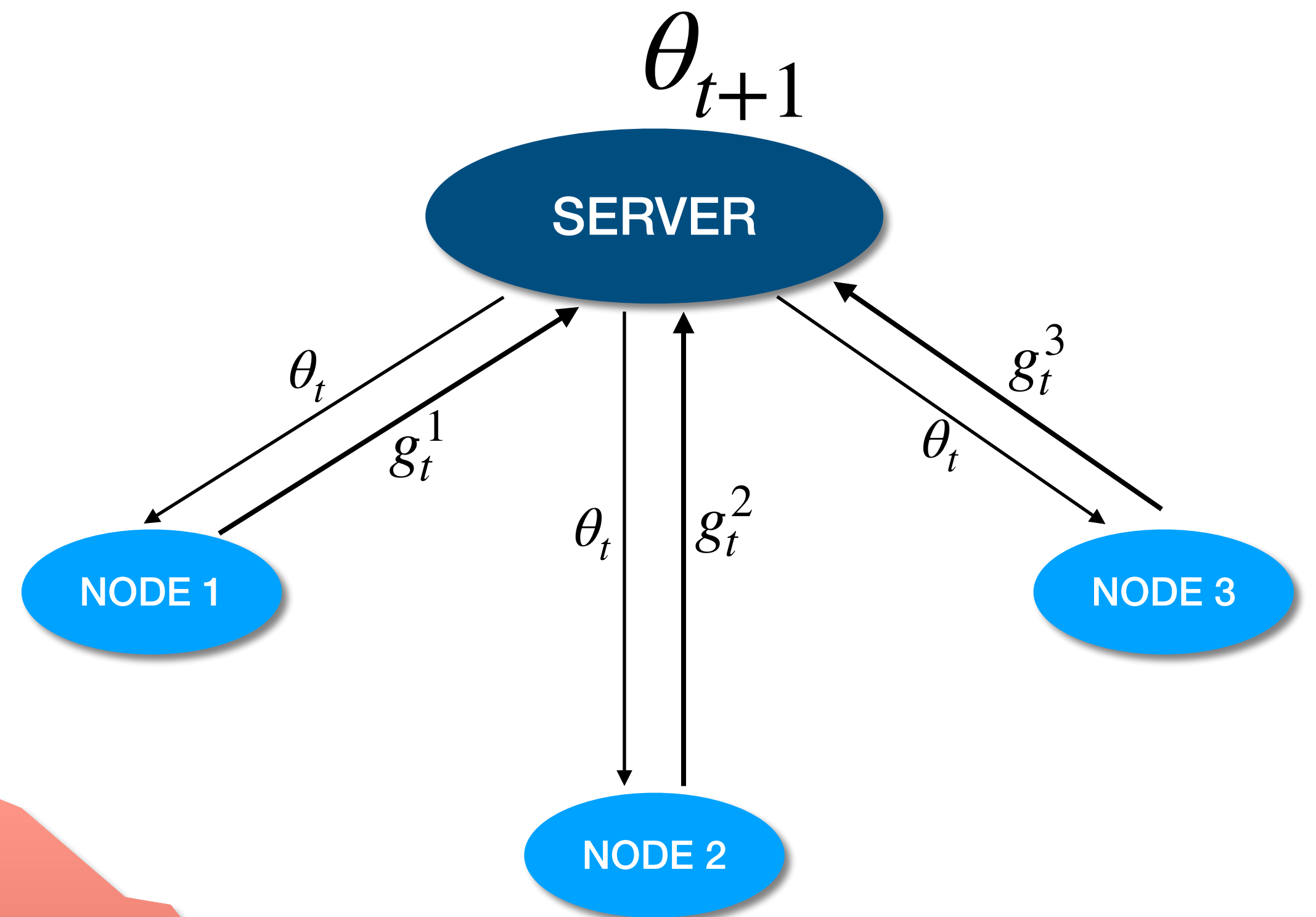
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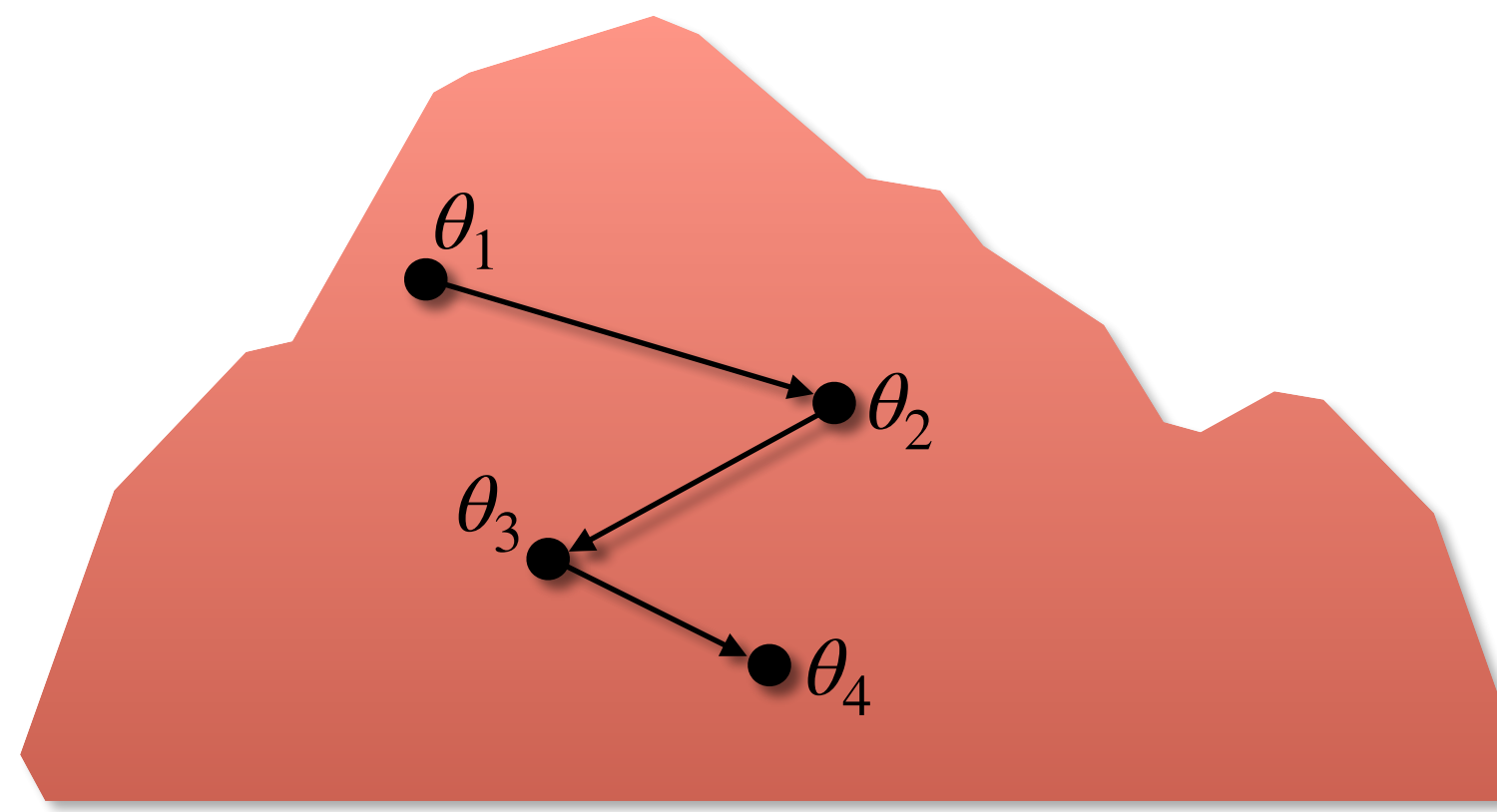
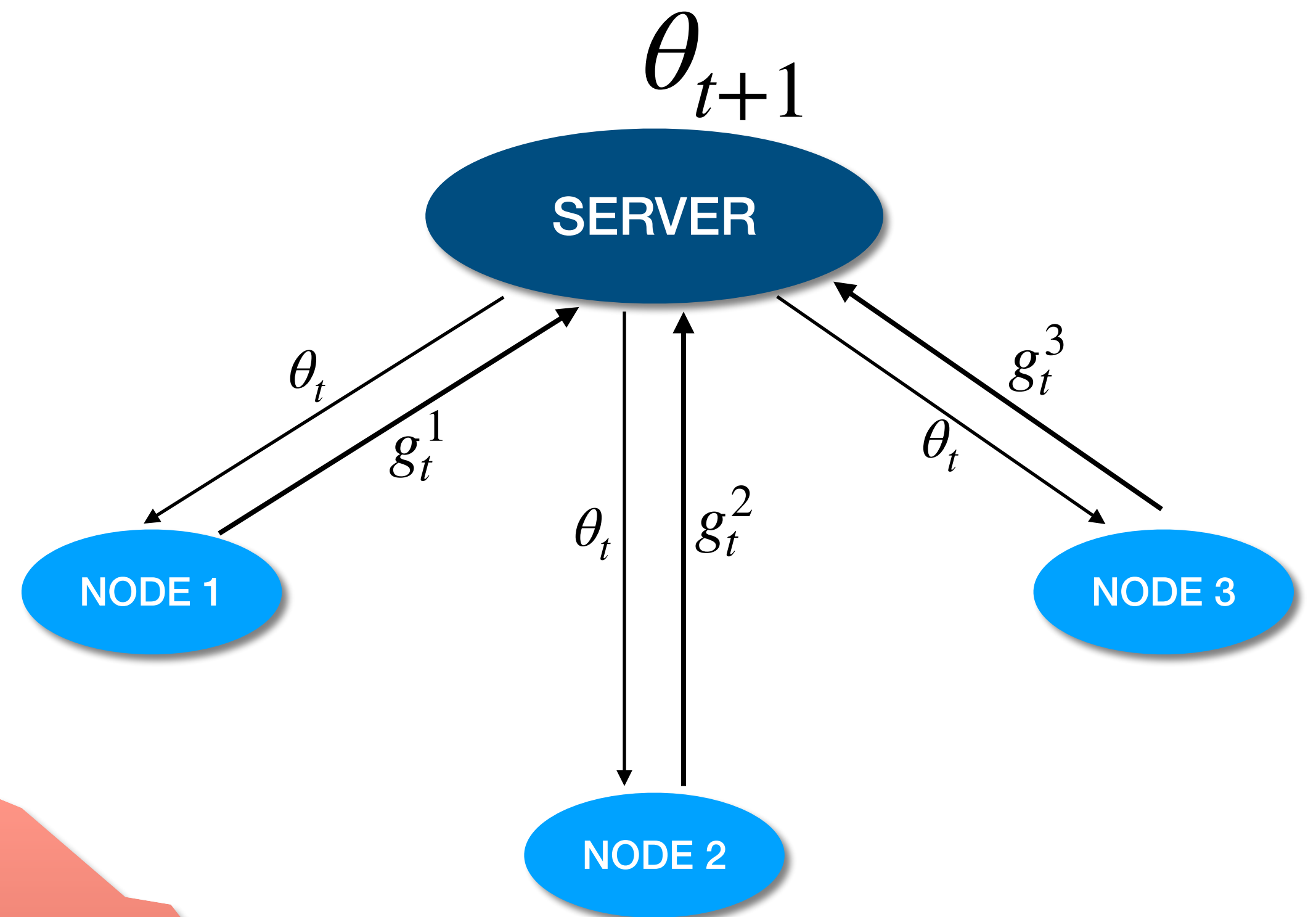
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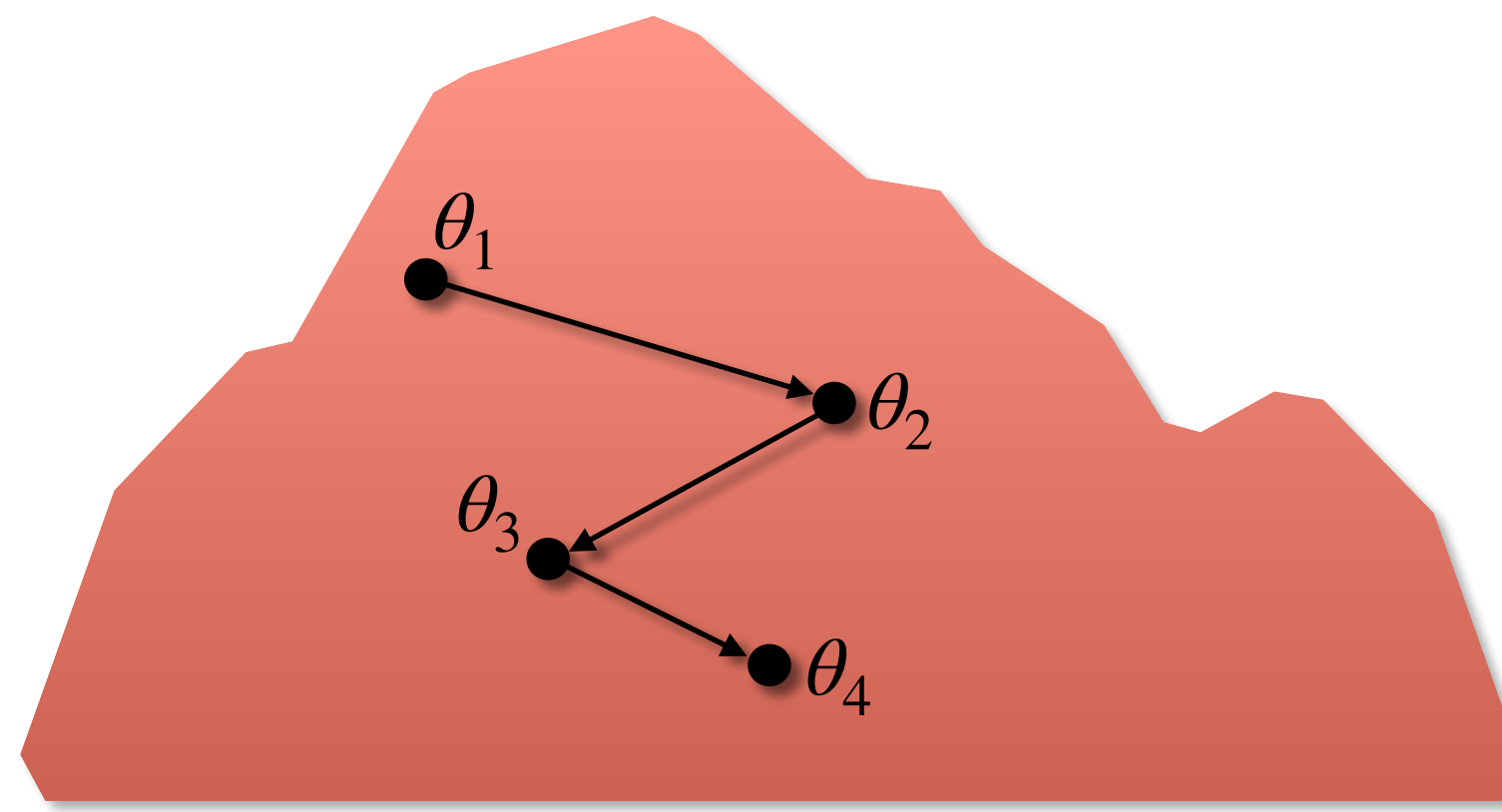
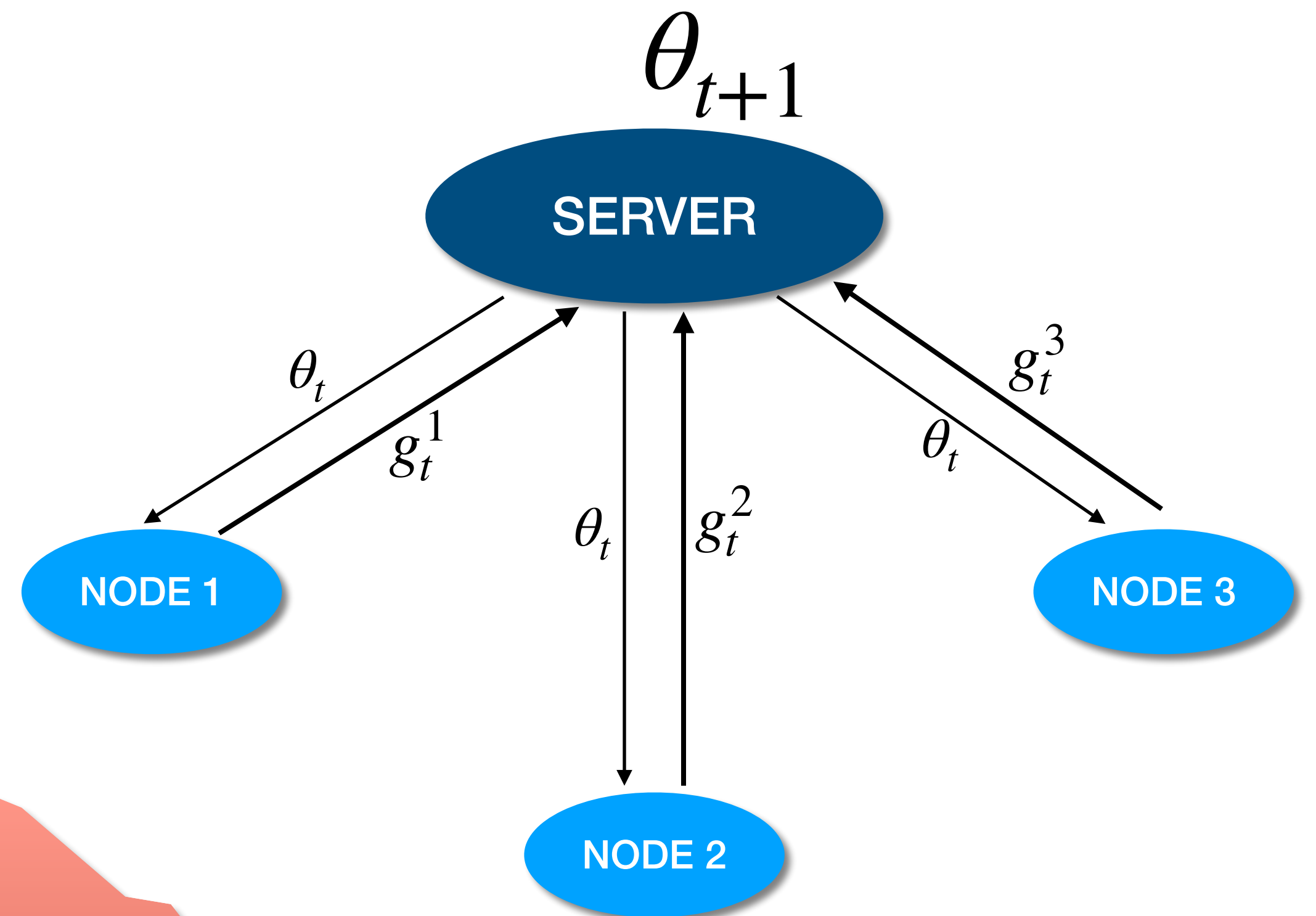
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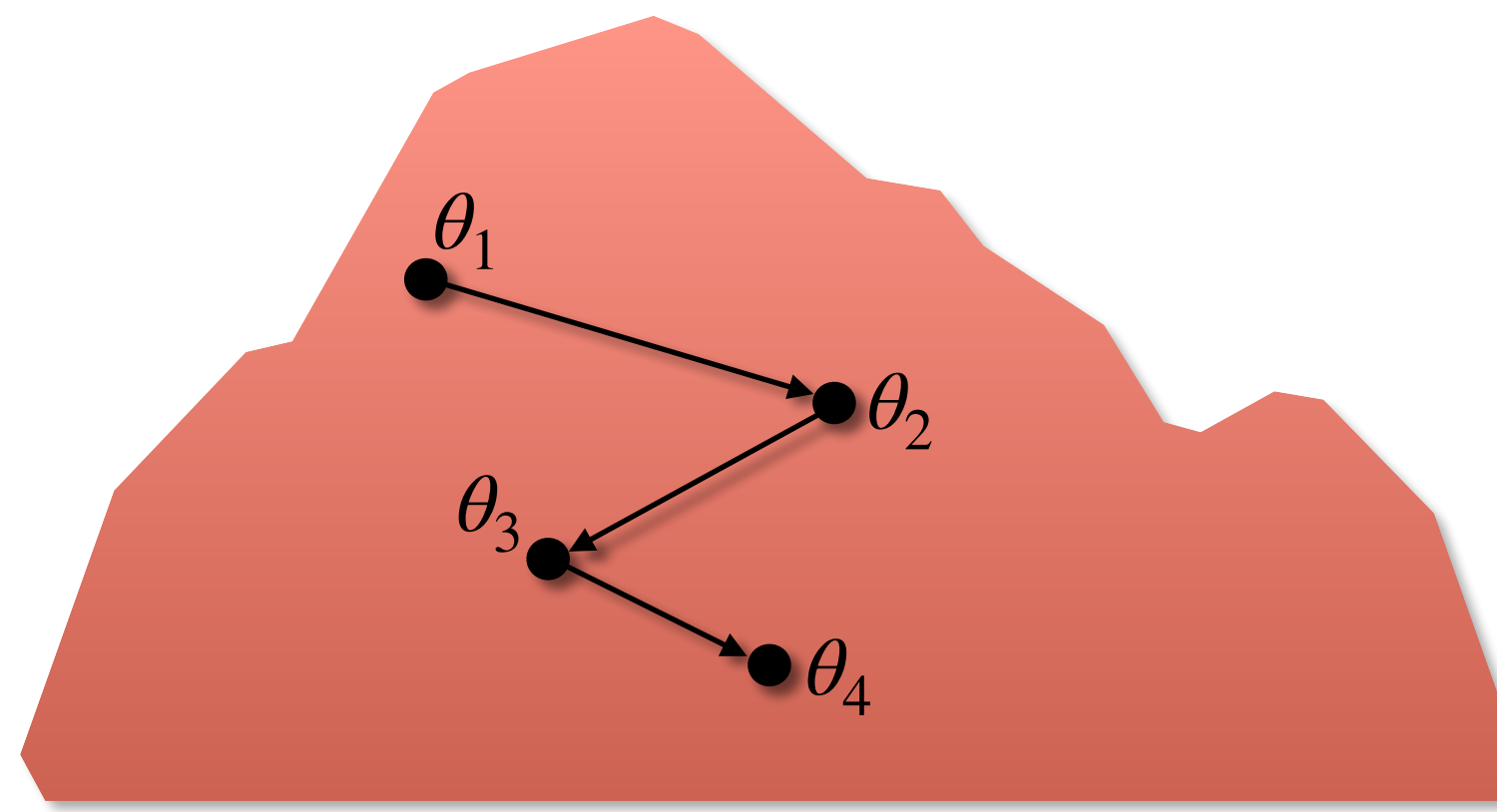
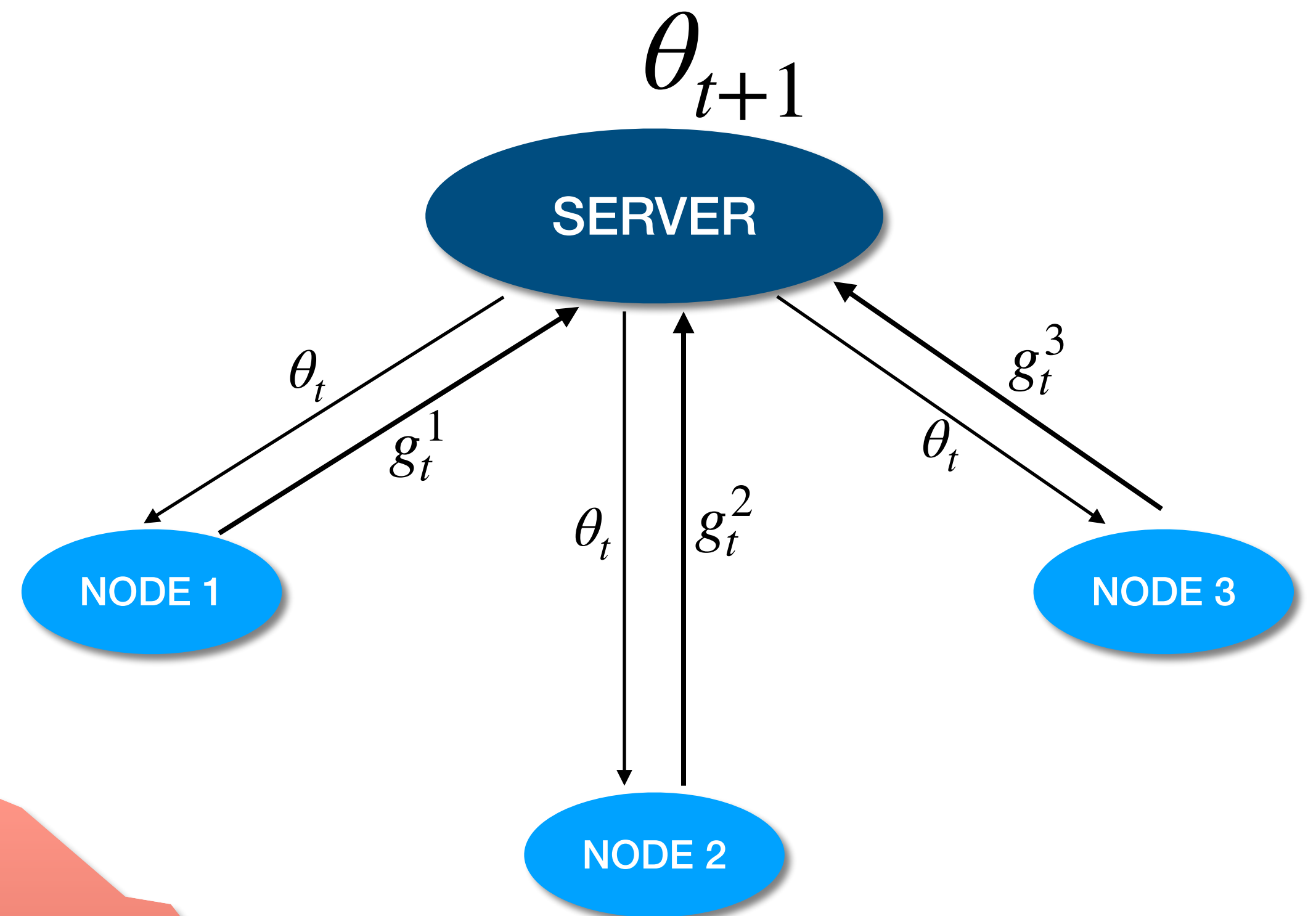
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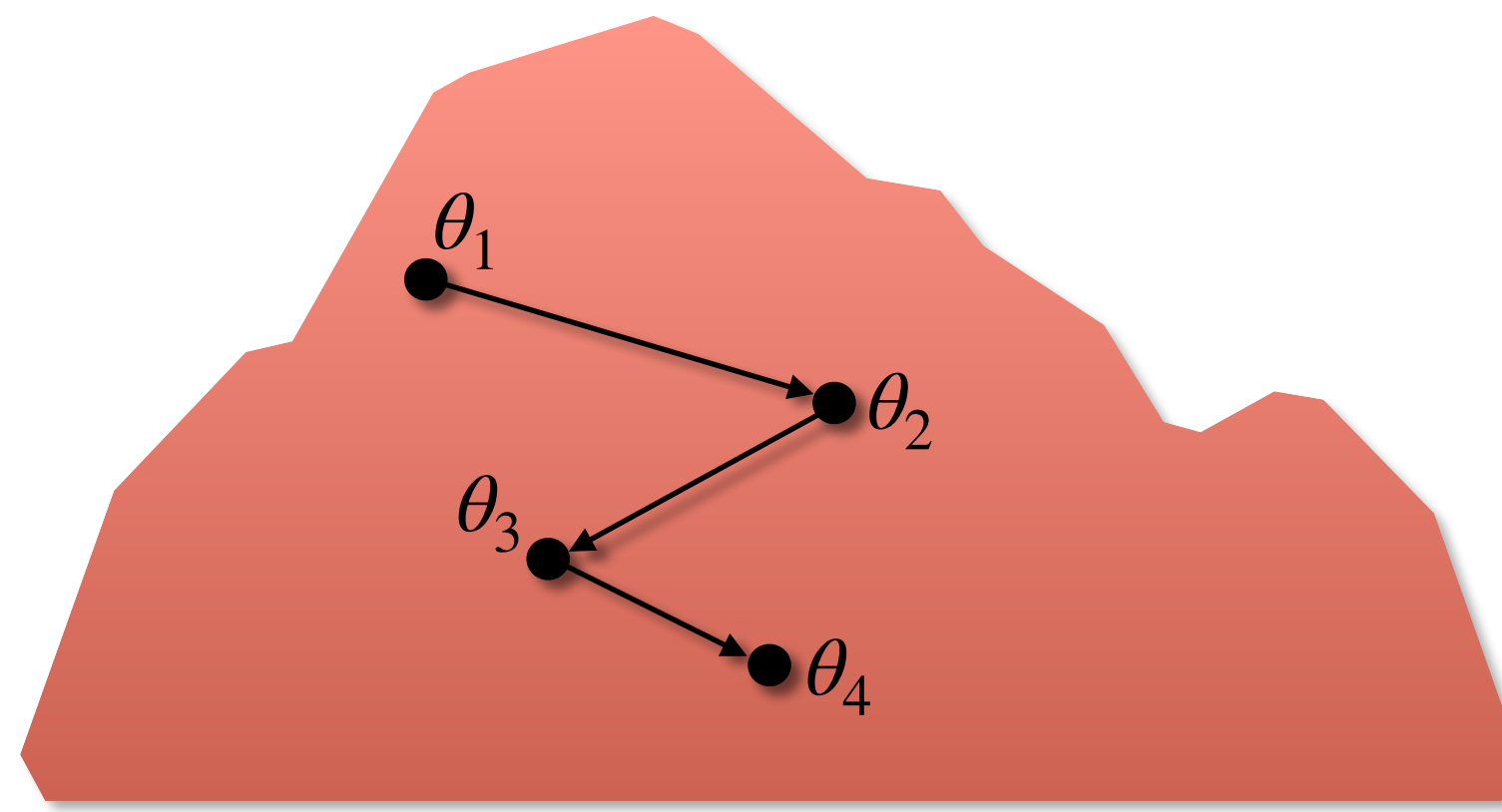
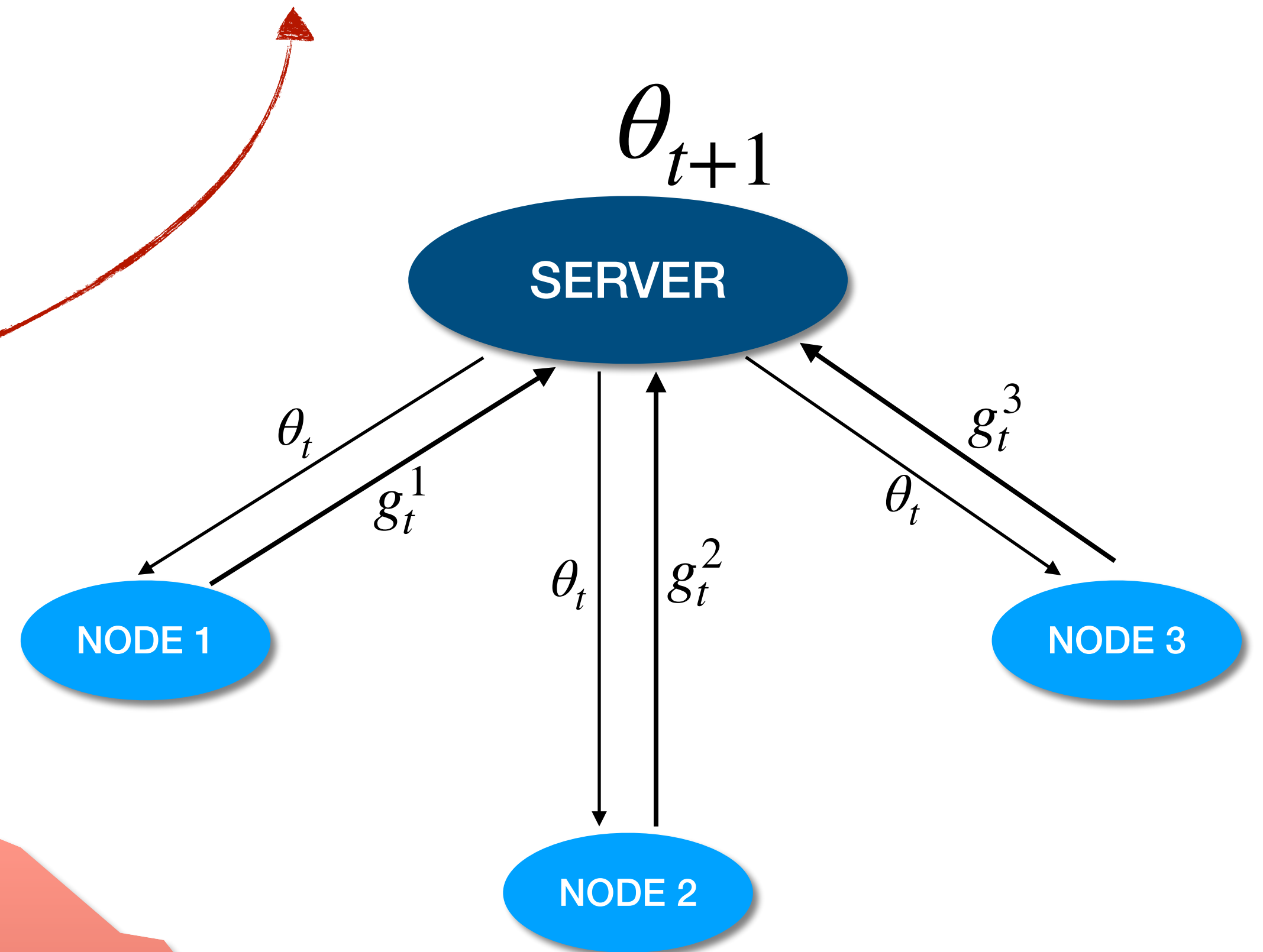
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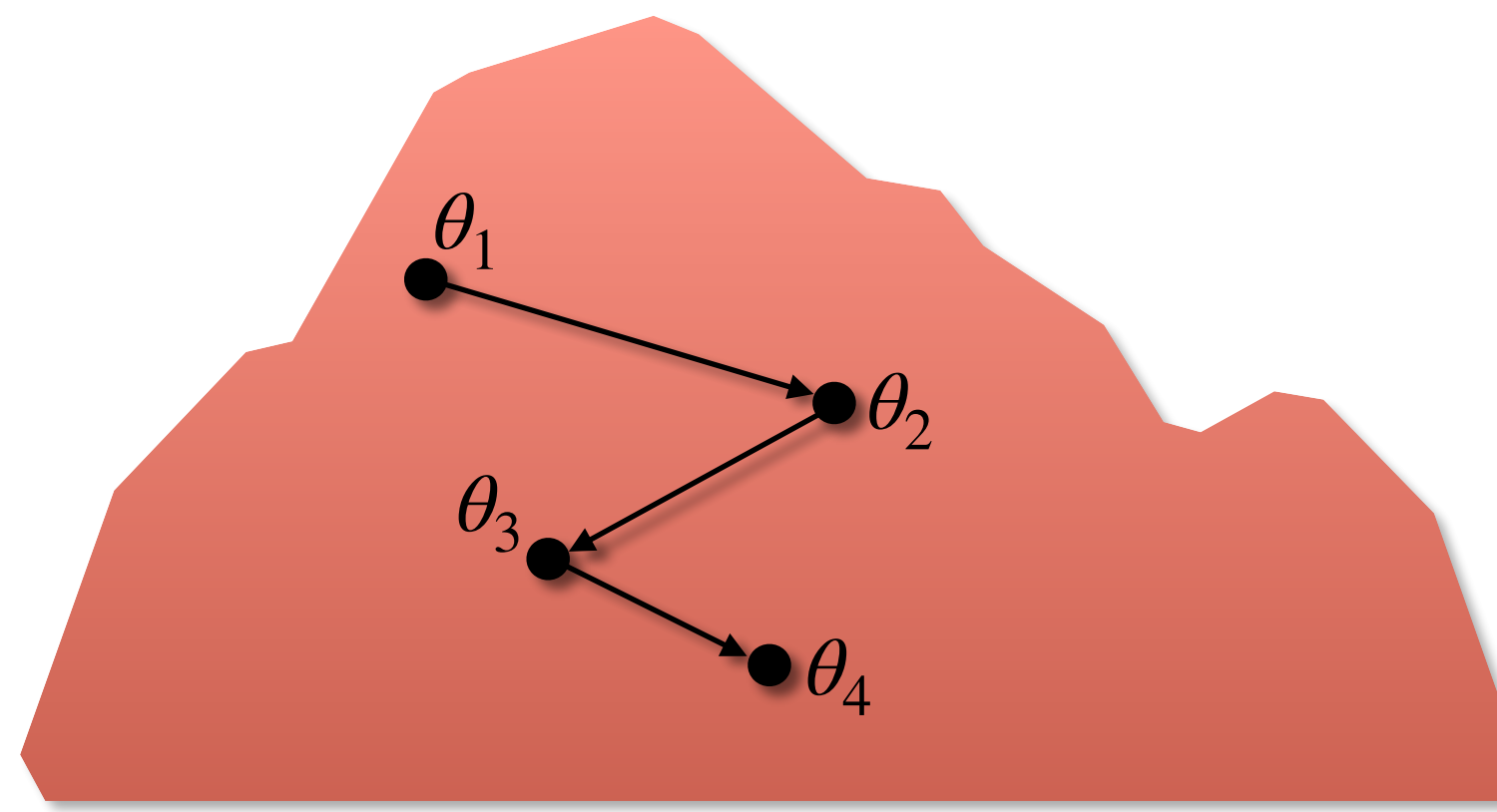
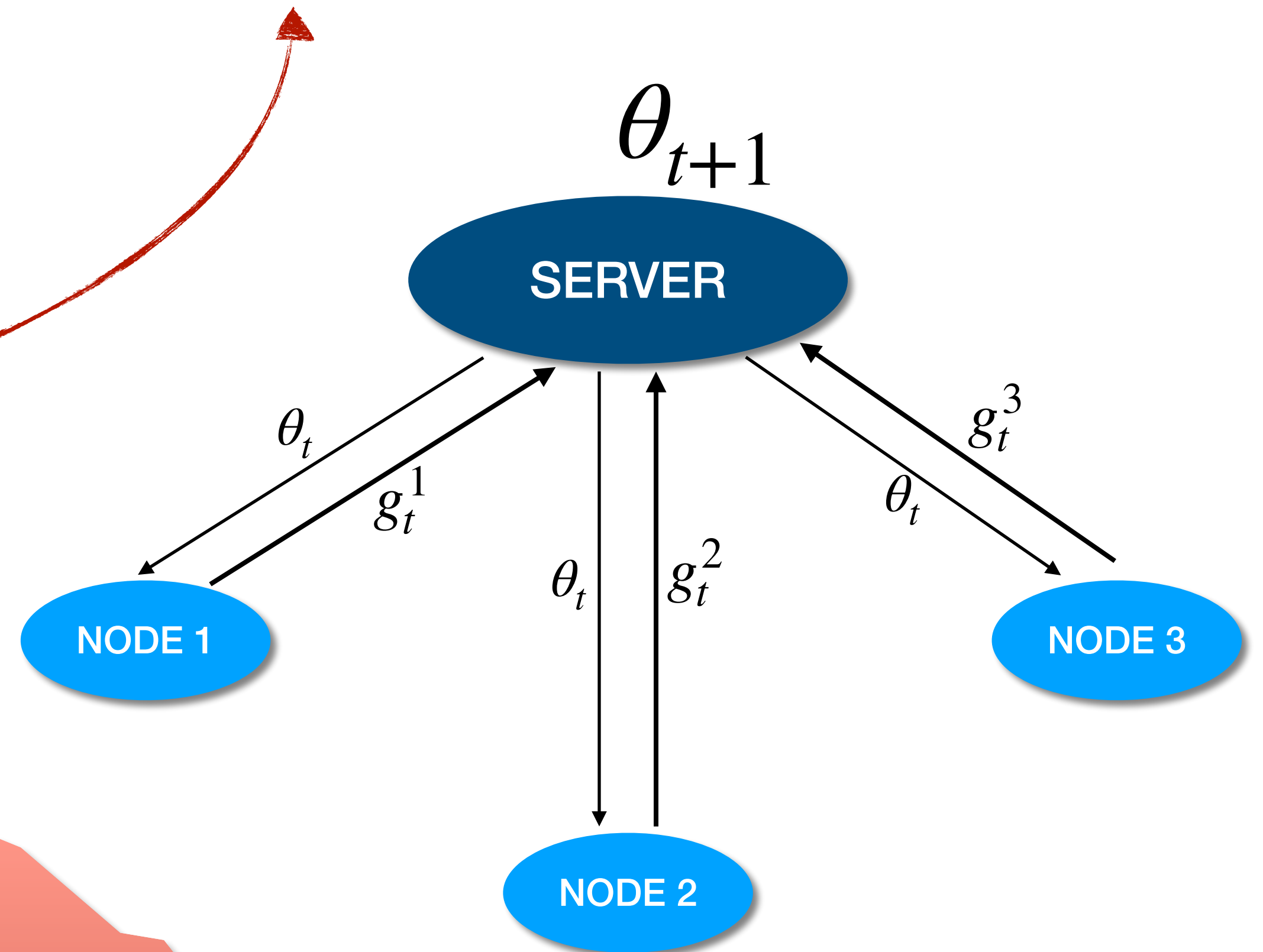
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Upon T iterations



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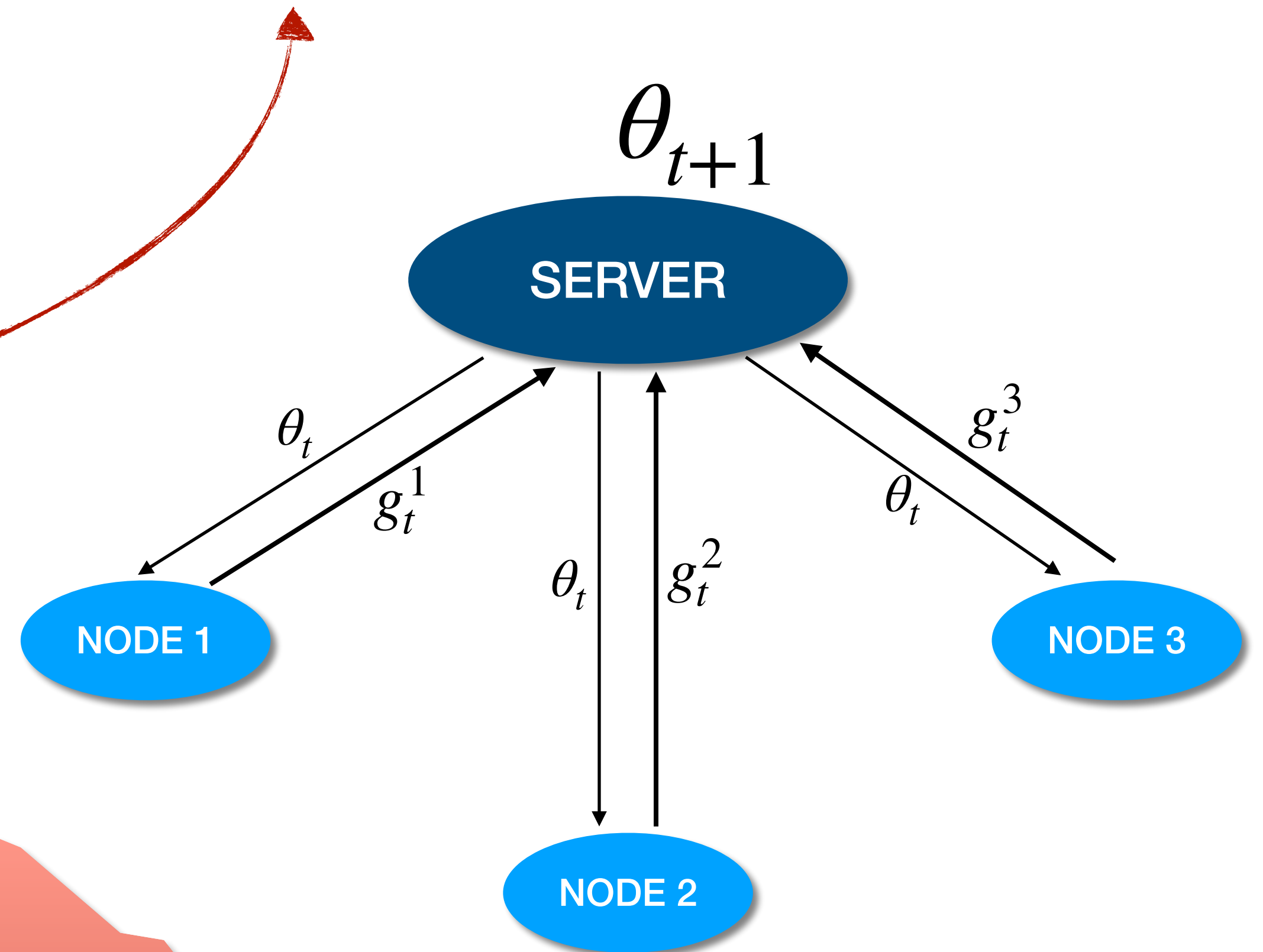
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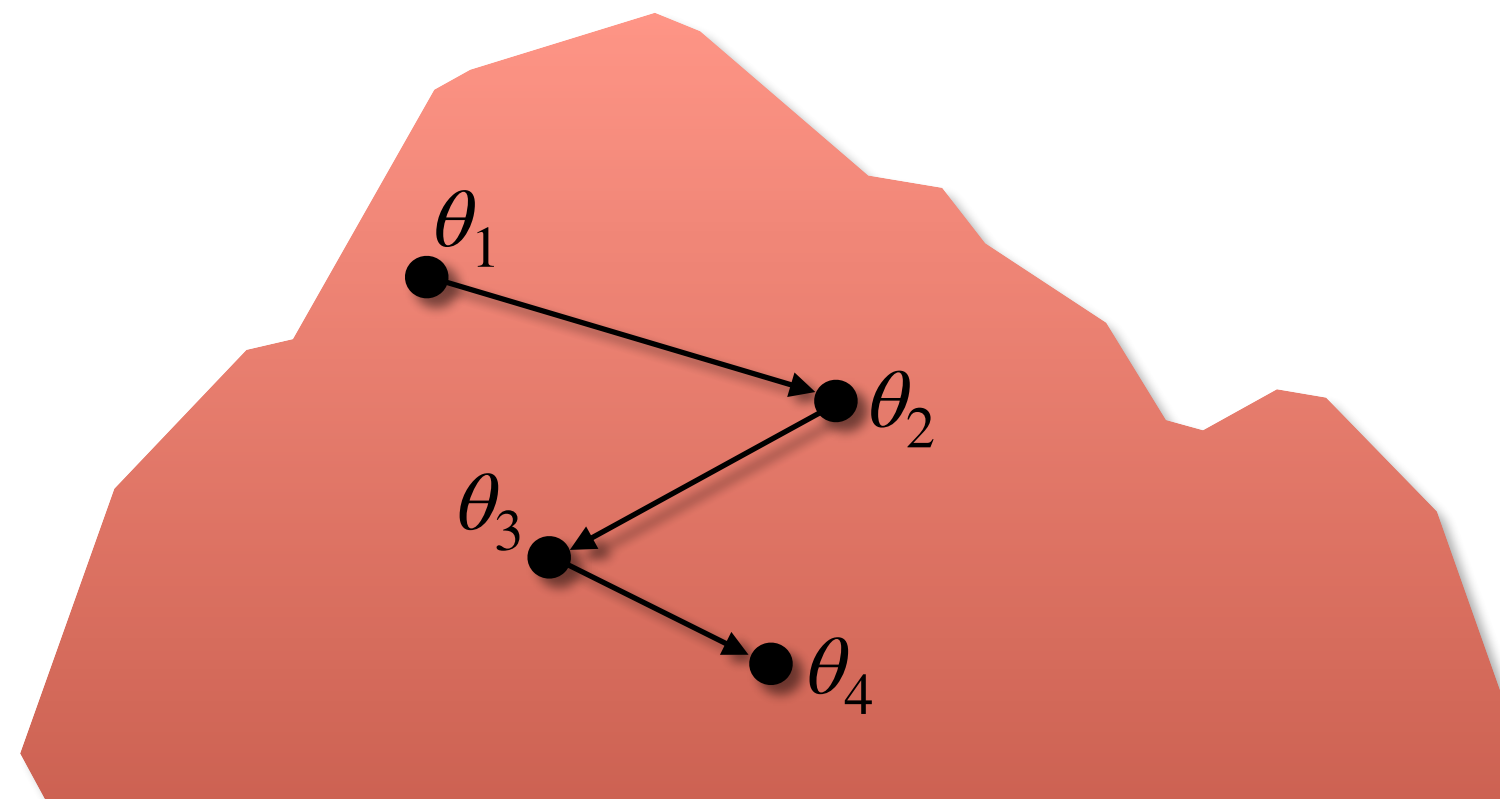
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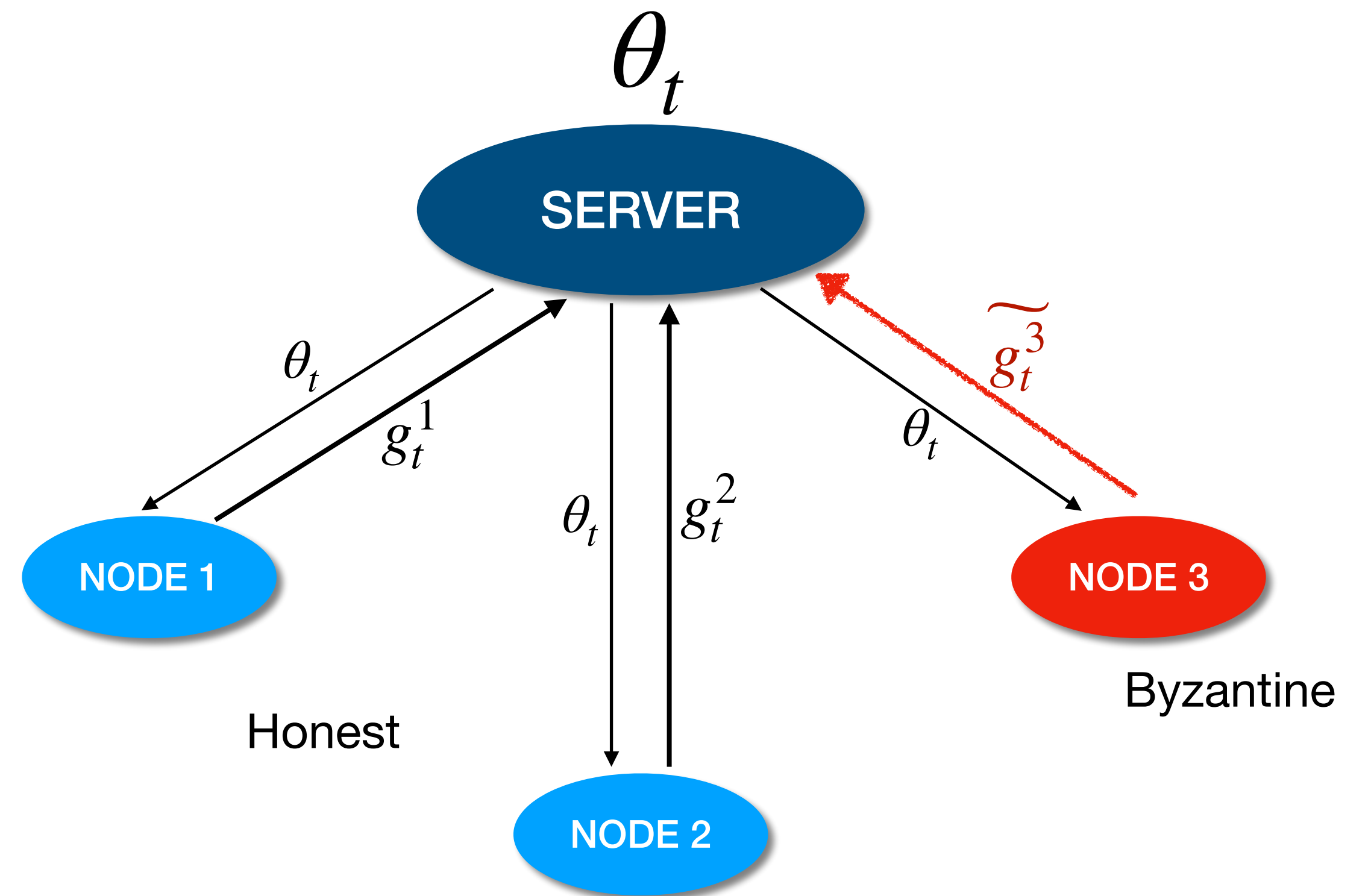


Upon T iterations

$$\frac{1}{T} \sum_{t=1}^T \mathbb{E} \left[\|\nabla Q(\theta_t)\|^2 \right] \leq \epsilon \in \mathcal{O} \left(\sqrt{\frac{\sigma^2}{nT}} \right)$$

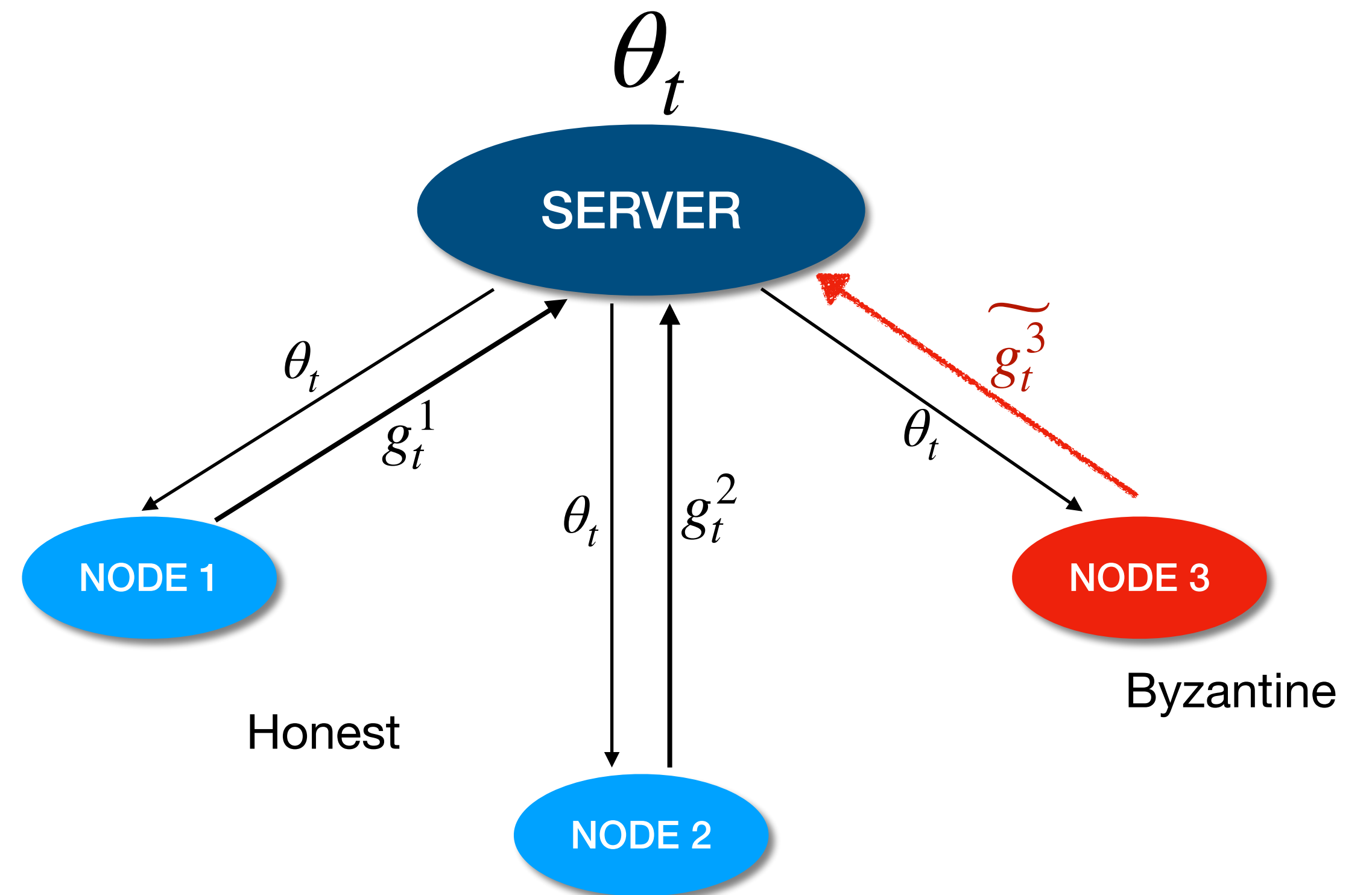


Byzantine Resilience in Distributed Learning



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f out of n nodes are Byzantine faulty

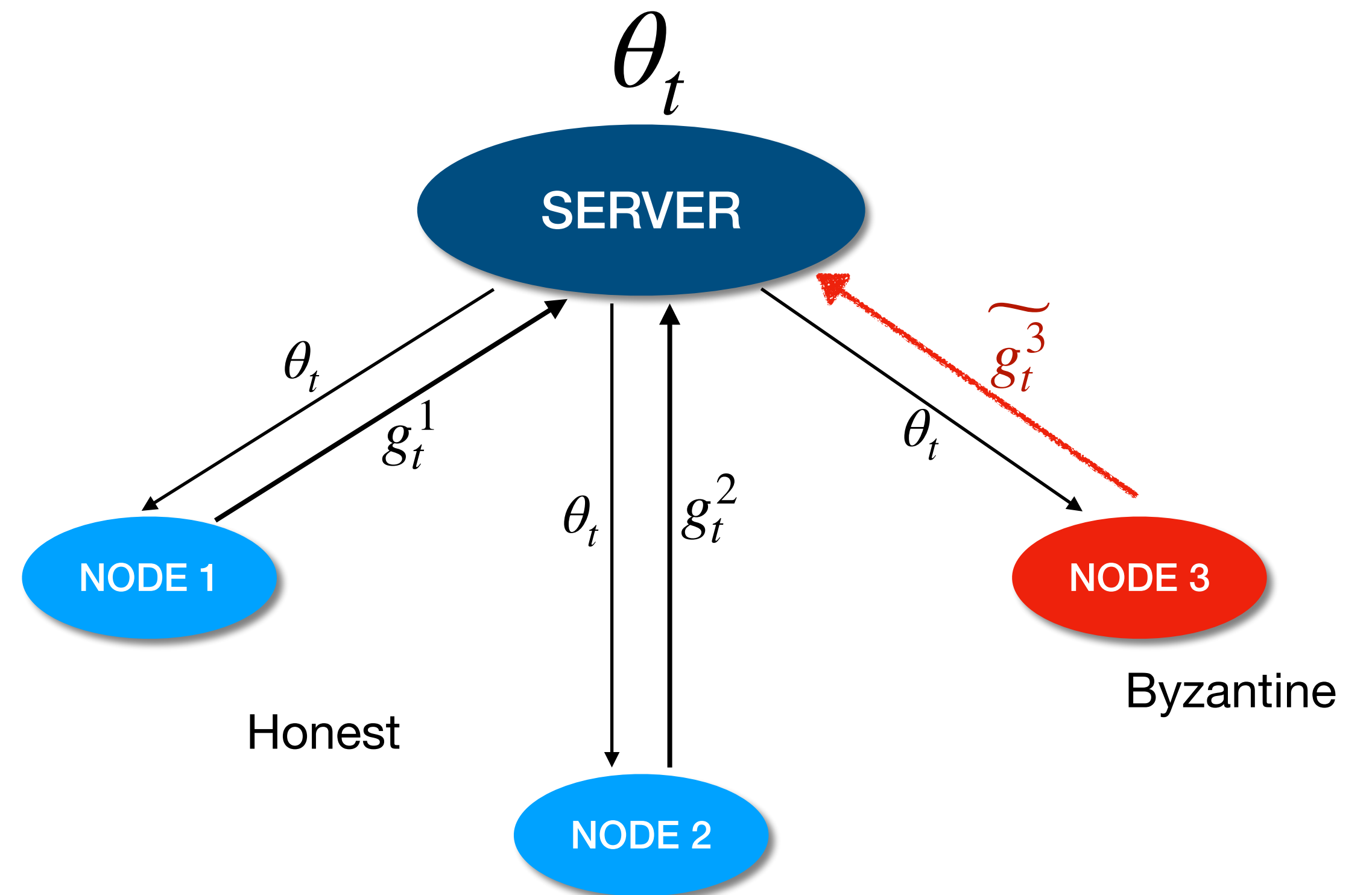


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CAN THE SERVER STILL OBTAIN

$$\theta^* \in (\theta ; \nabla Q(\theta) = 0)$$



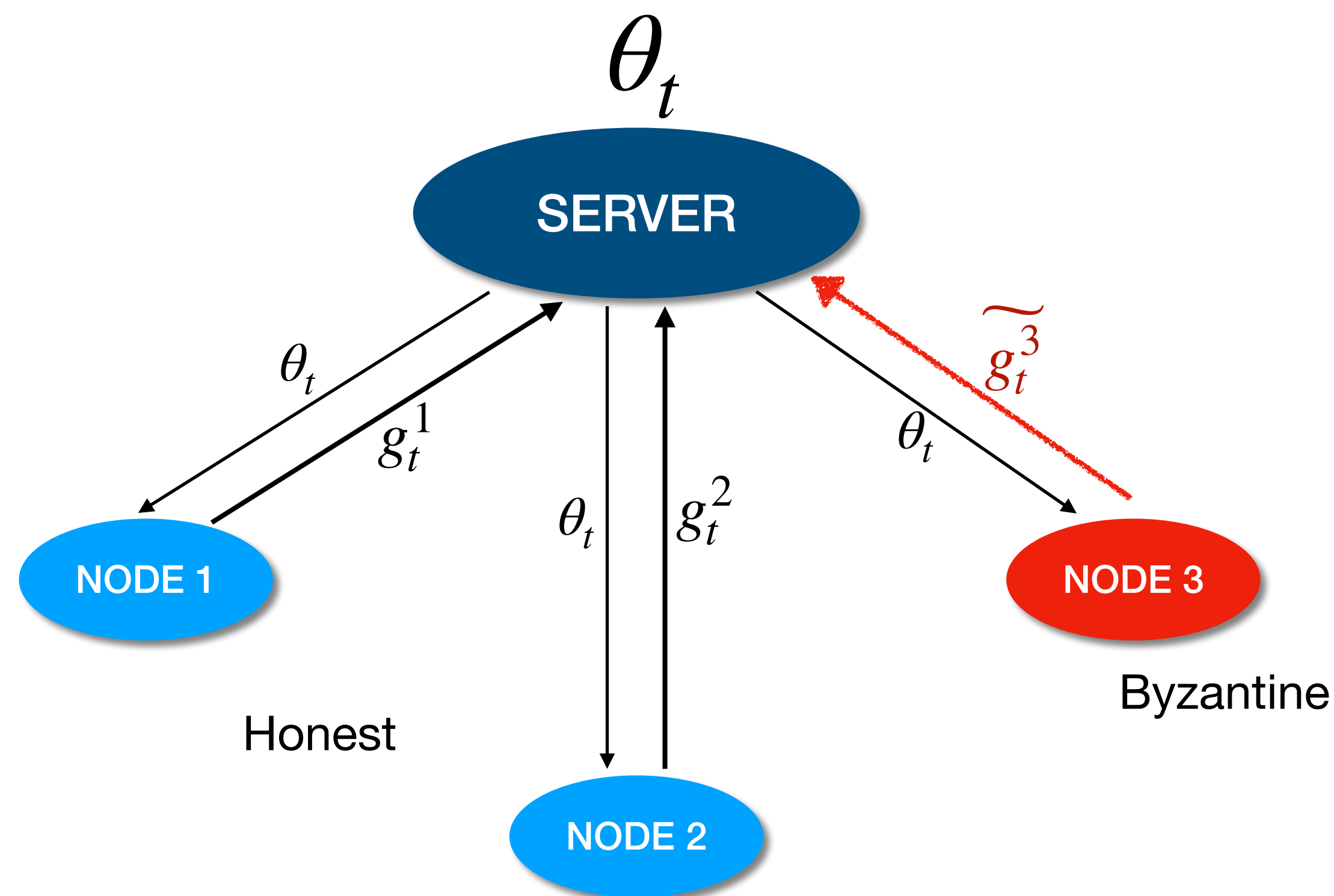
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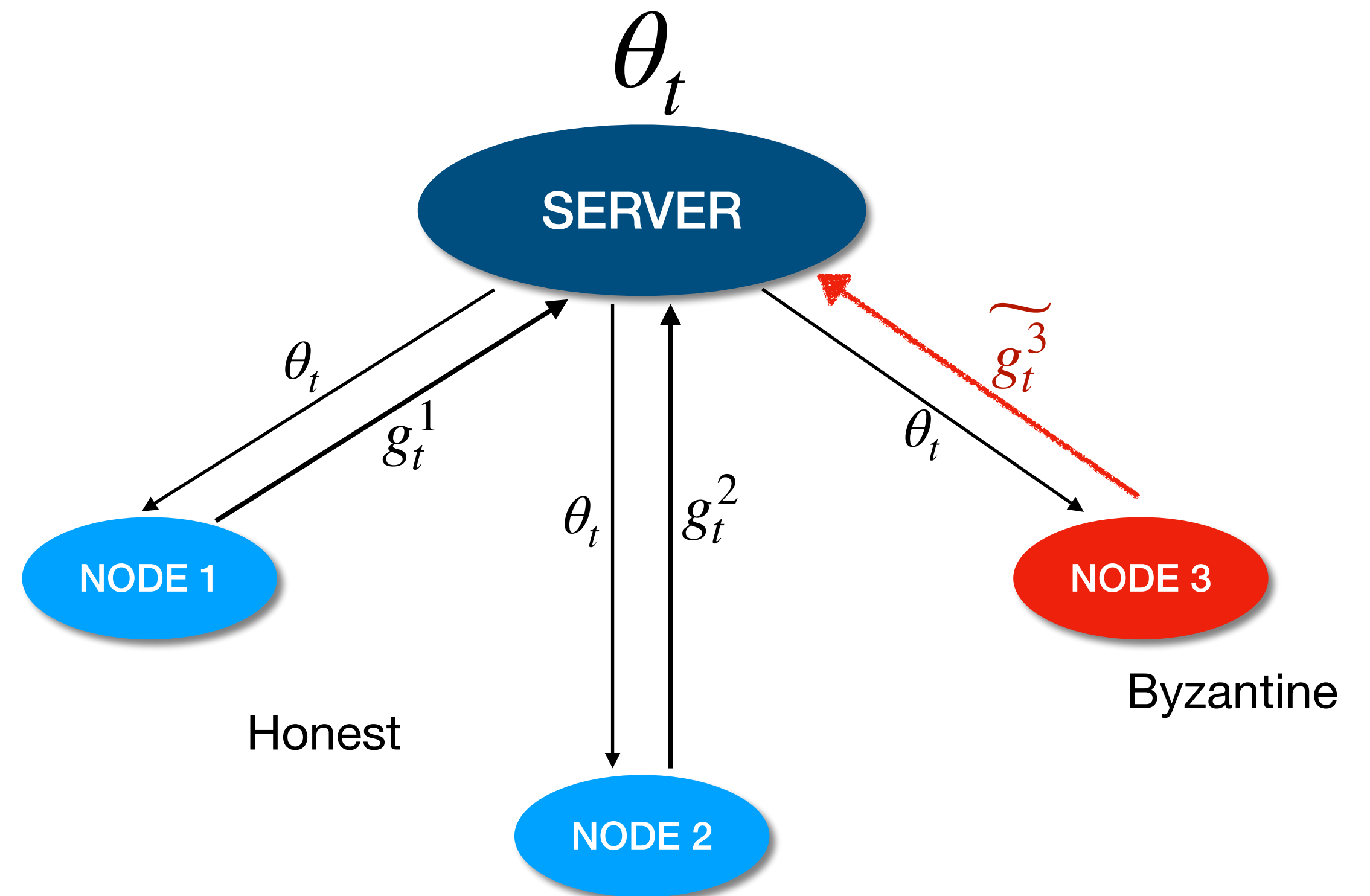
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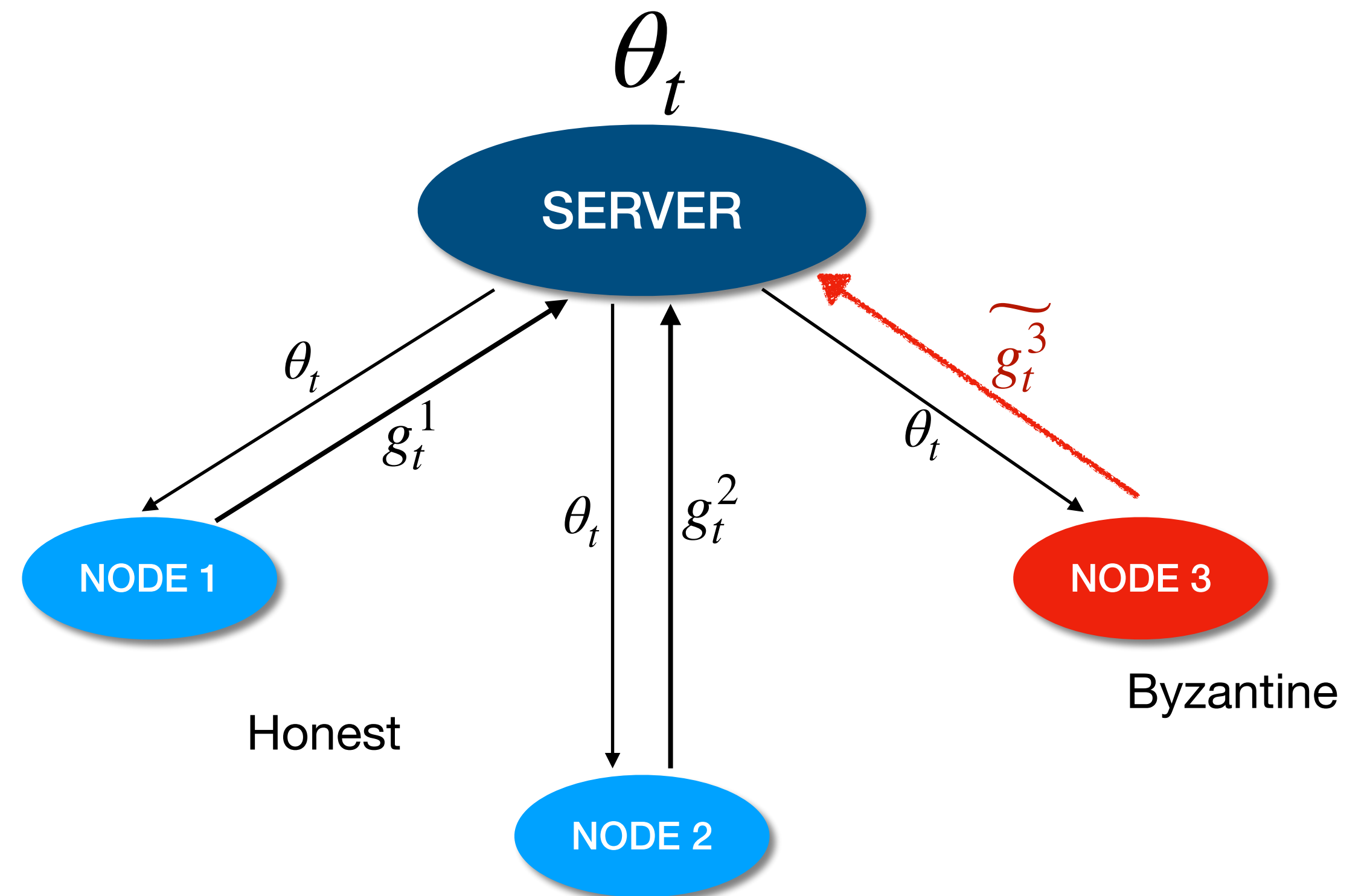
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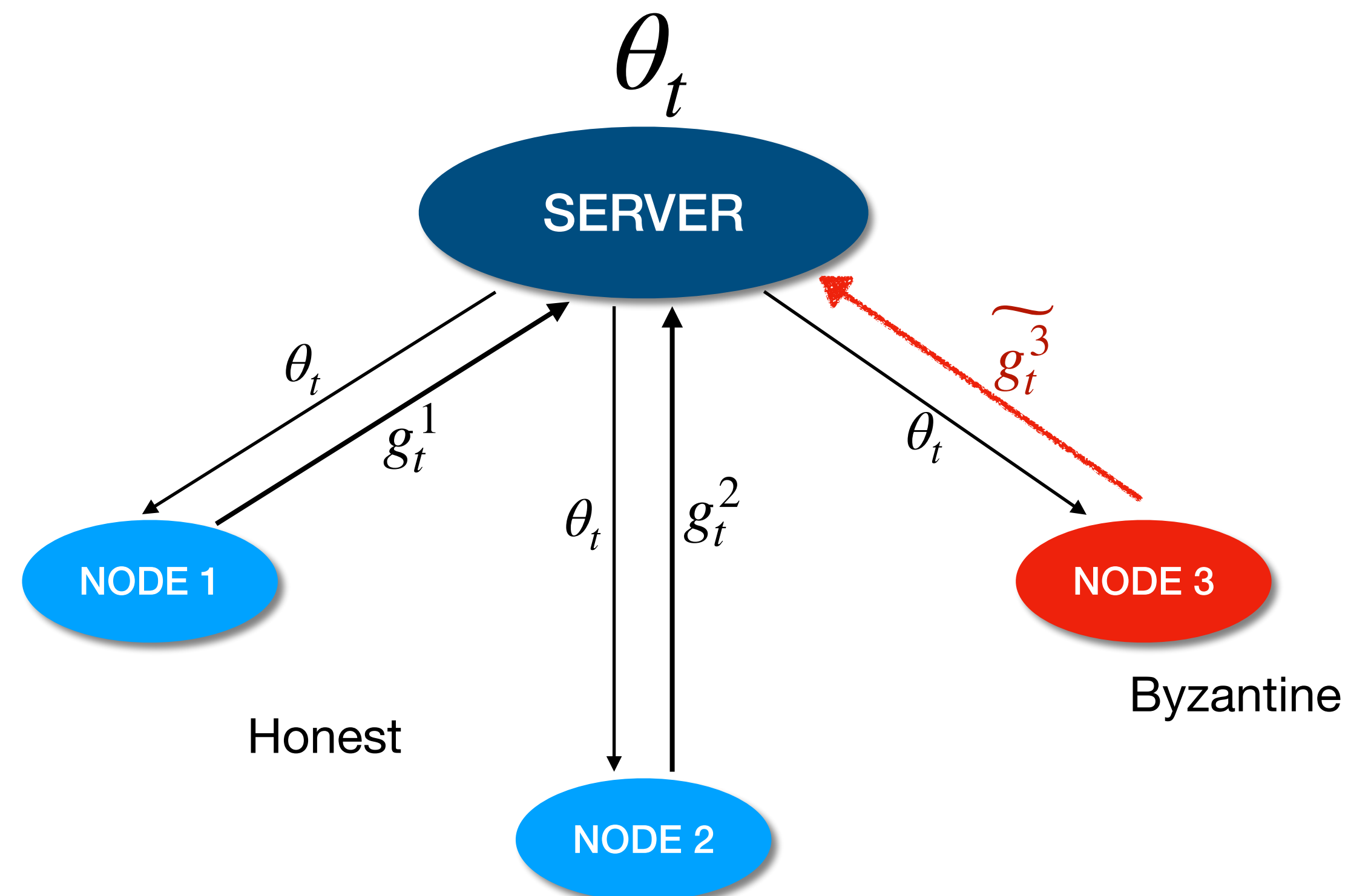
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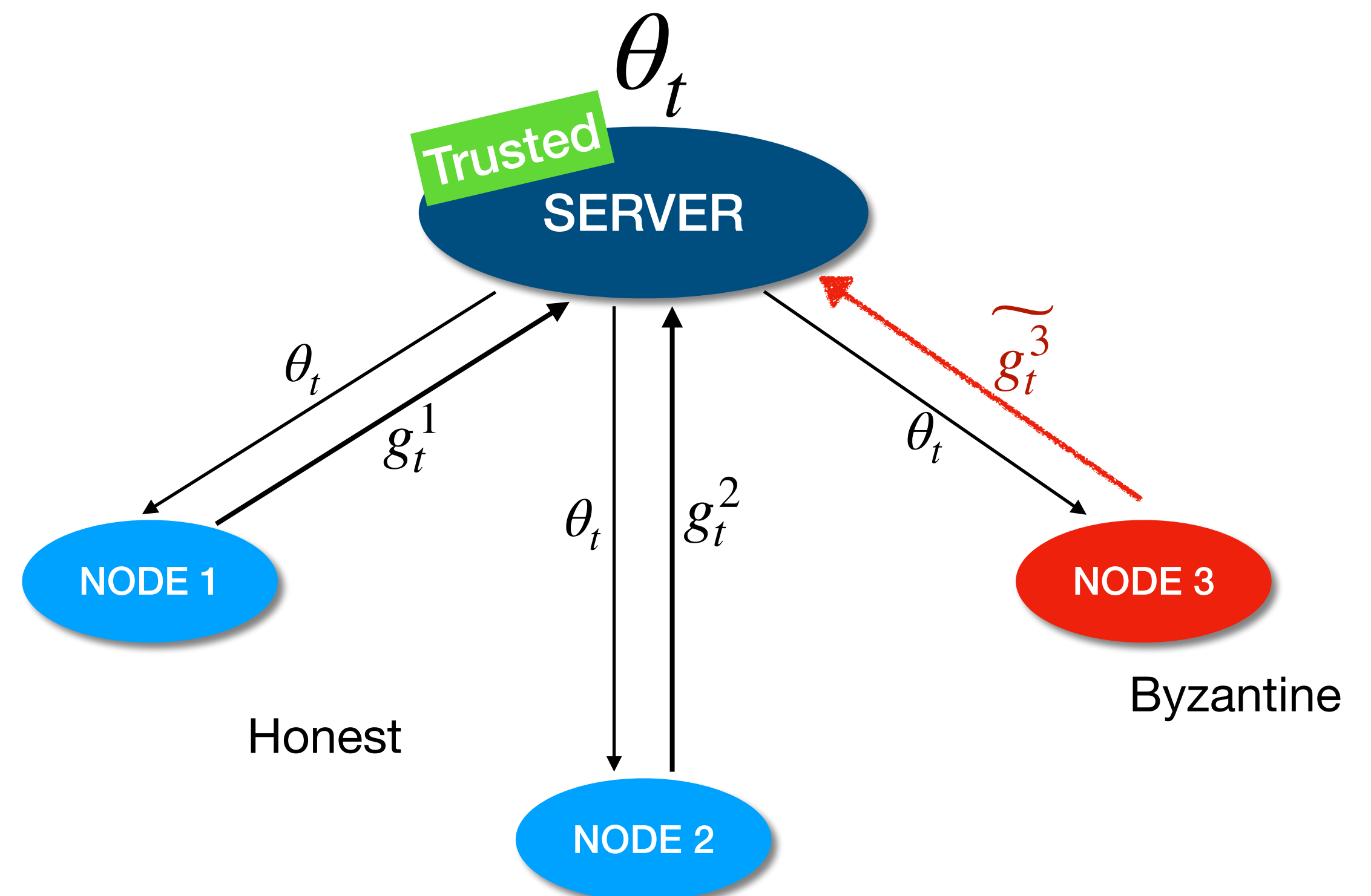
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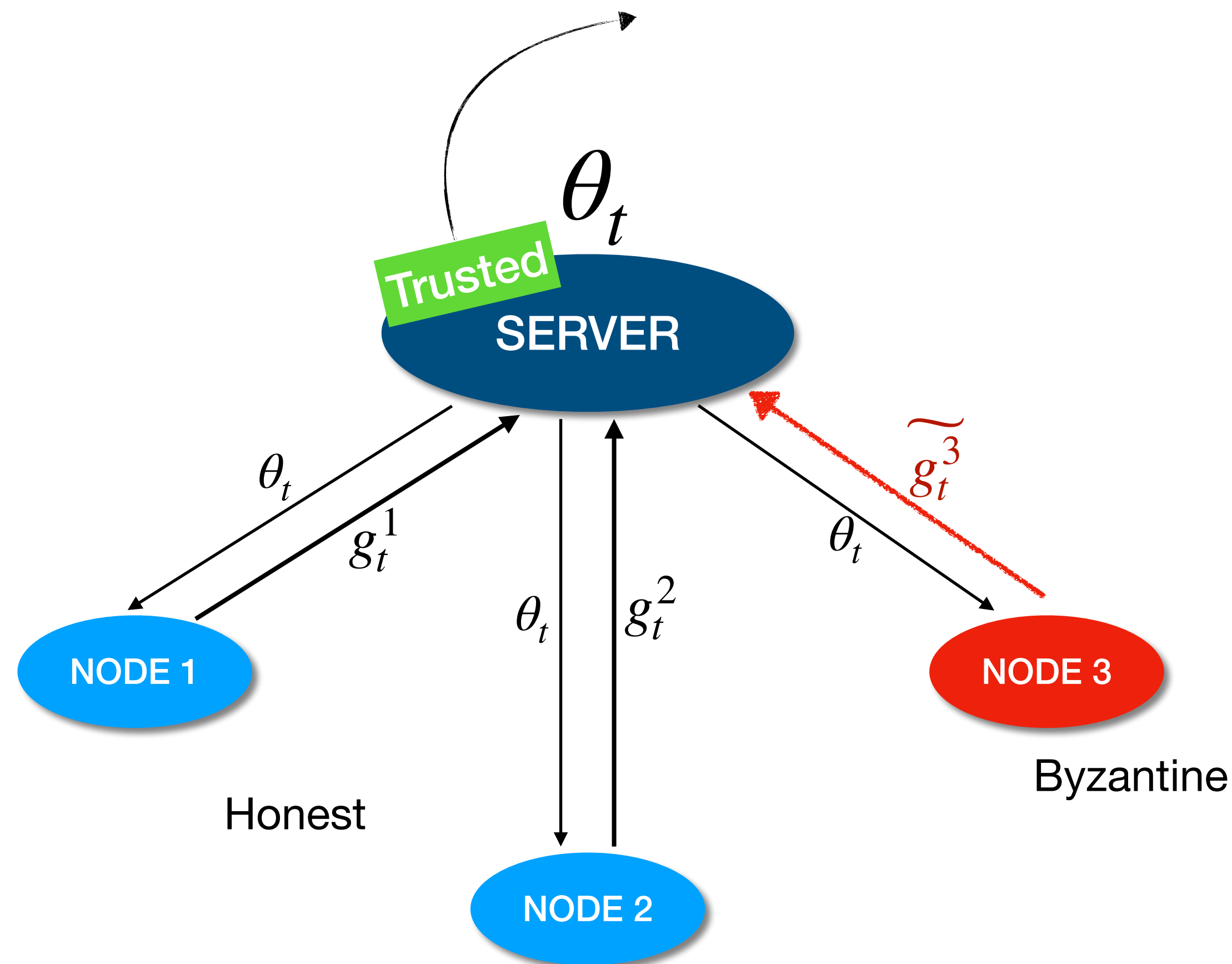
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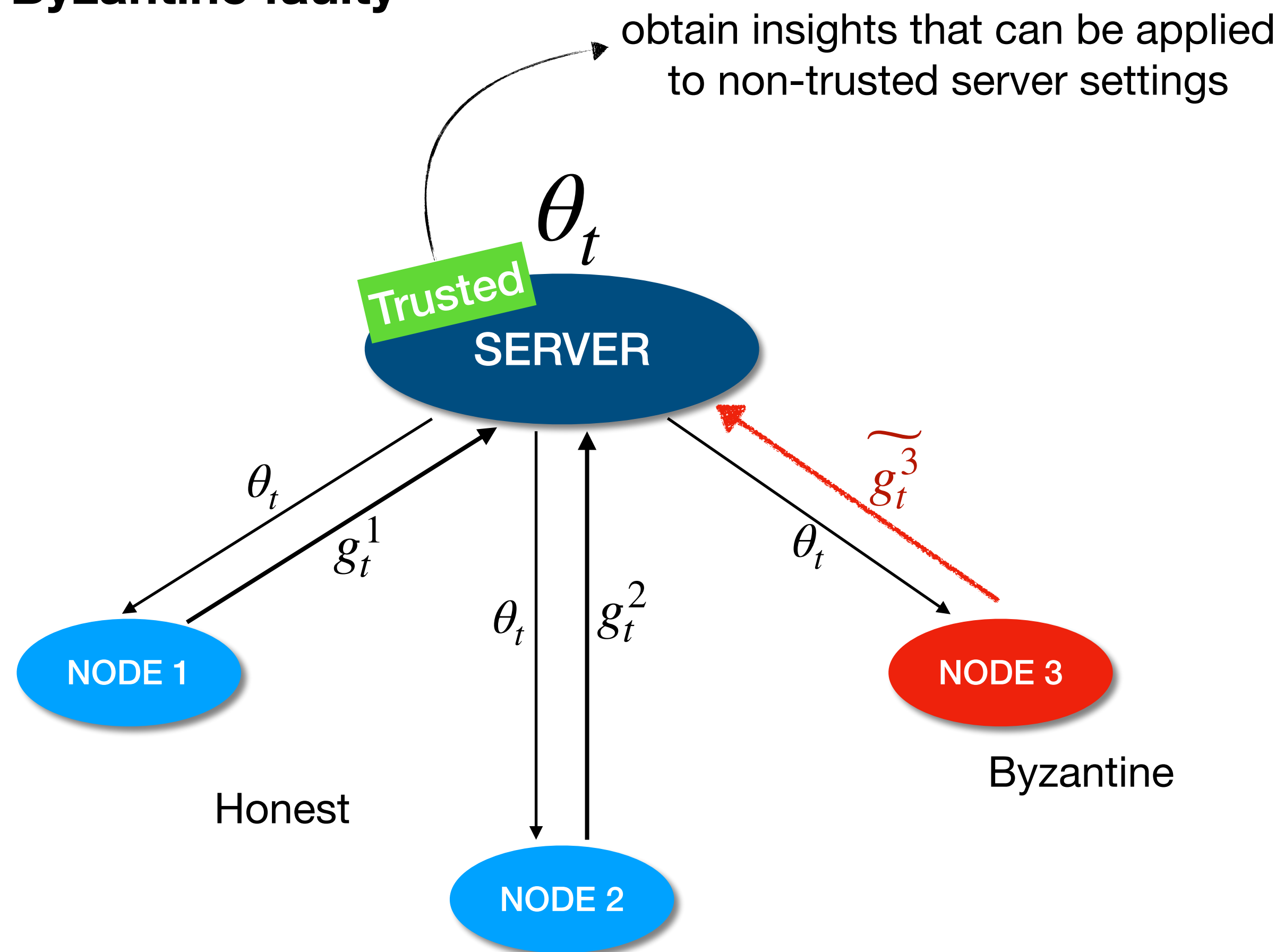
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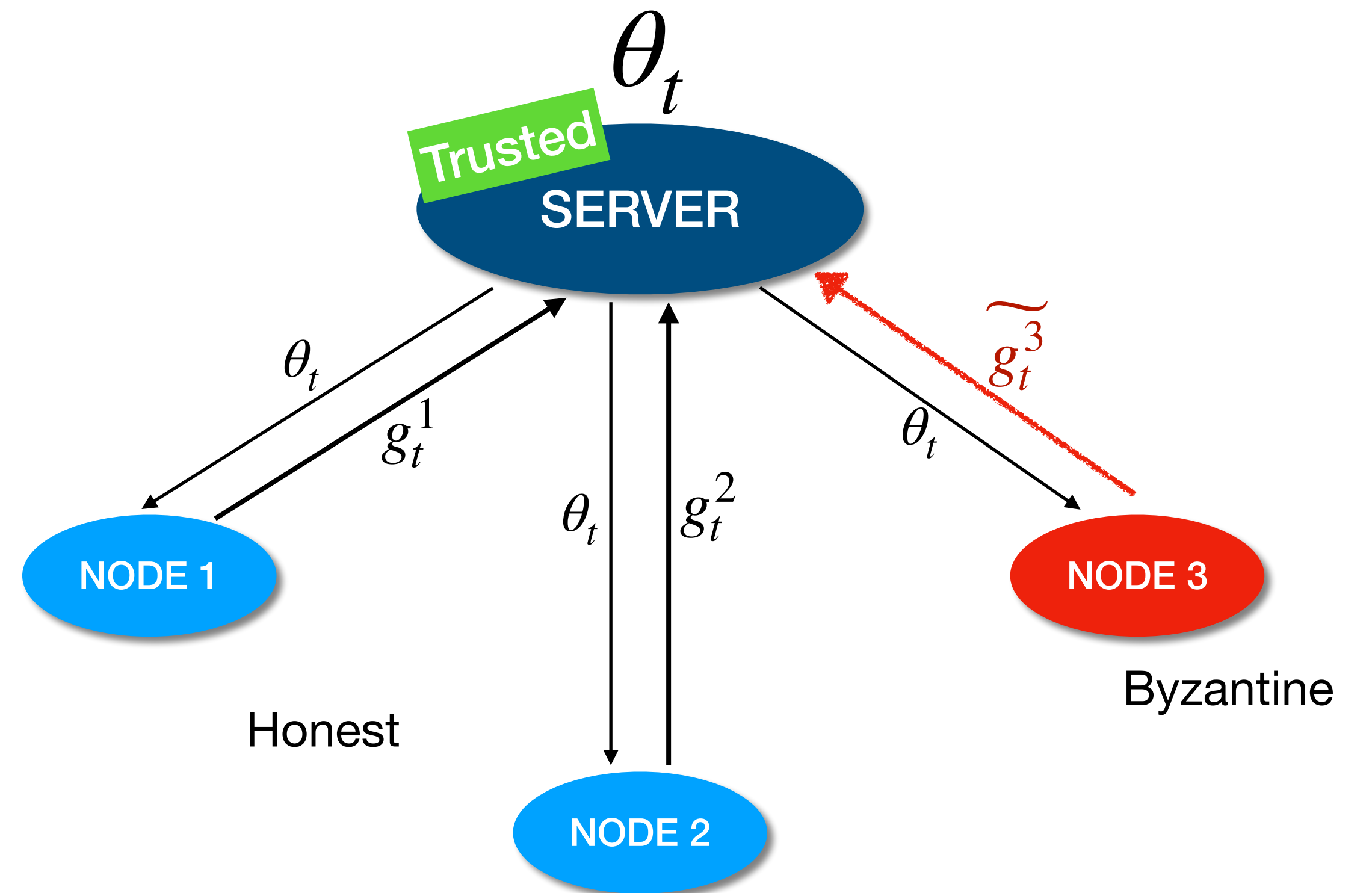
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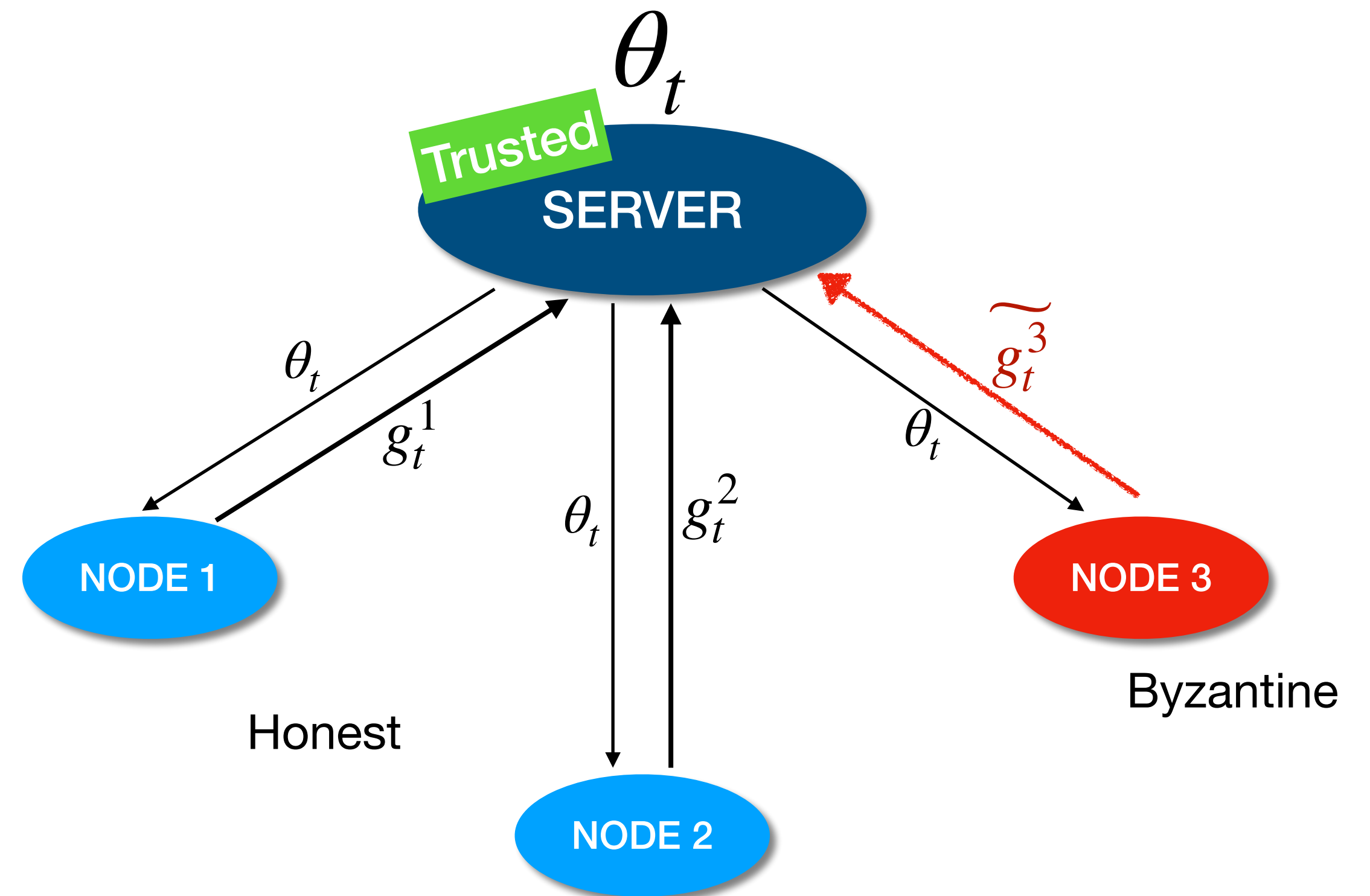
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Making D-SGD Byzantine Resilient



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Classical D-SGD - Server updates $\theta_{t+1} \leftarrow \theta_t - \gamma_t \hat{g}_t$

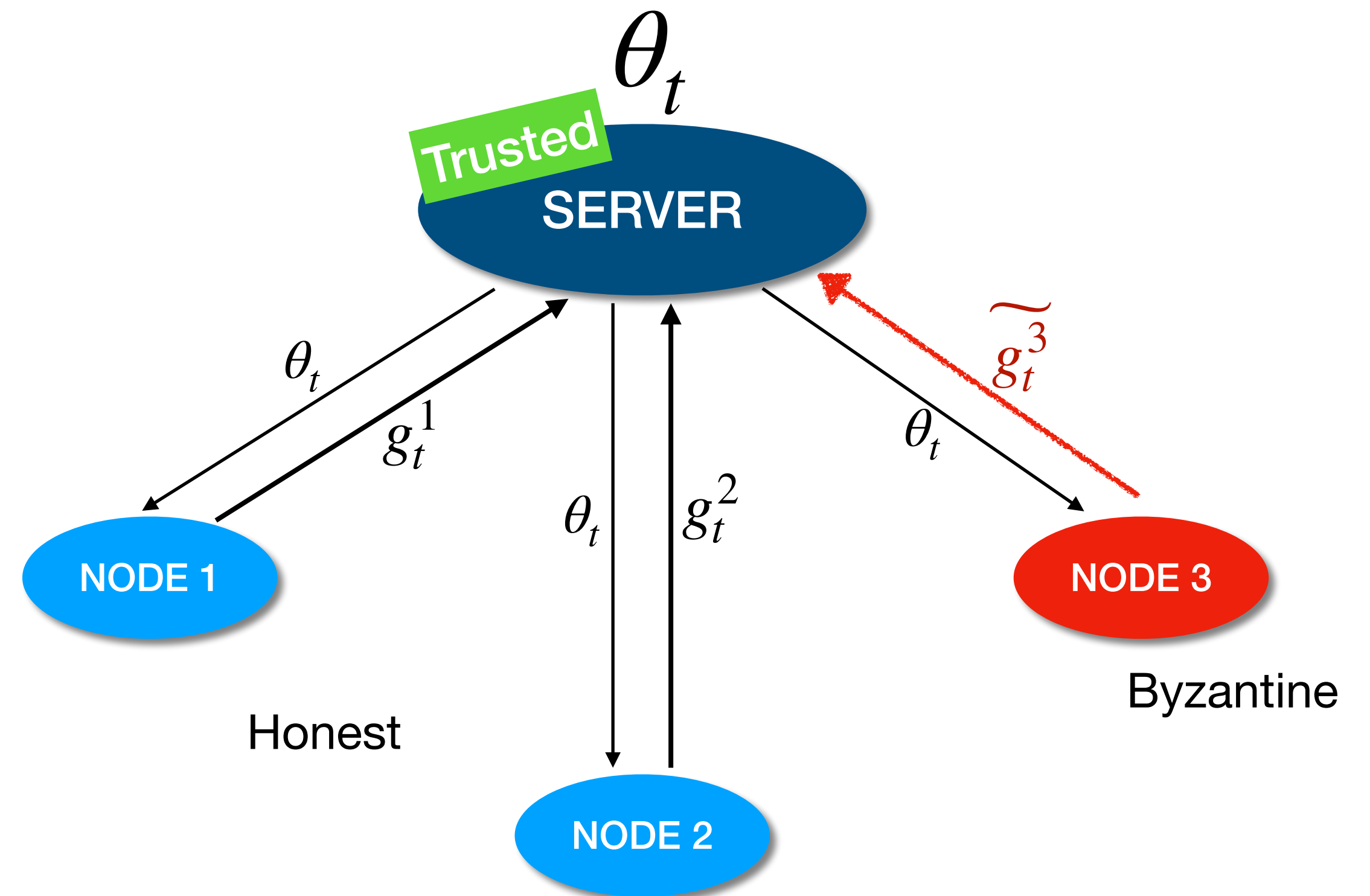


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Classical D-SGD - Server updates $\theta_{t+1} \leftarrow \theta_t - \gamma_t \hat{g}_t$

We **cannot use**, for updates, $\hat{g}_t = \frac{1}{n} \sum_i g_t^i$

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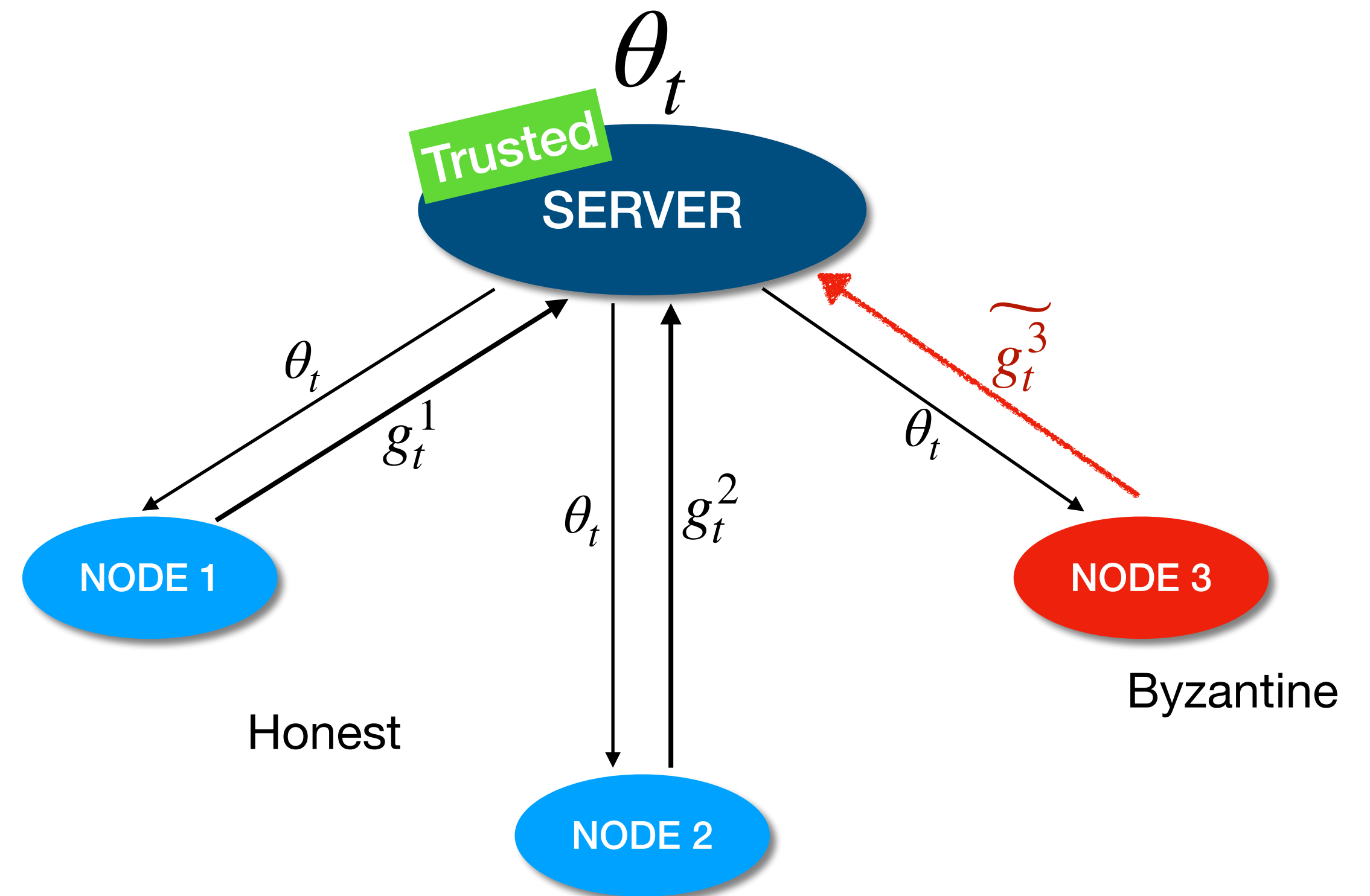
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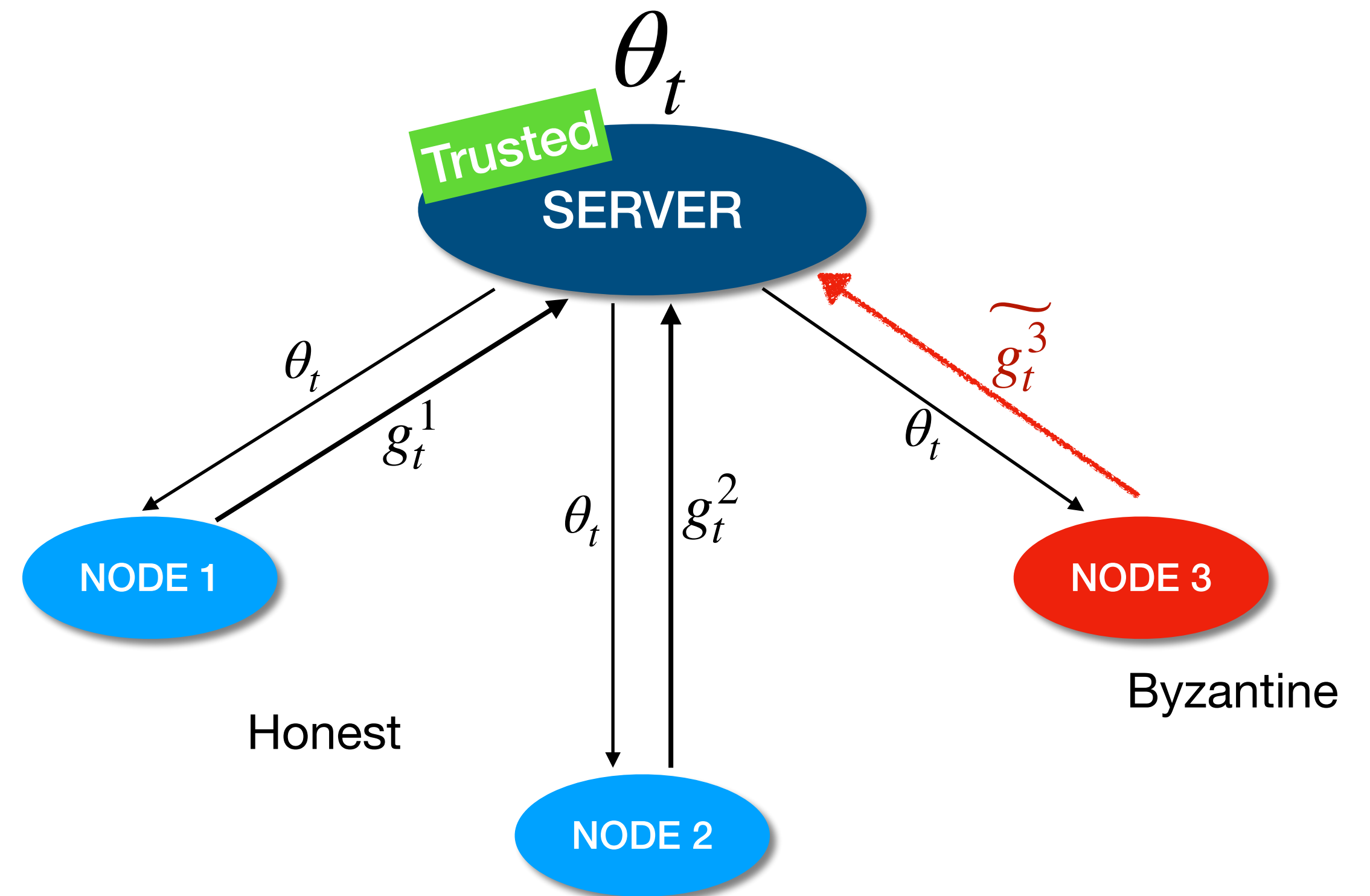
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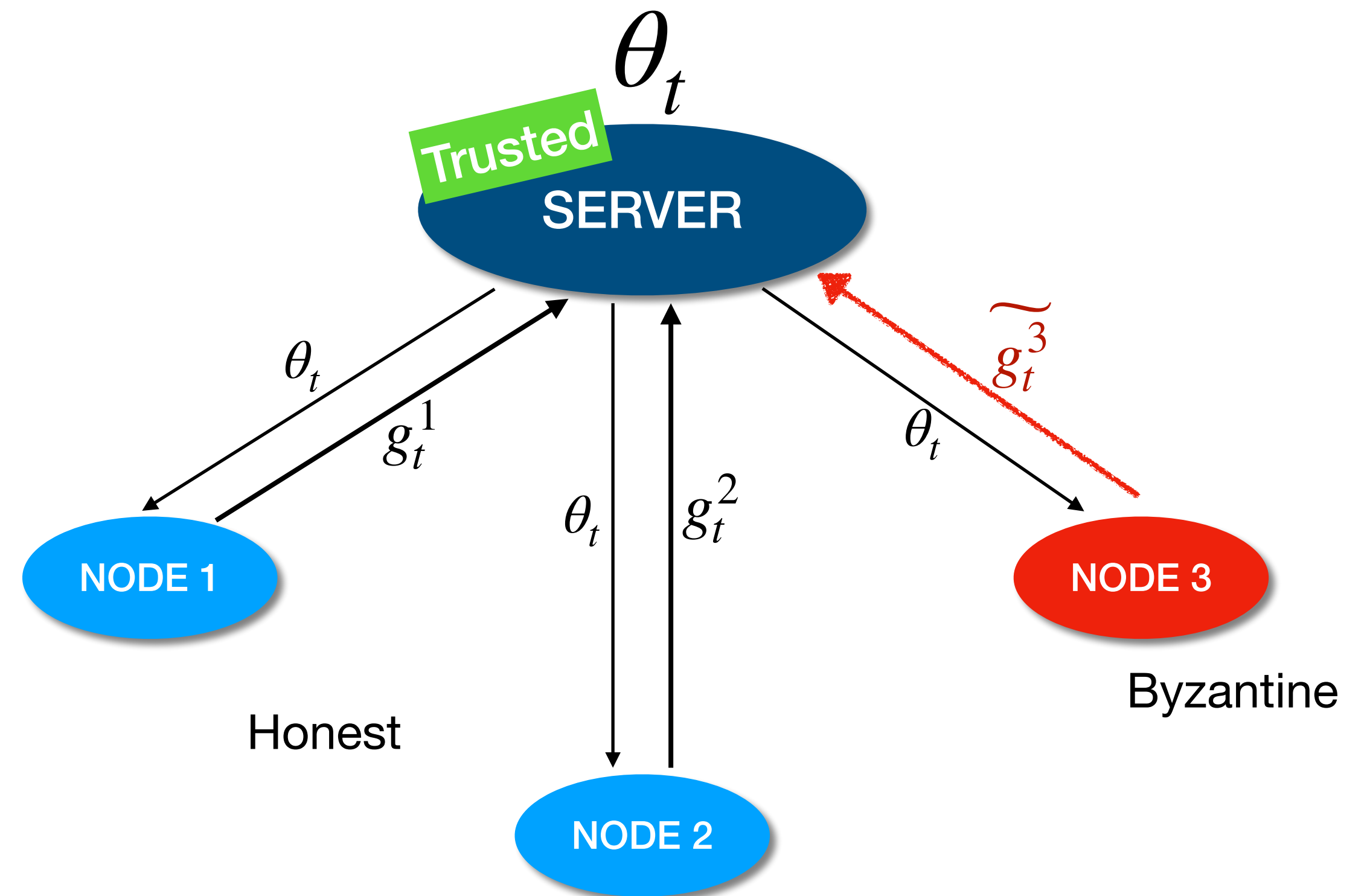
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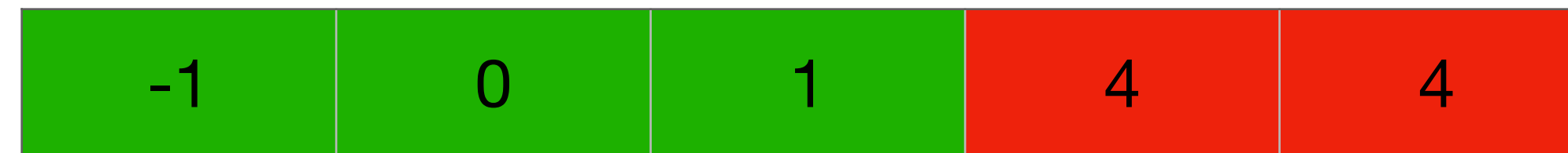
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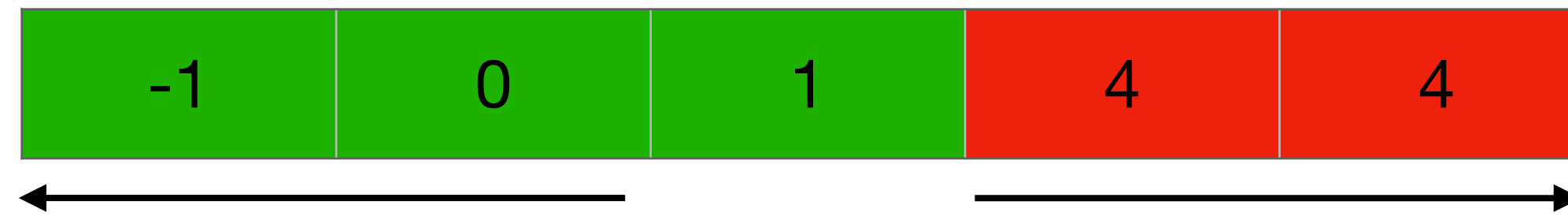


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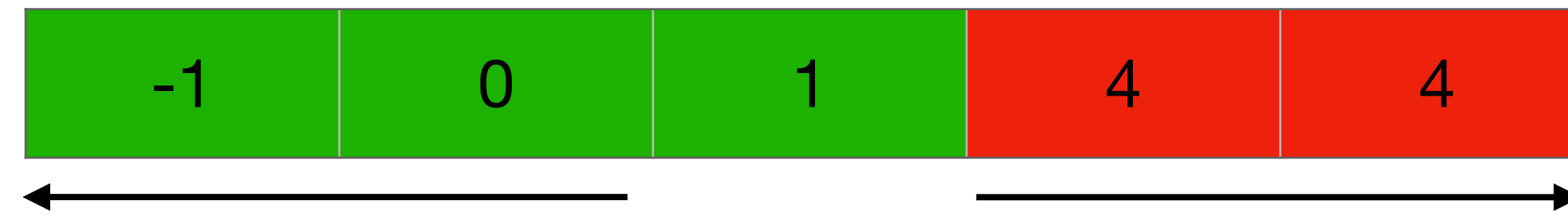


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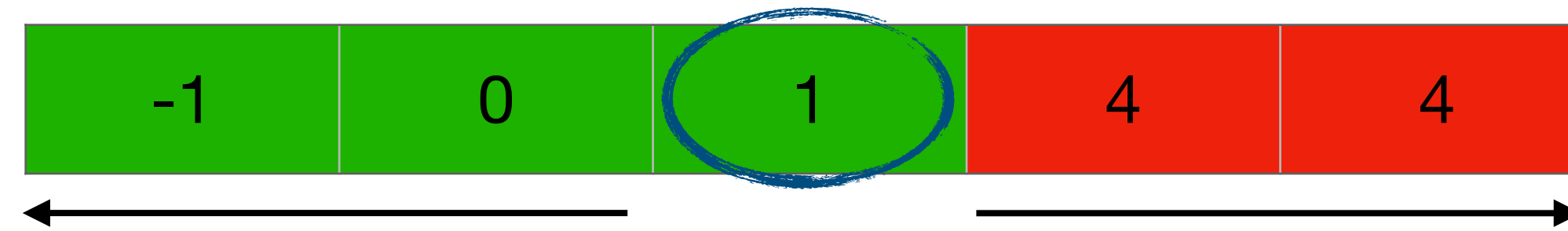
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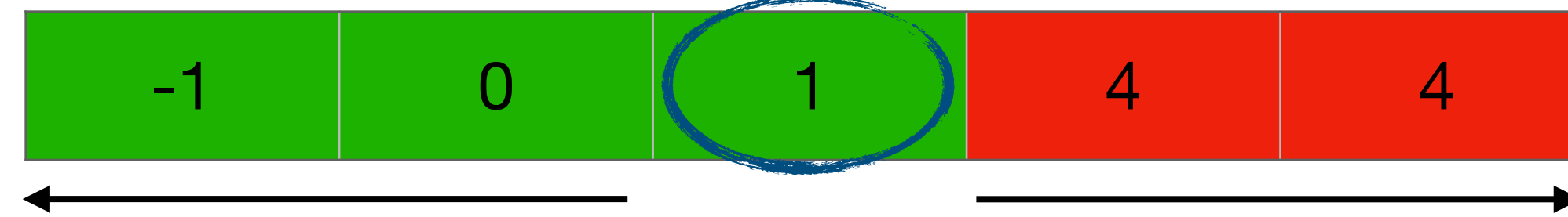
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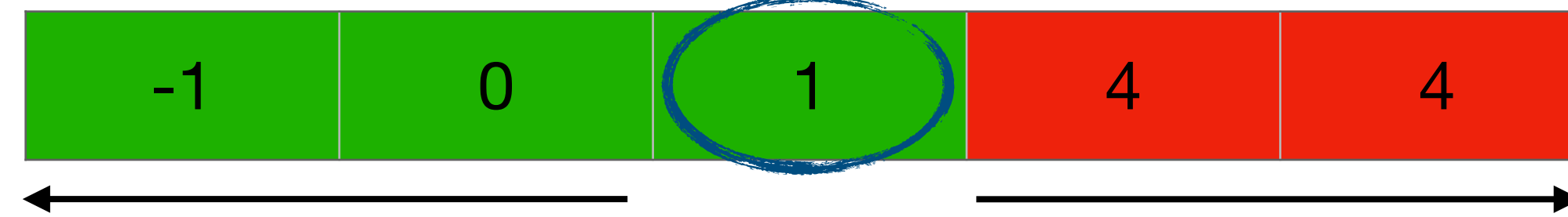
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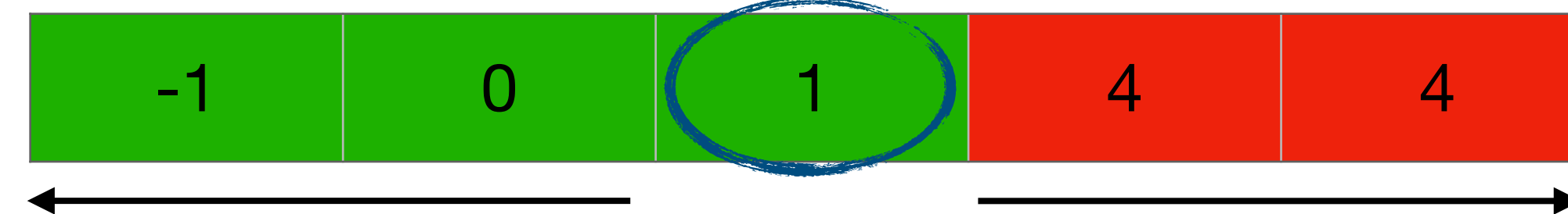
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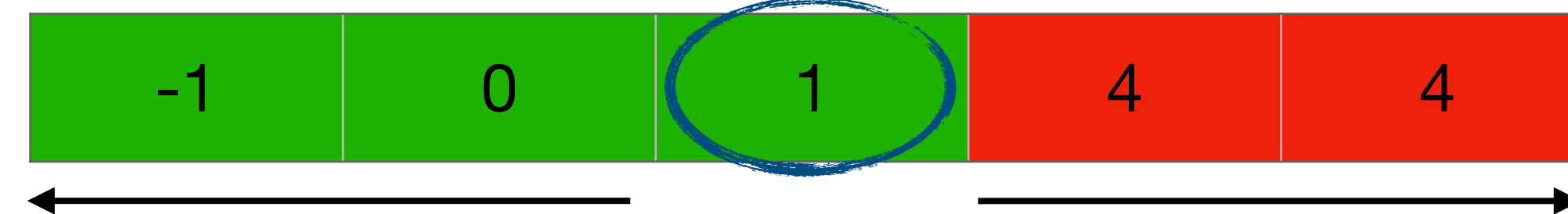
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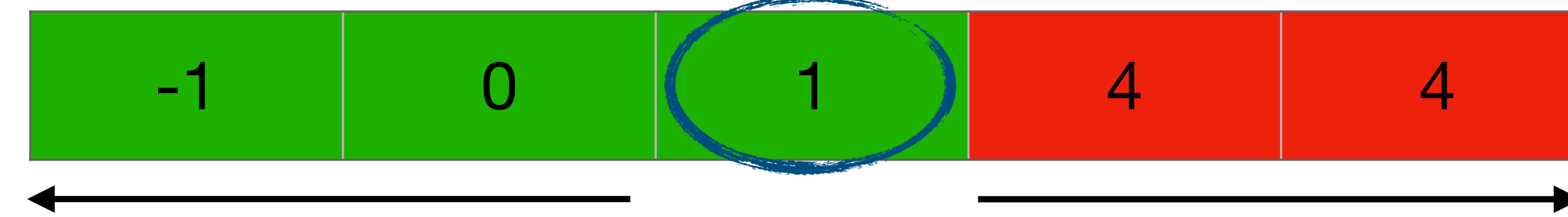


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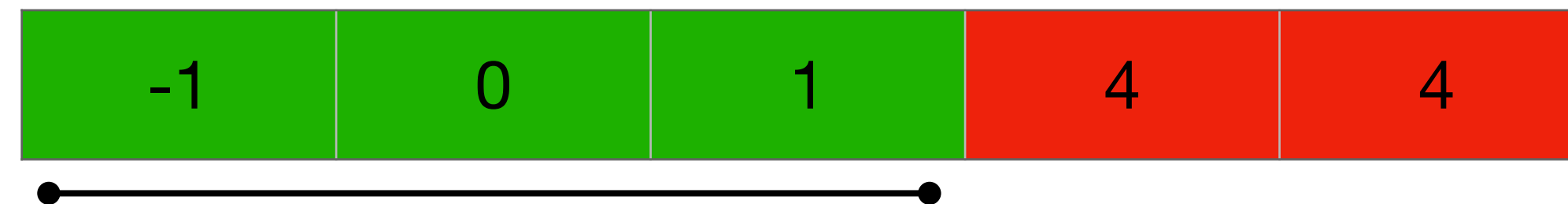
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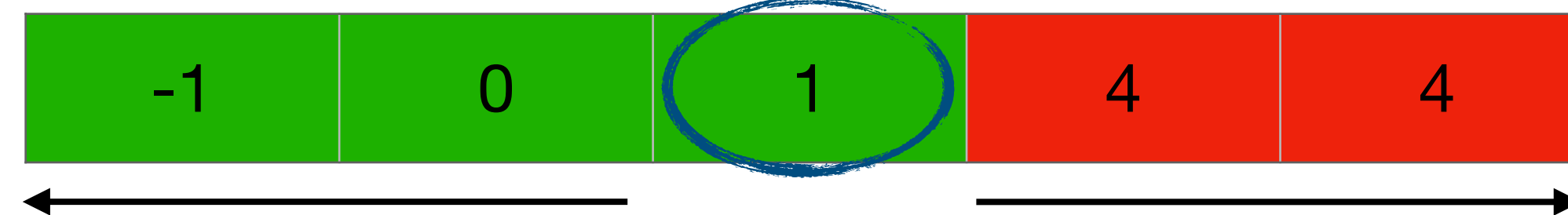


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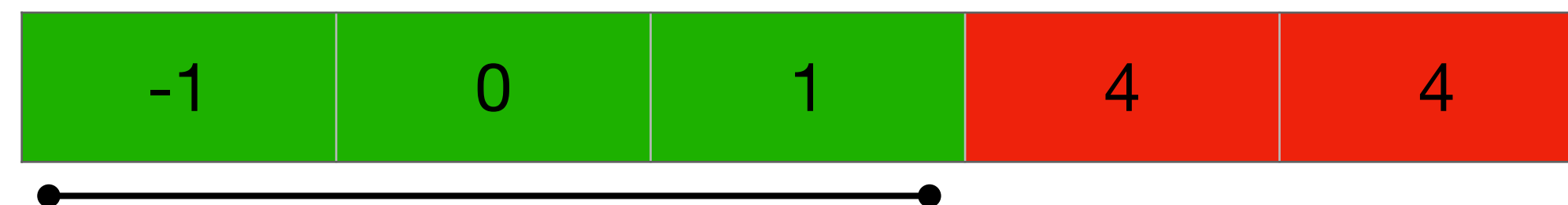
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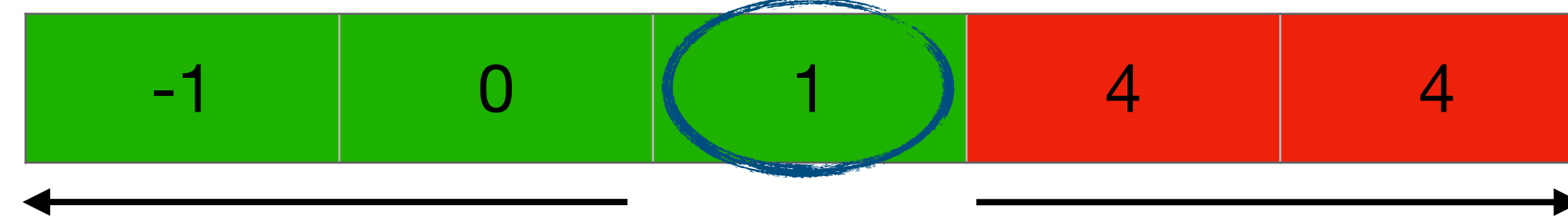
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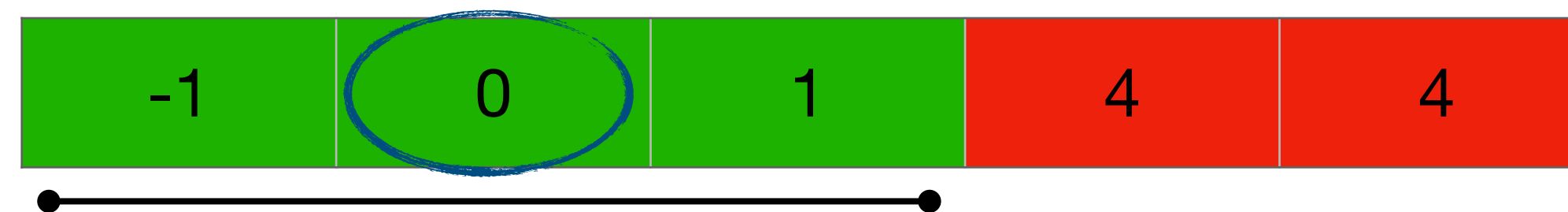
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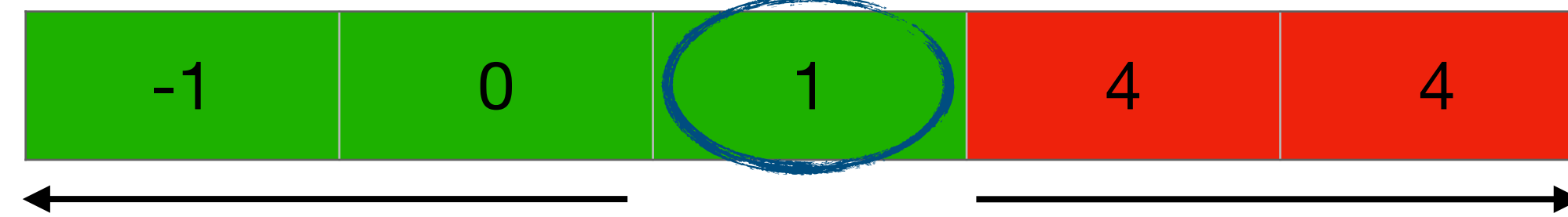


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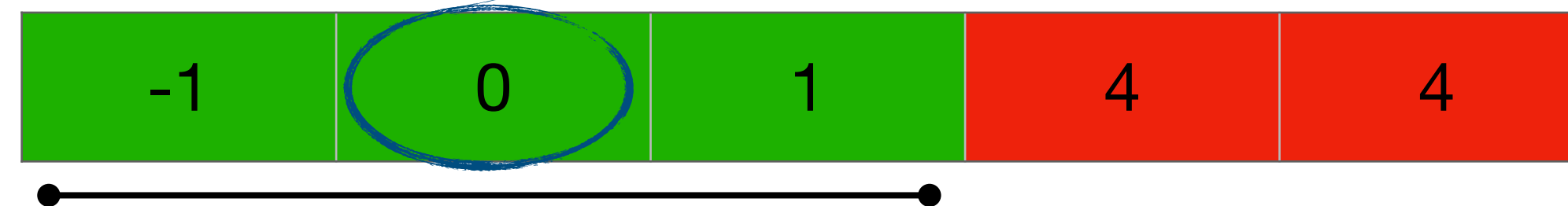
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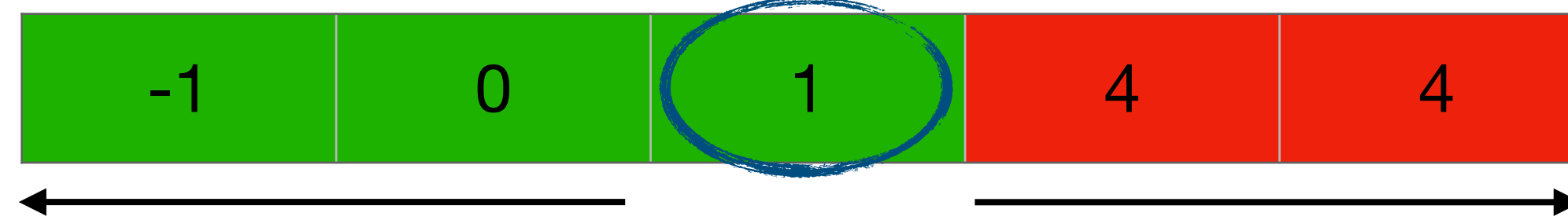
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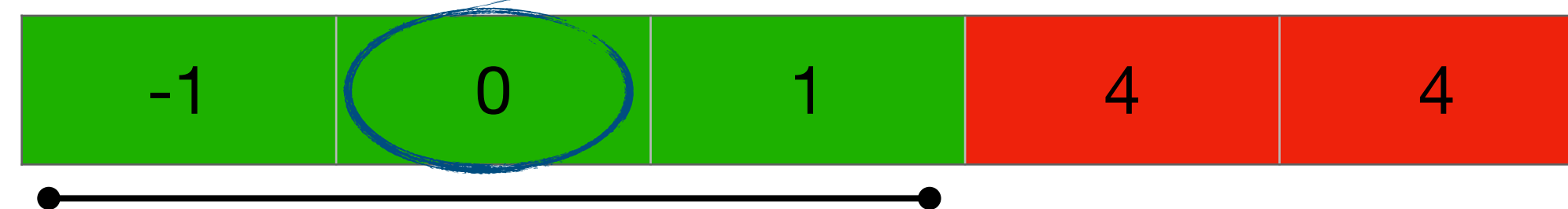
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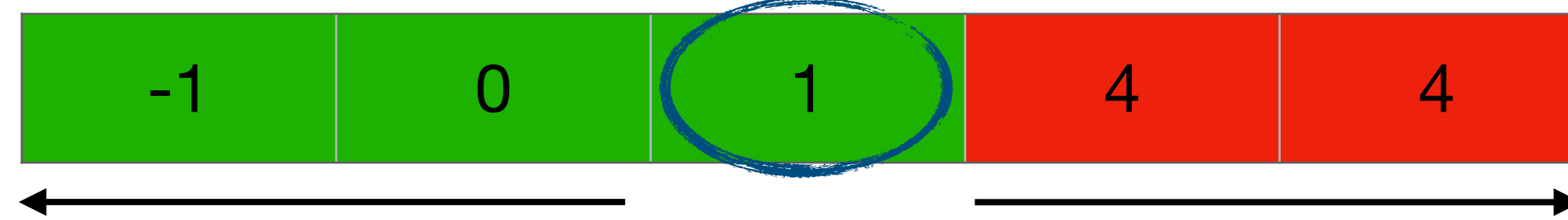
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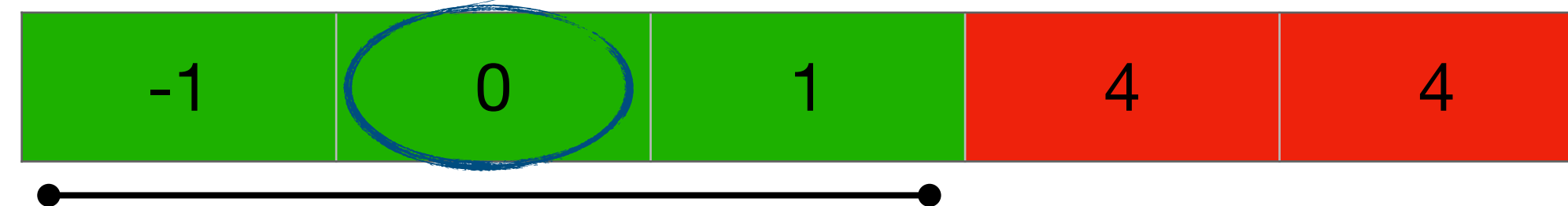
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* Very costly in high-dimension

Does Robust Aggregation Suffice

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Aggregation Rule/Scheme	Additional Assumption
Trimmed Mean <i>(Yin et al., 2018)</i>	Sub-exponential stochasticity
Geometric Median <i>(Chen et al., 2017)</i>	Sub-exponential stochasticity
Krum/multi-Krum <i>(Blanchard et al., 2017)</i>	Vanishing variance
Monitoring temporal averages of gradients <i>(Alistarh et al., 2018)</i>	(a.s.) Absolutely boundedness

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Most give resilience only against a small fraction of Byzantines $\ll 1/2$

Vulnerable due to Stringent Assumptions

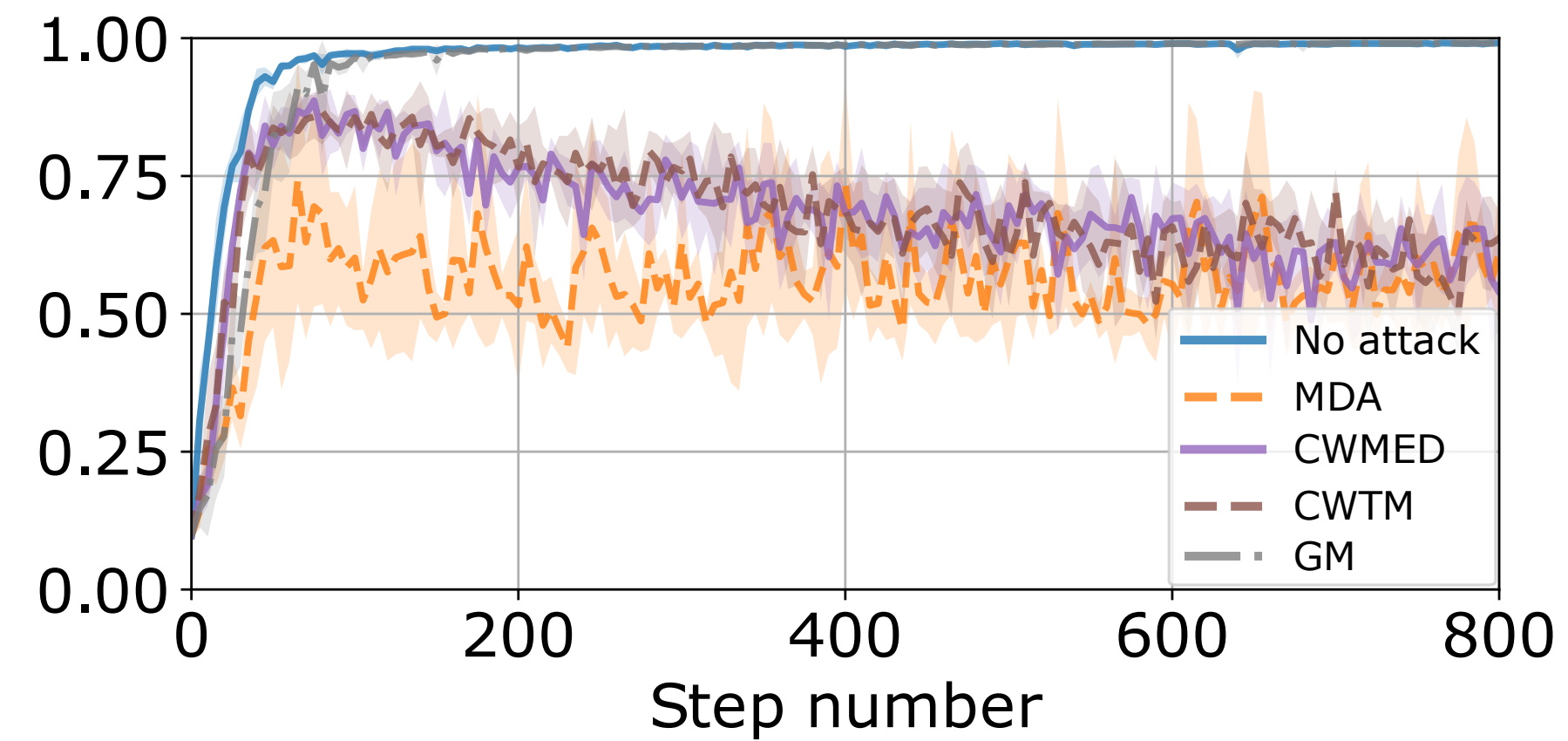
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5 out of 25 nodes are Byzantine faulty

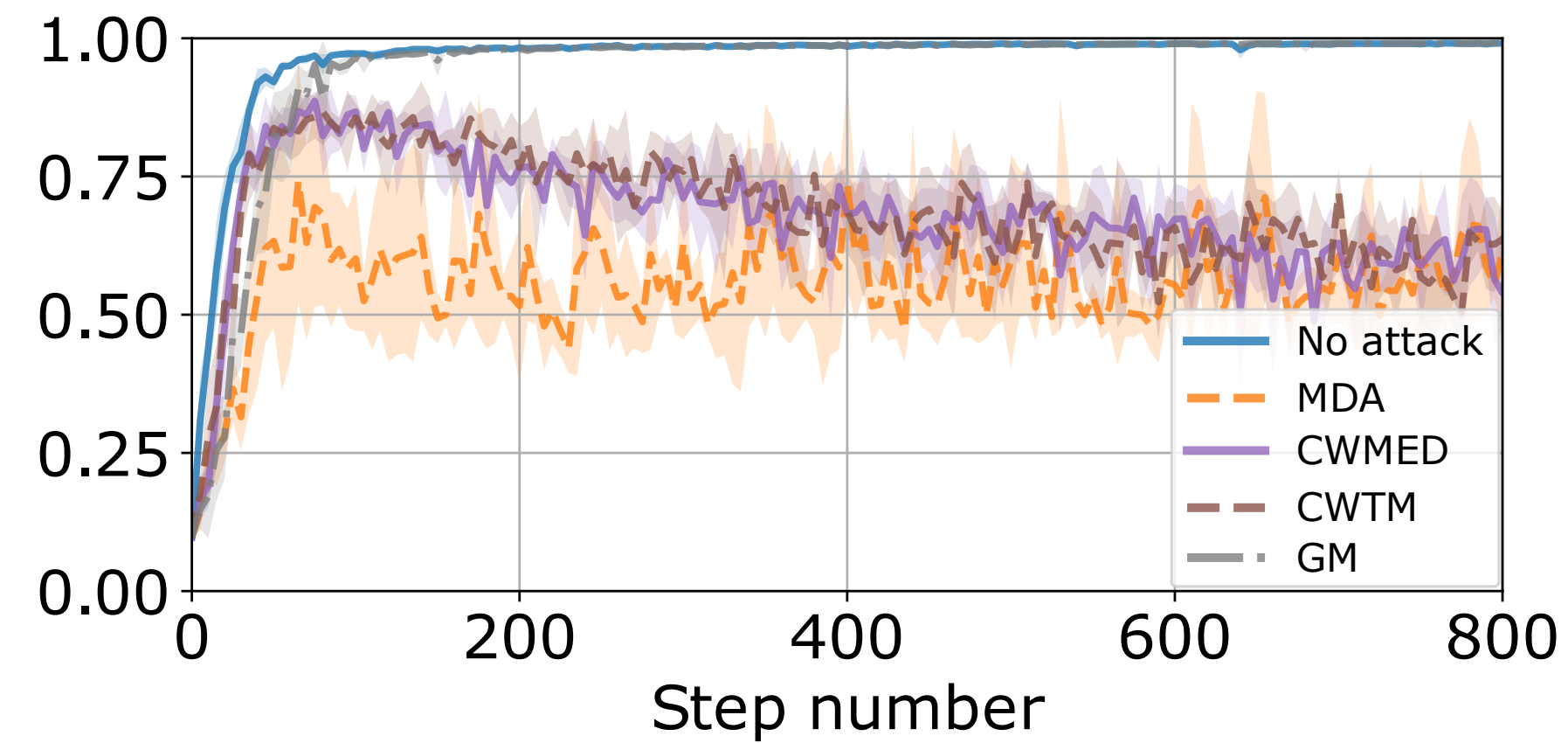
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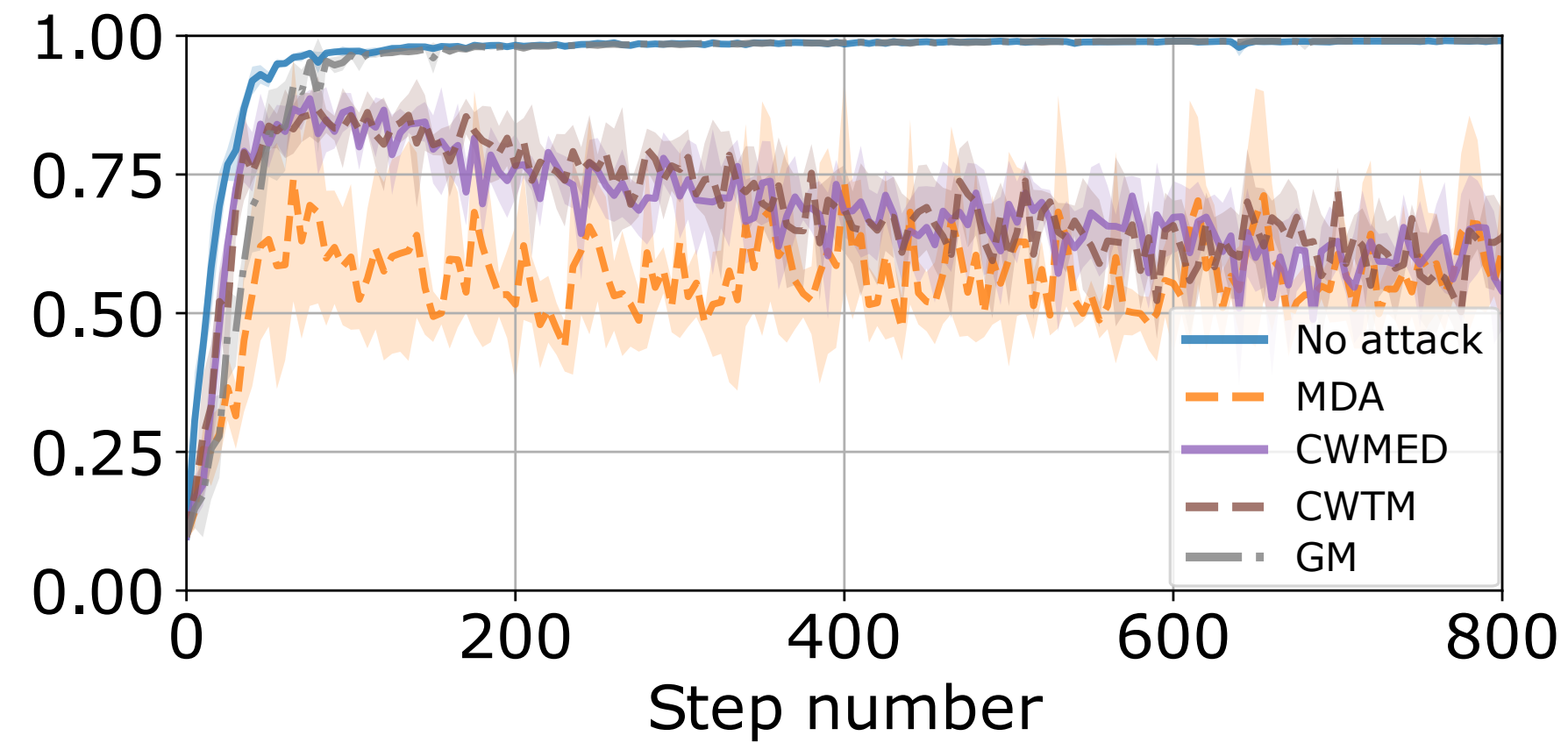
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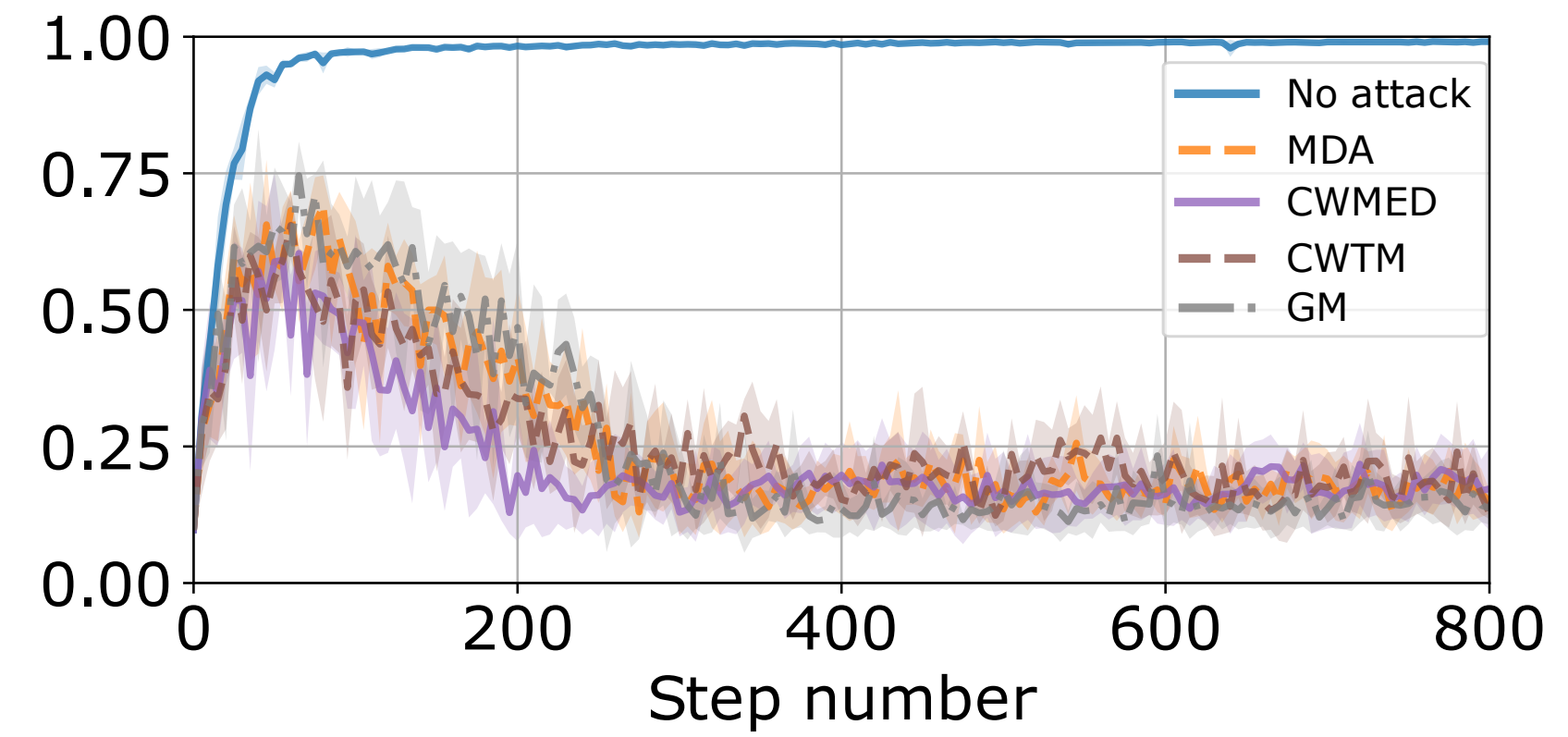
Label-flipping

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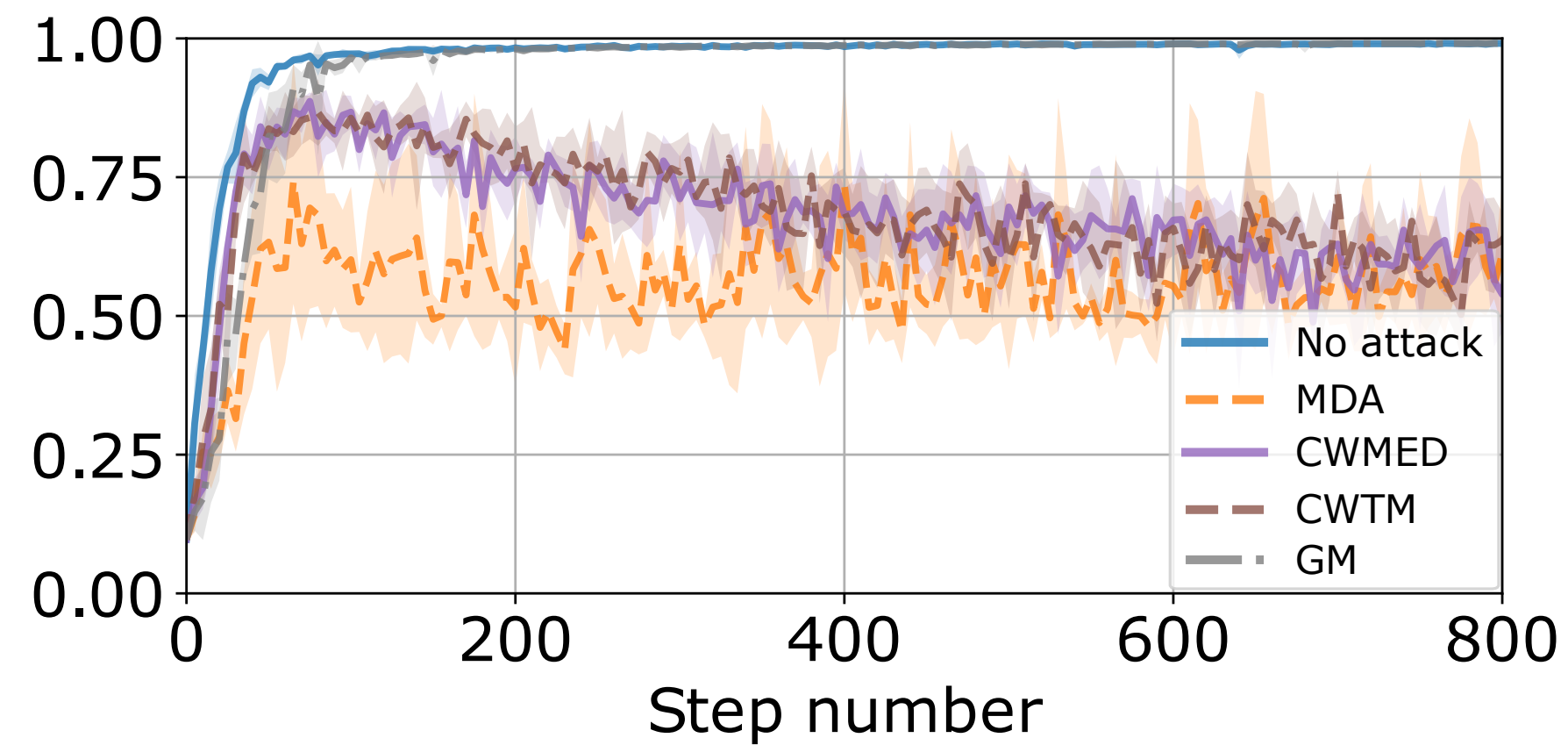


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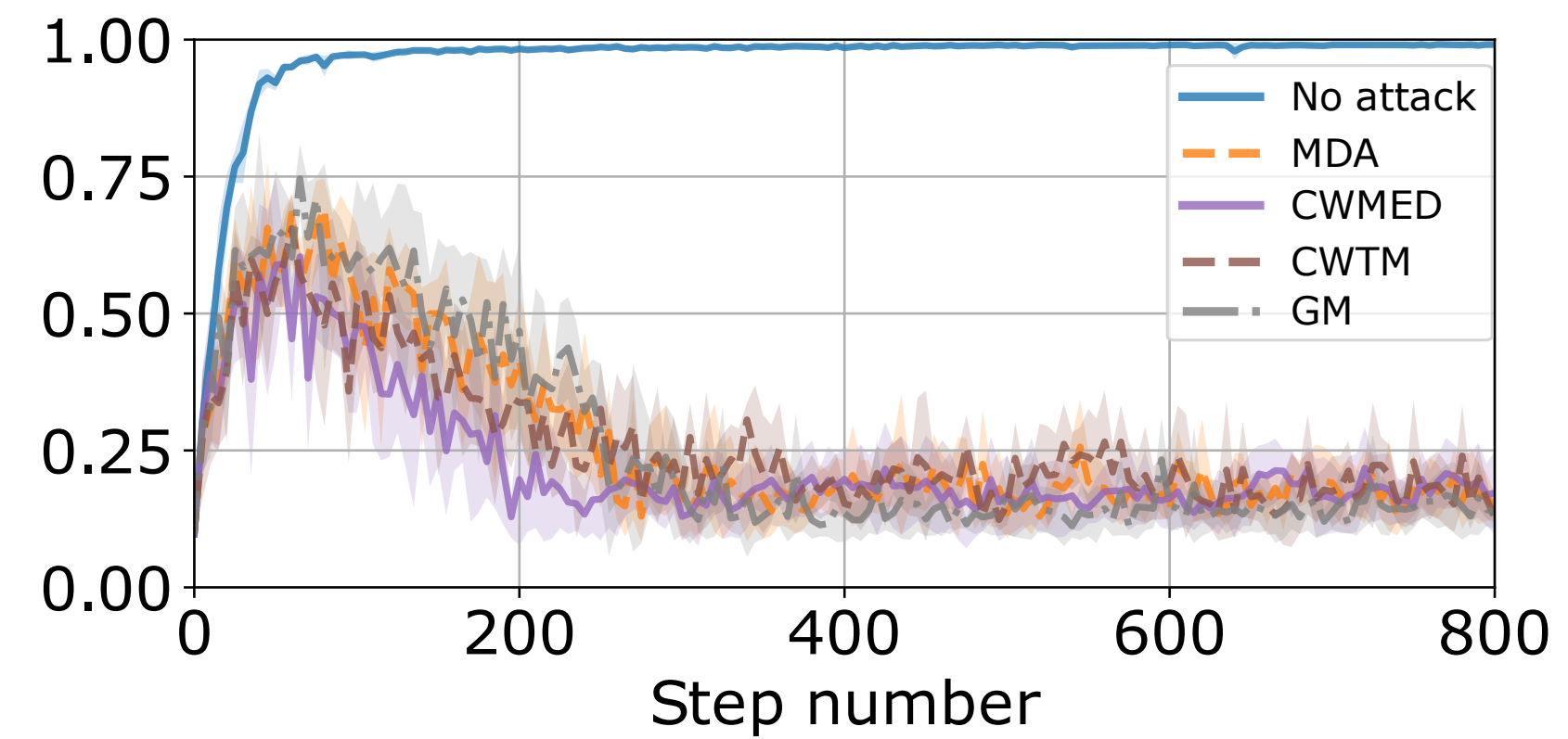


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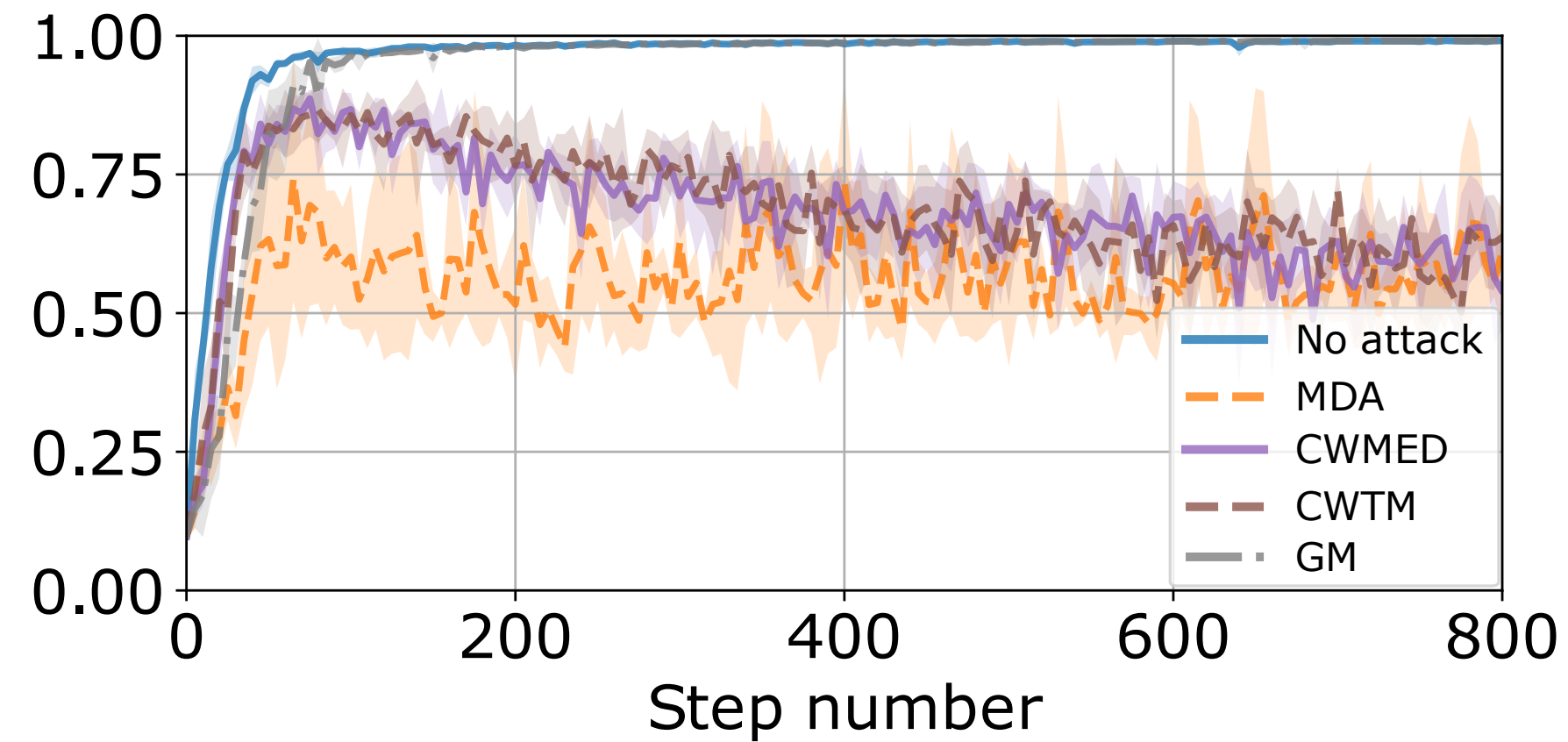
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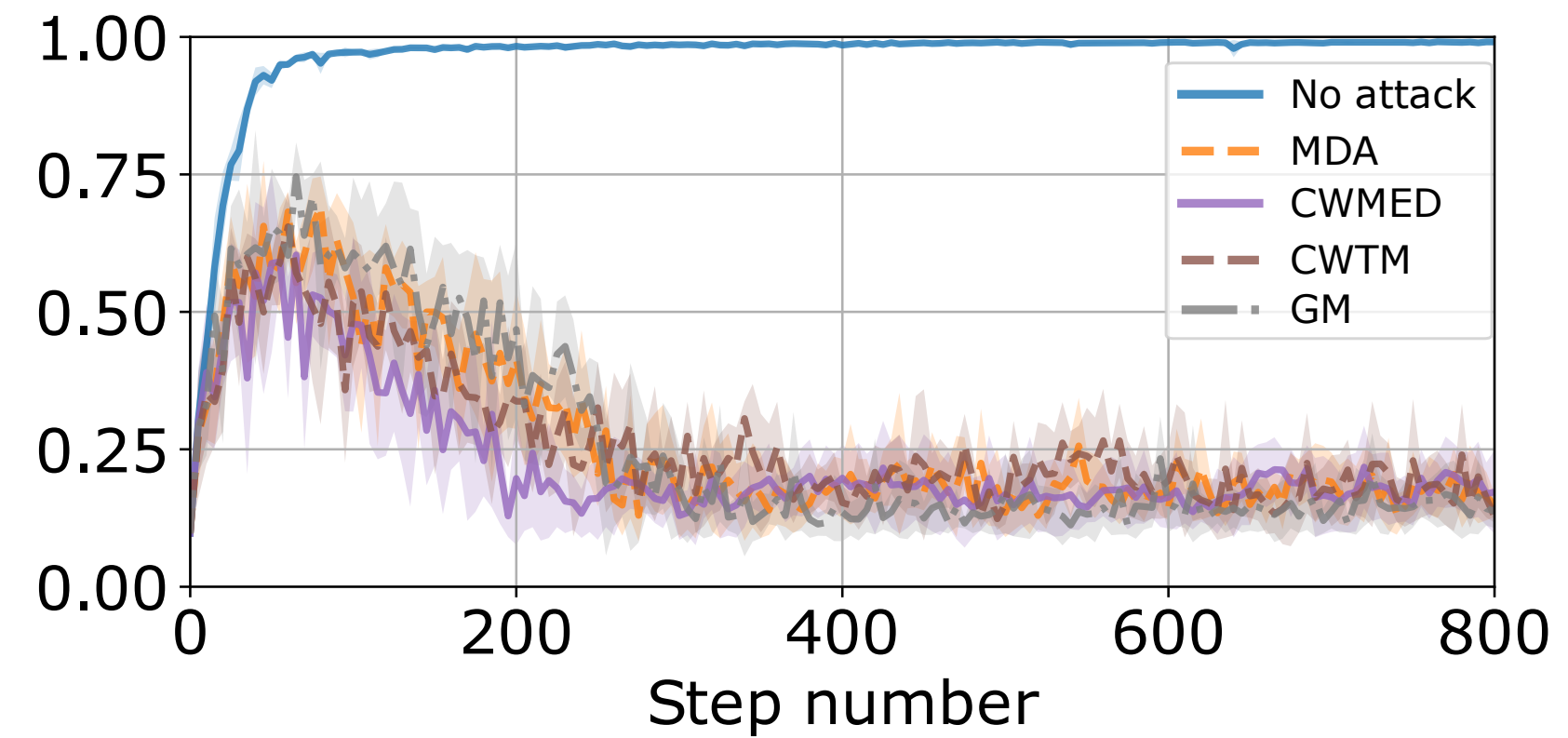
Little is enough (*Baruch et al., 2019*)

Vulnerable due to Stringent Assumptions

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Little is enough (*Baruch et al., 2019*)

Memoryless robust aggregation need not be sufficient (*Karimireddy et al., 2021*)

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Non-trivial variance of stochastic gradients

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θ_t

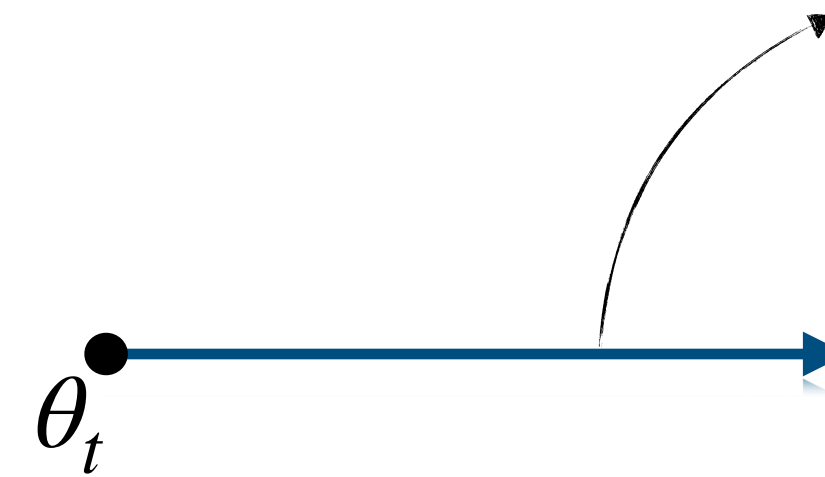
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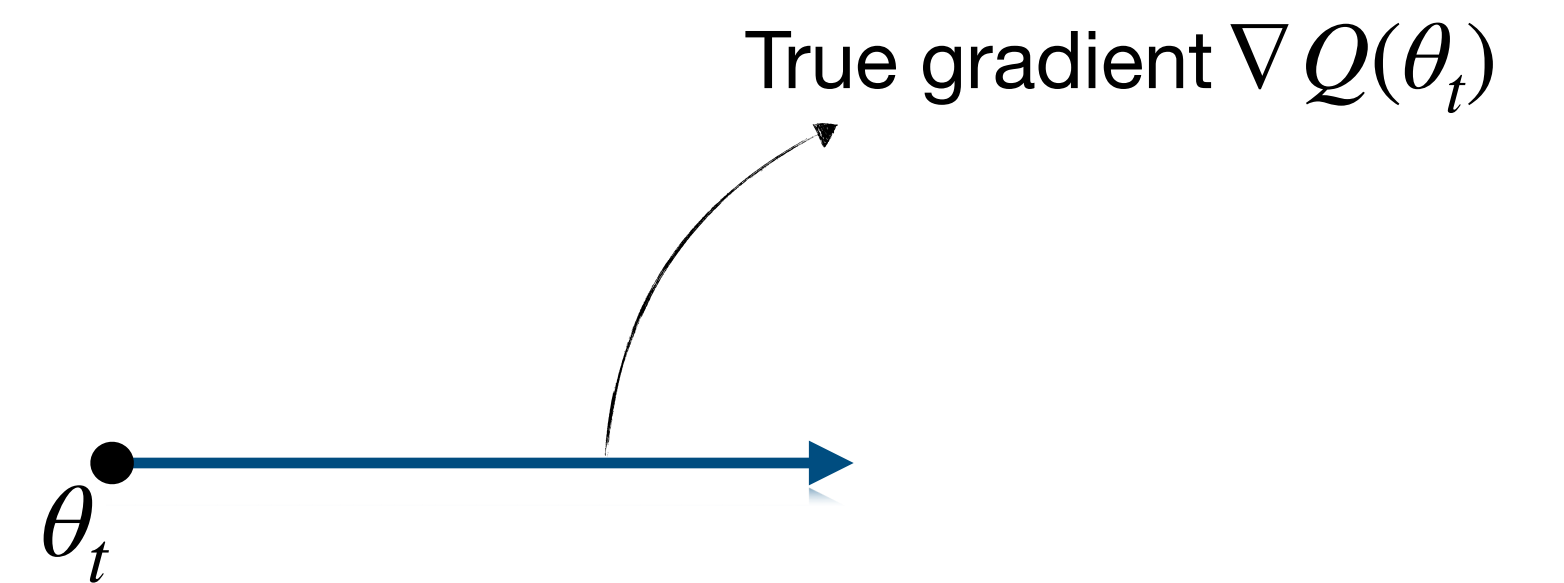
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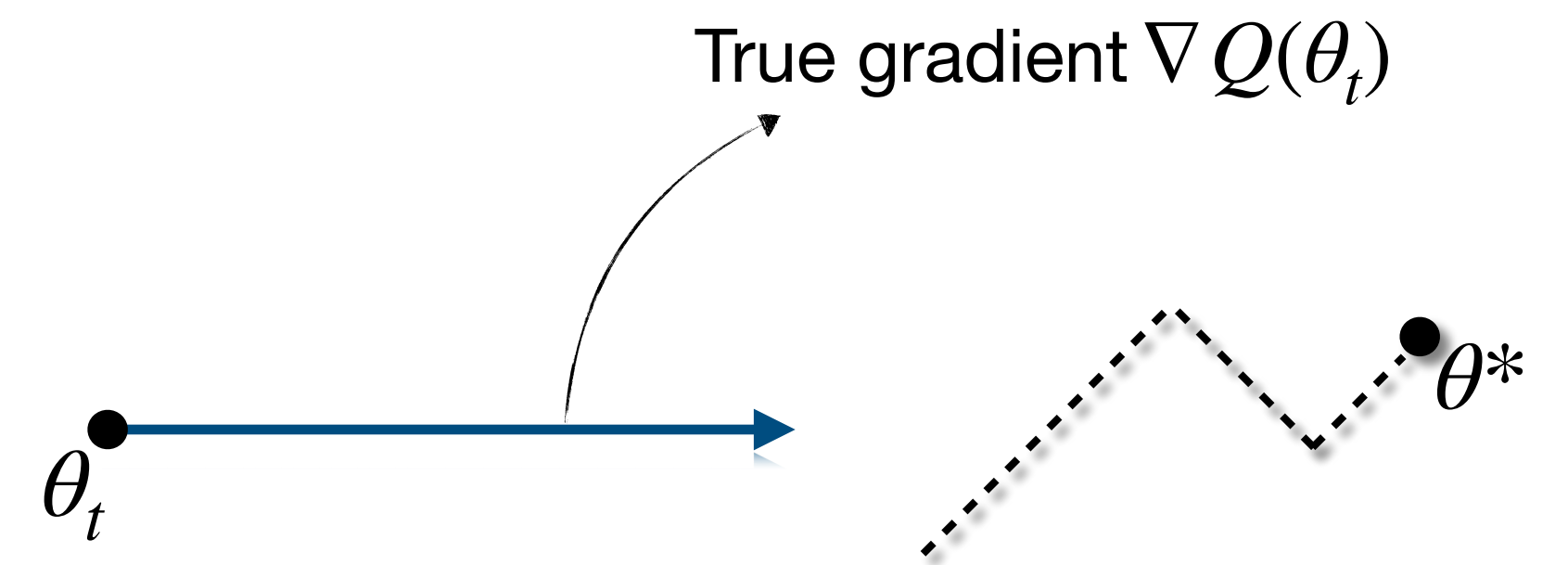
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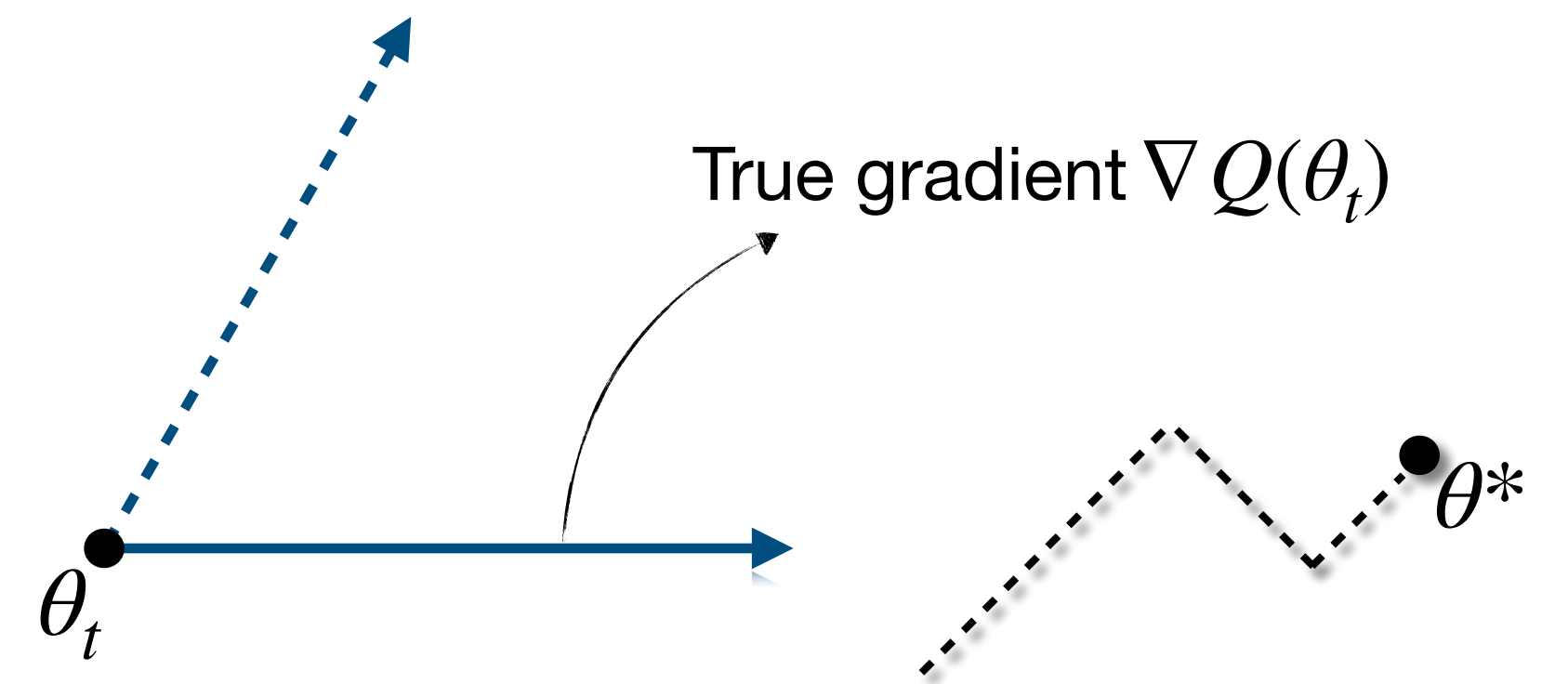
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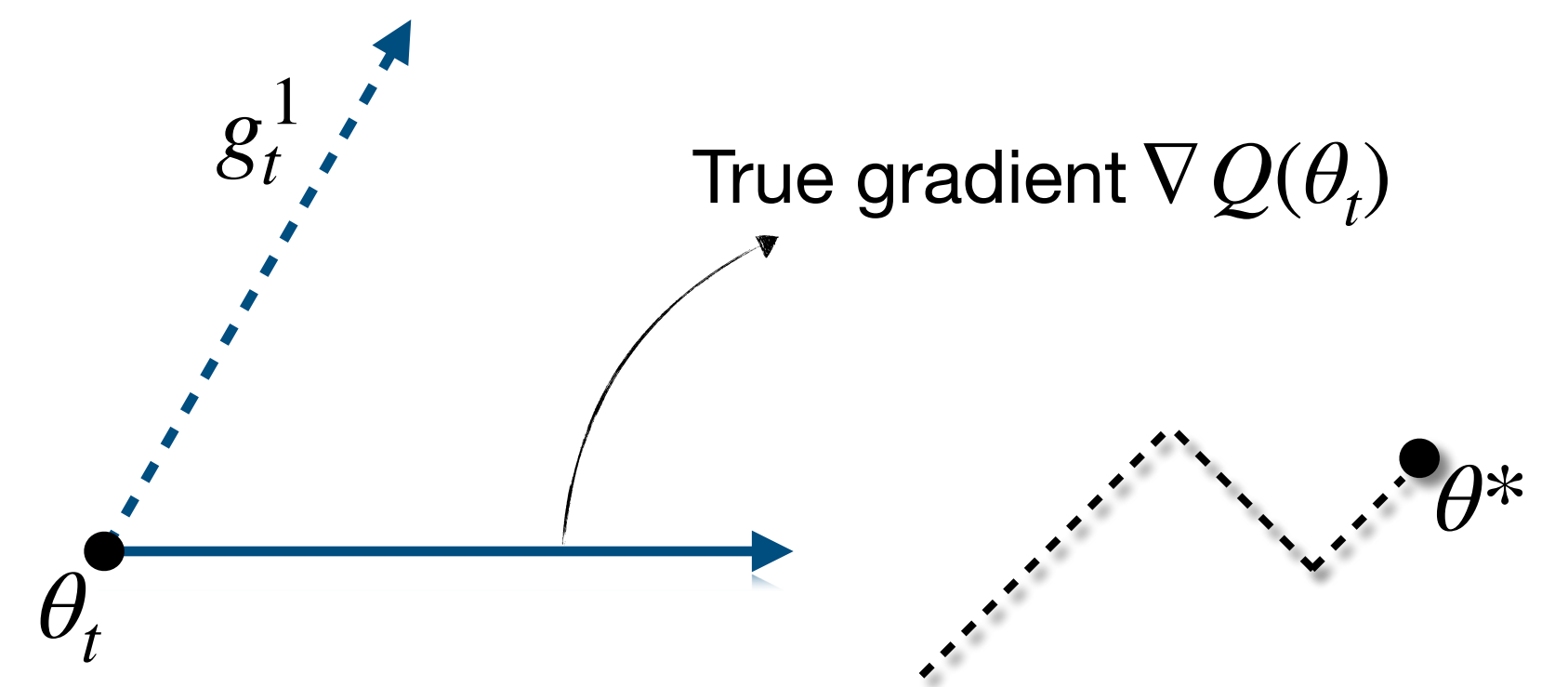
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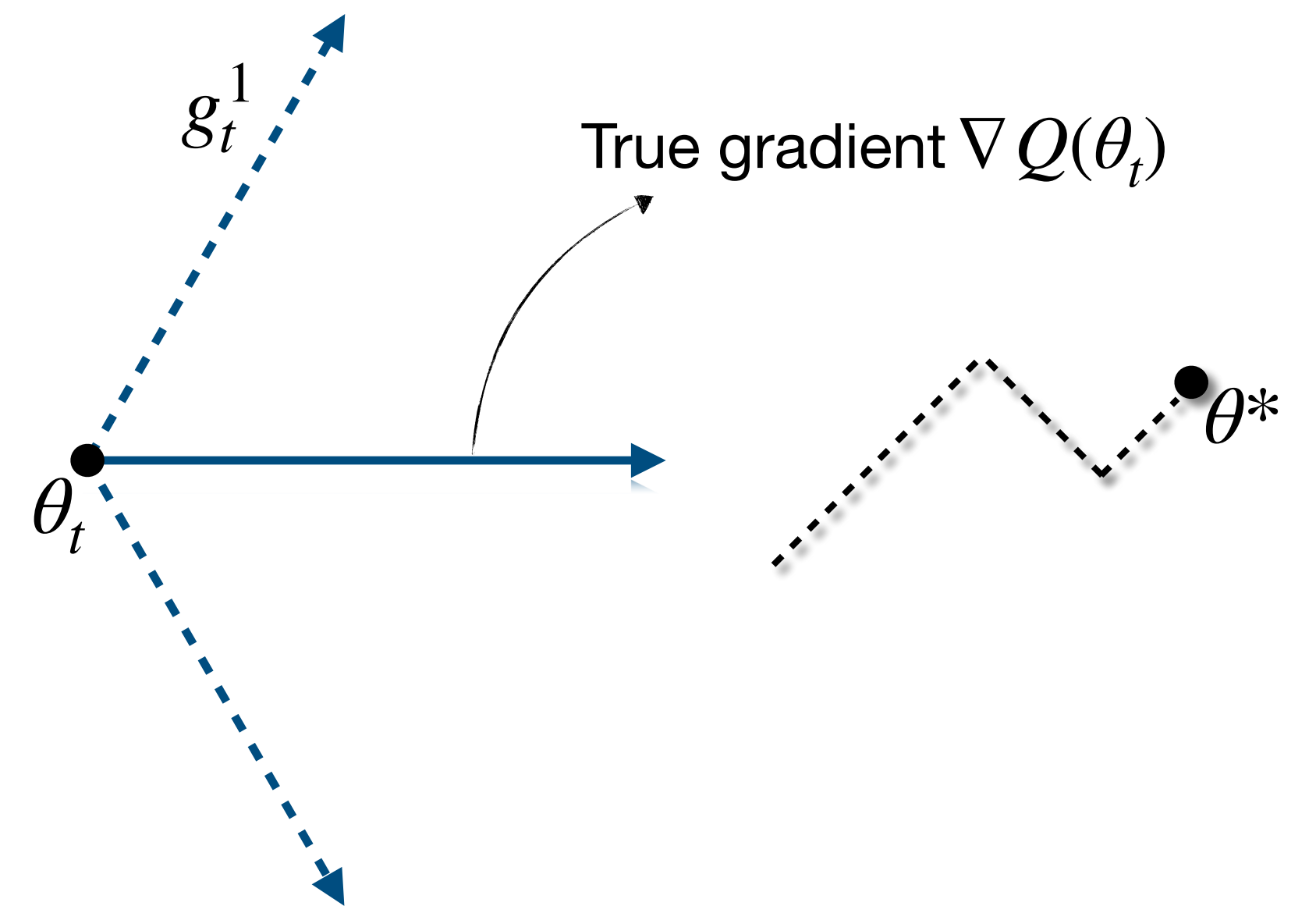
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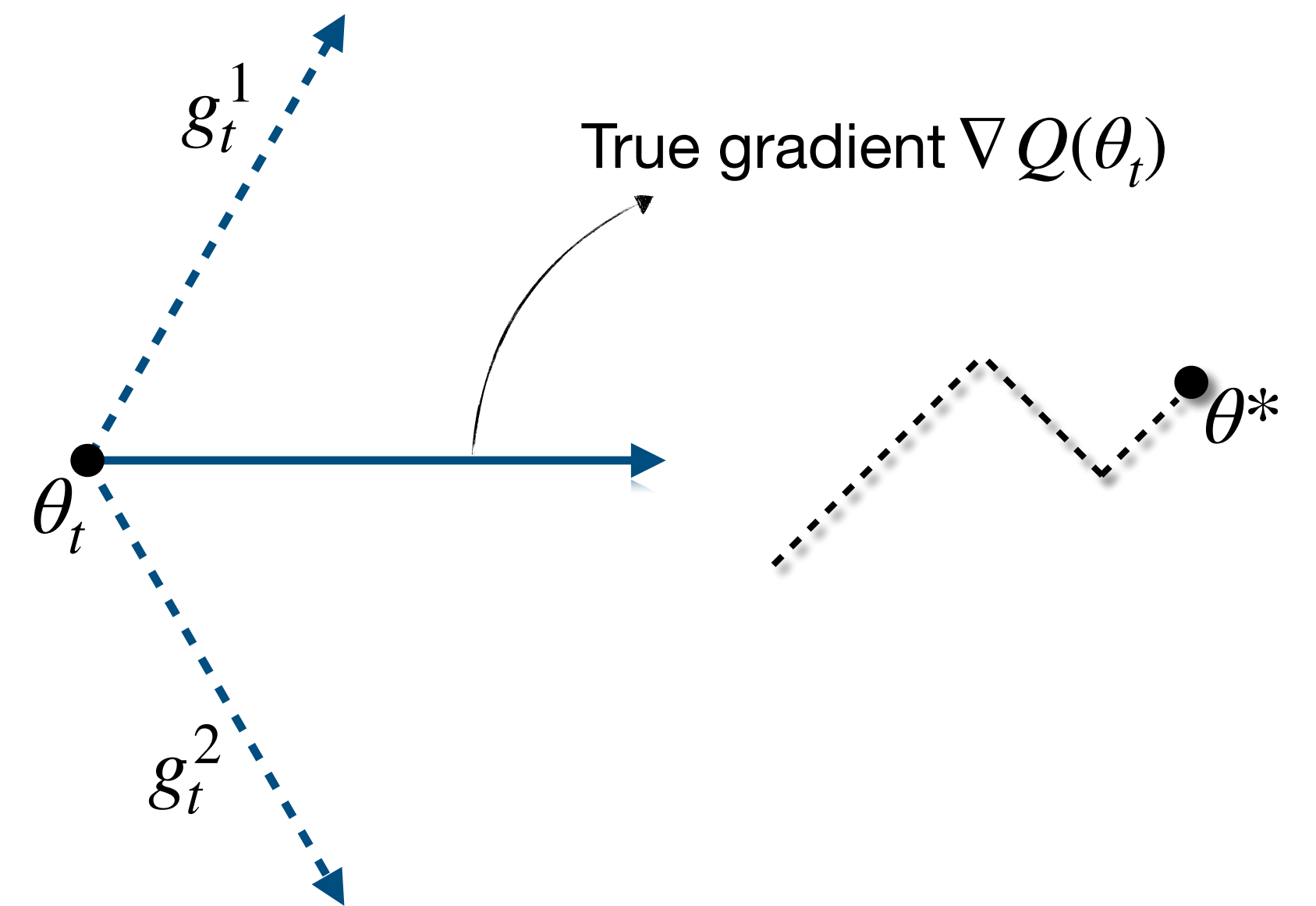
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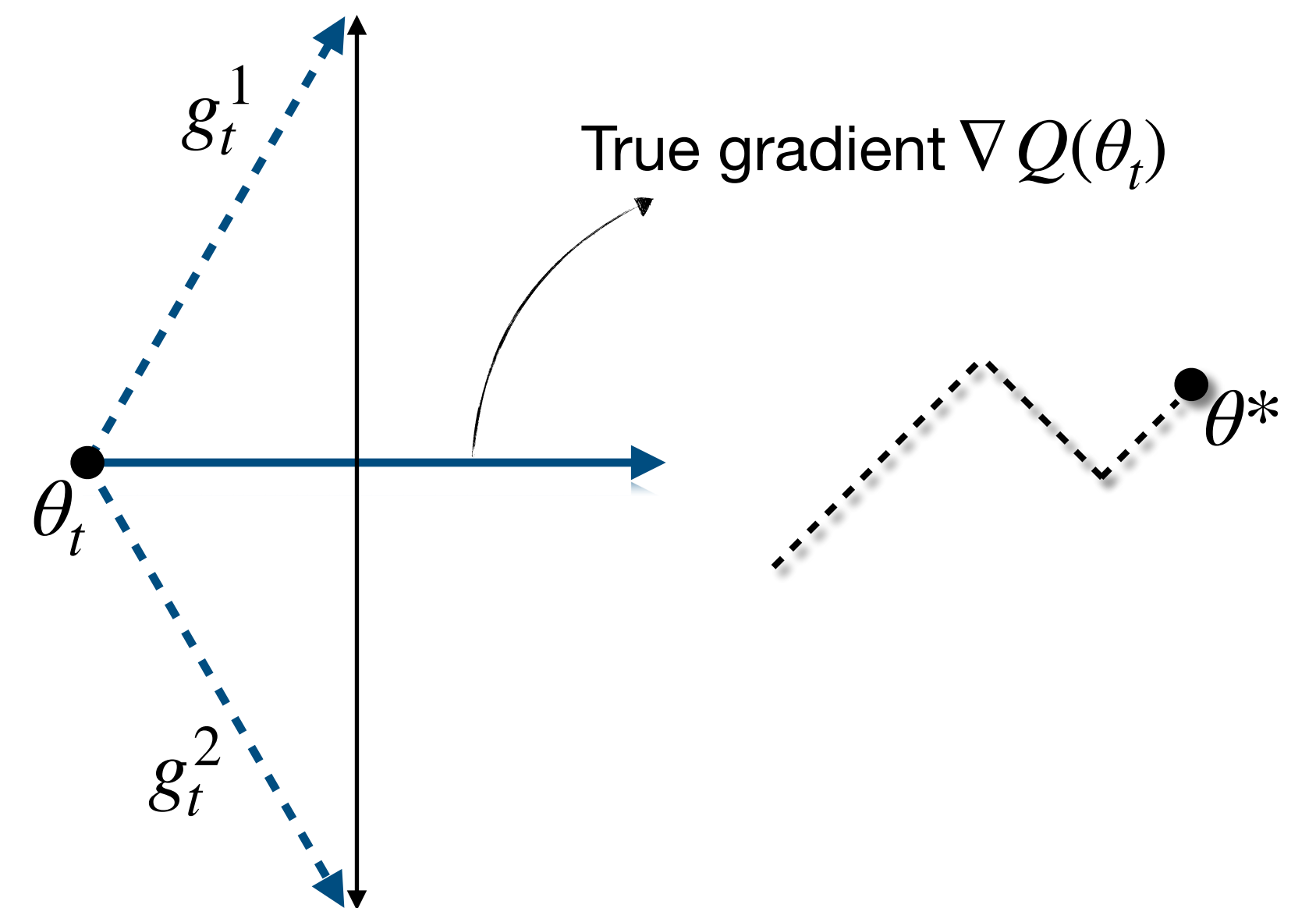
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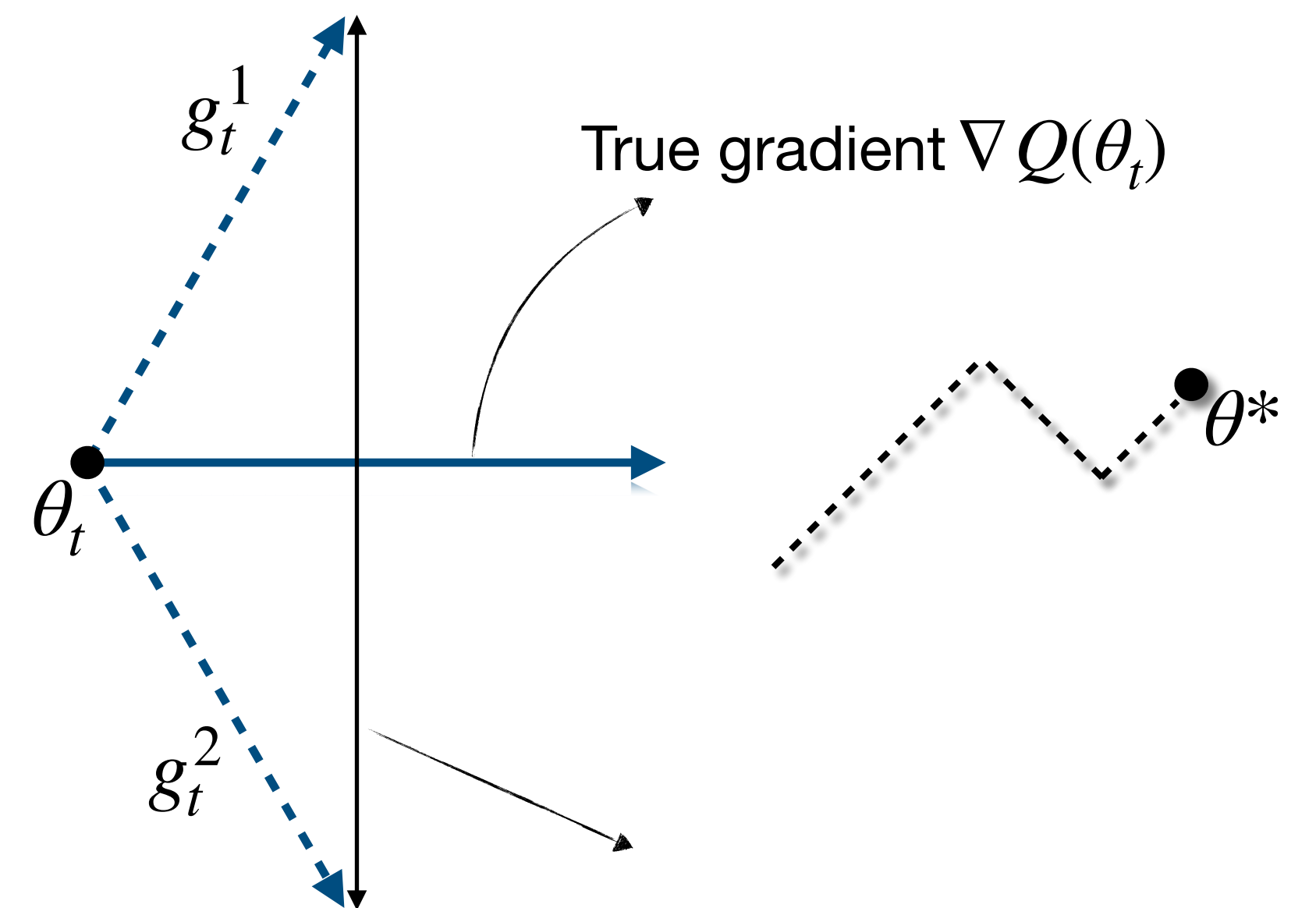
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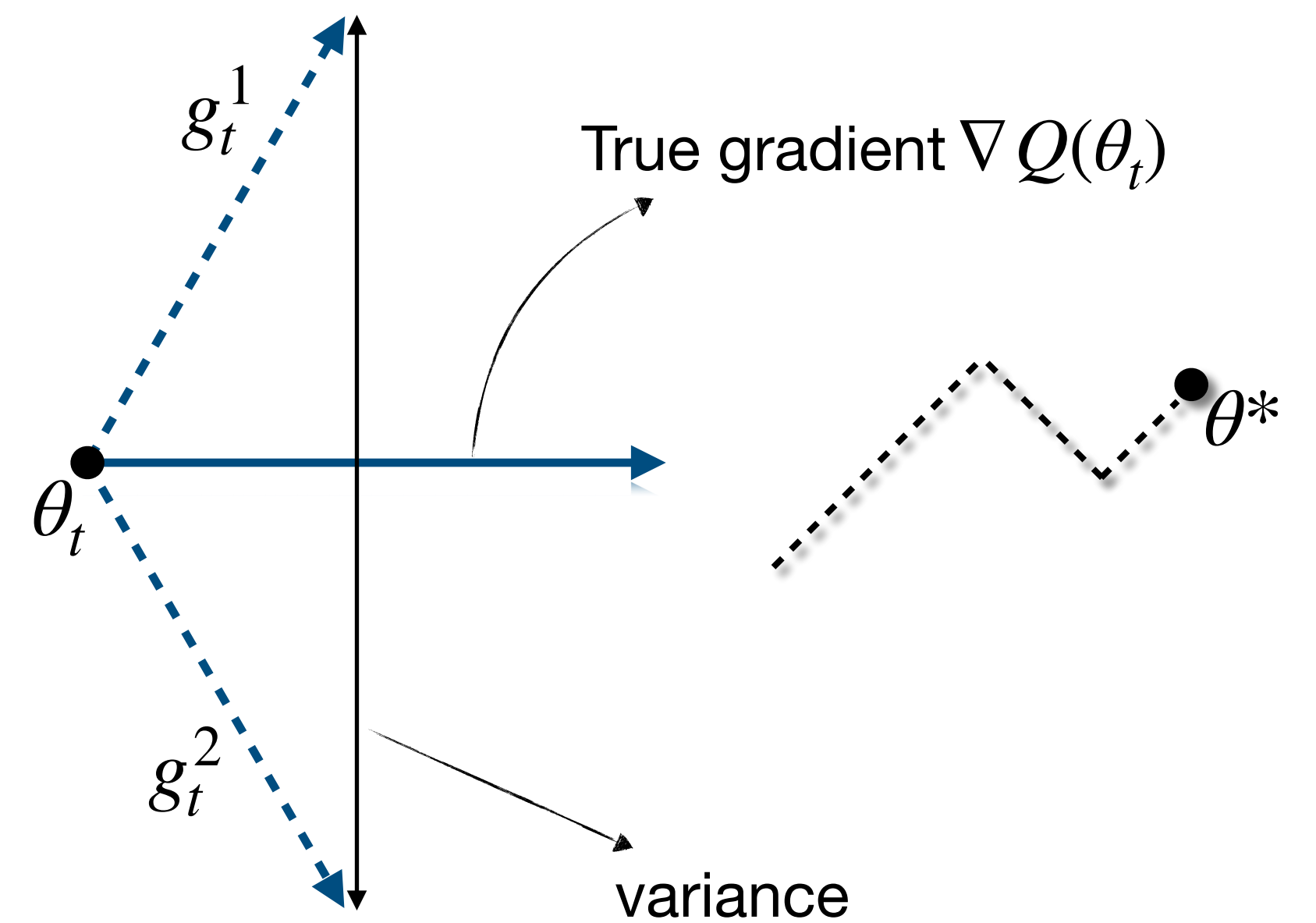
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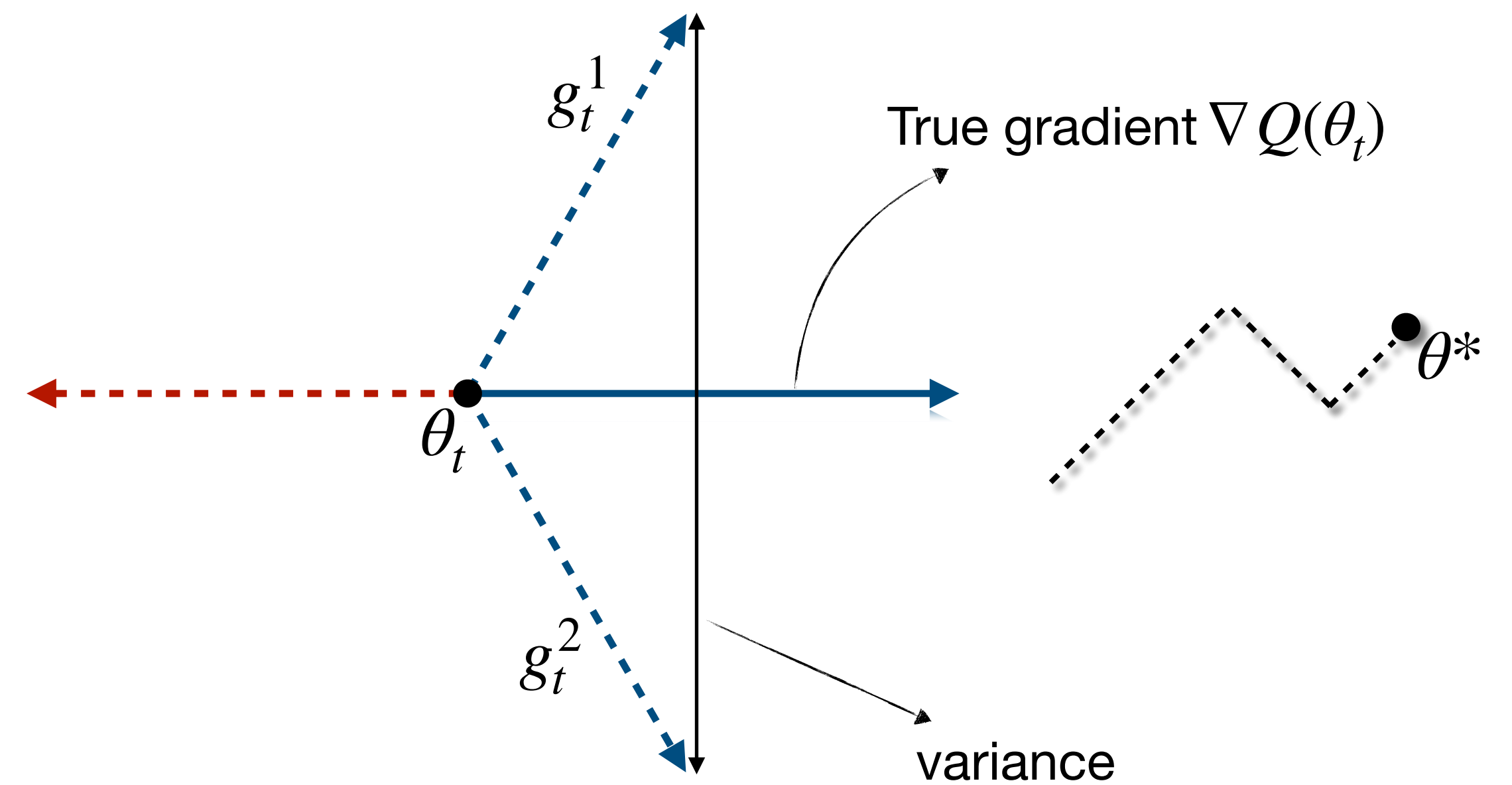
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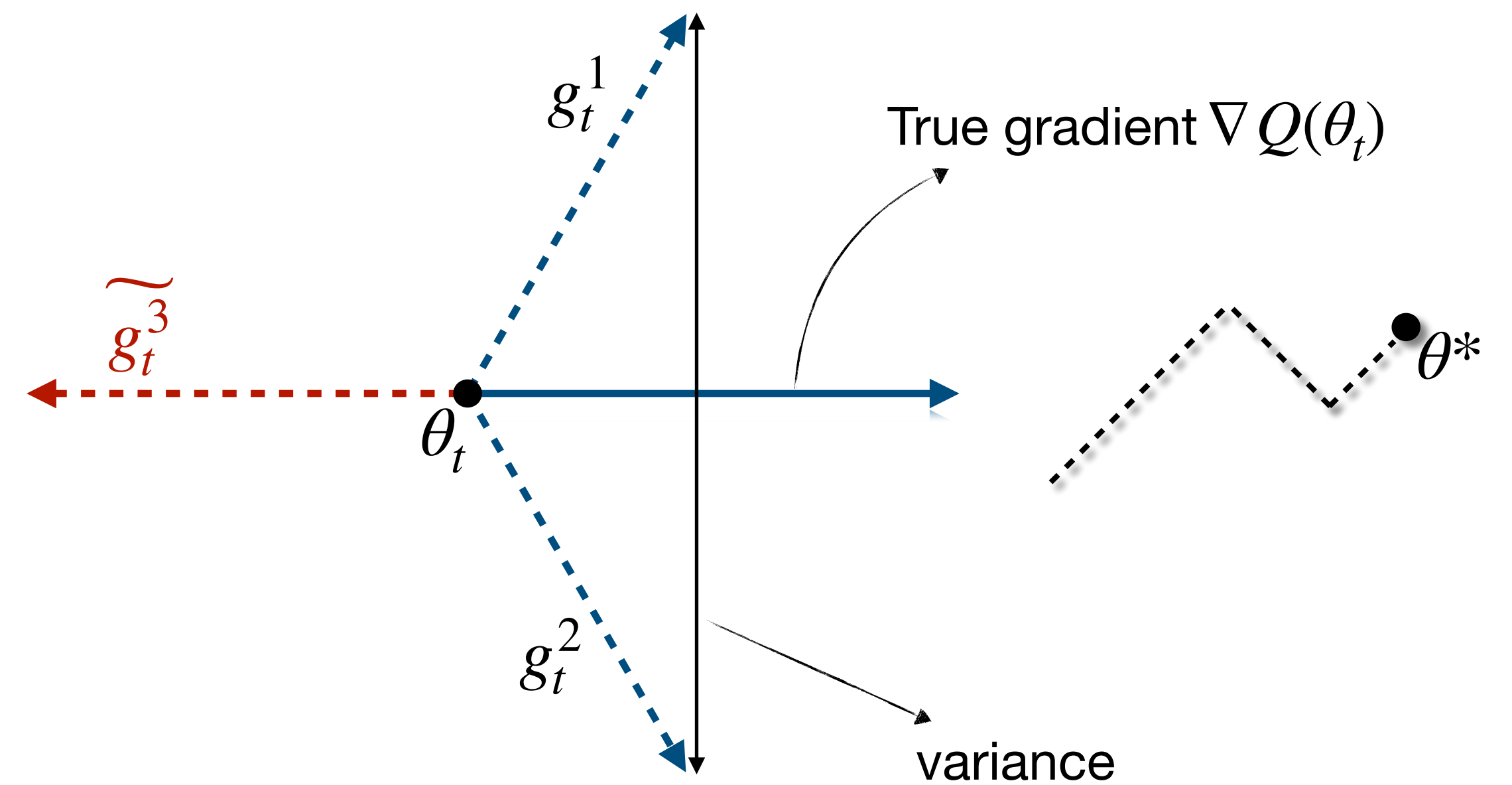
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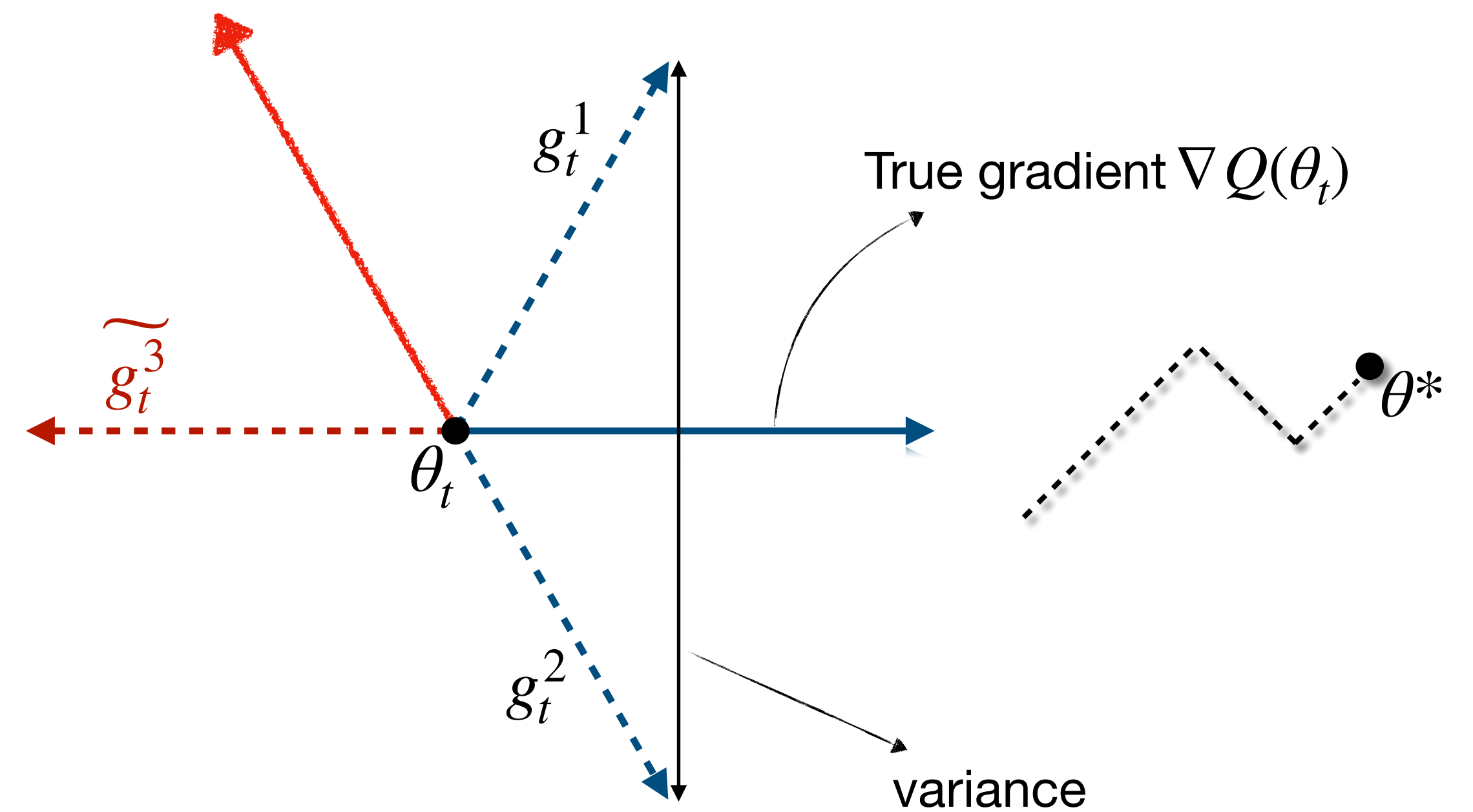
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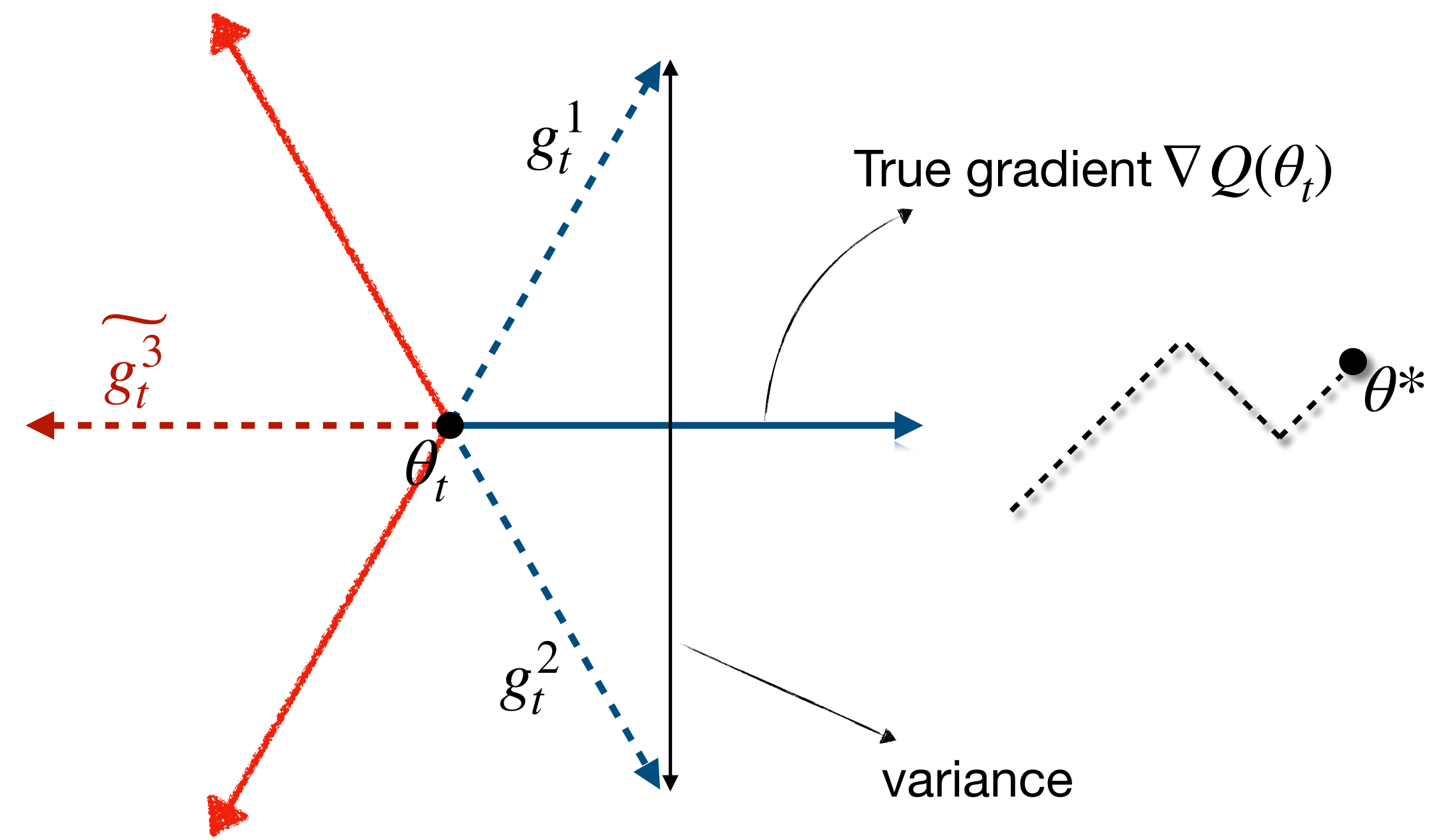
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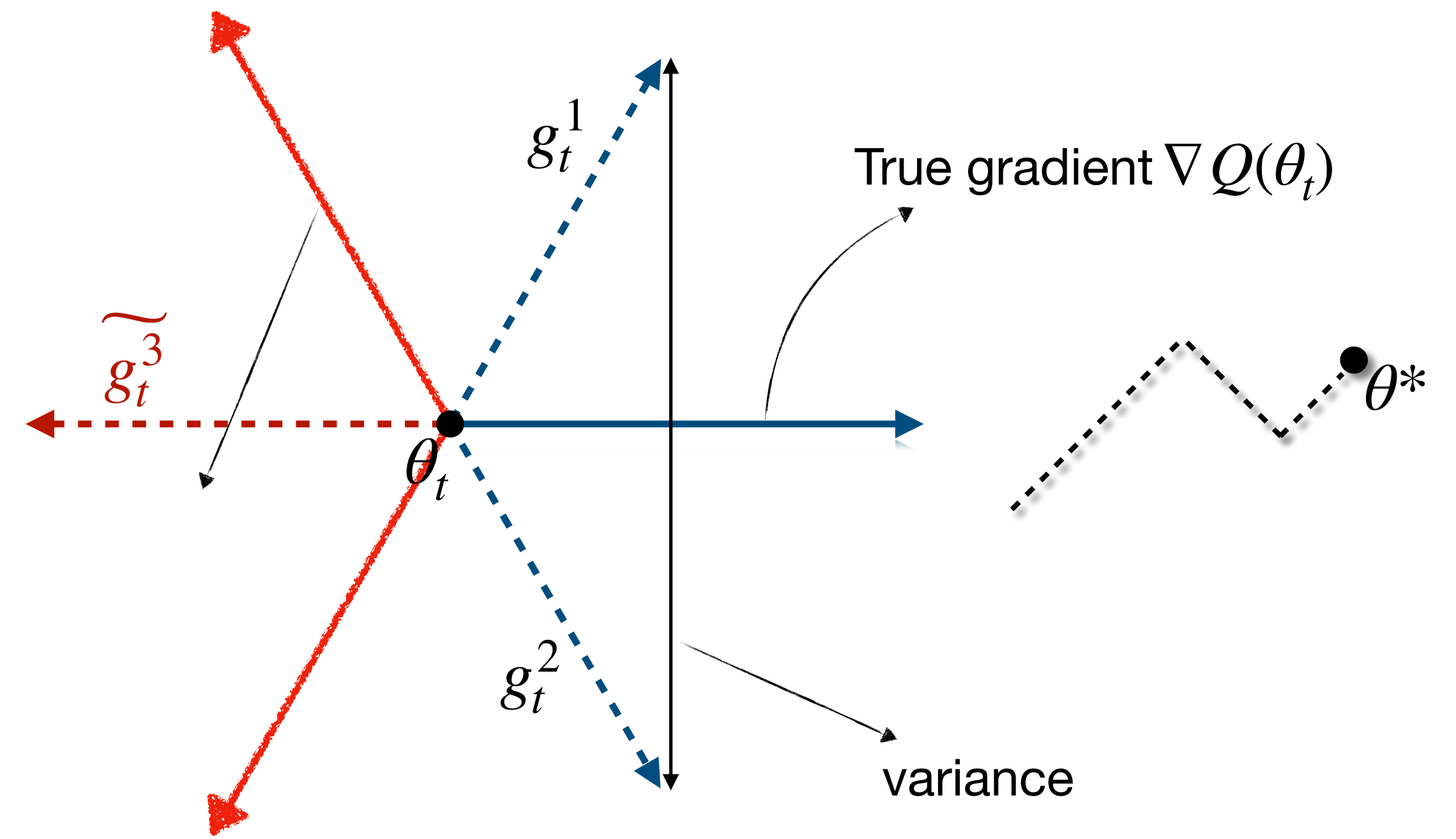
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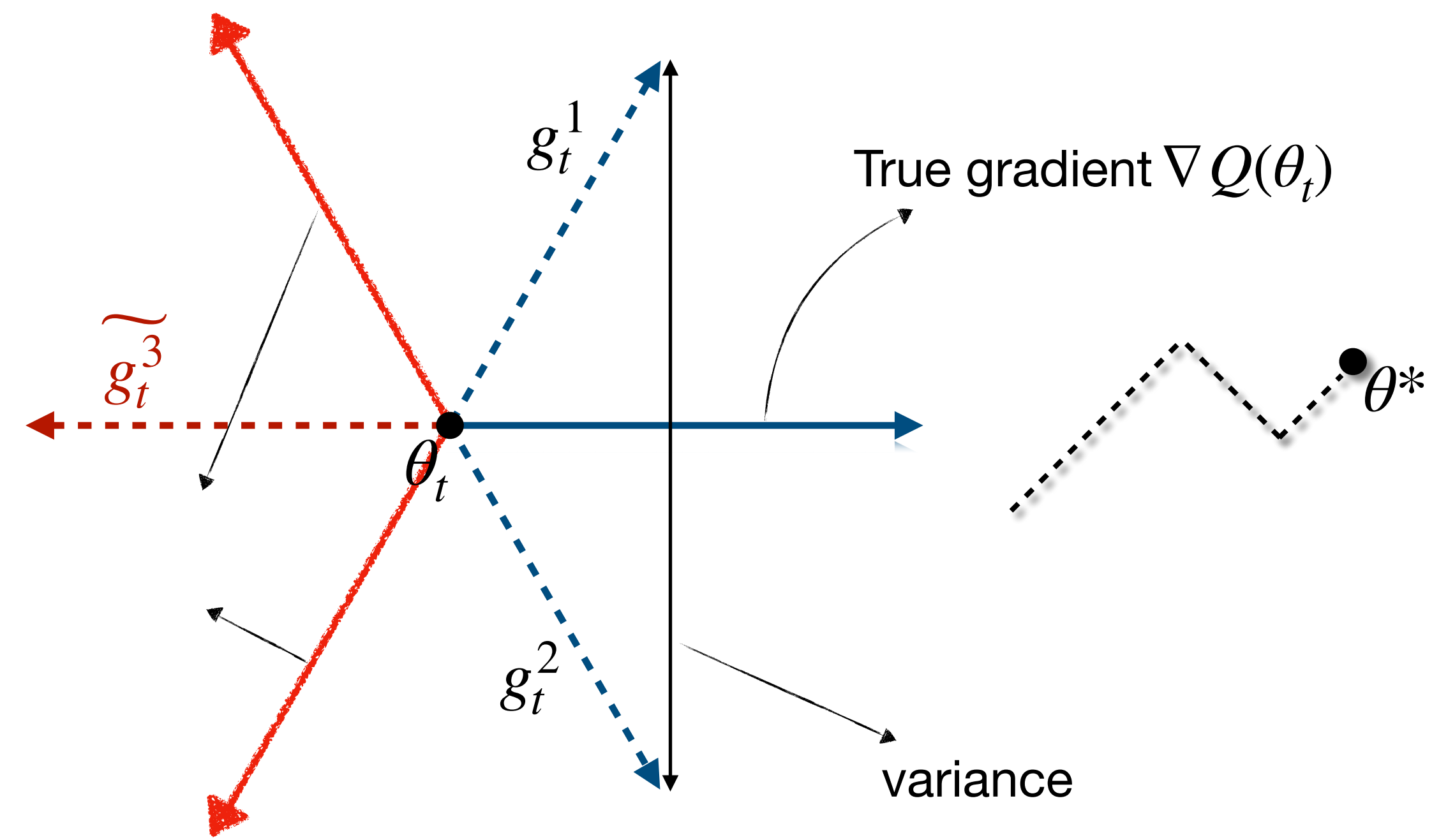
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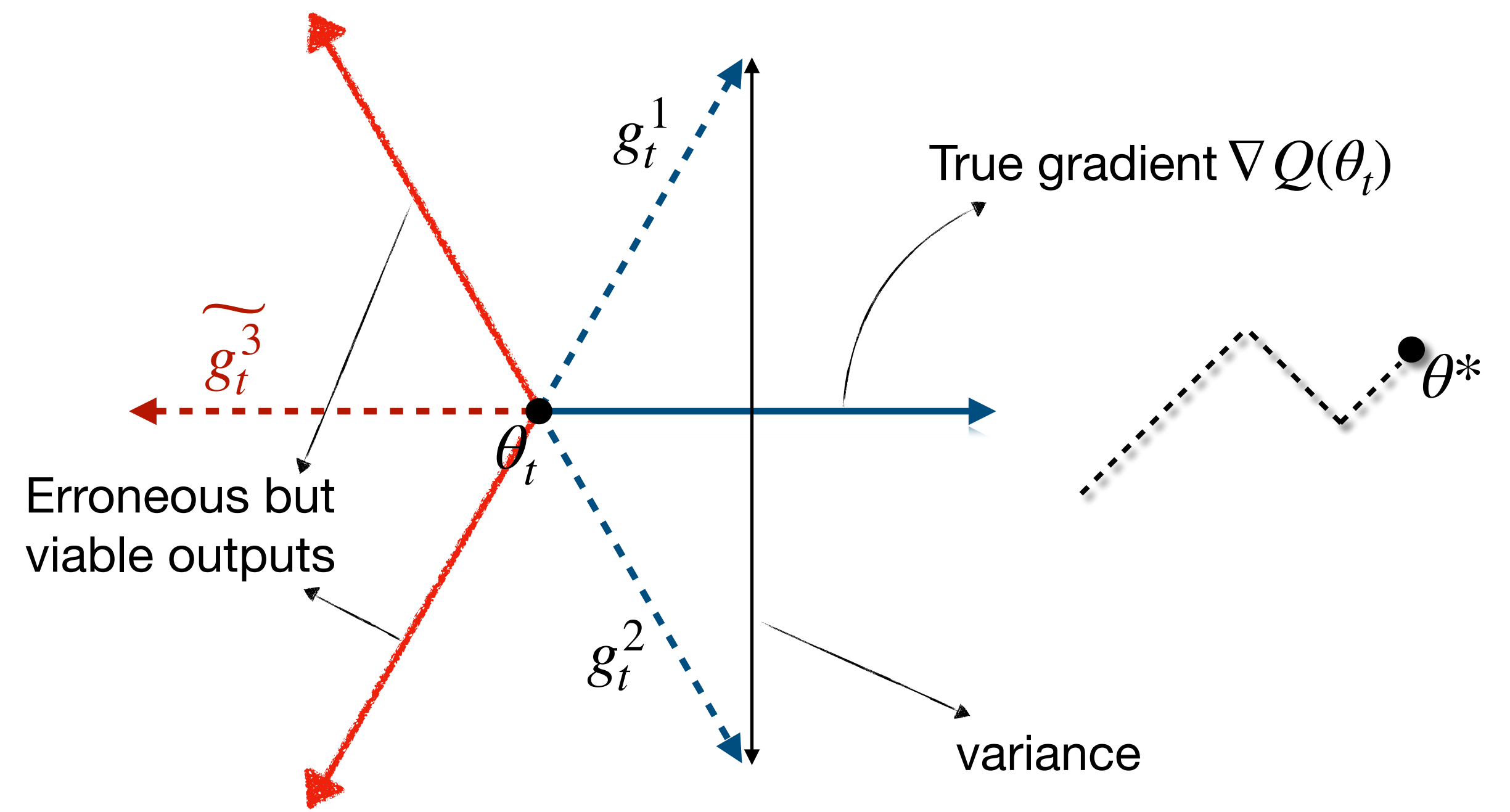
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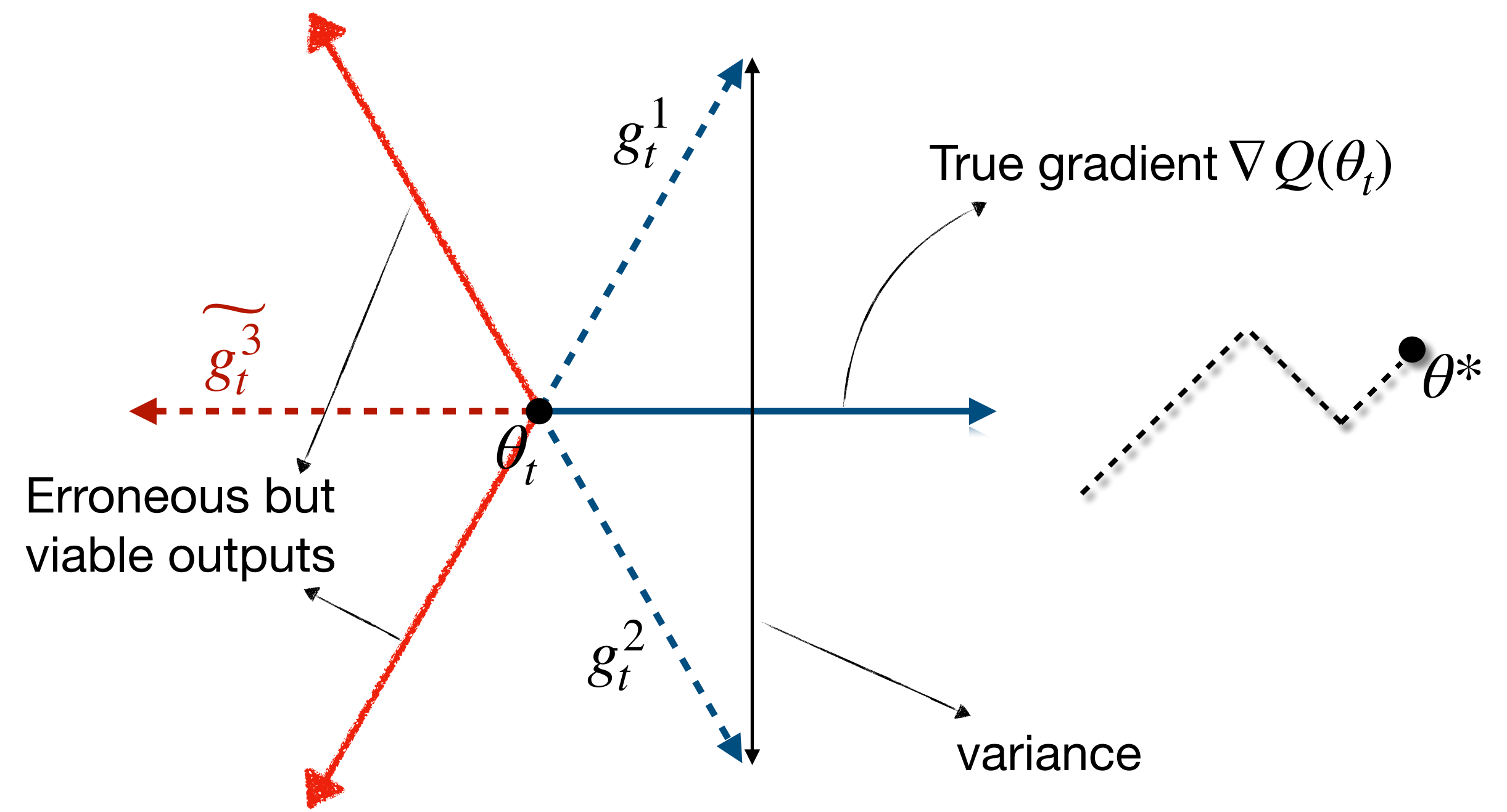
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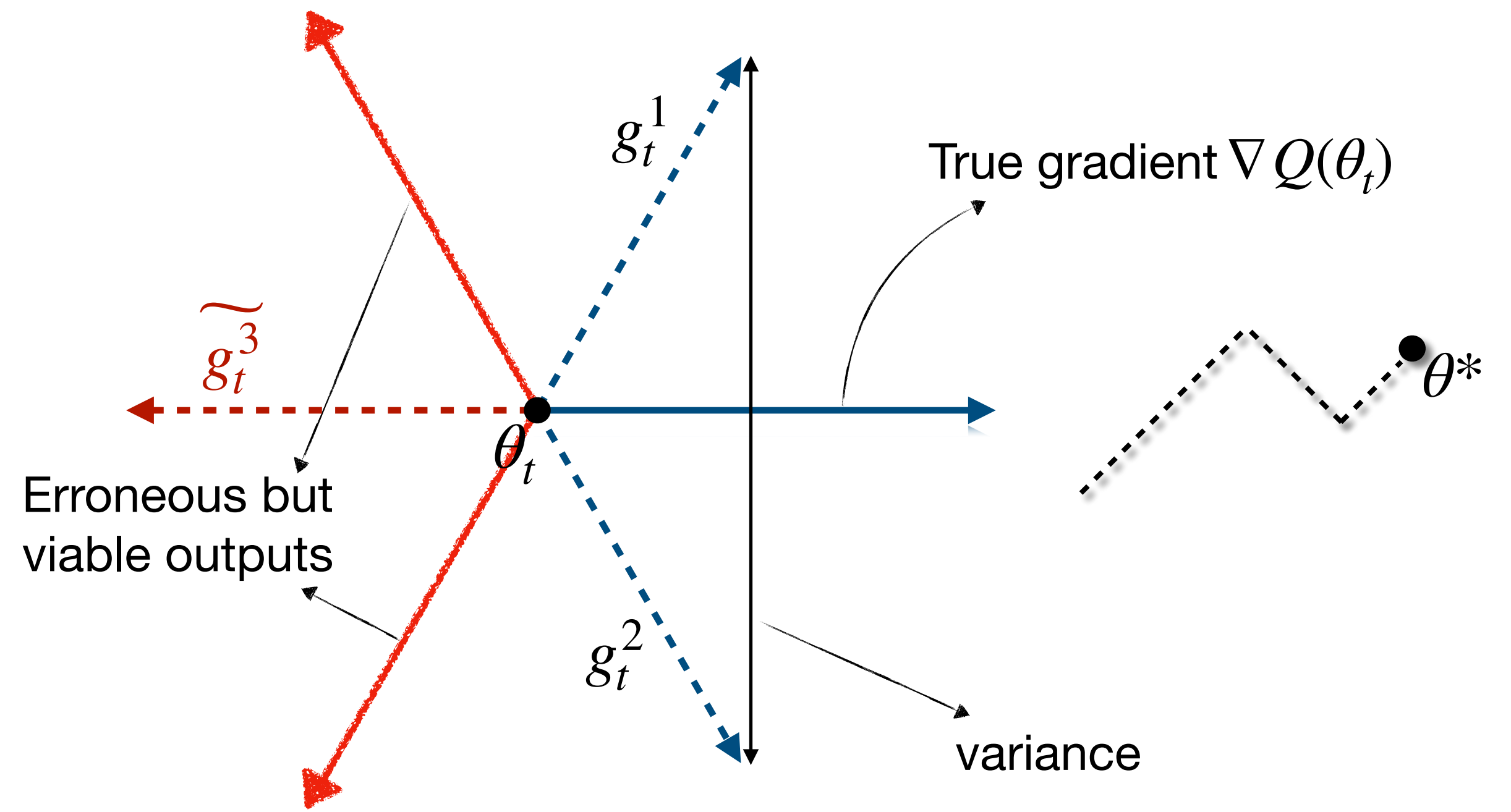


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Variance reduction schemes -



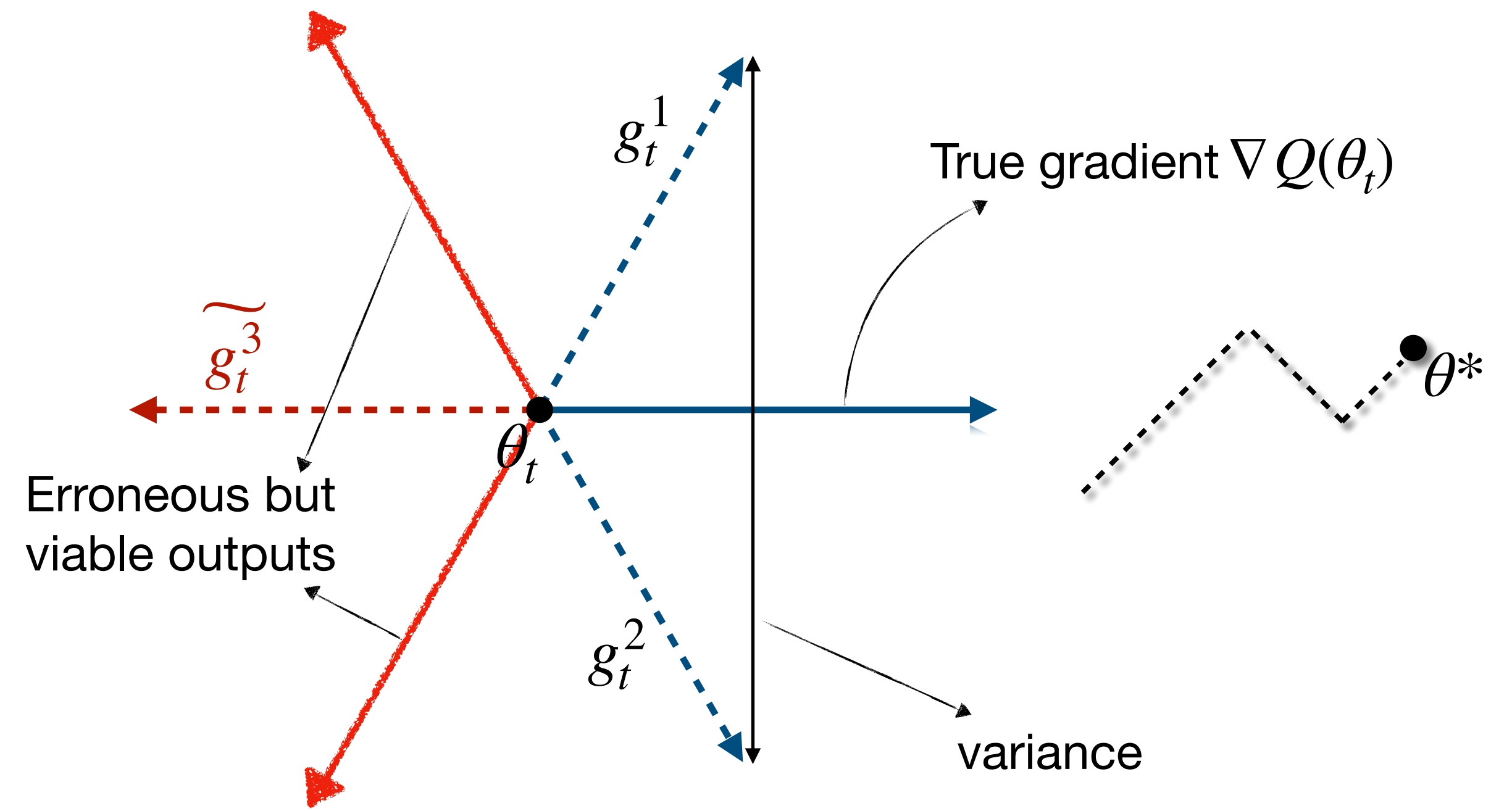
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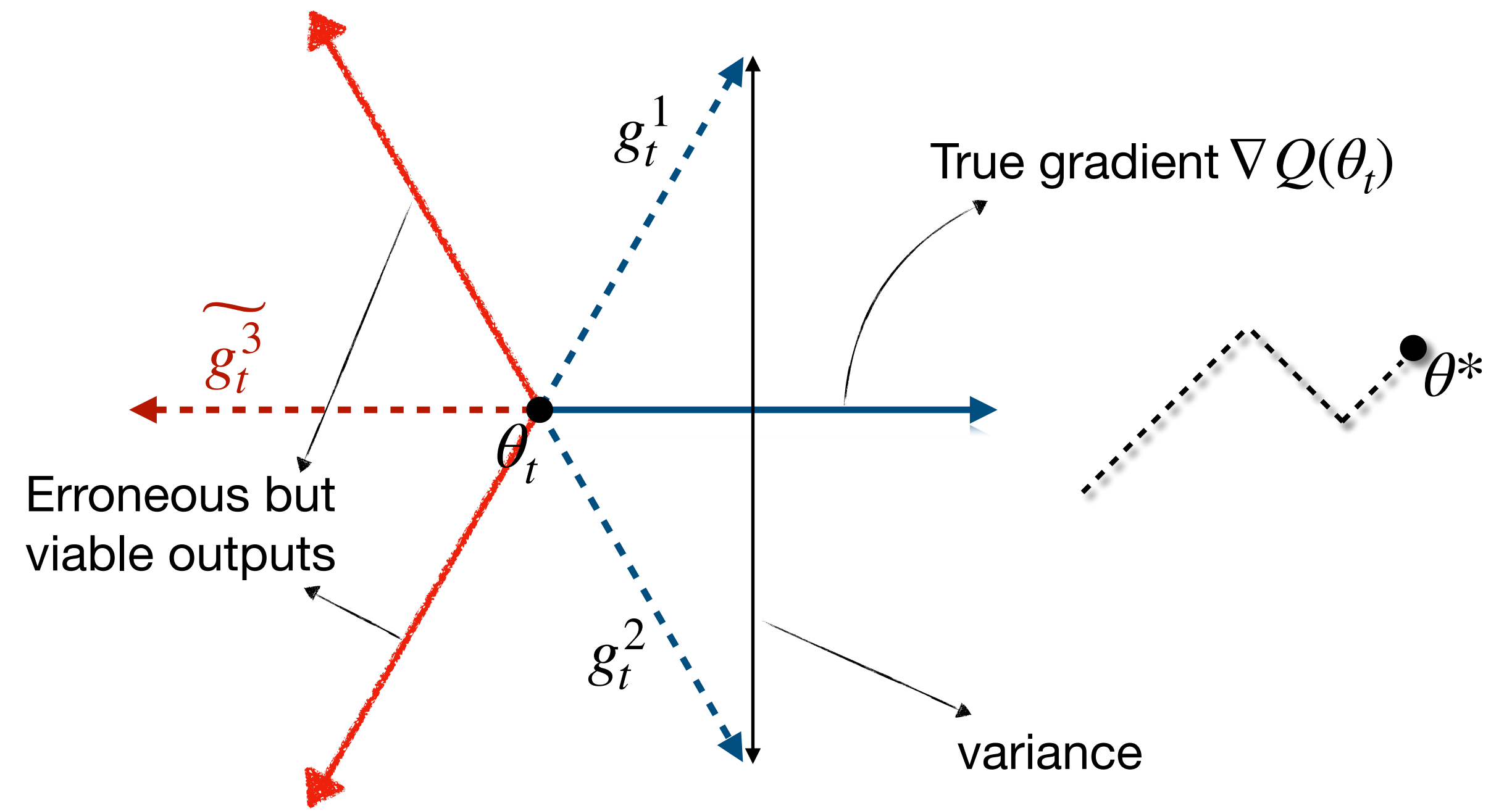
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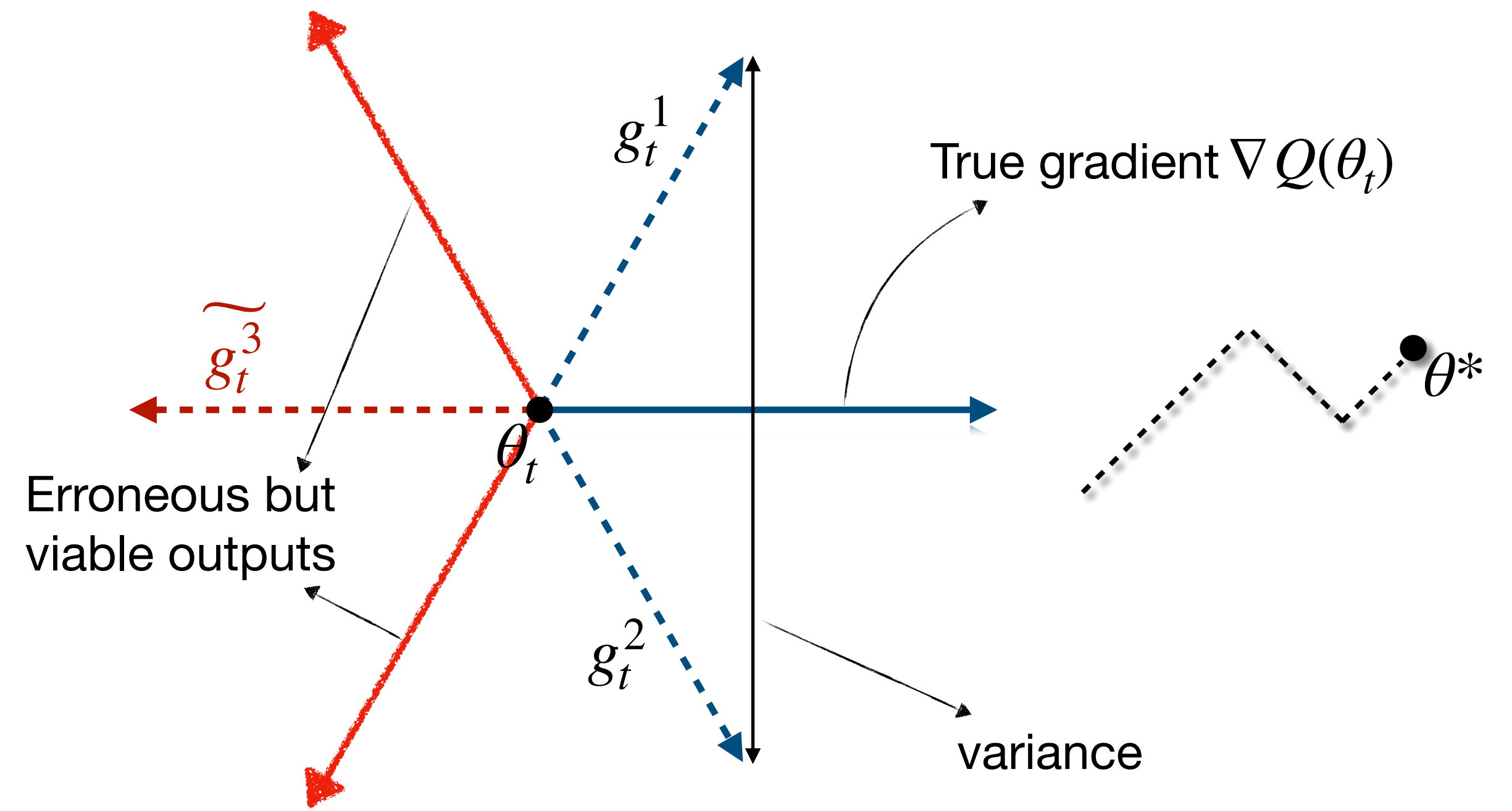
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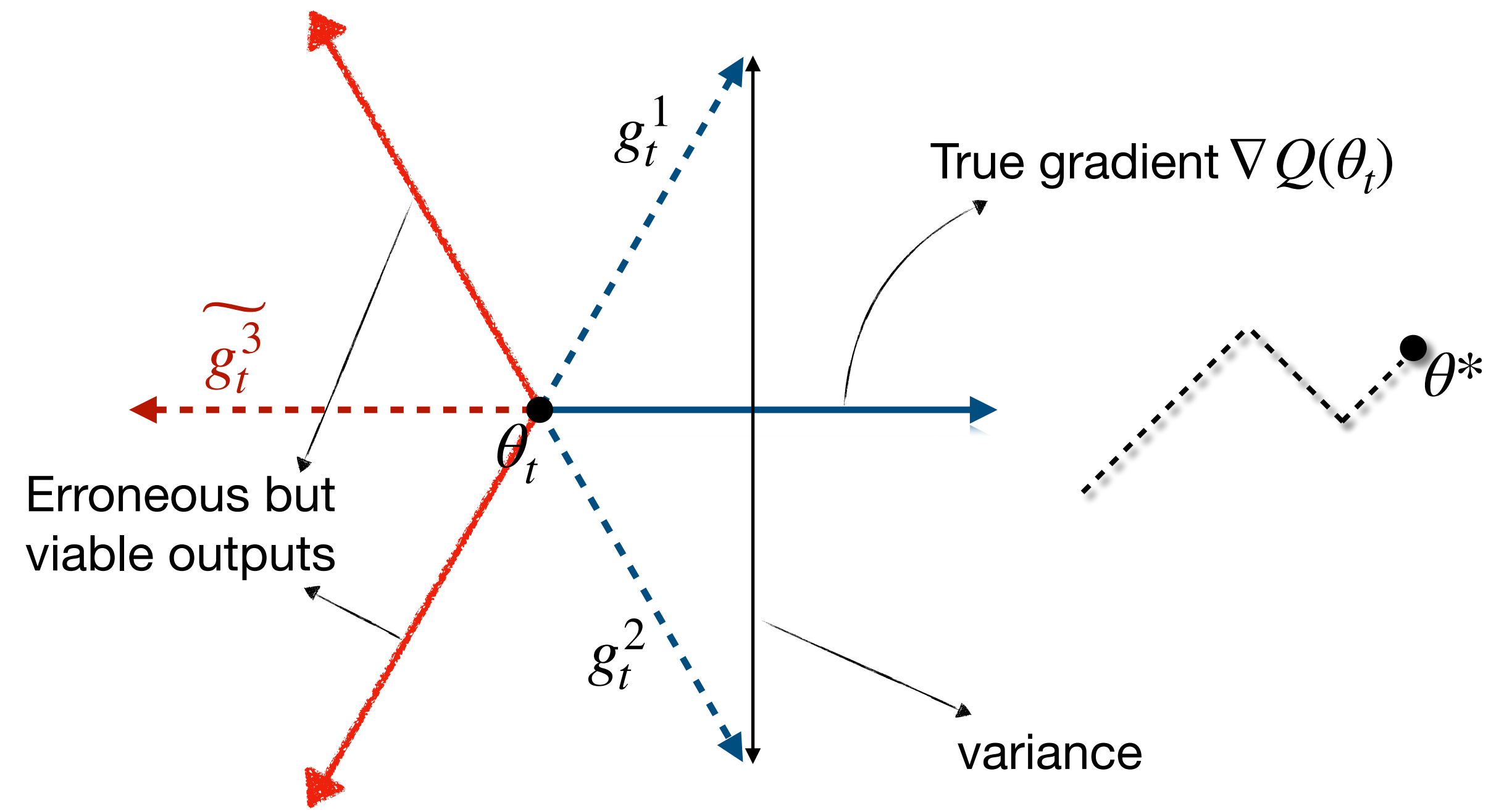
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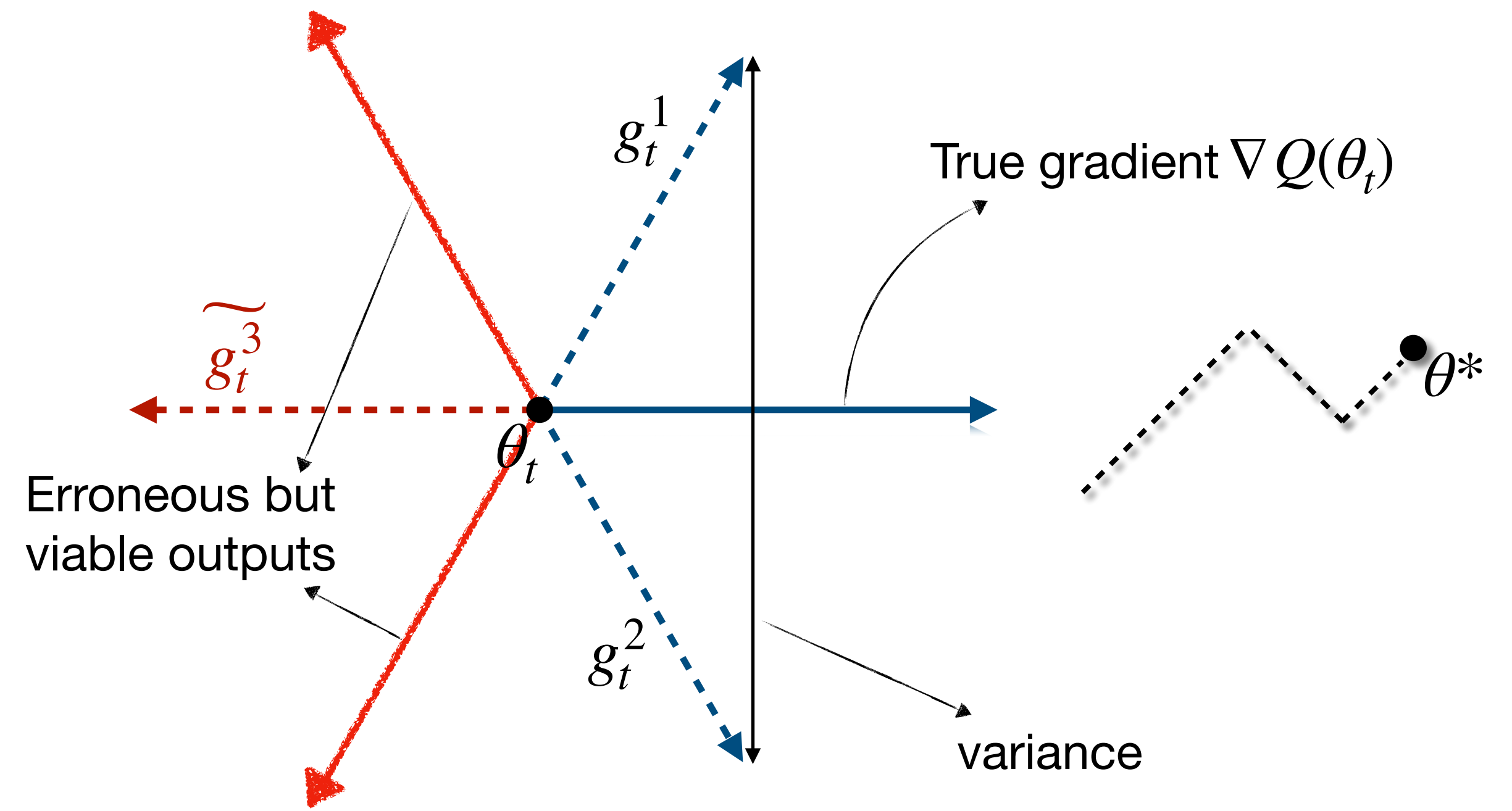
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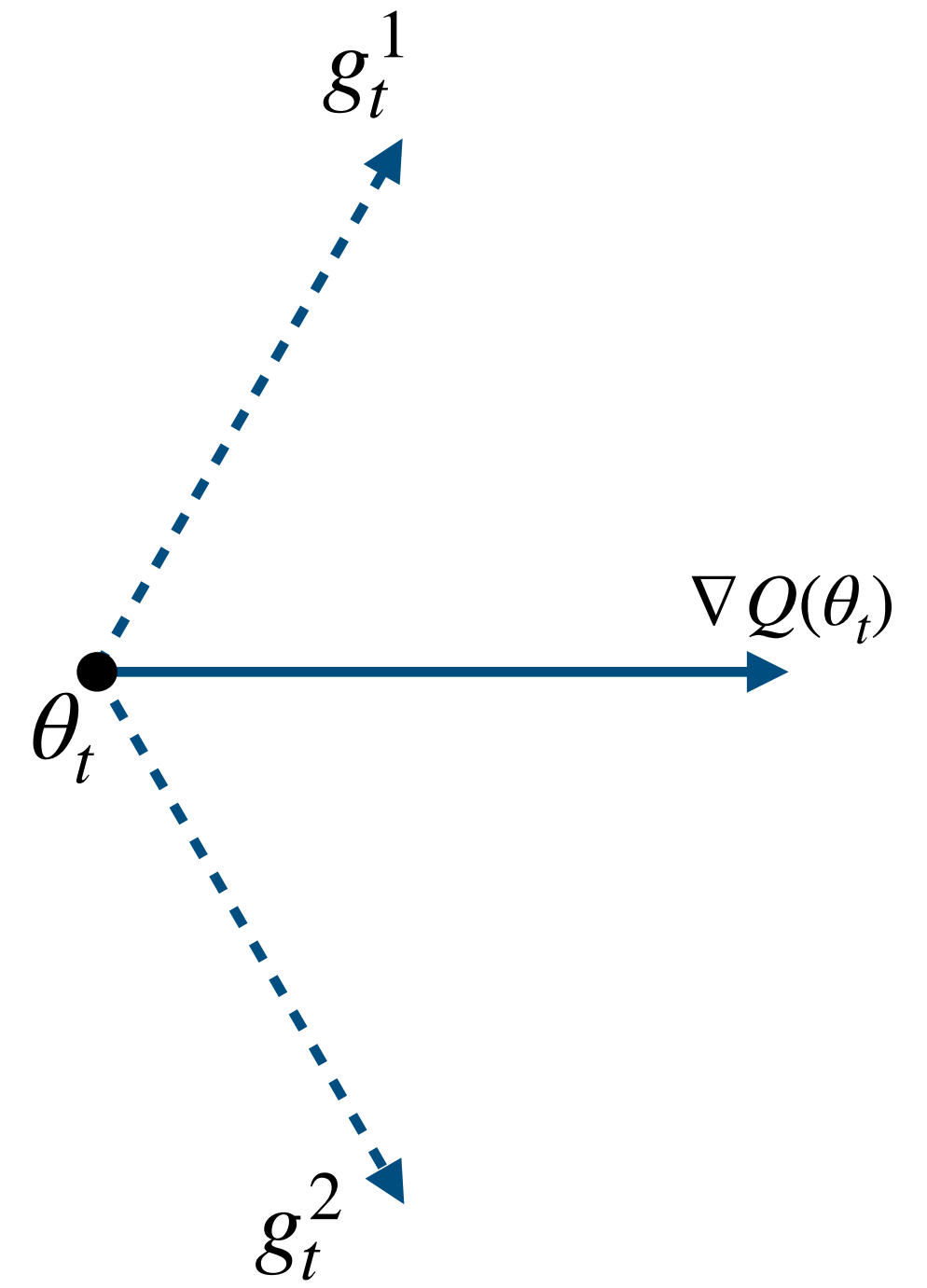
Threatens the convergence



**“With every mistake, me must surely be learning ...
While my *GPU* gently weeps.”**

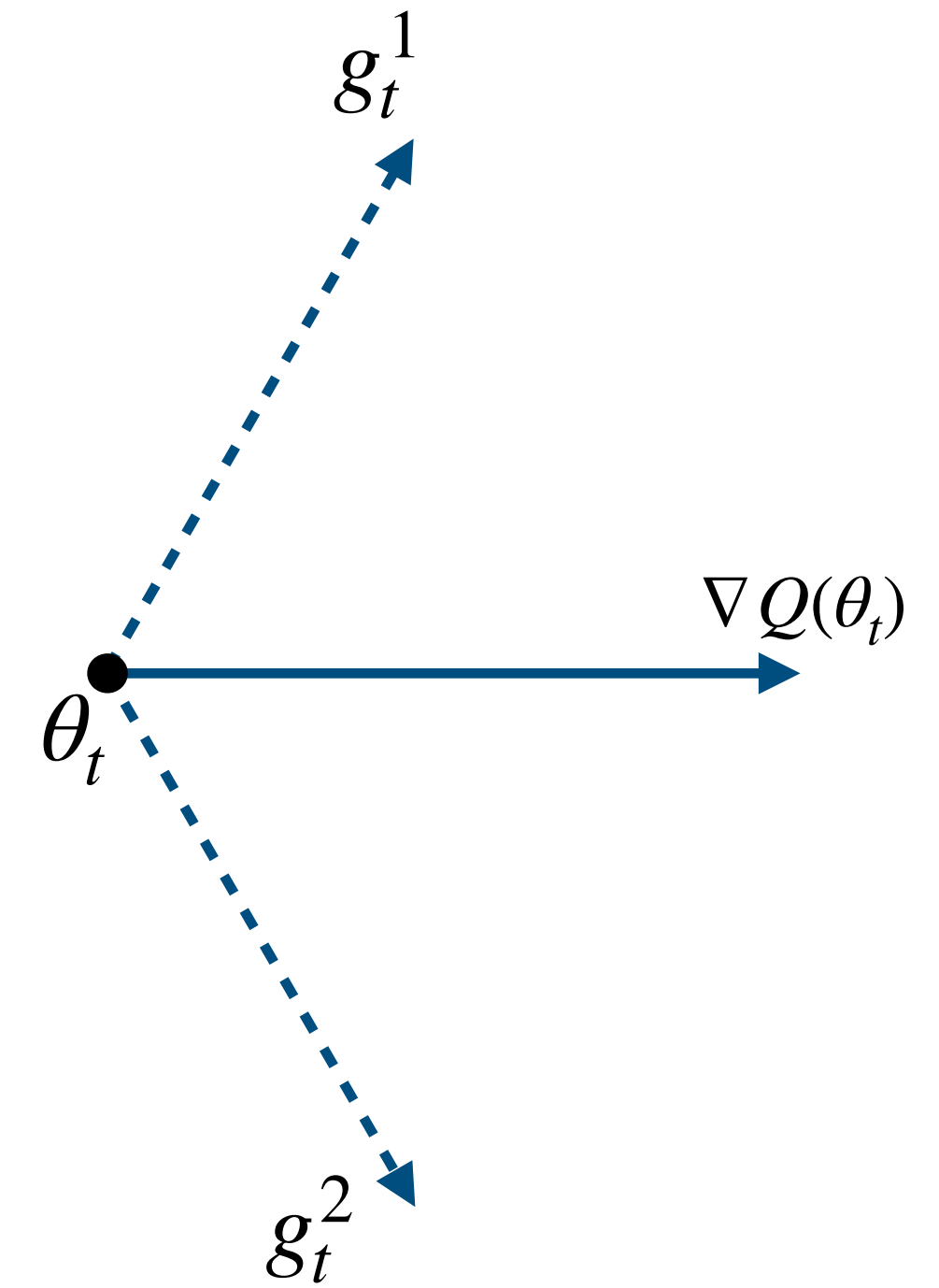
- George Harrison

Local Gradient Momentum



Local Gradient Momentum

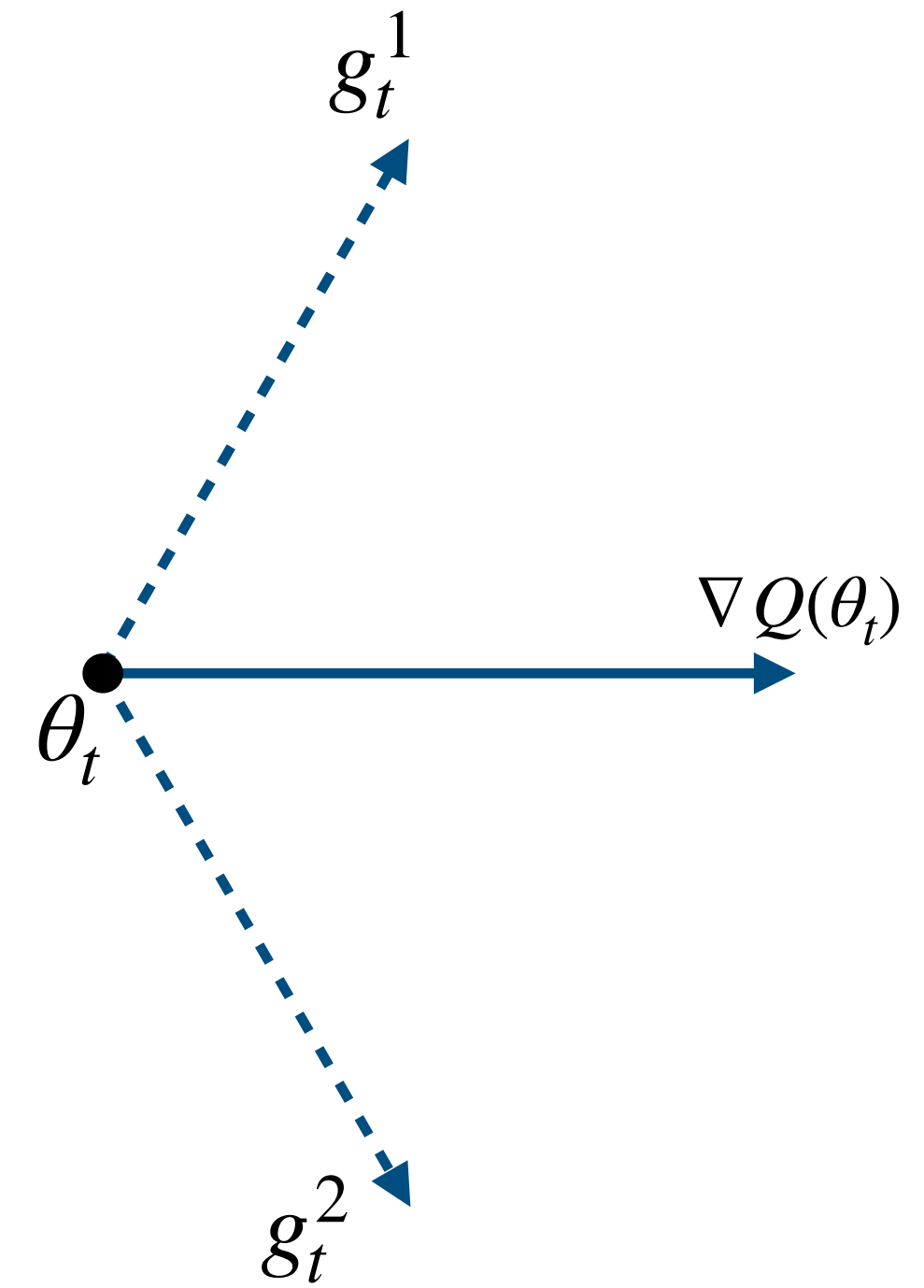
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Local Gradient Momentum

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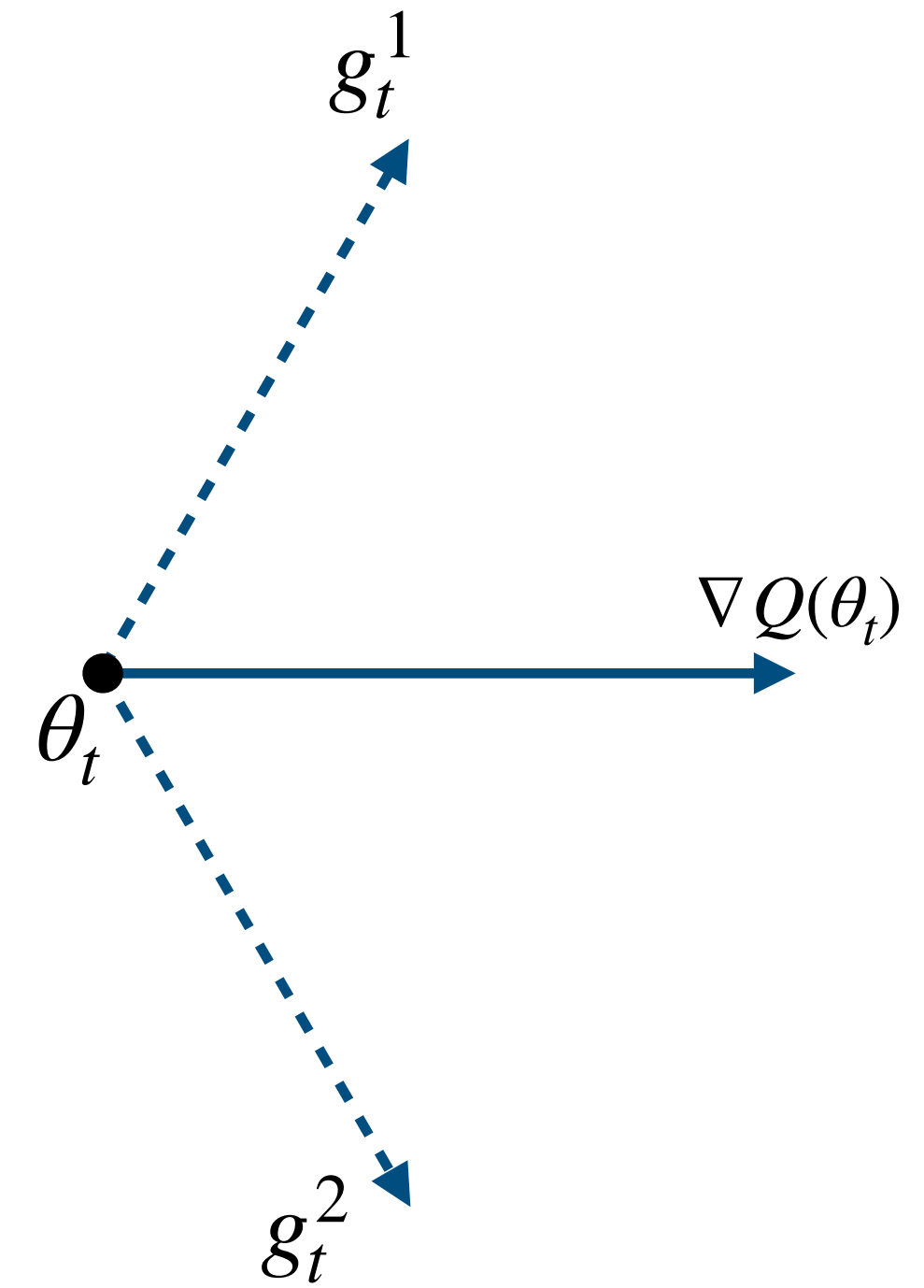


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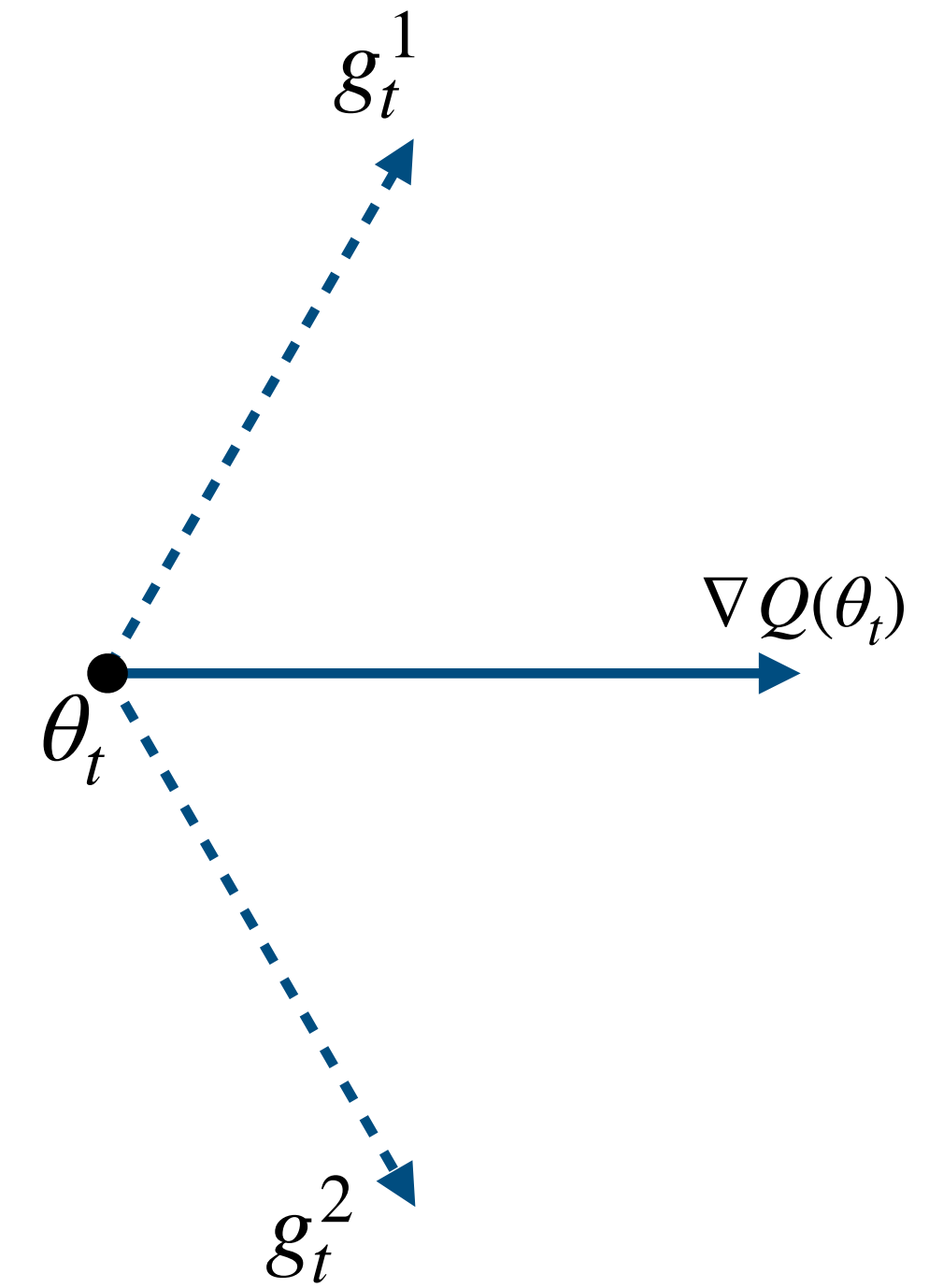


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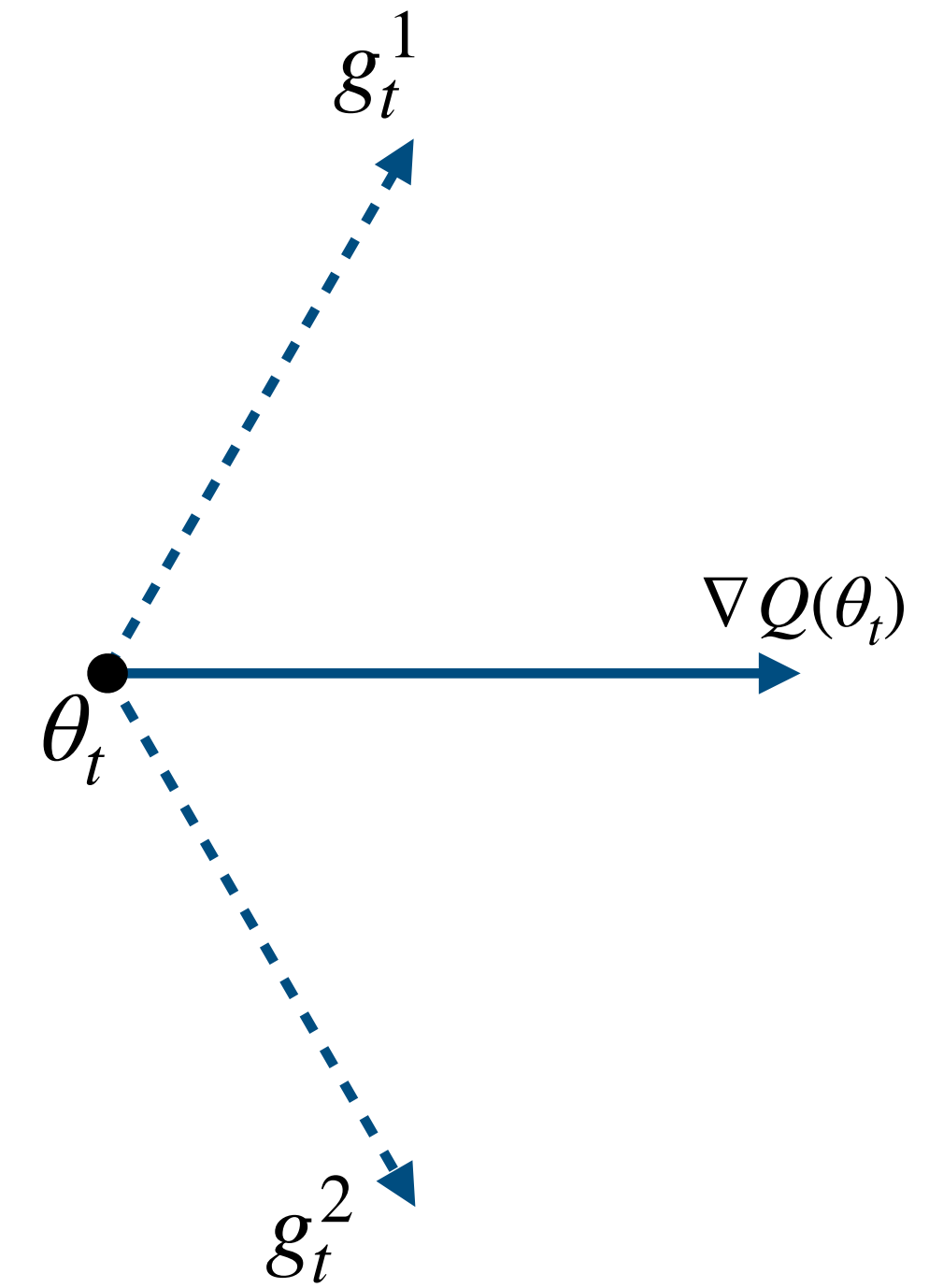


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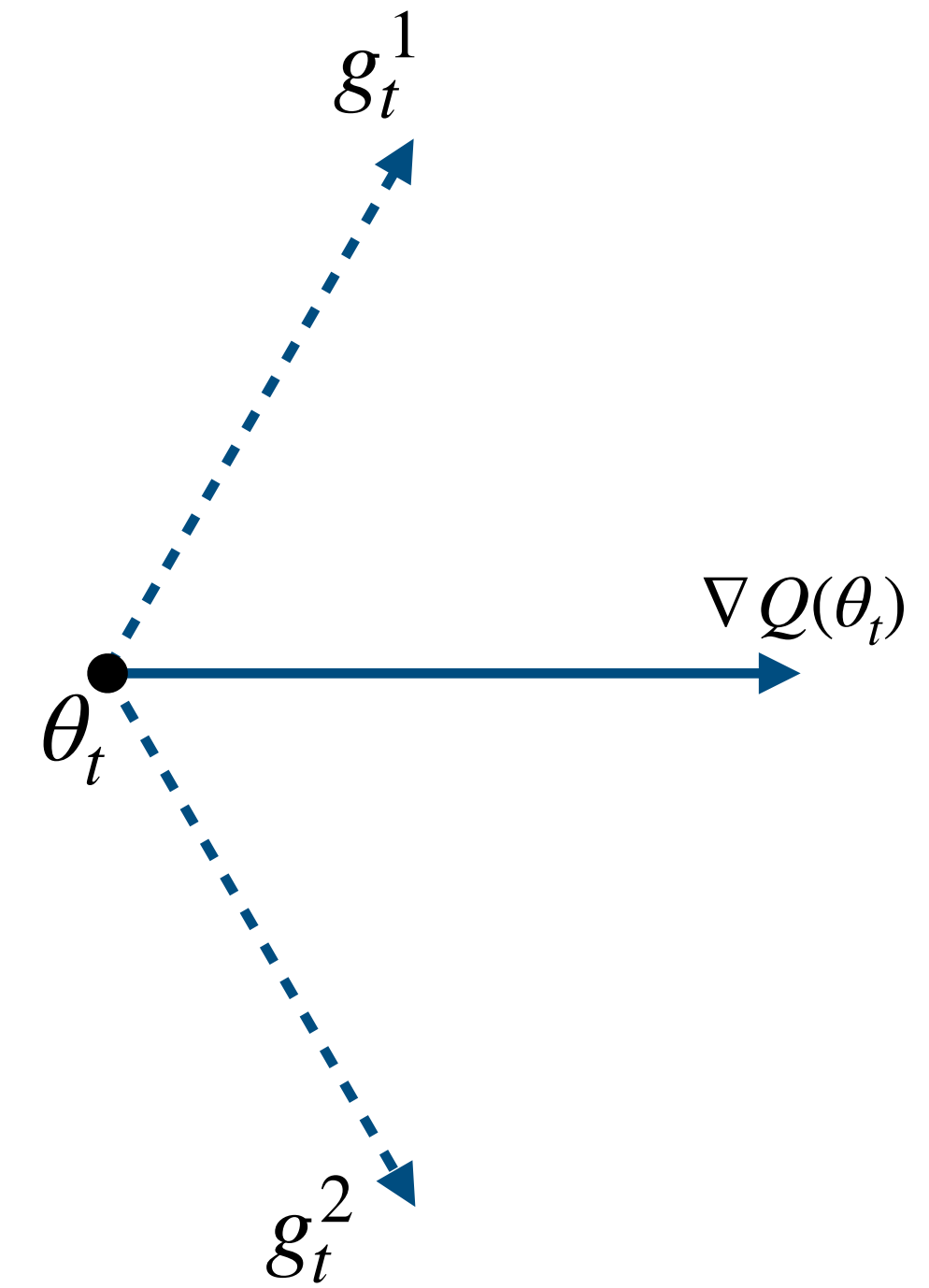
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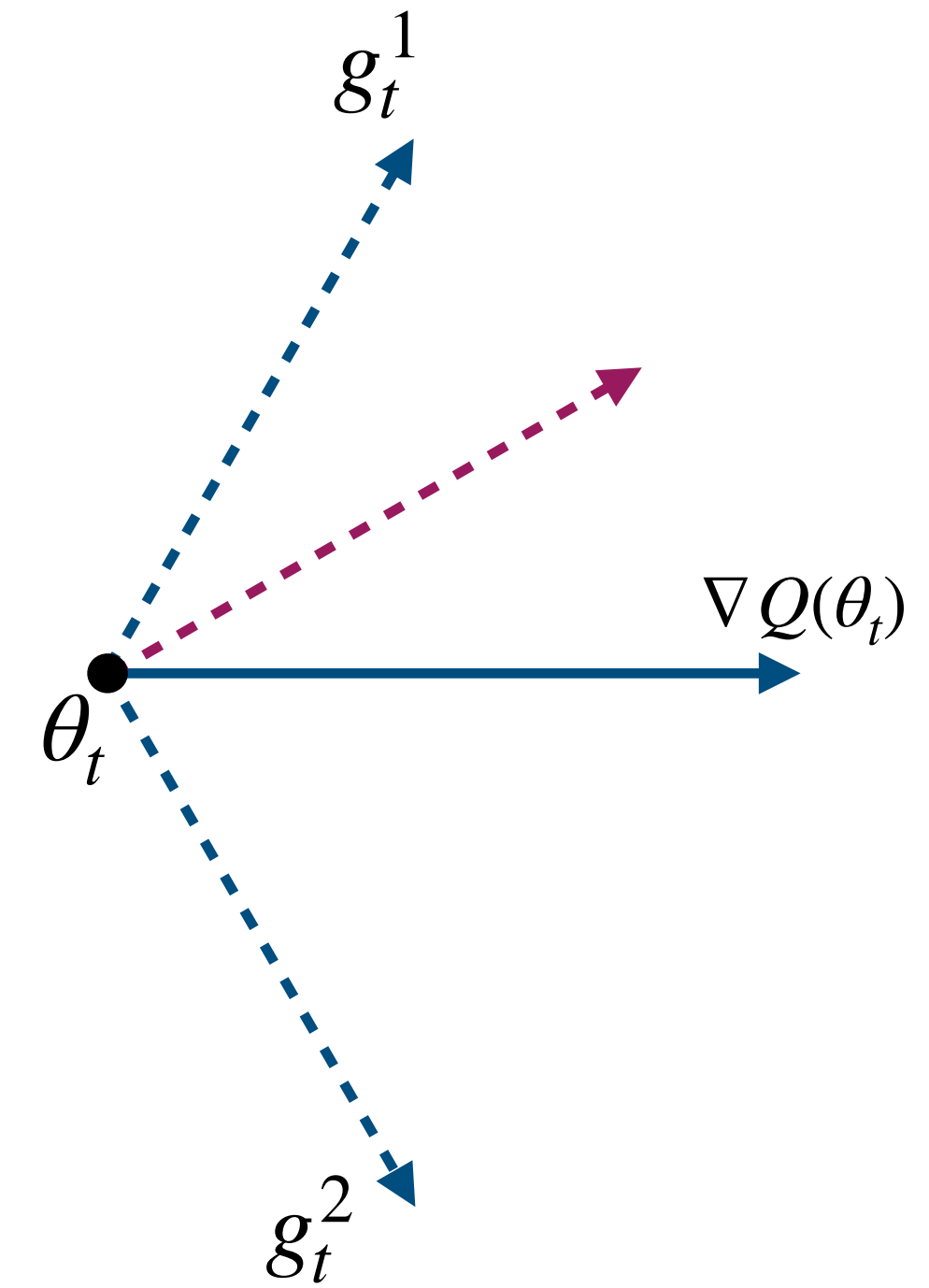
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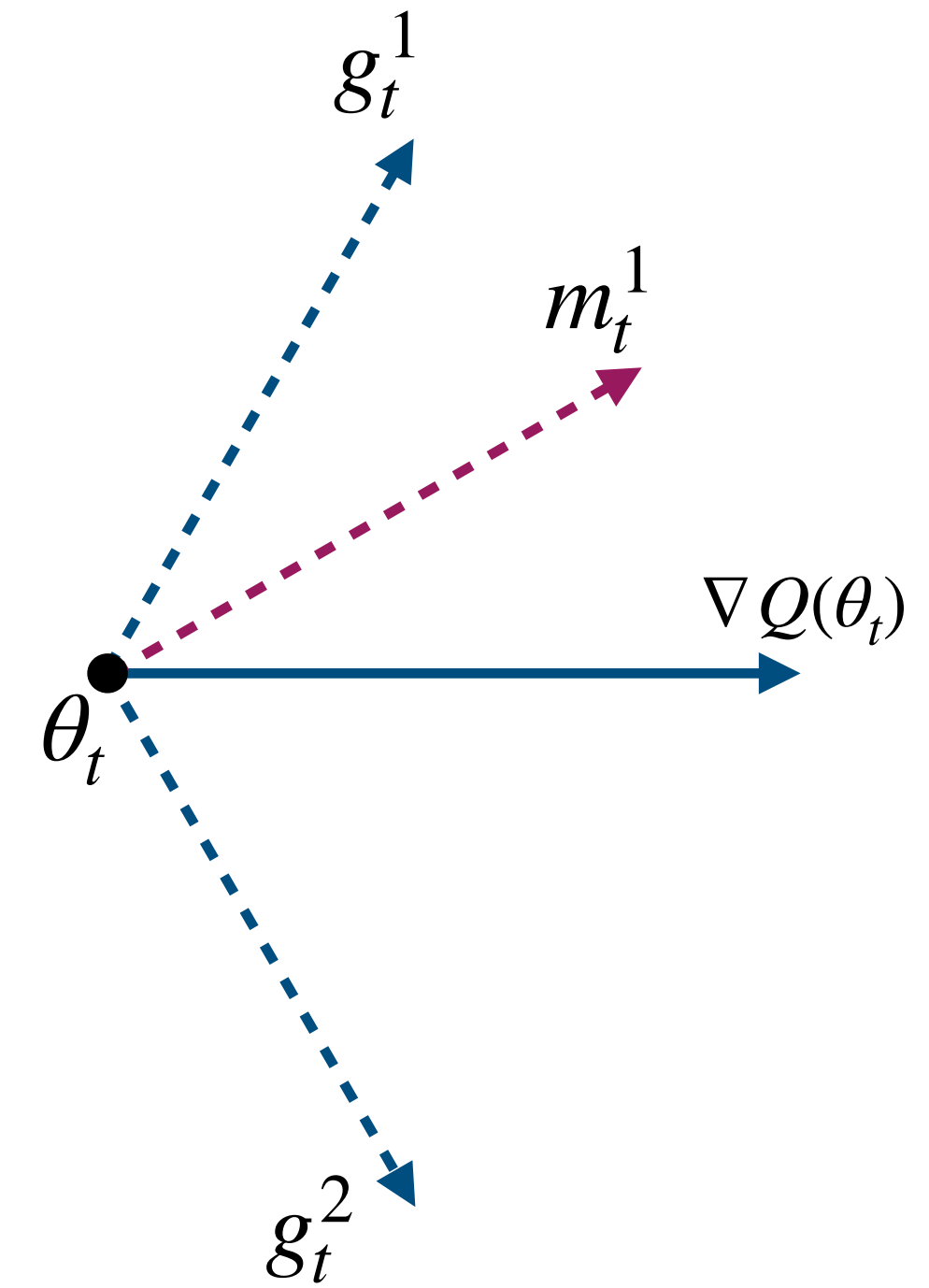
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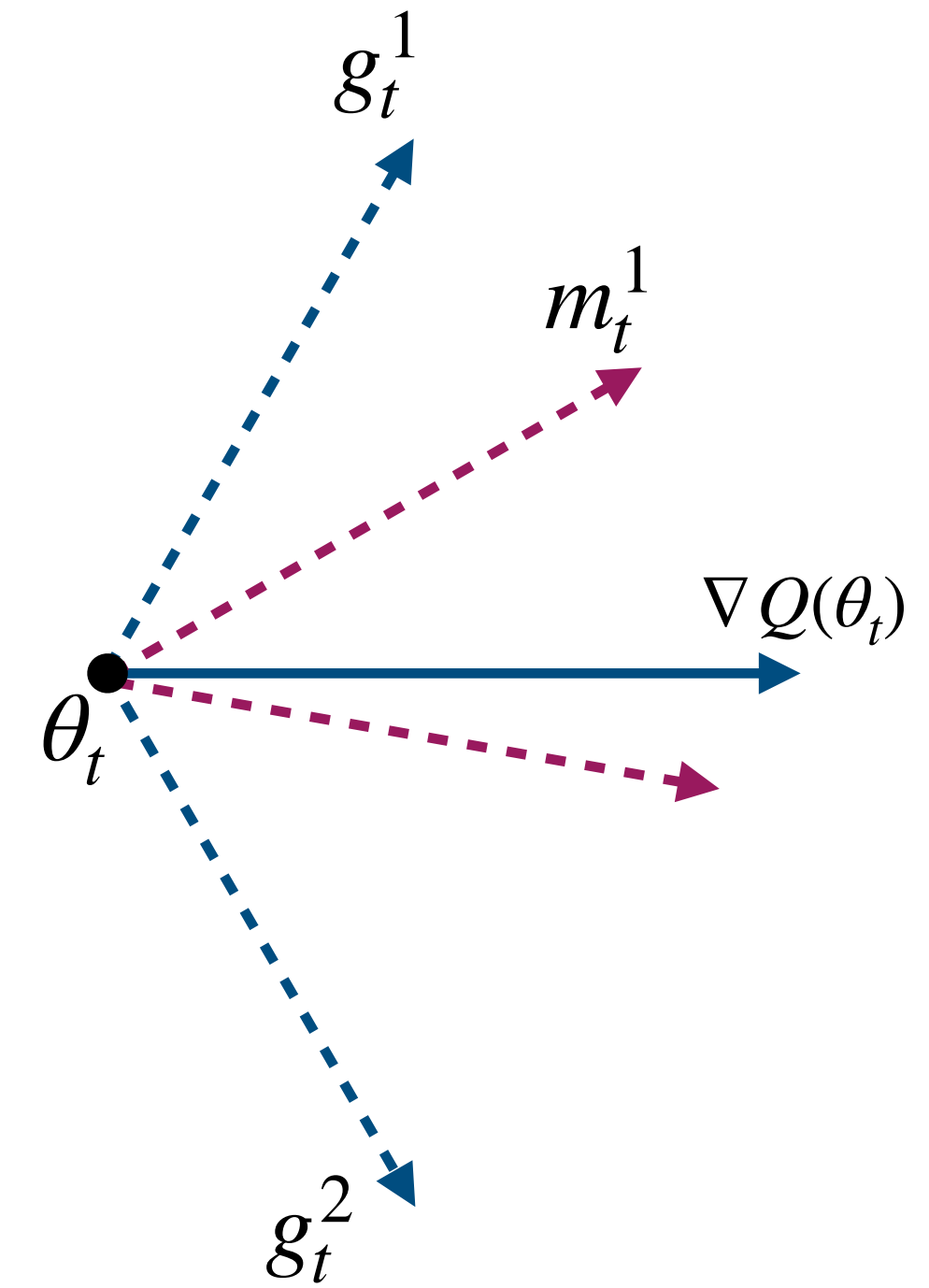
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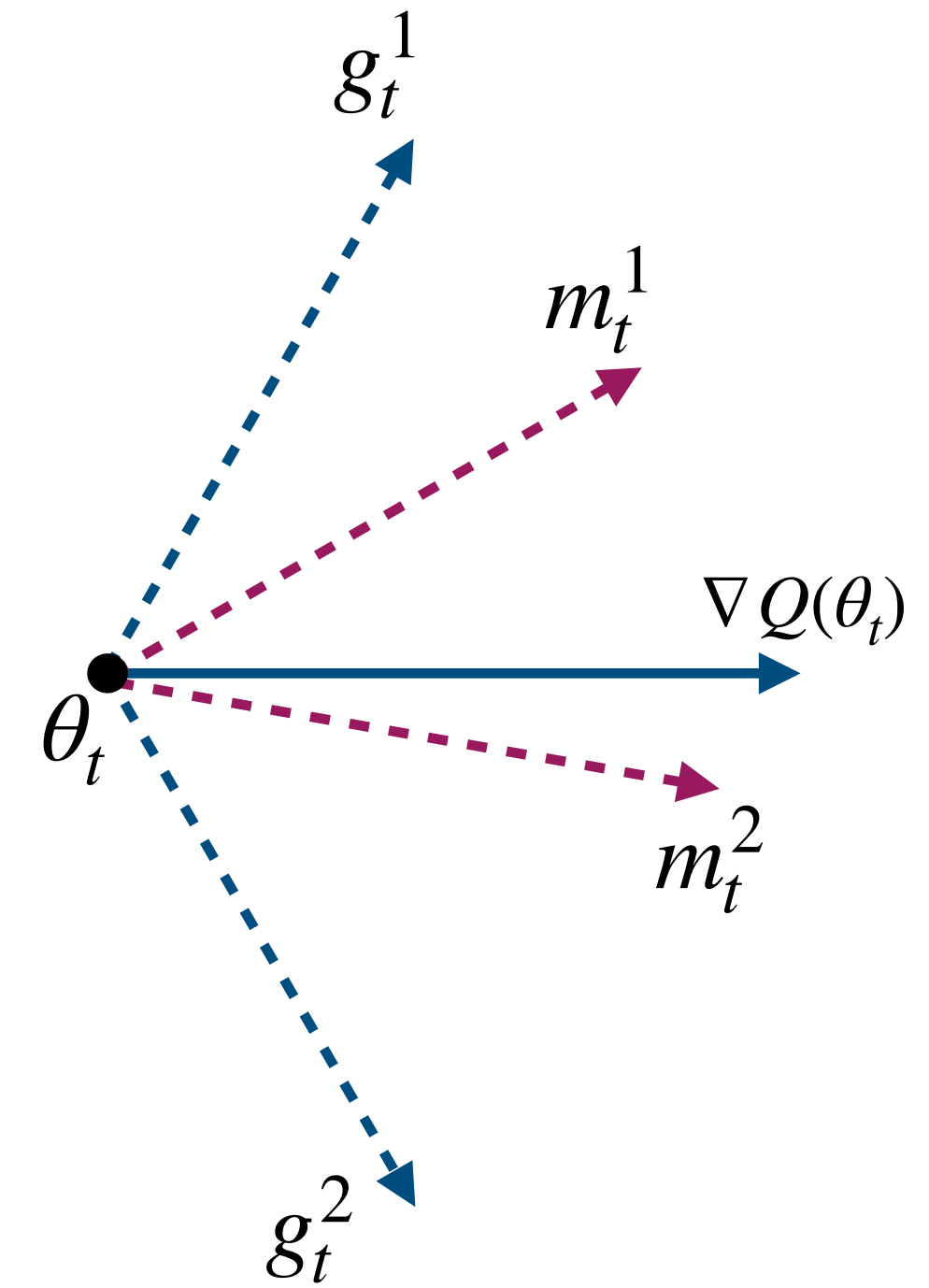
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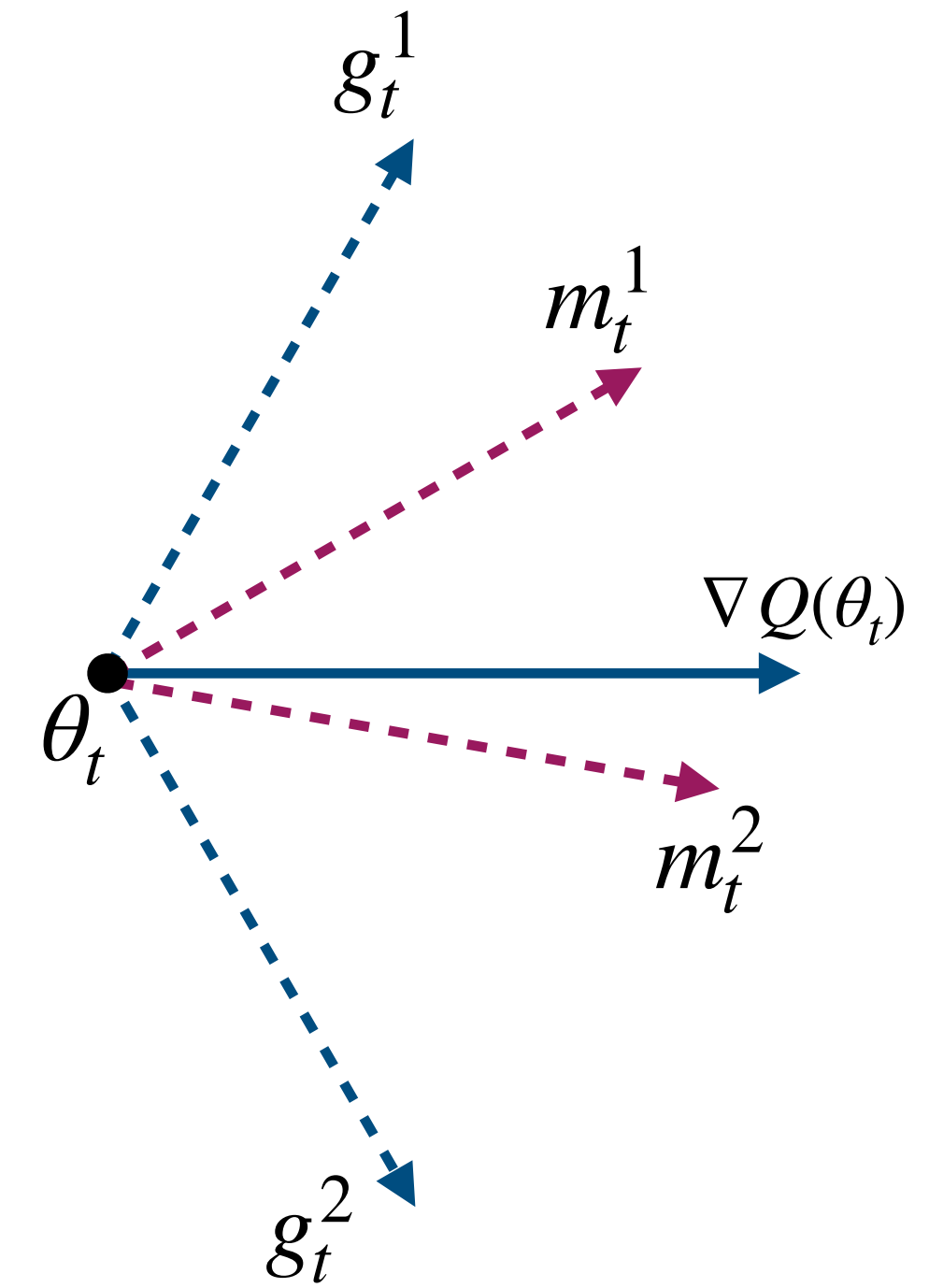
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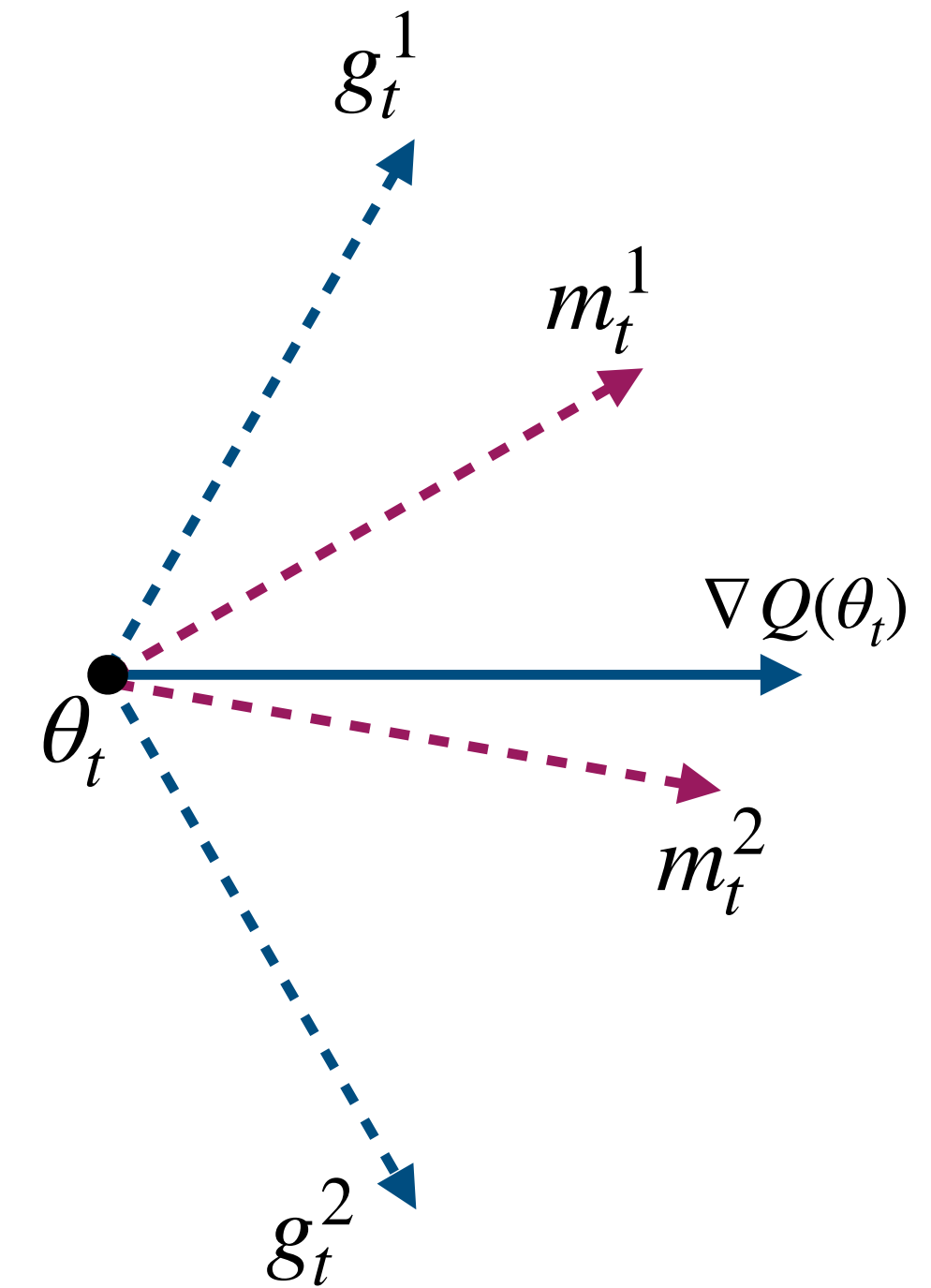
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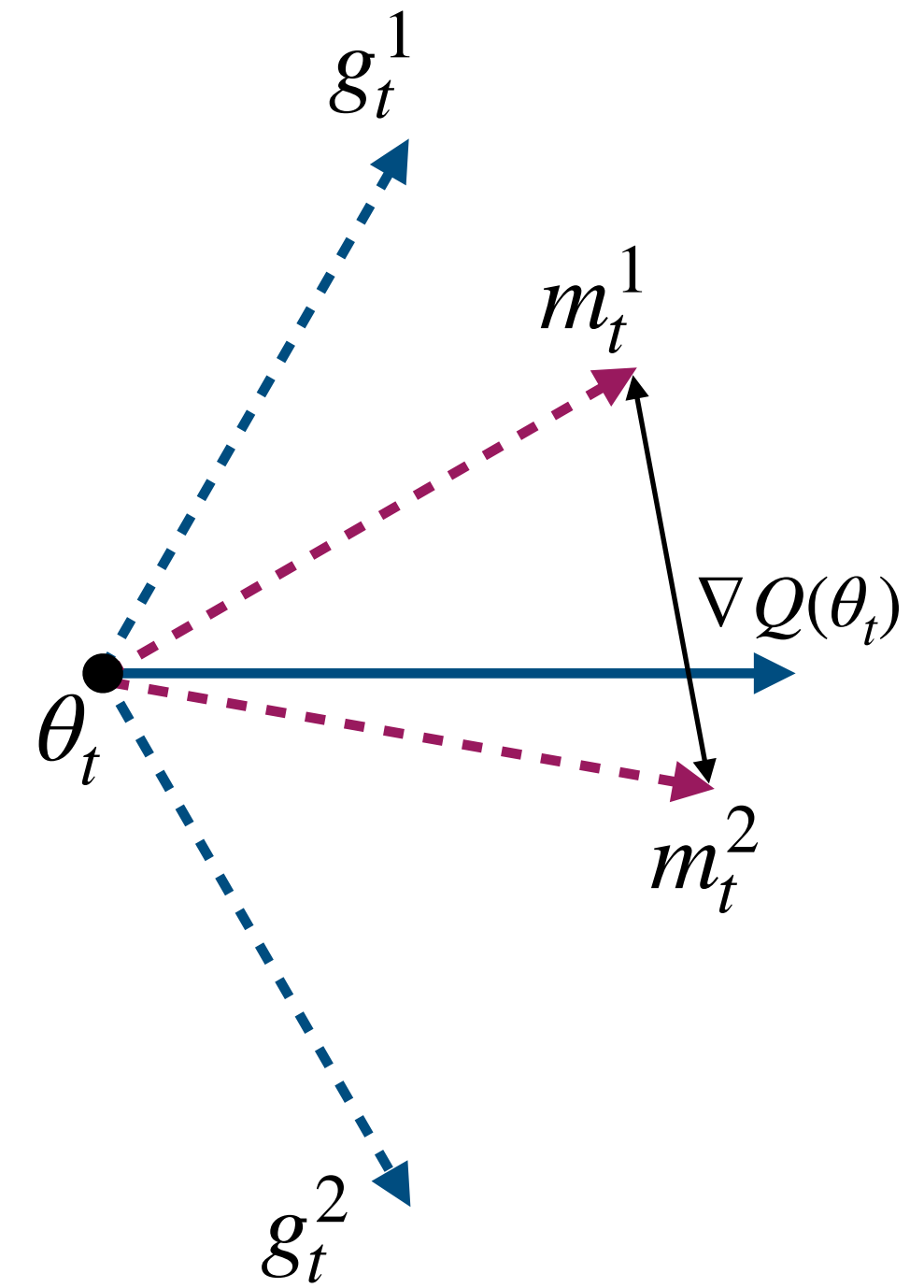
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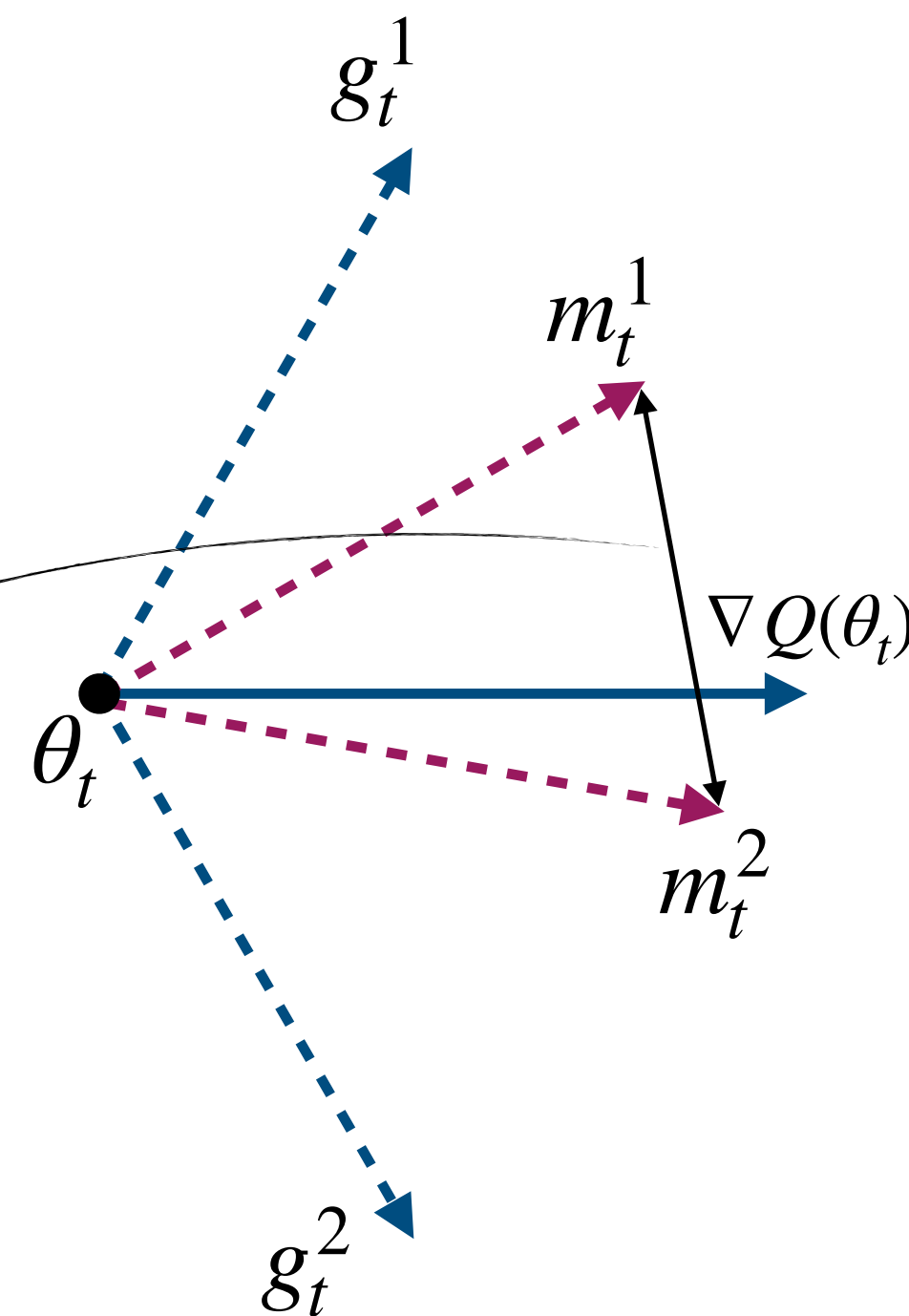
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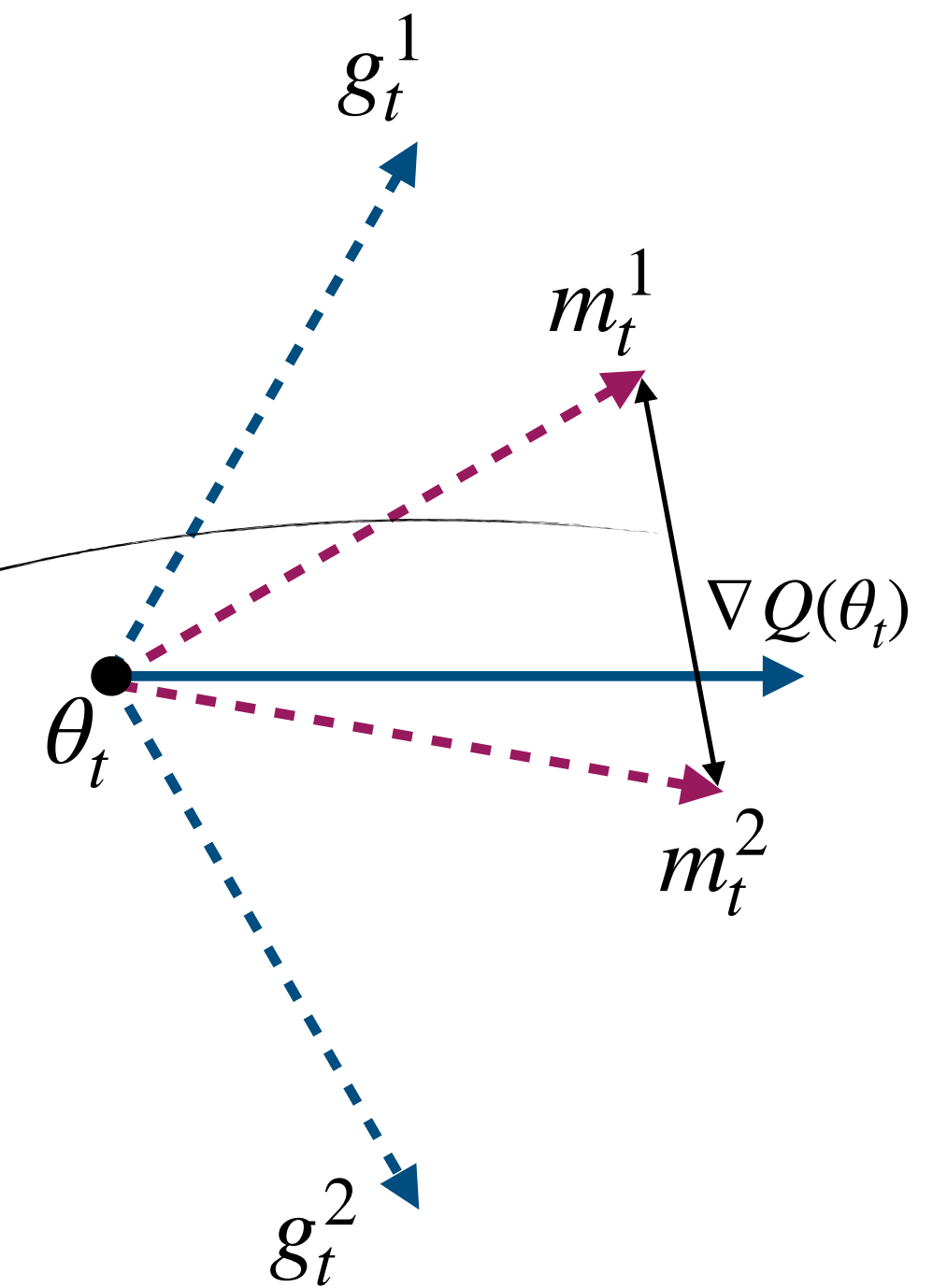
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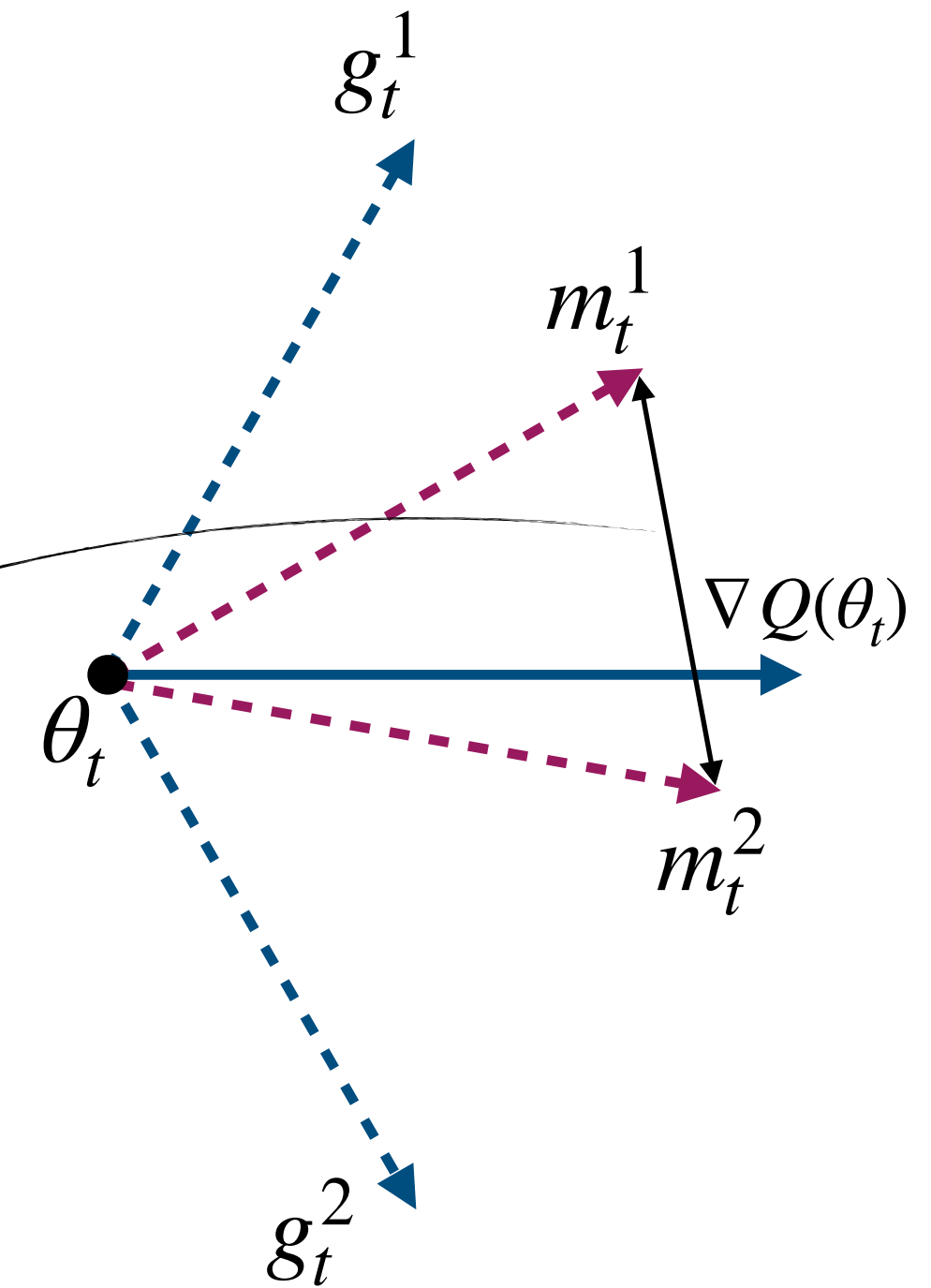
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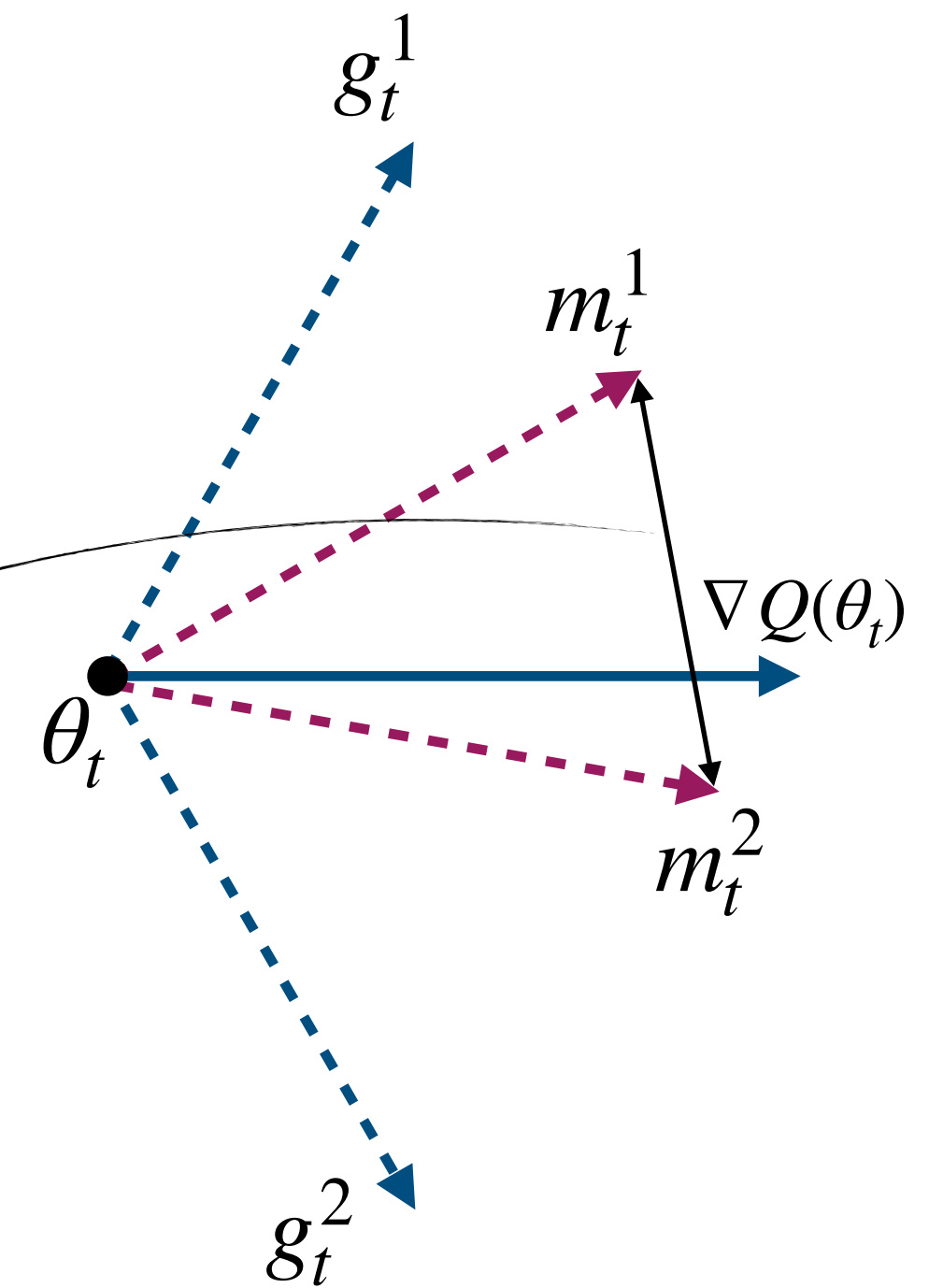
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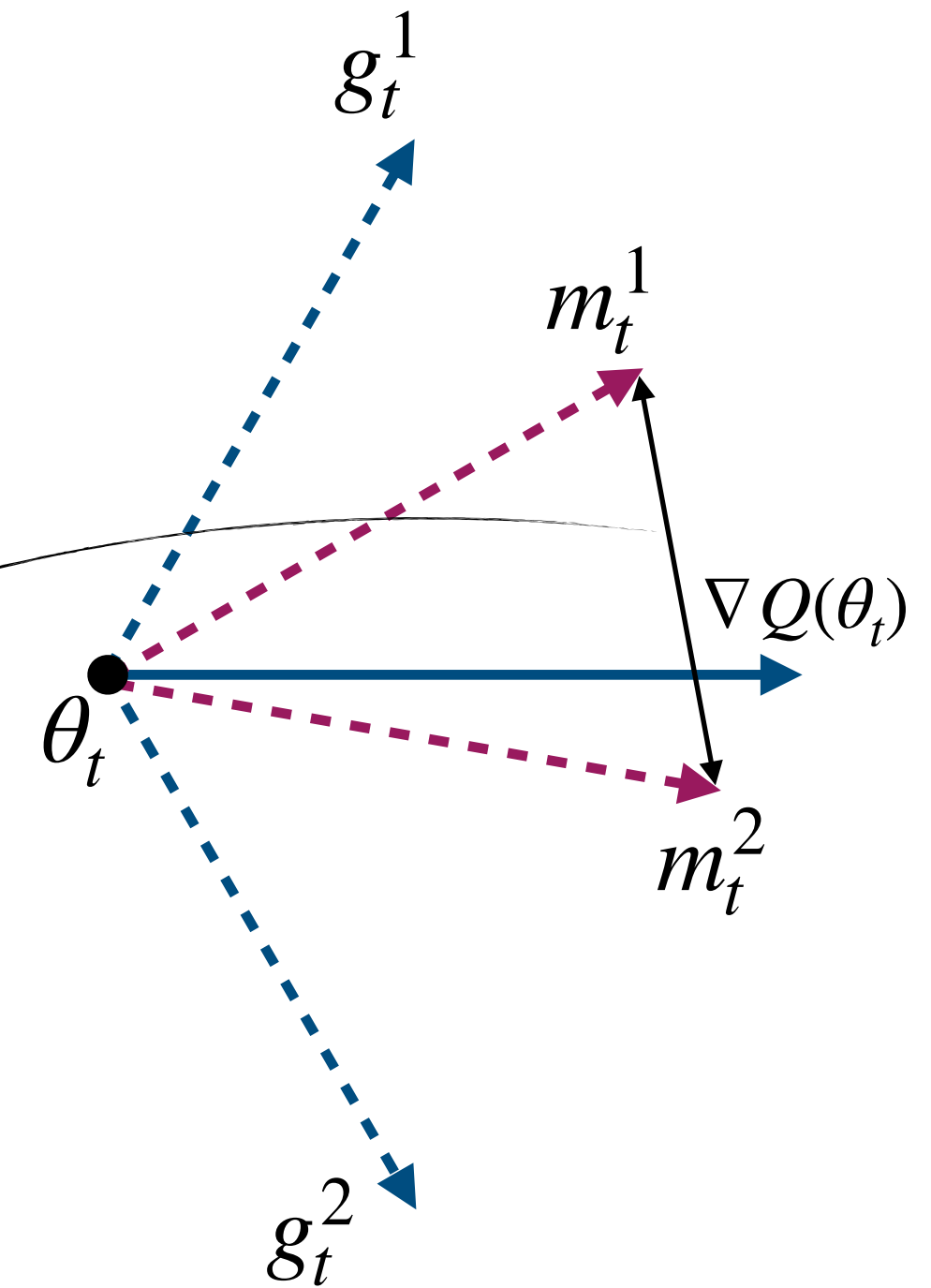
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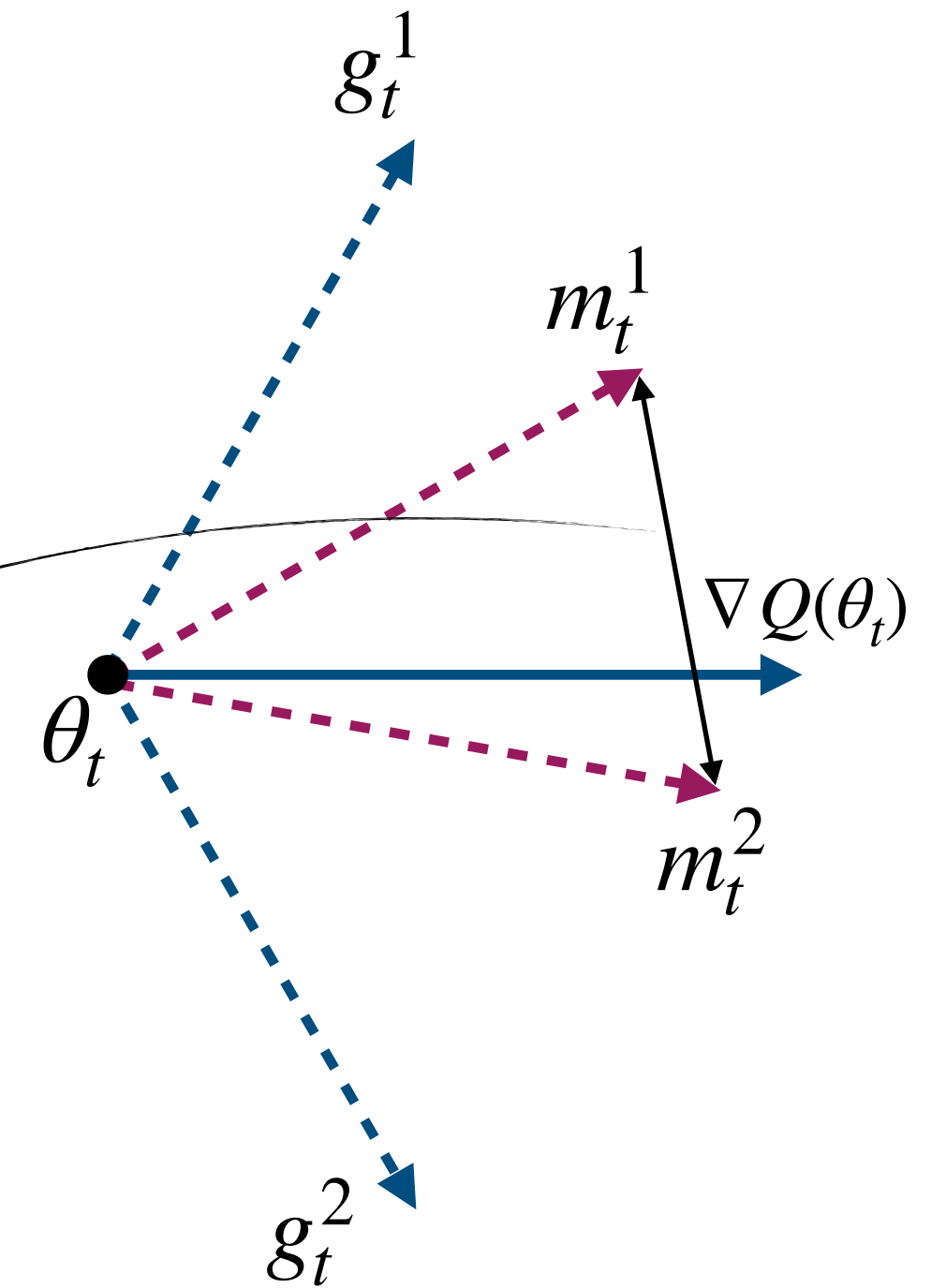
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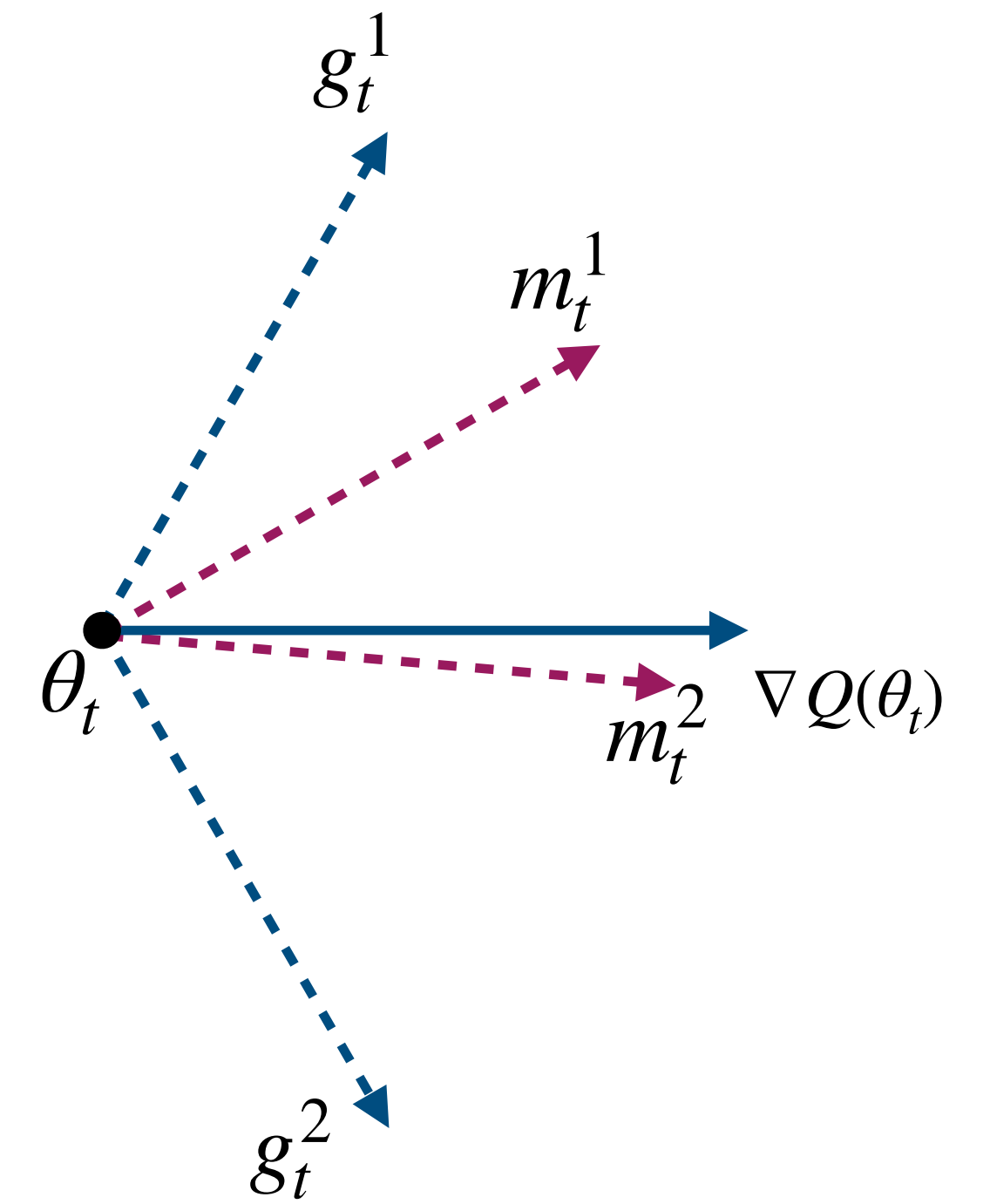


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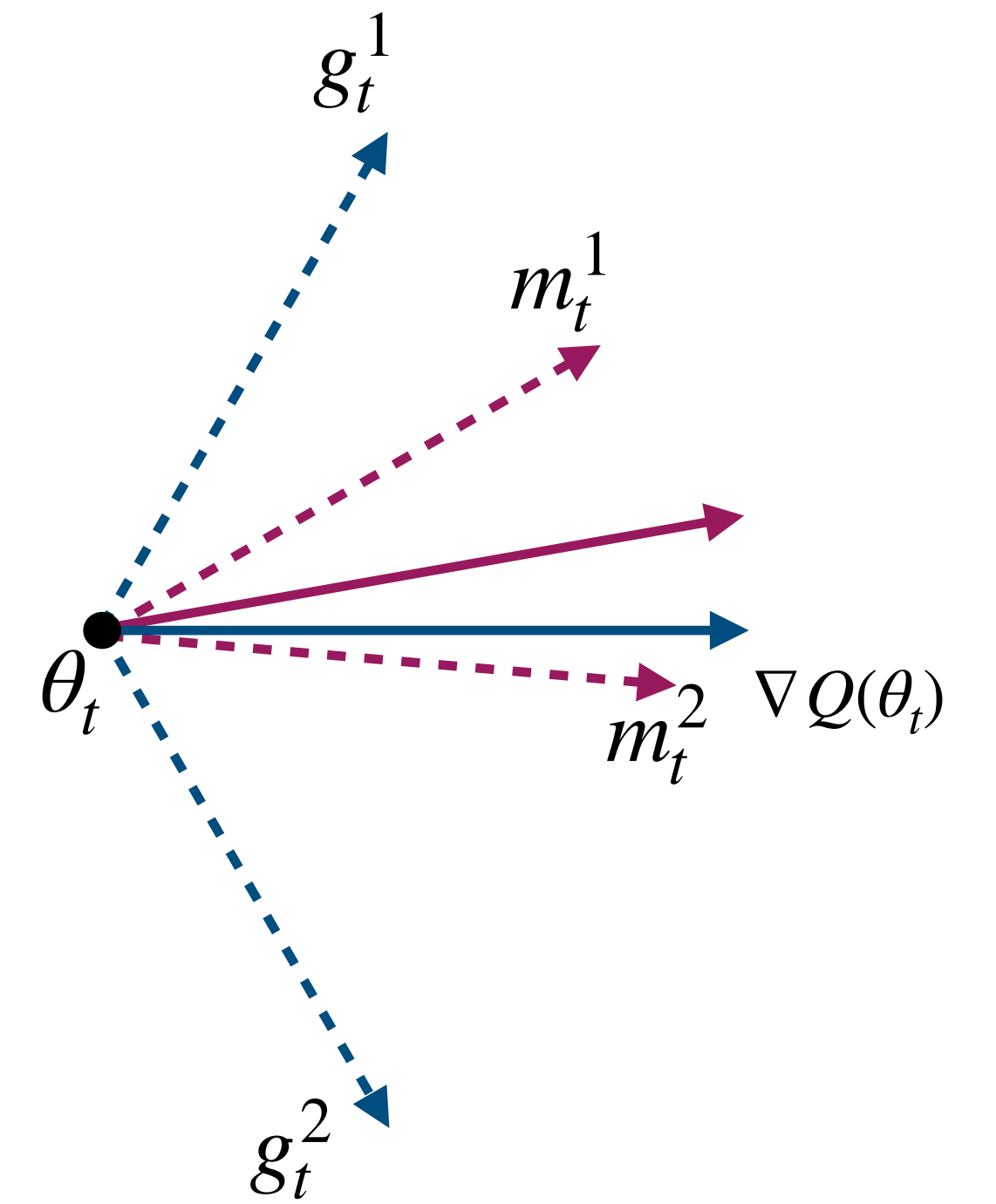
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Ideally large

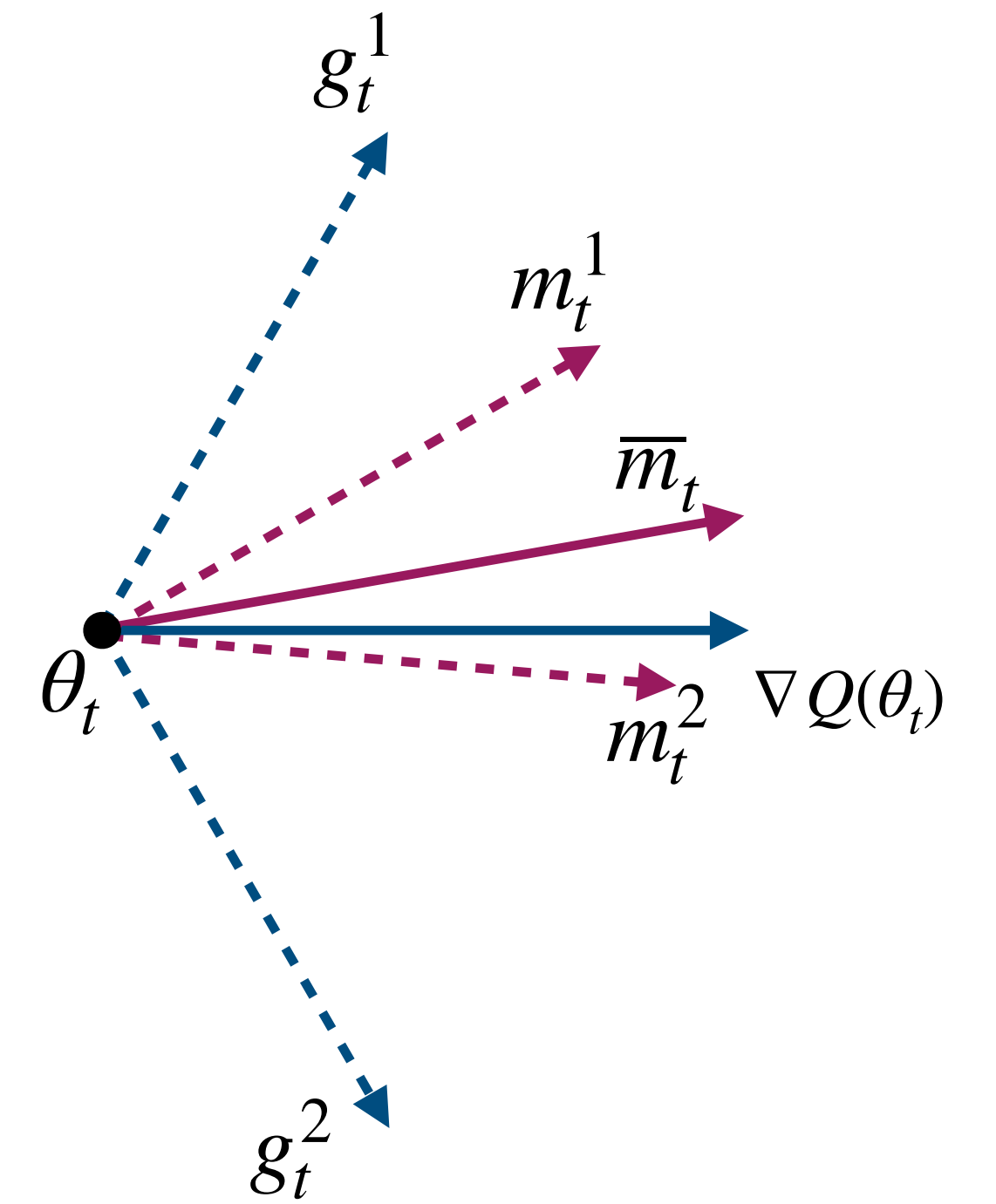
Caveat of Momentum



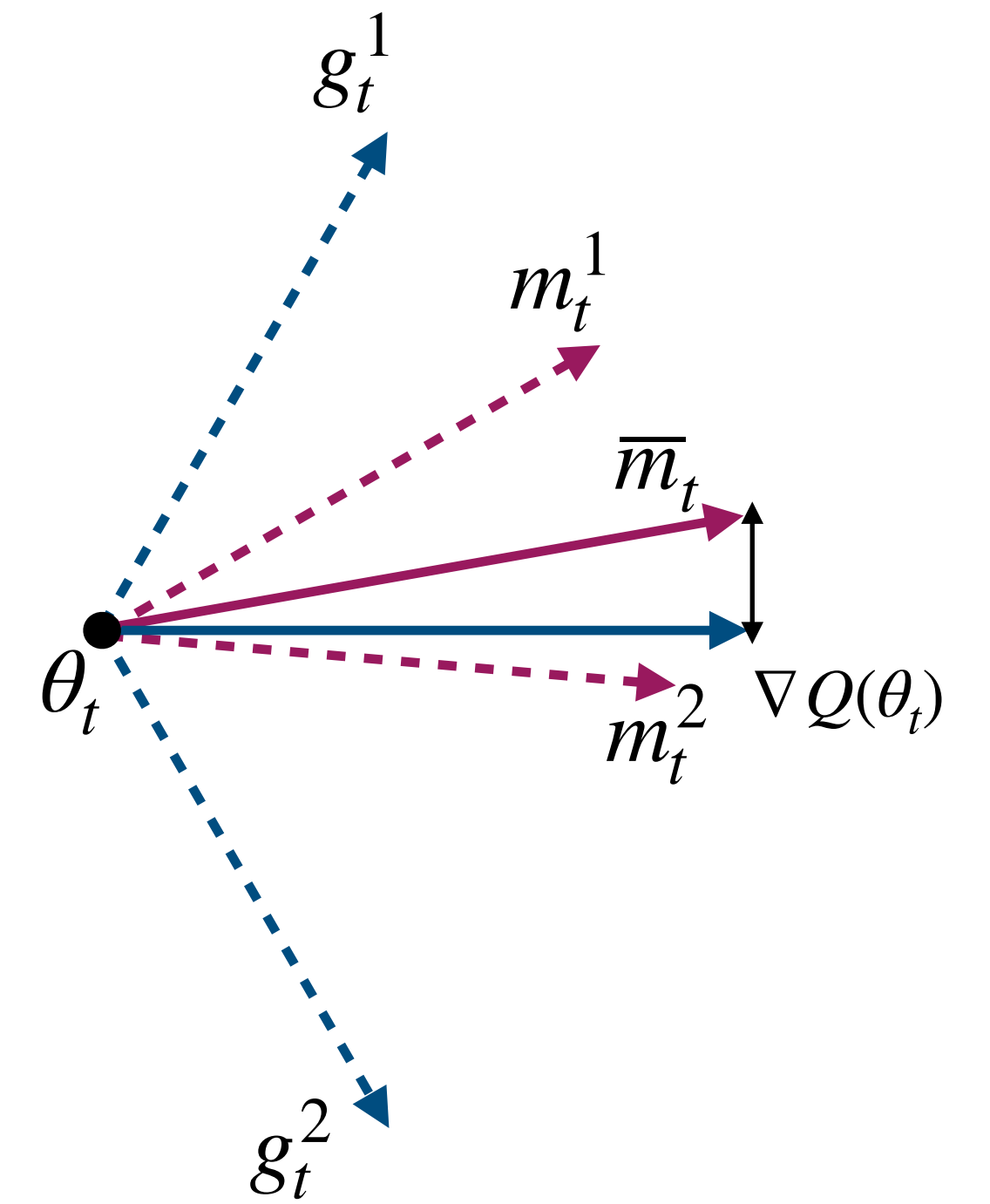
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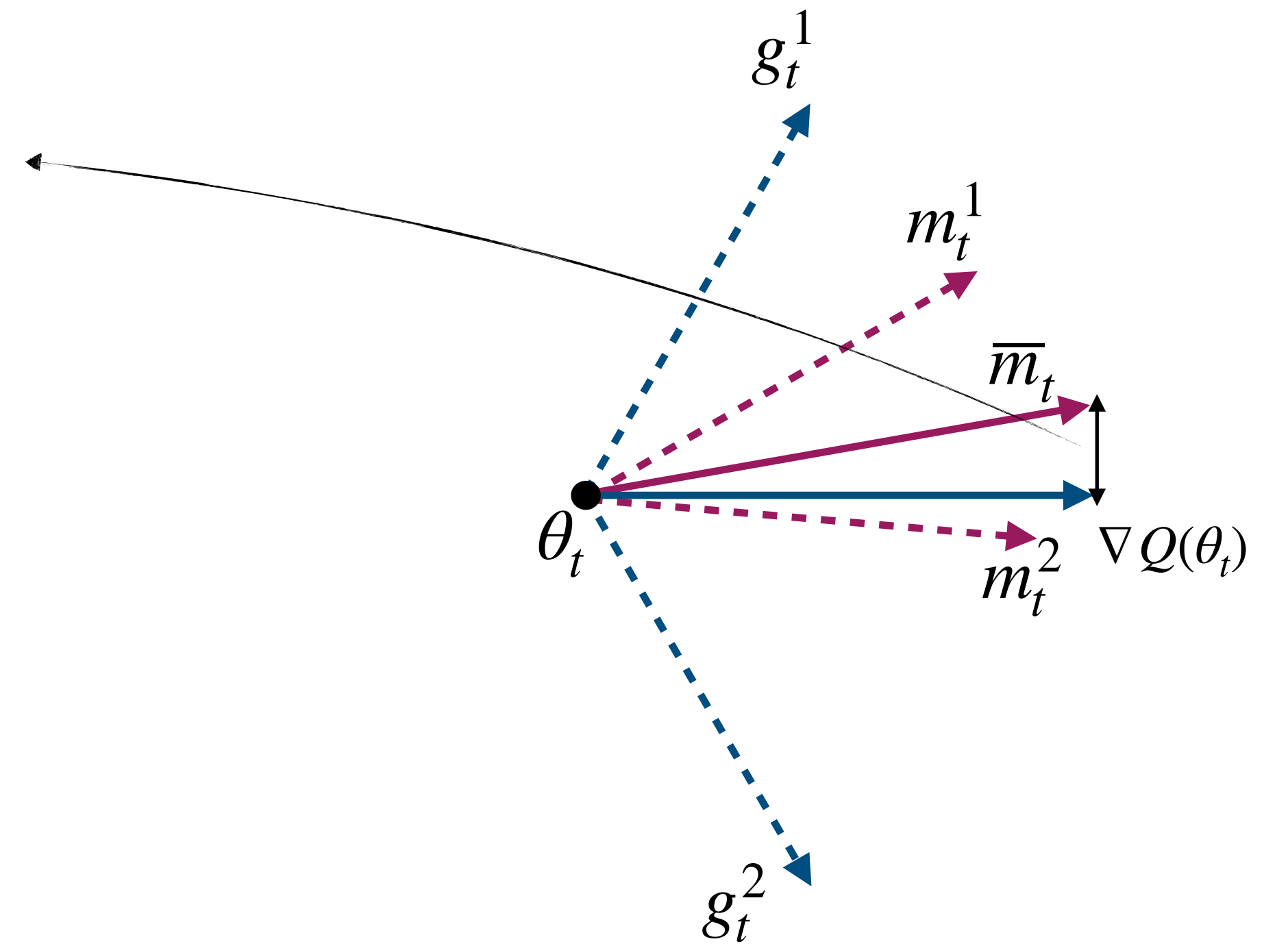
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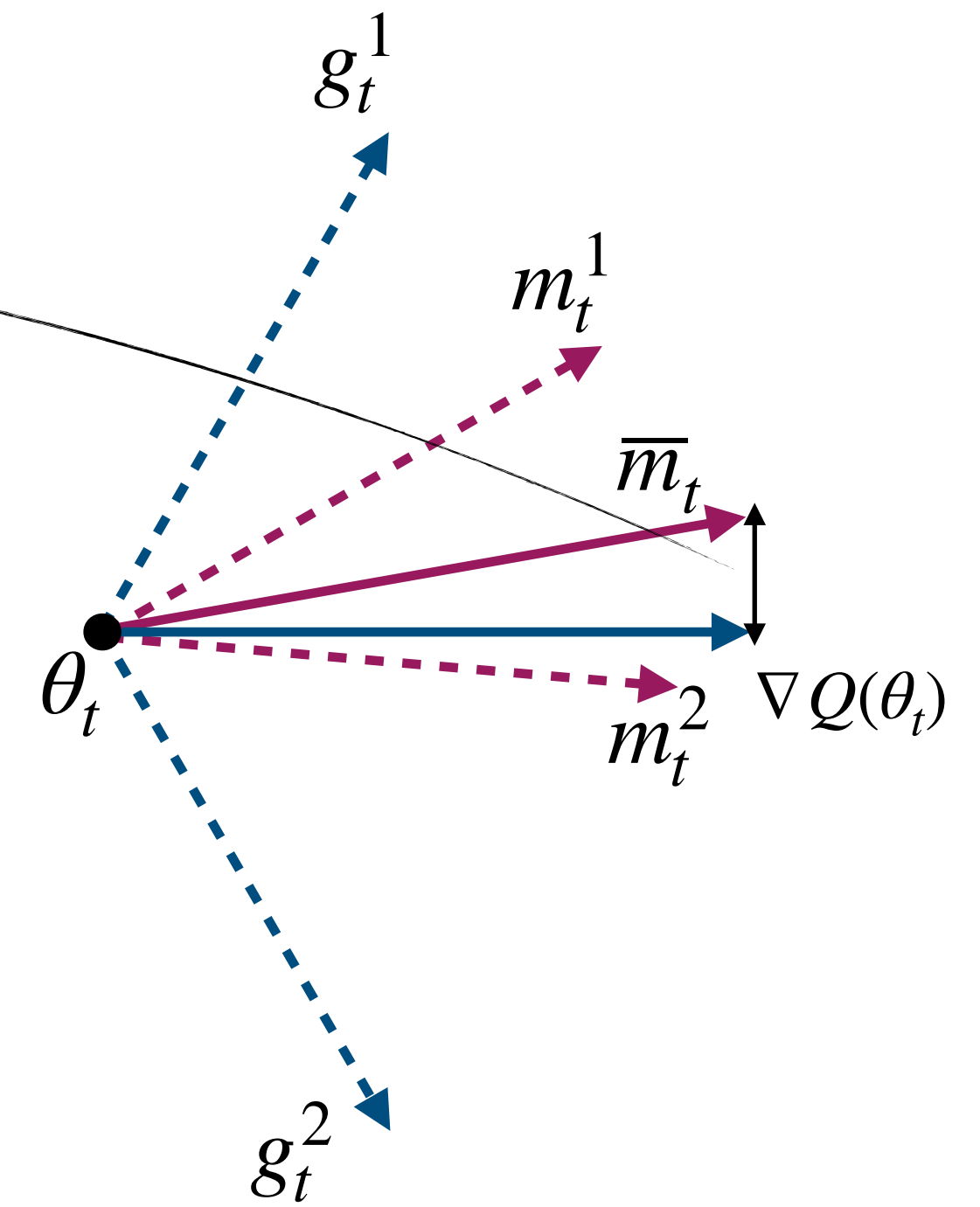


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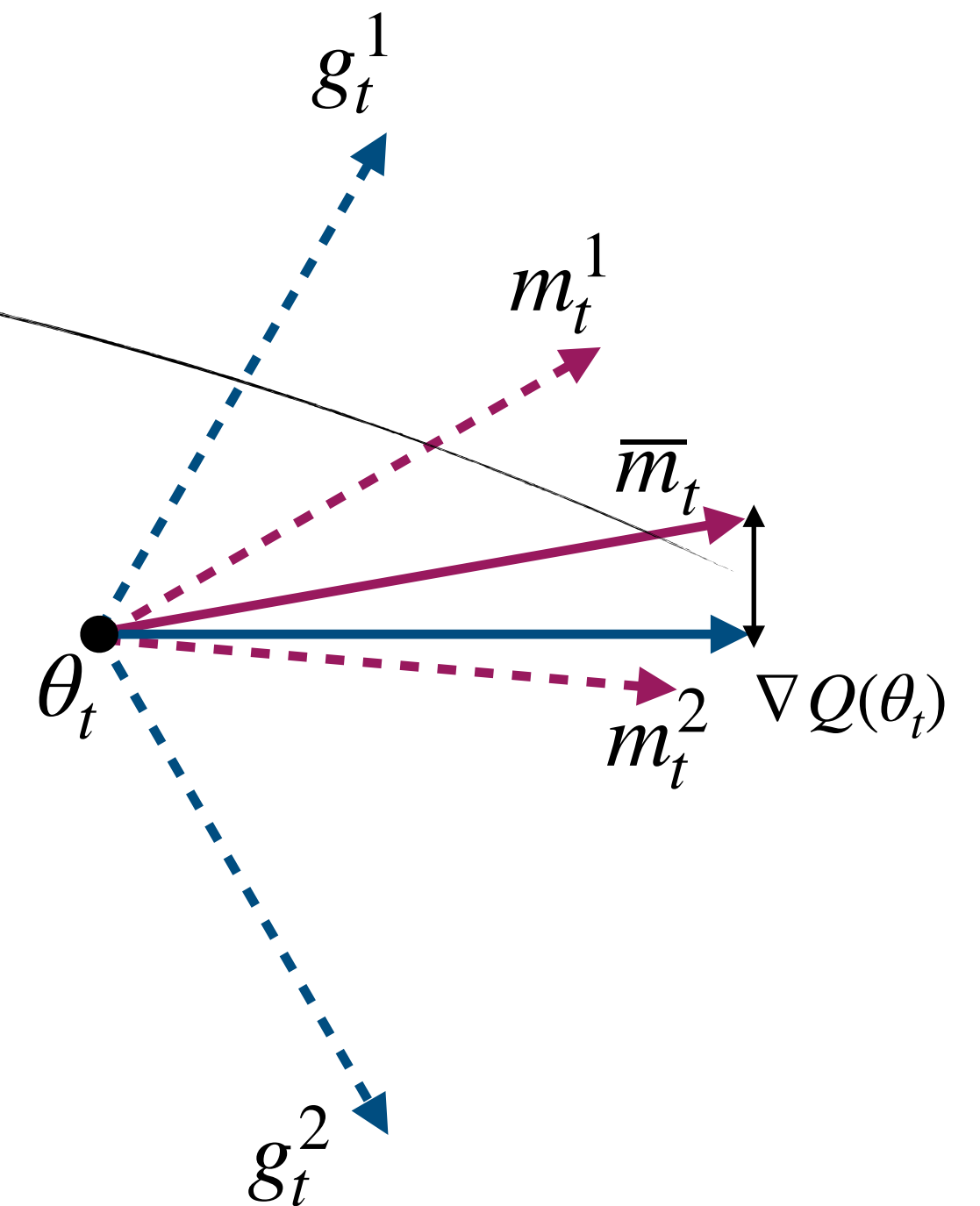
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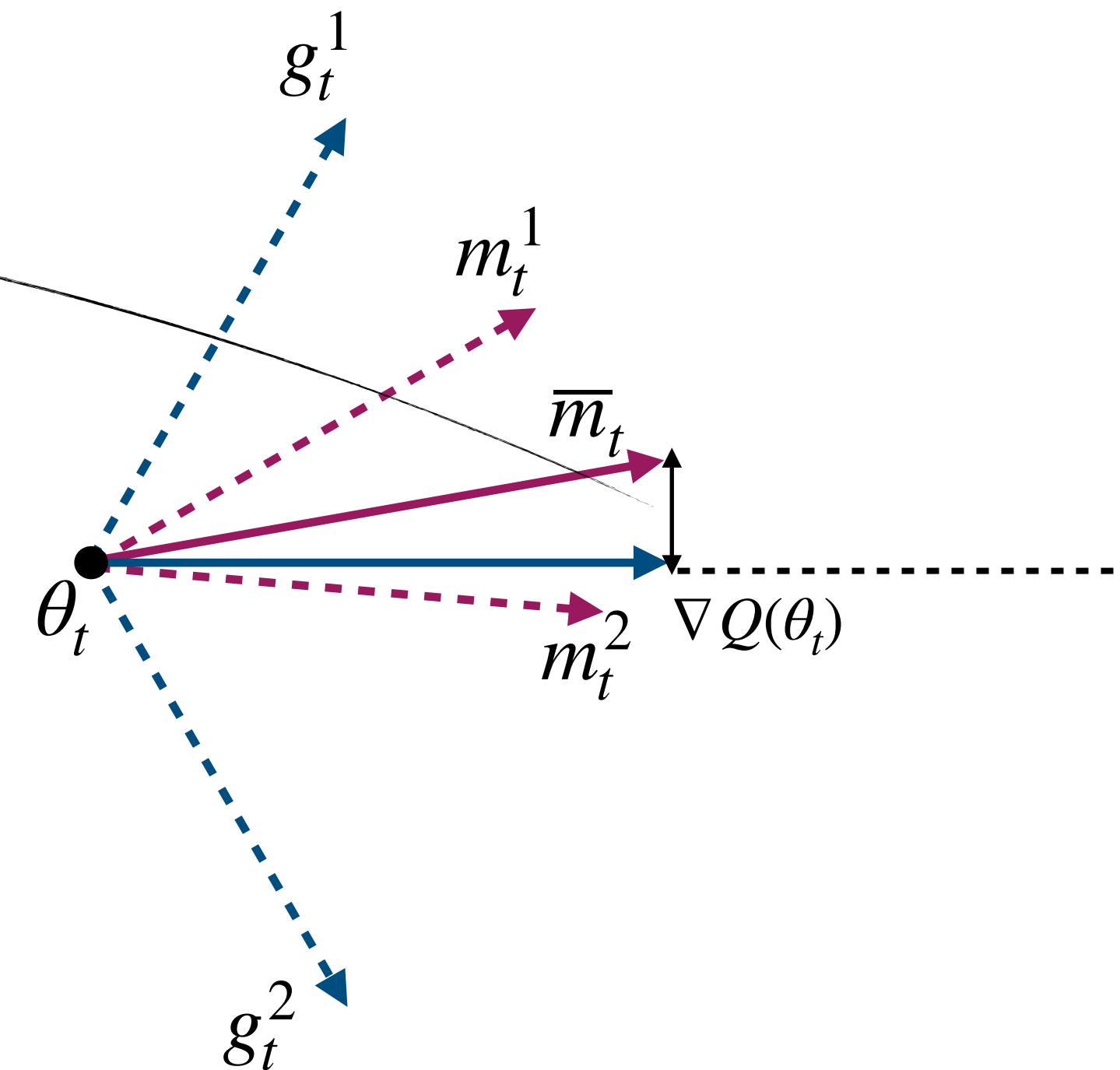
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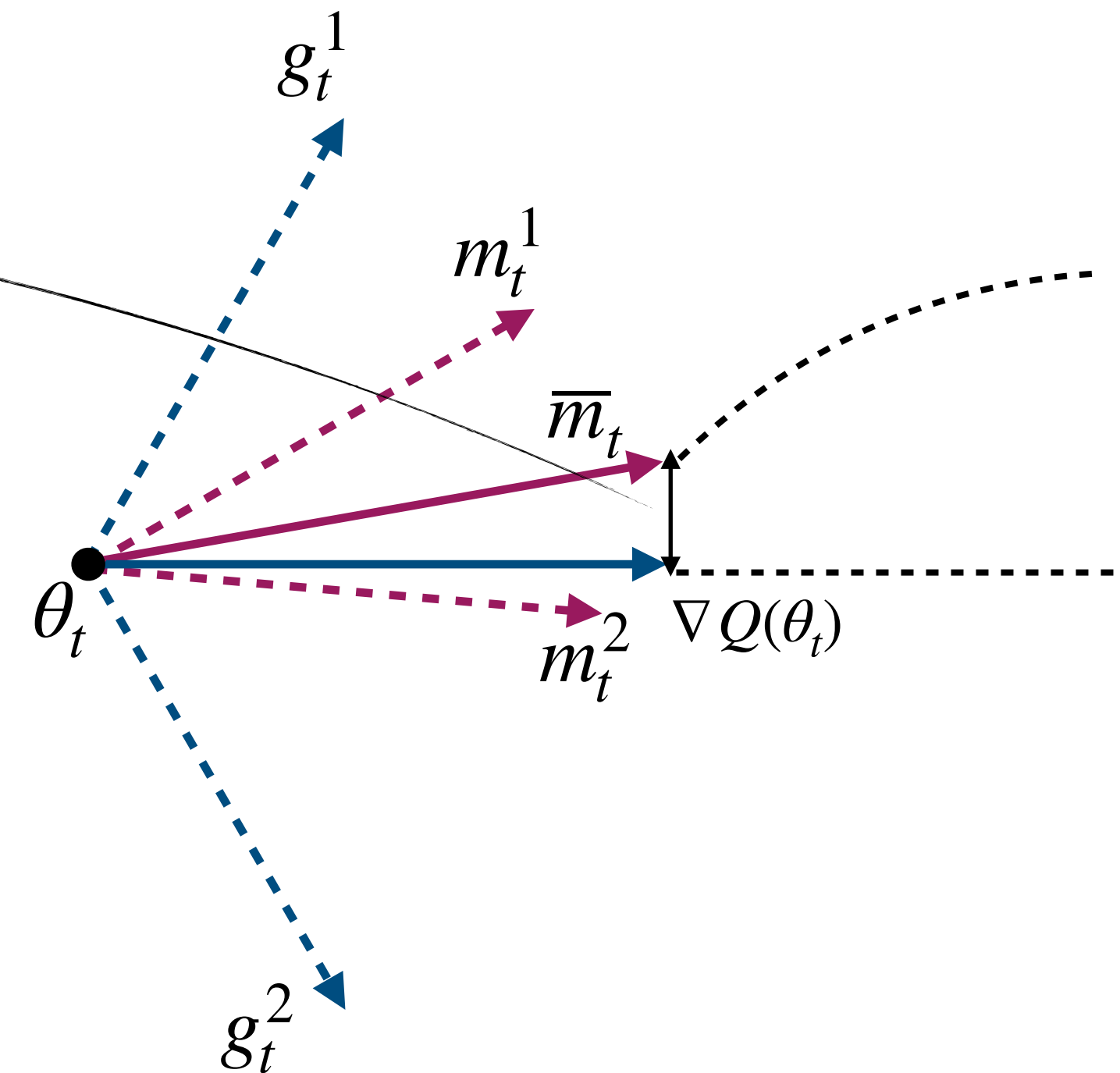
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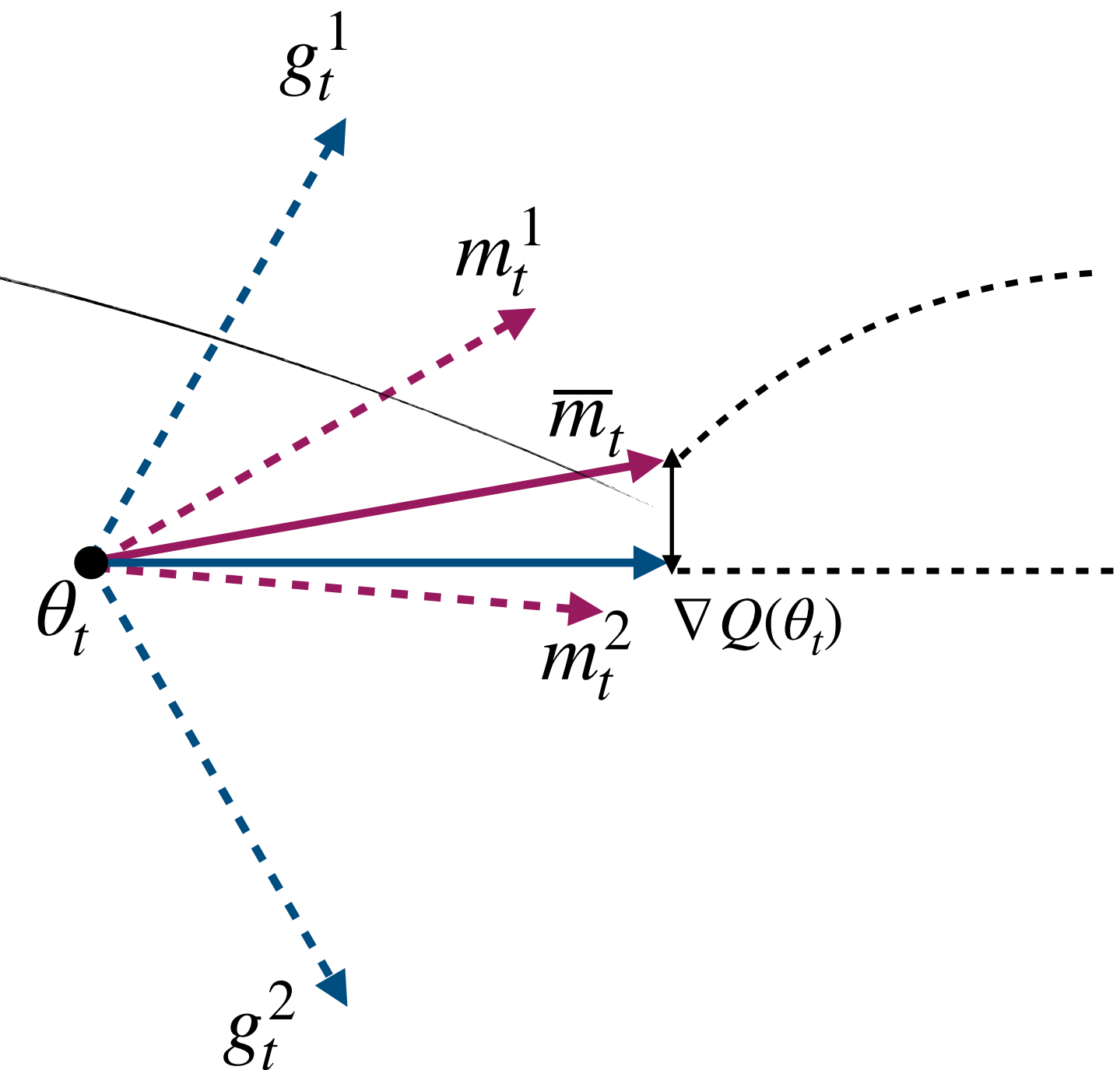
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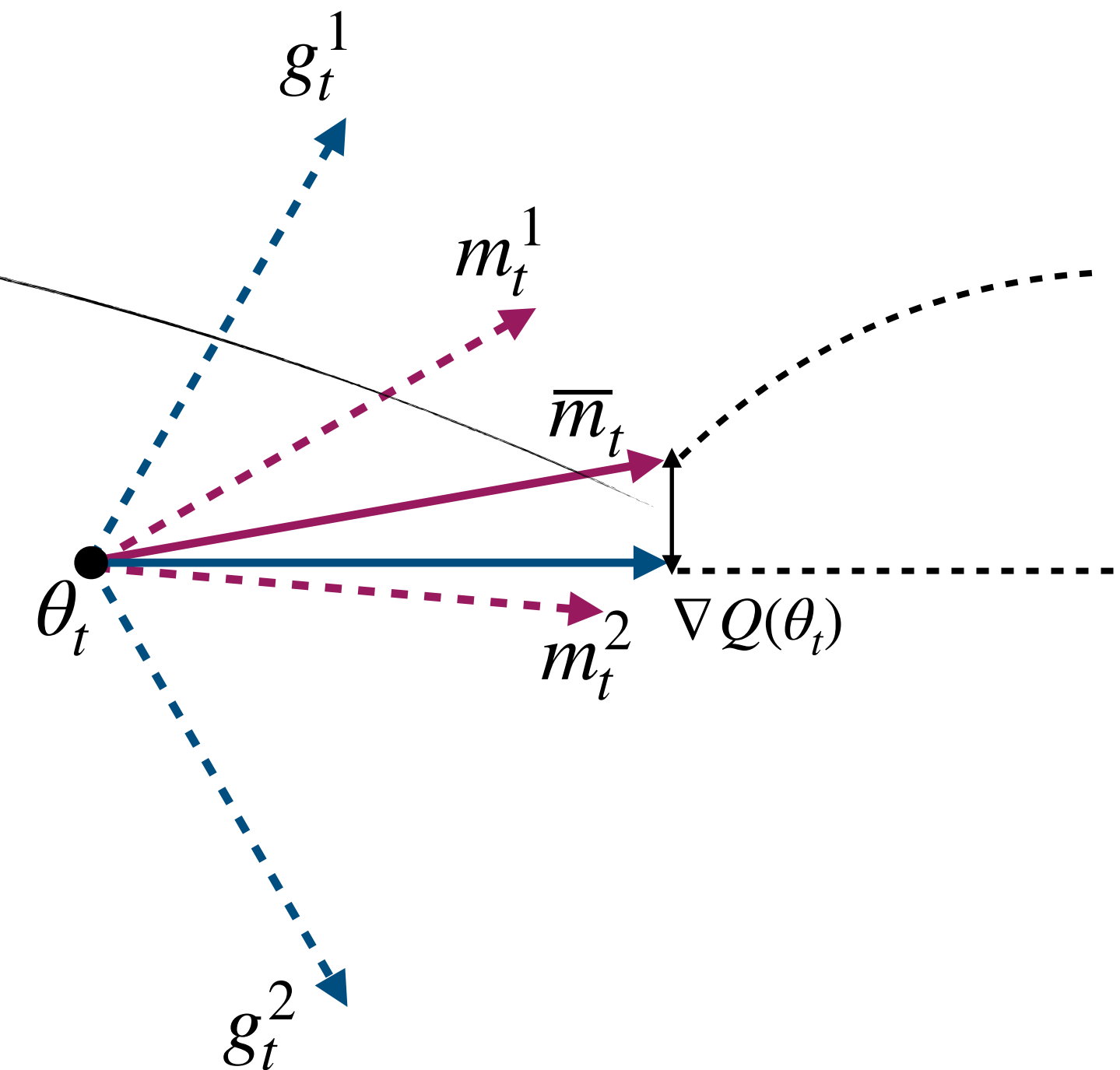
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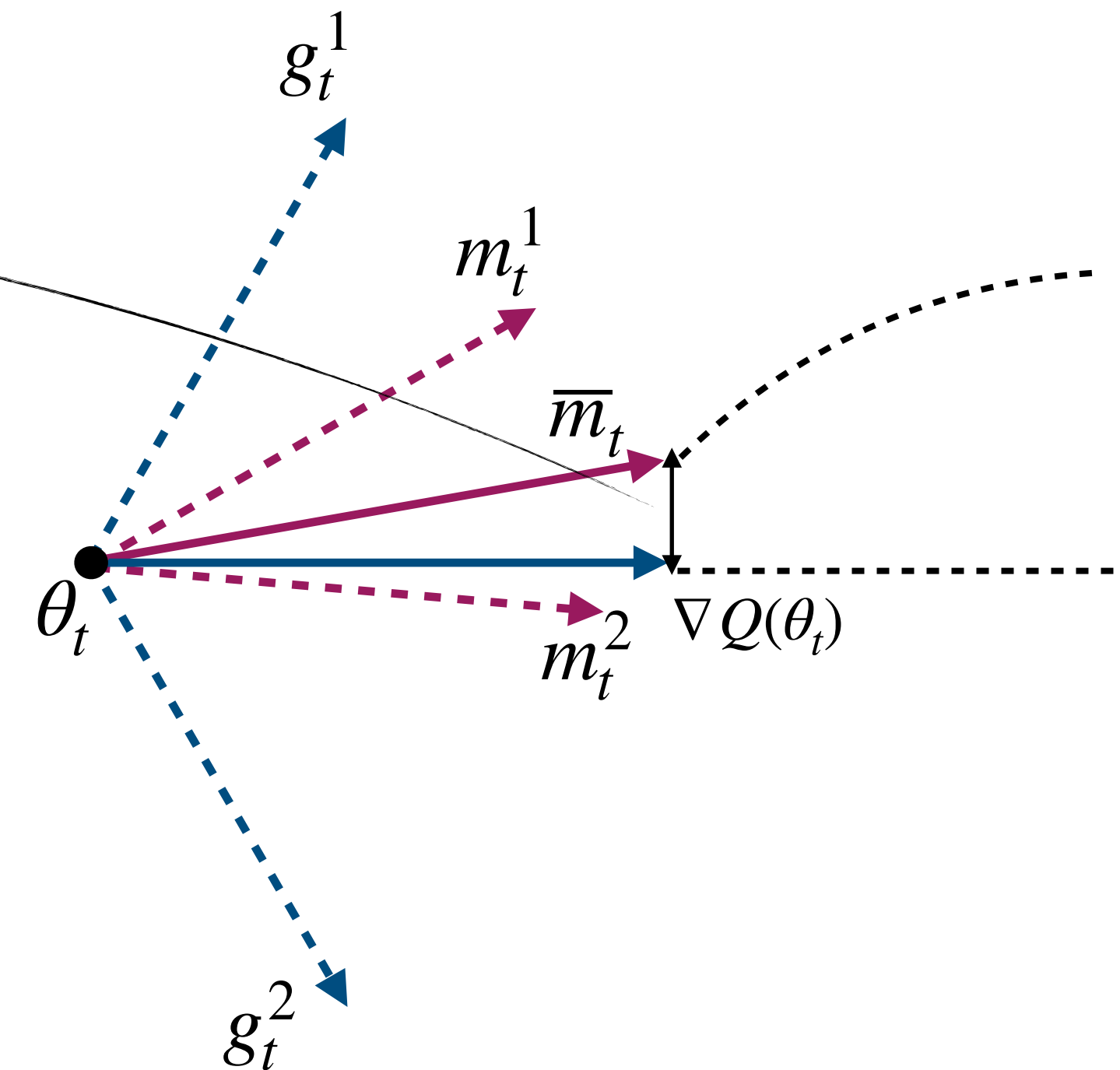


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β^2 \rightarrow Ideally small



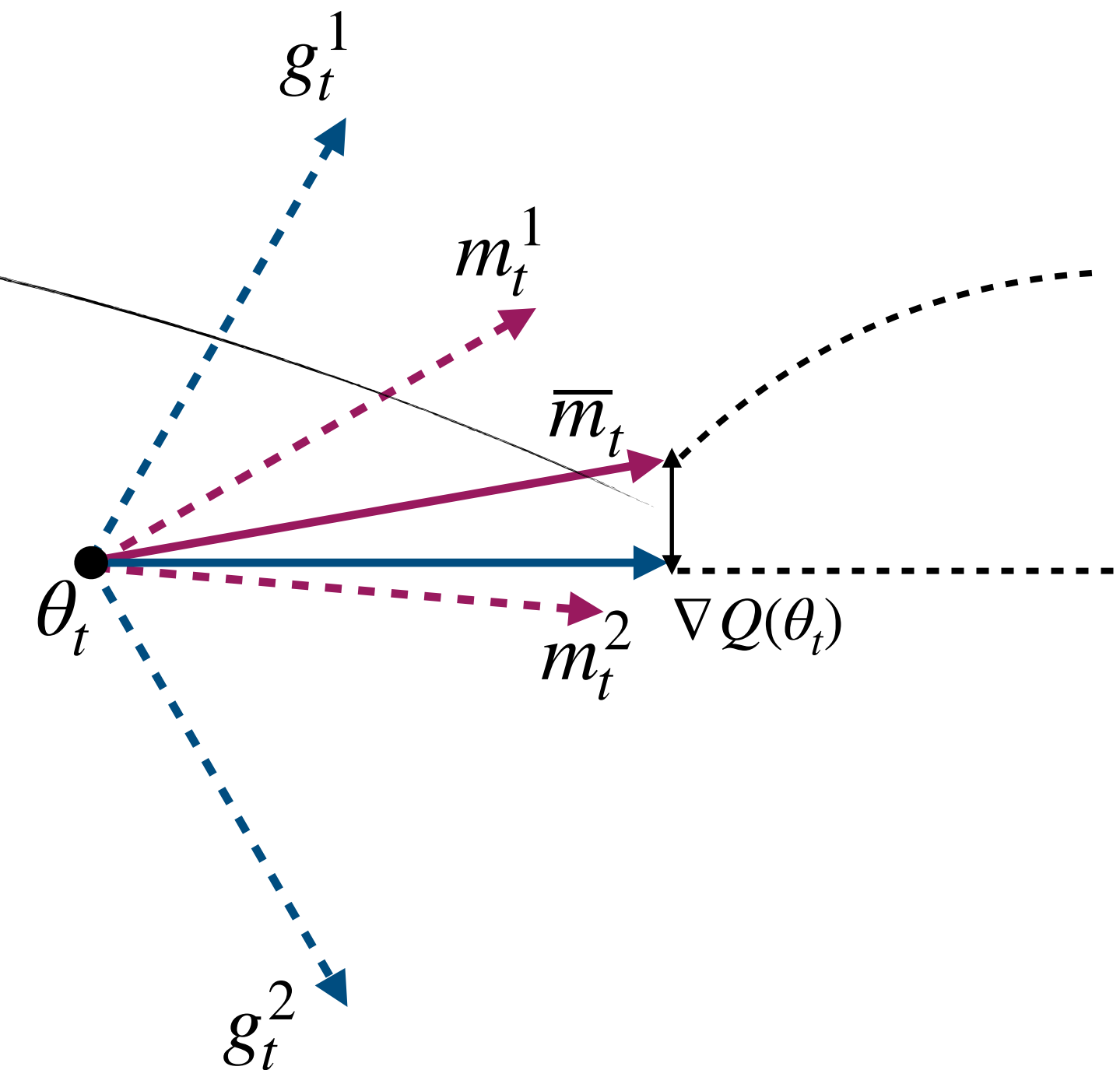
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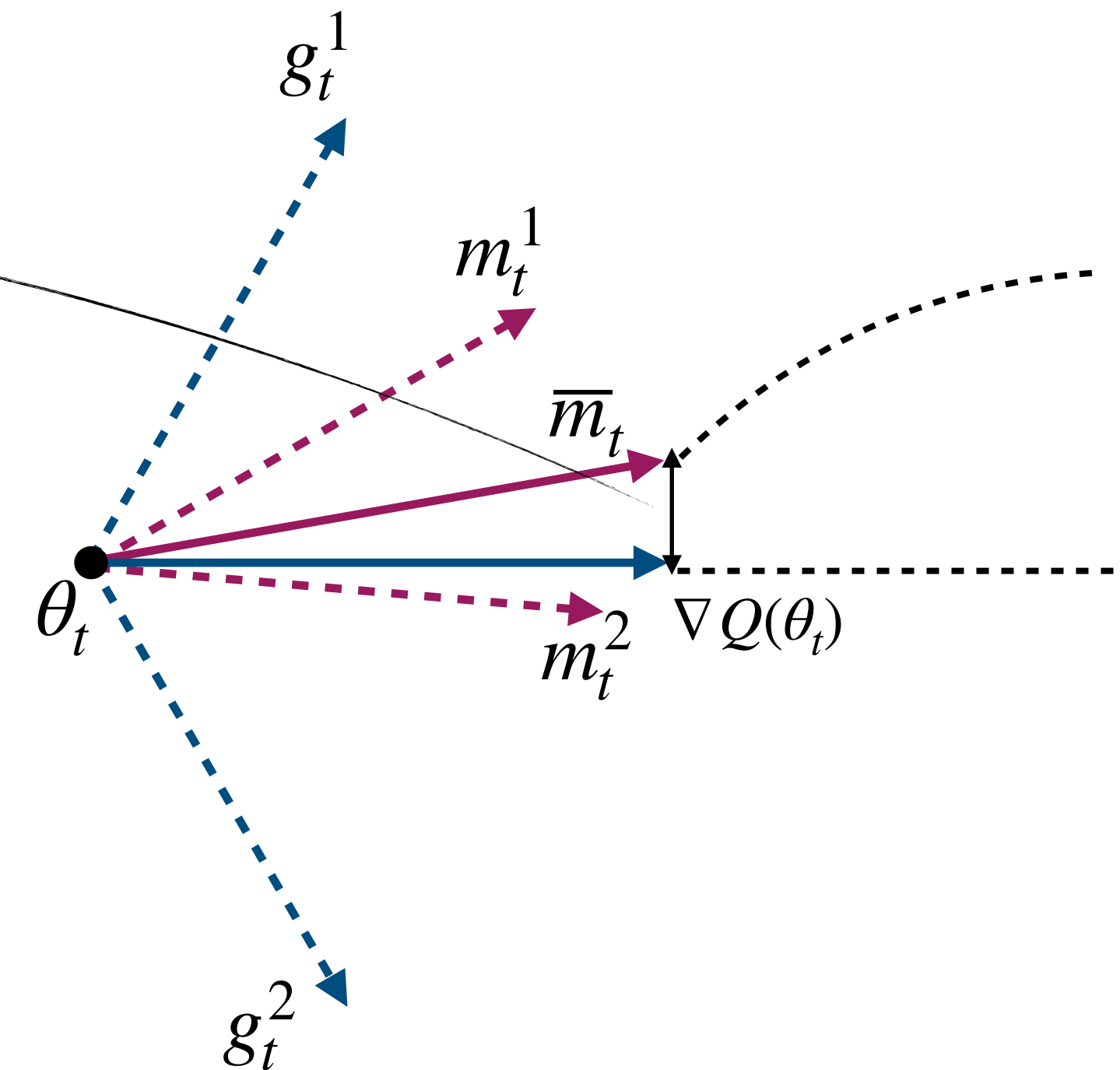
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IF the momentum coefficient is chosen wisely



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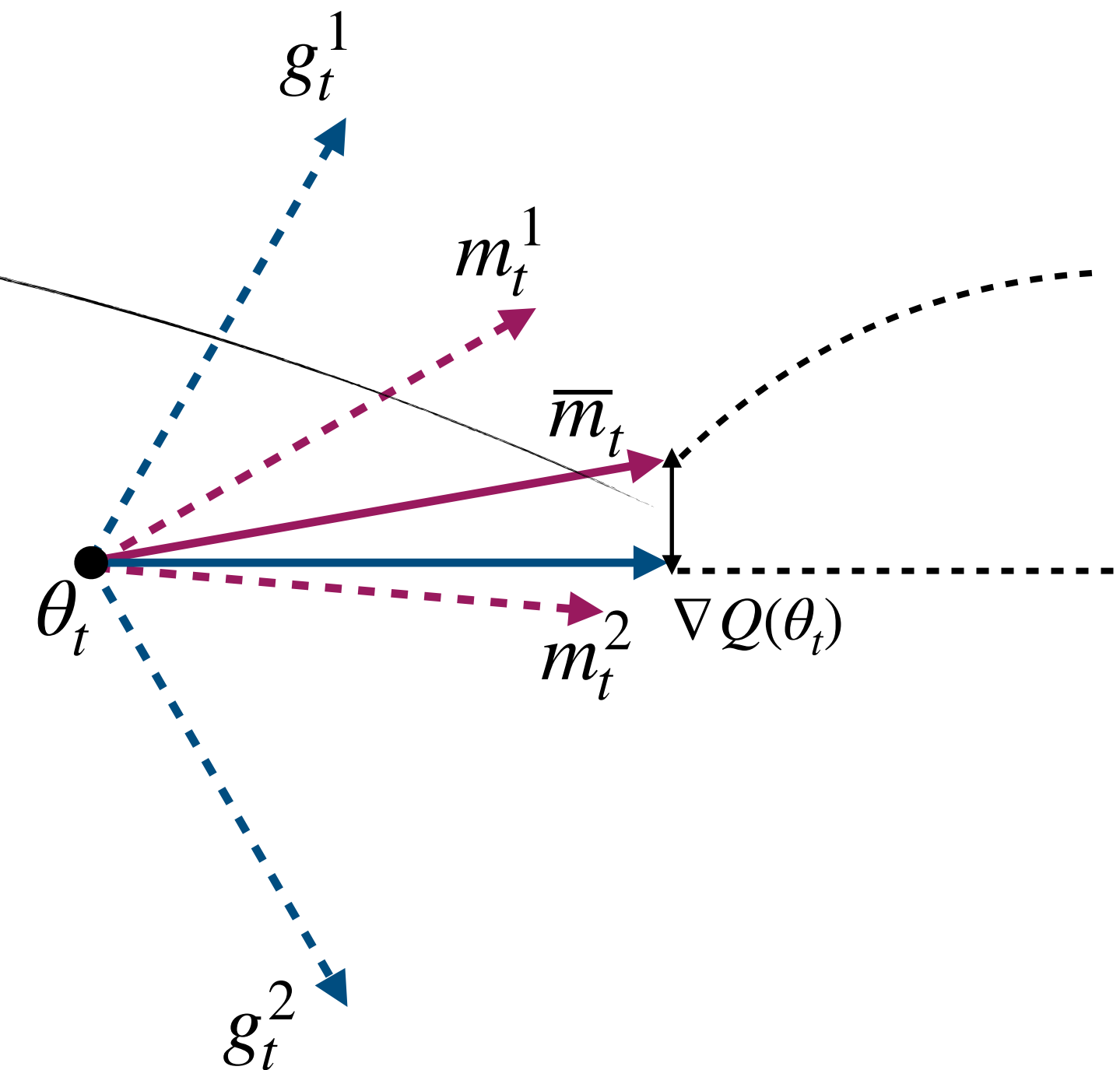
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IF the momentum coefficient is **chosen wisely**

THEN the **good** (reduced variance)
Outweighs the bad (biased gradient estimation)



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Robustness property of F - **key** to optimally utilize Momentum

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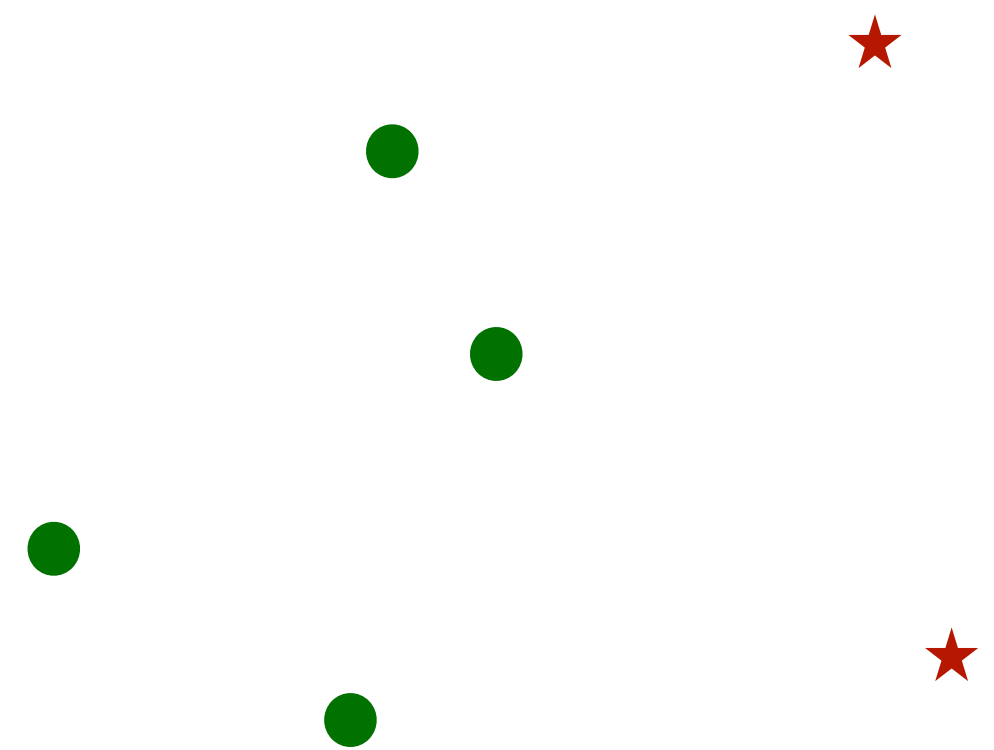
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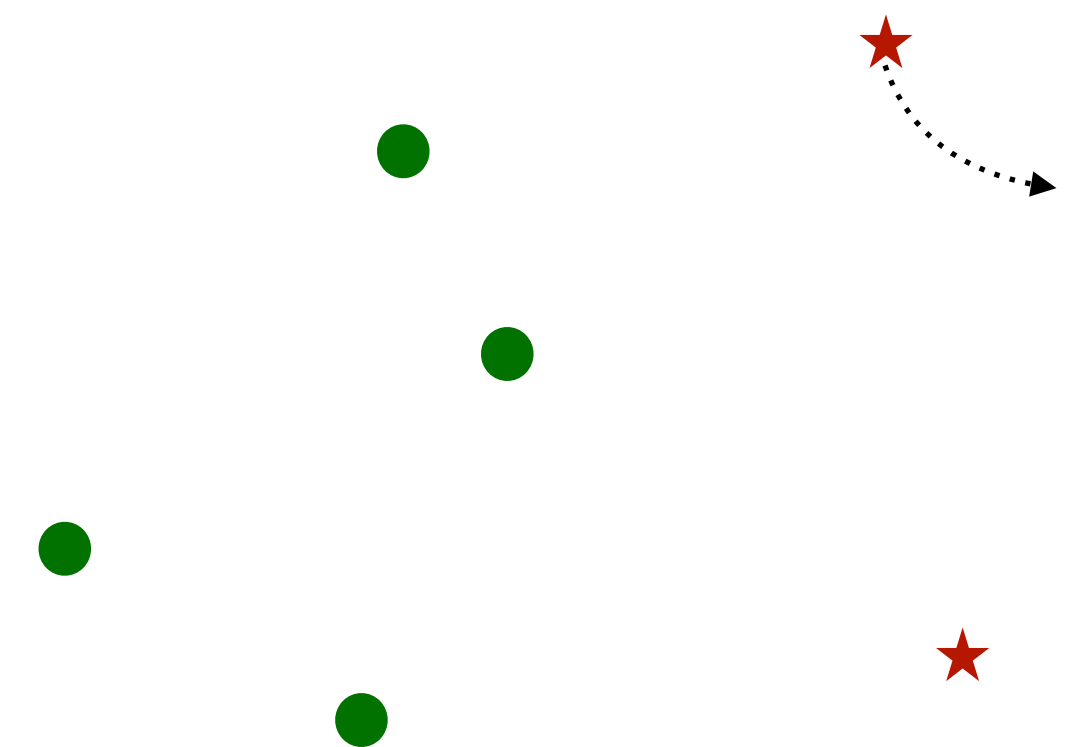
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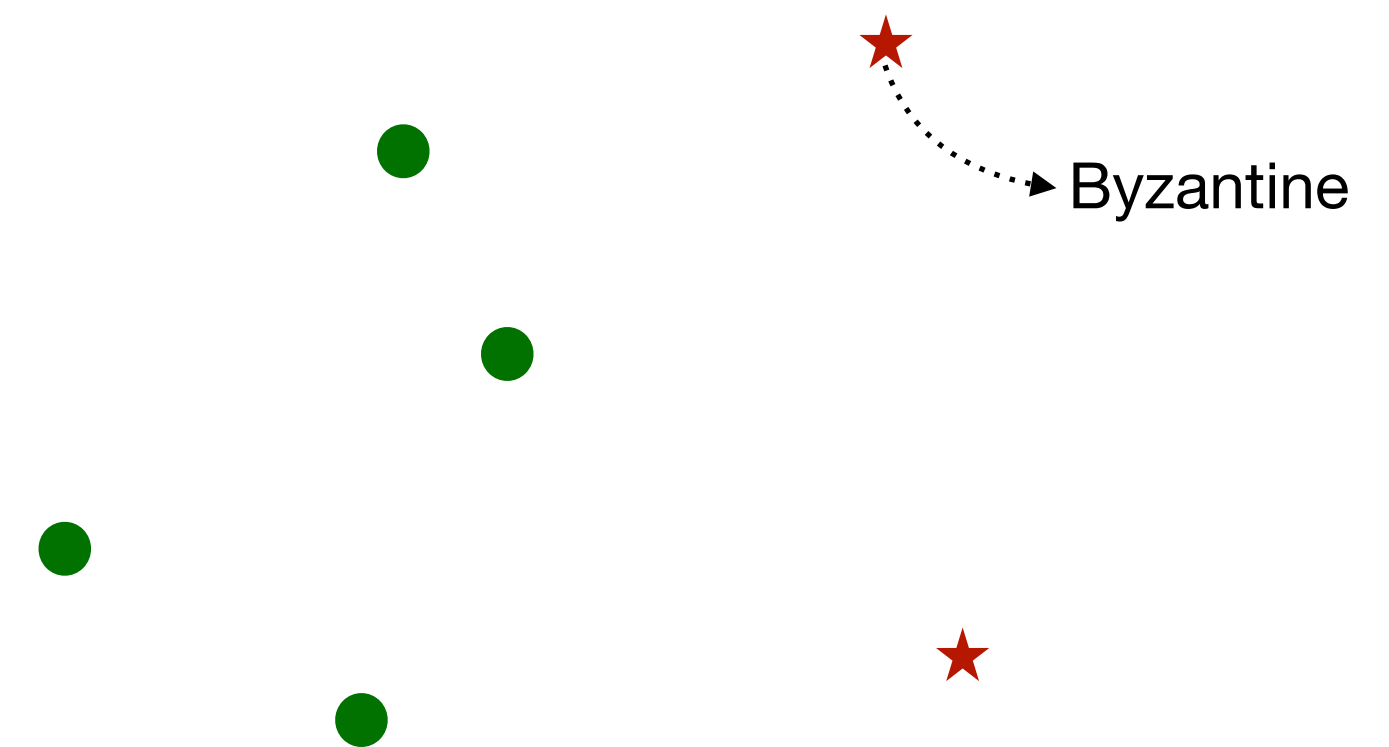
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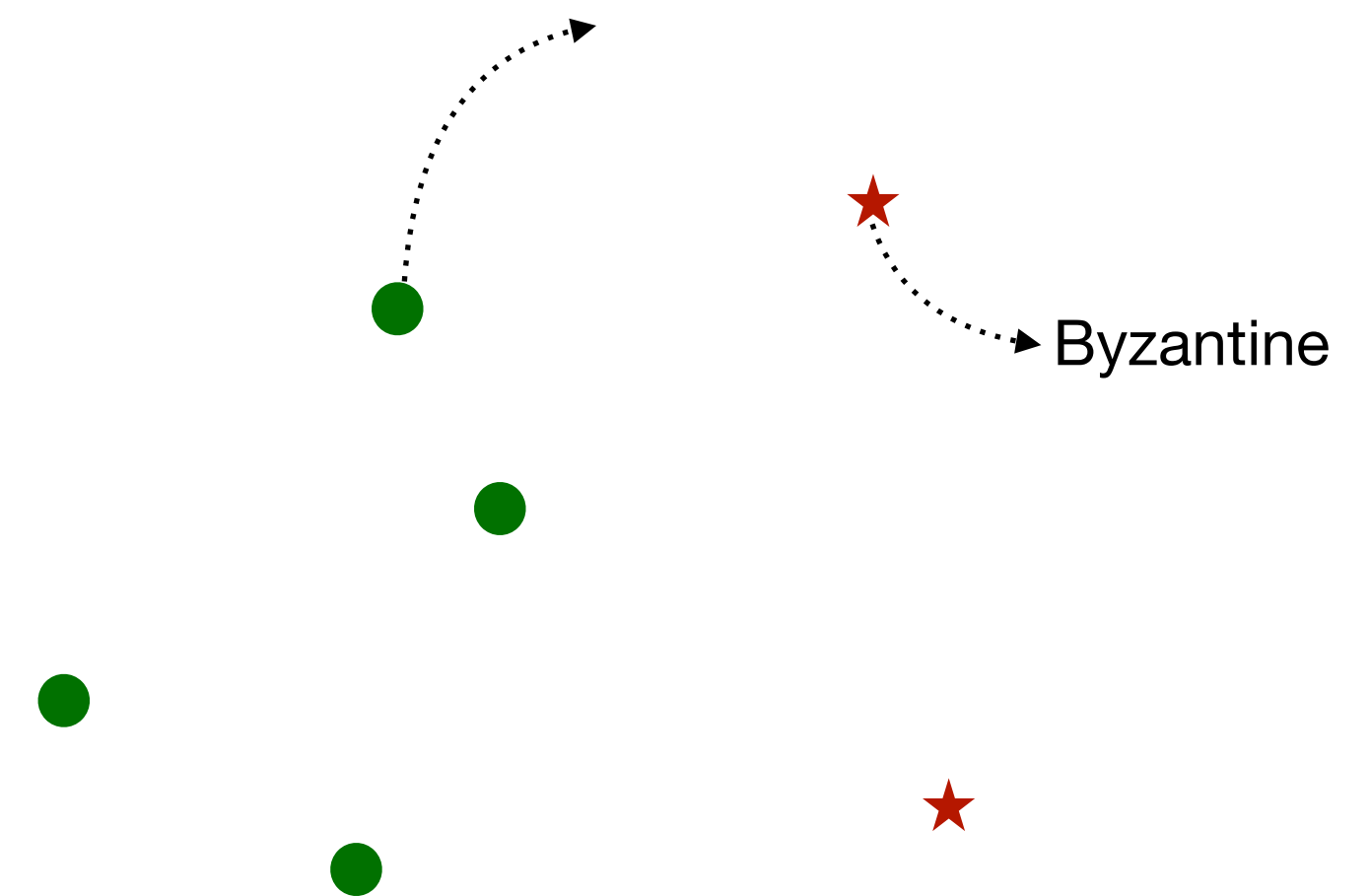
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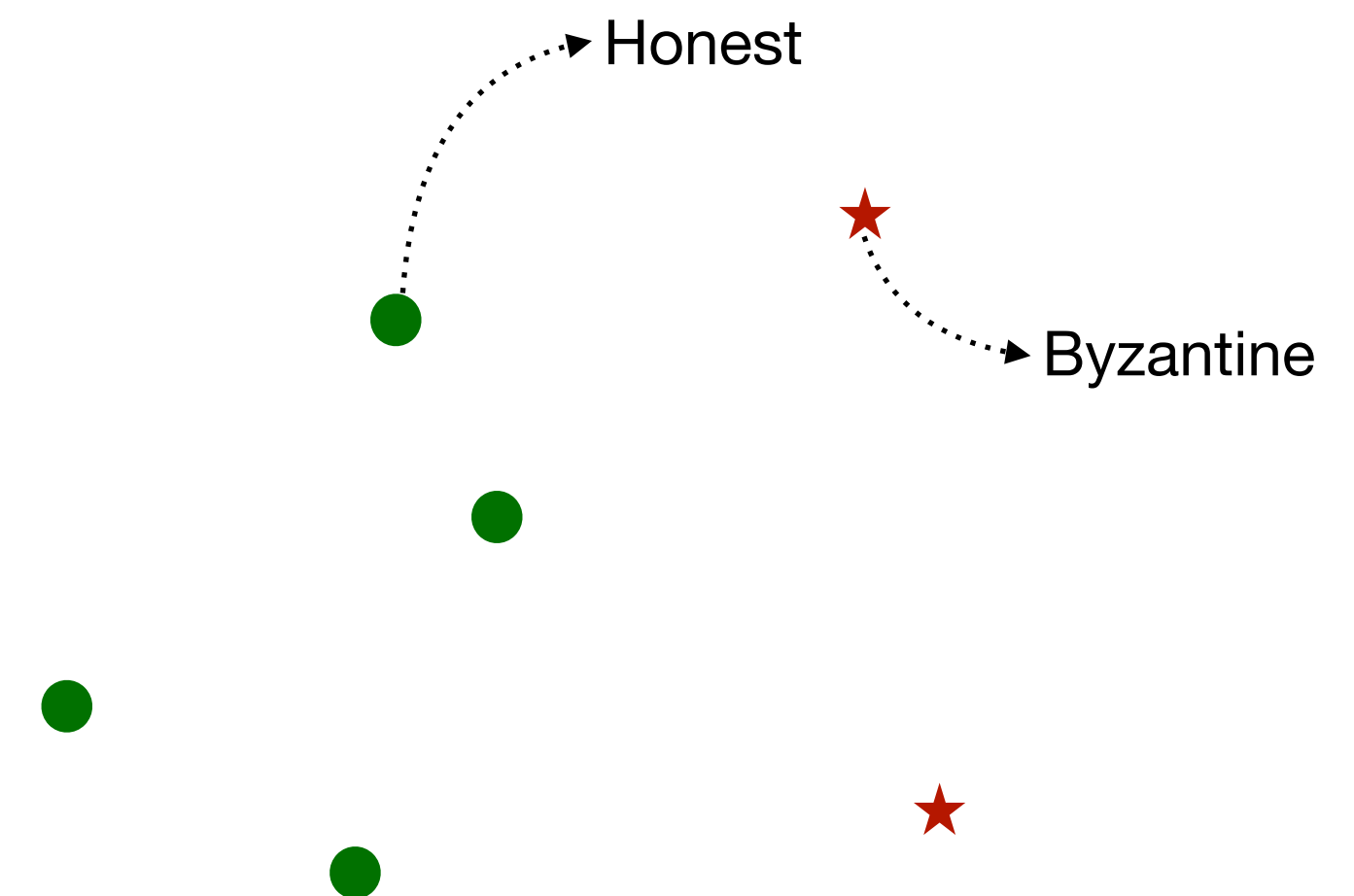
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Avg. of $\{x_i\}_{i \in S}$

Resilience coefficient



Resilient Averaging (RESA)

Robustness property of F - **key** to optimally utilize Momentum

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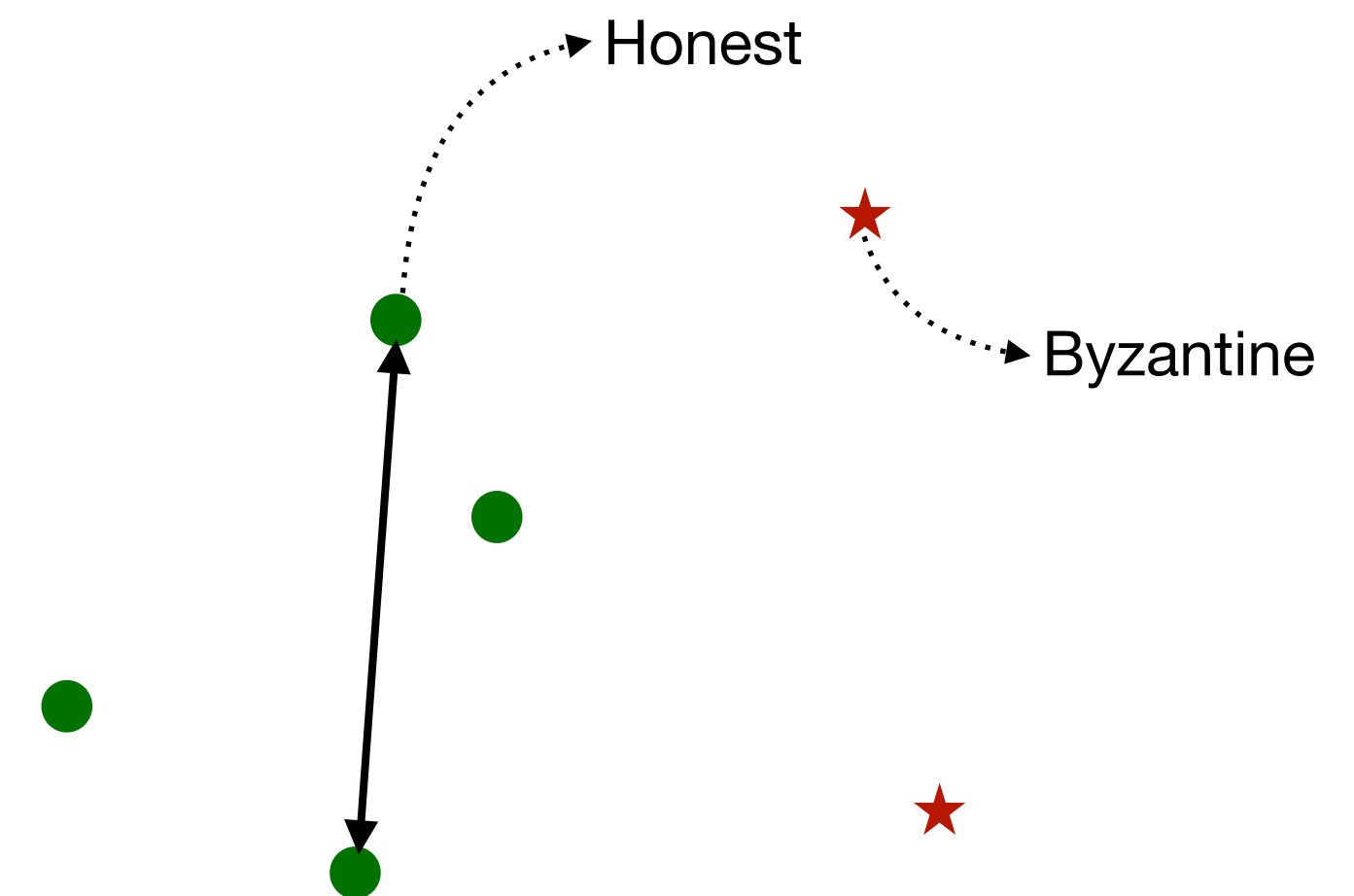
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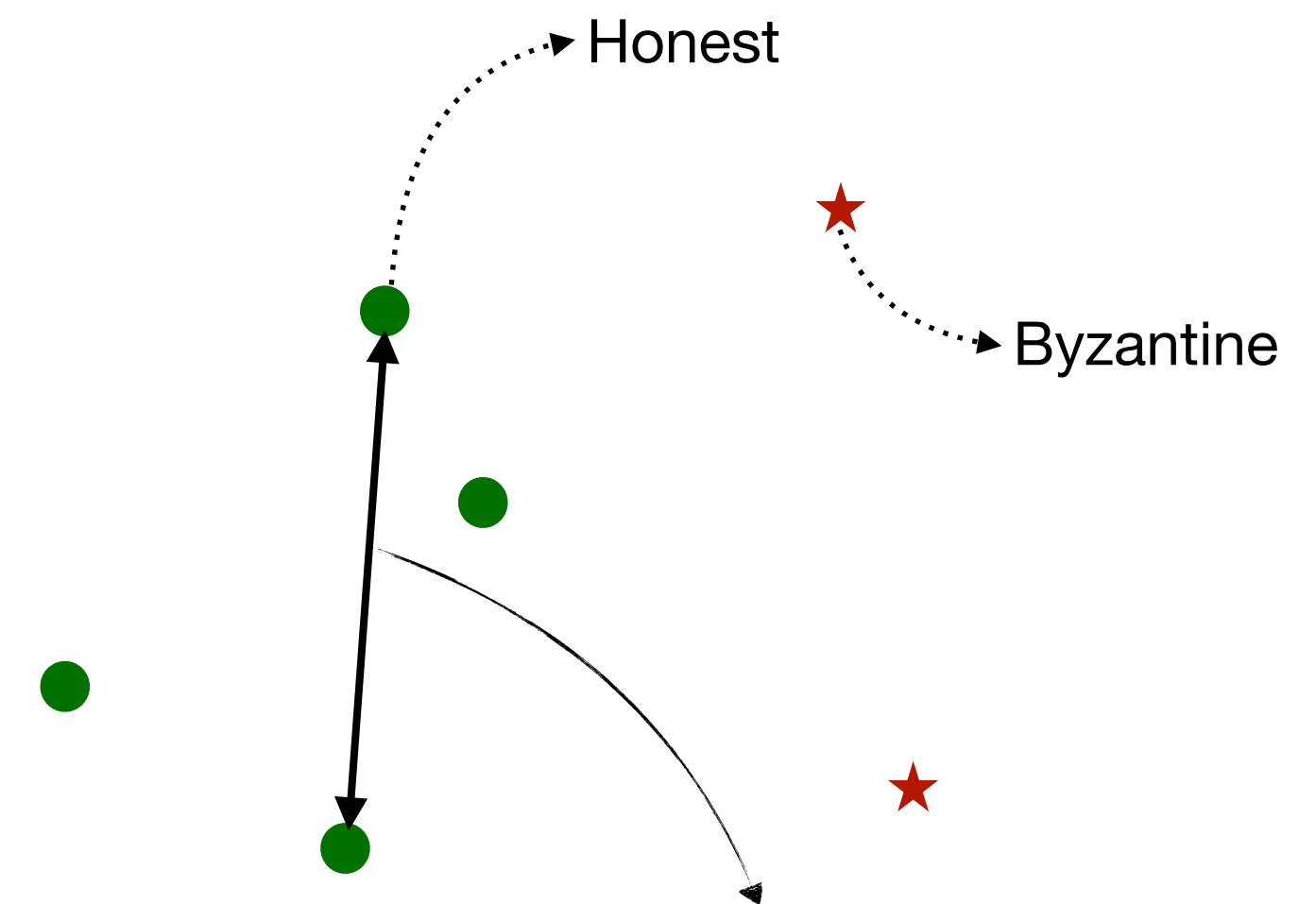
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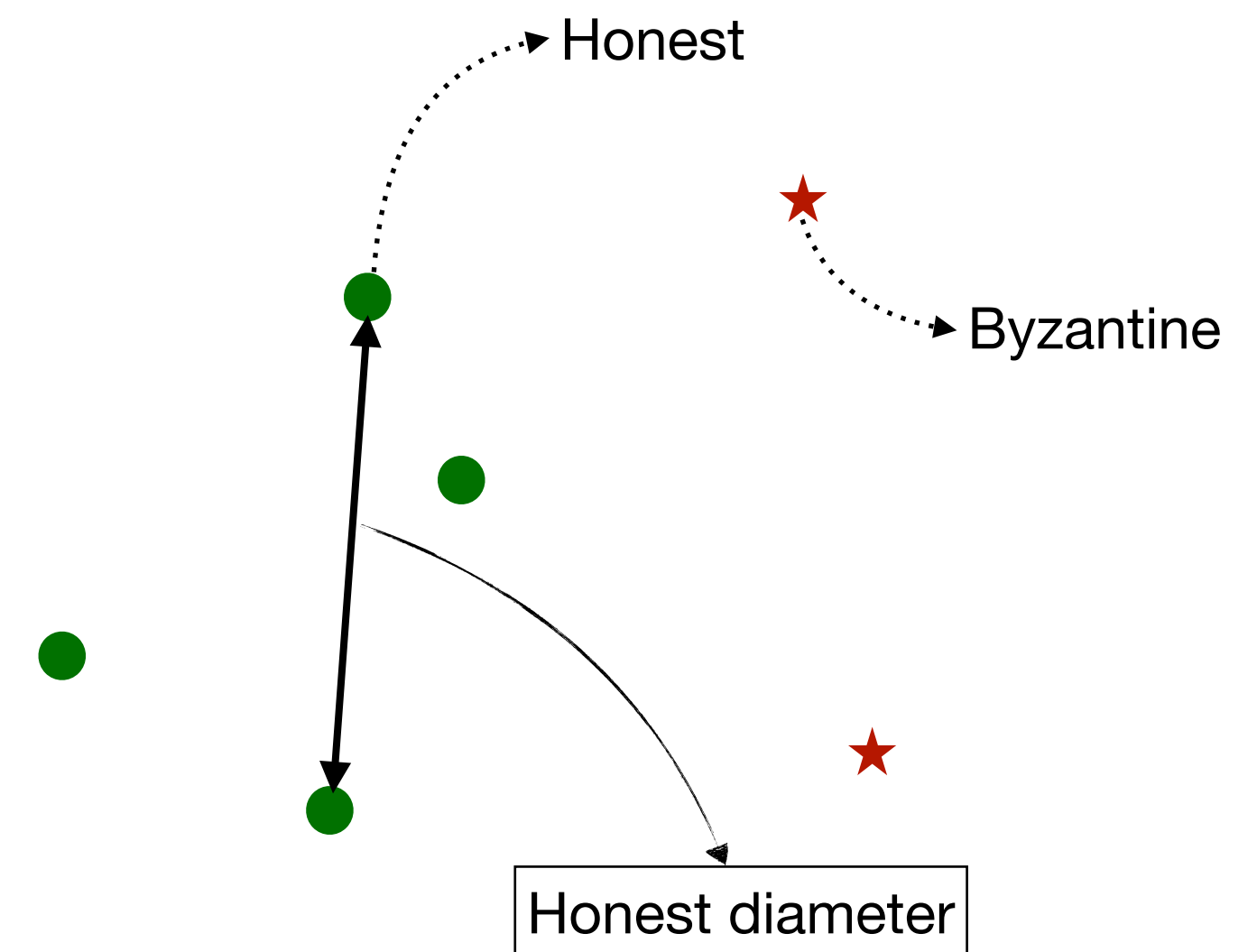
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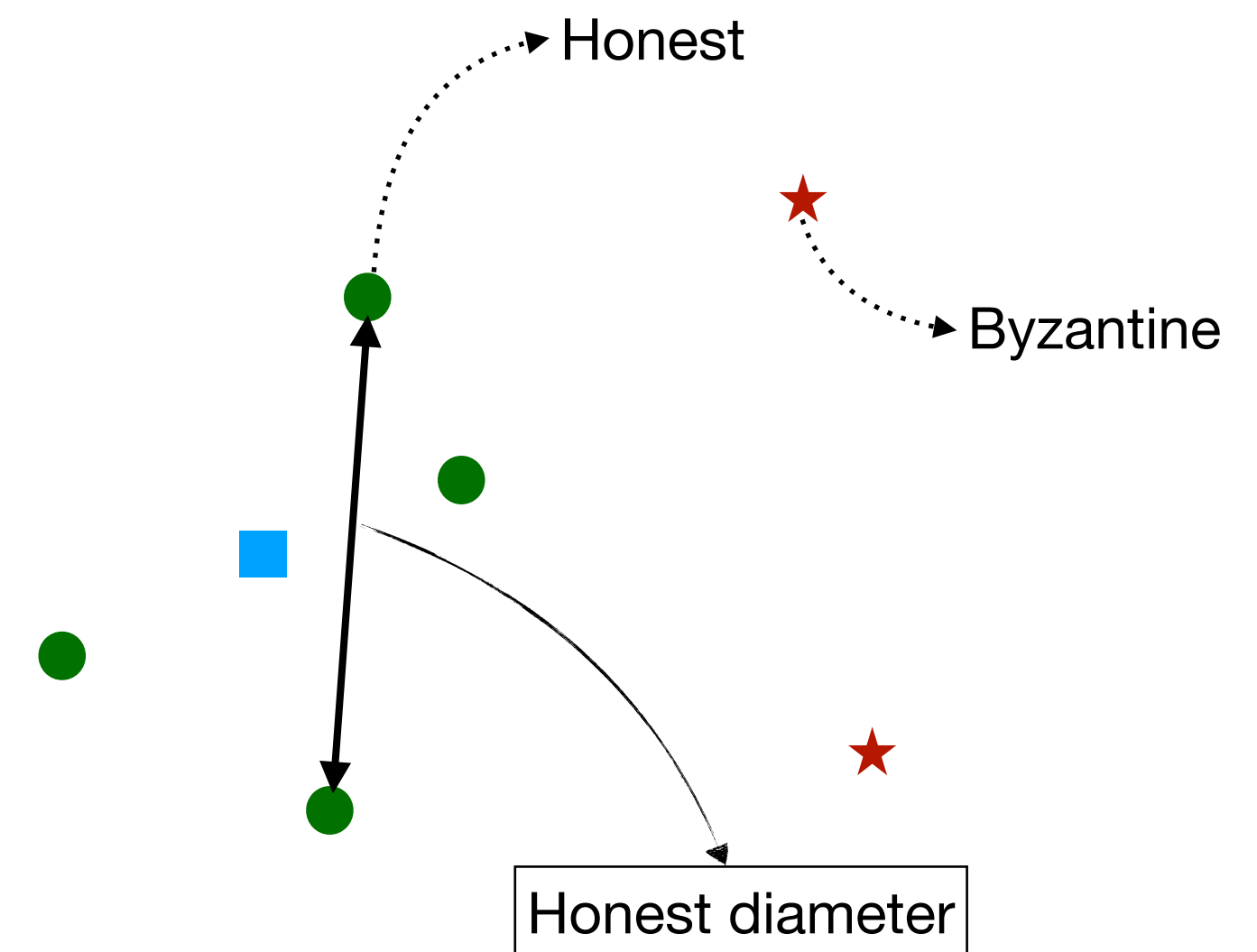
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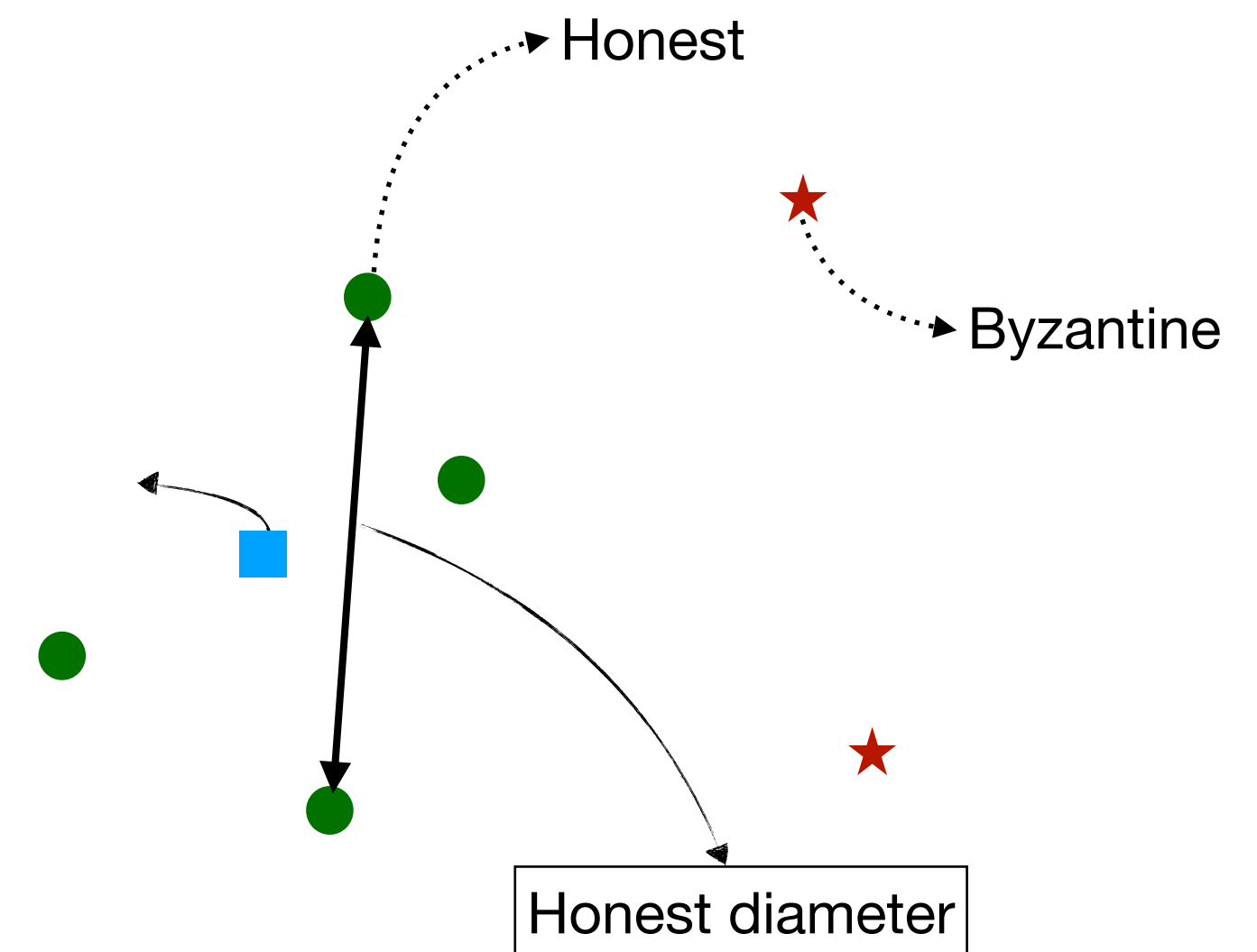
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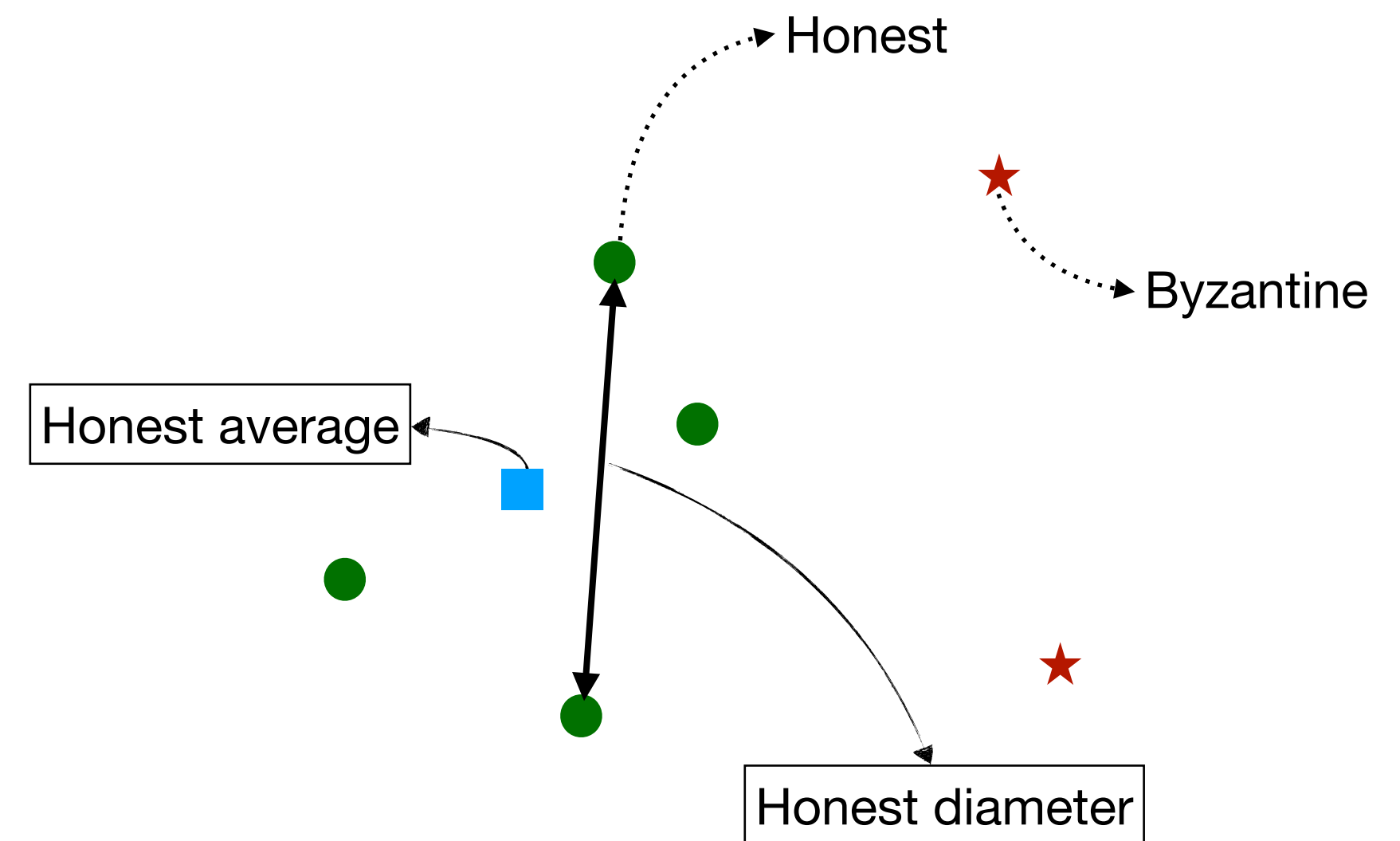
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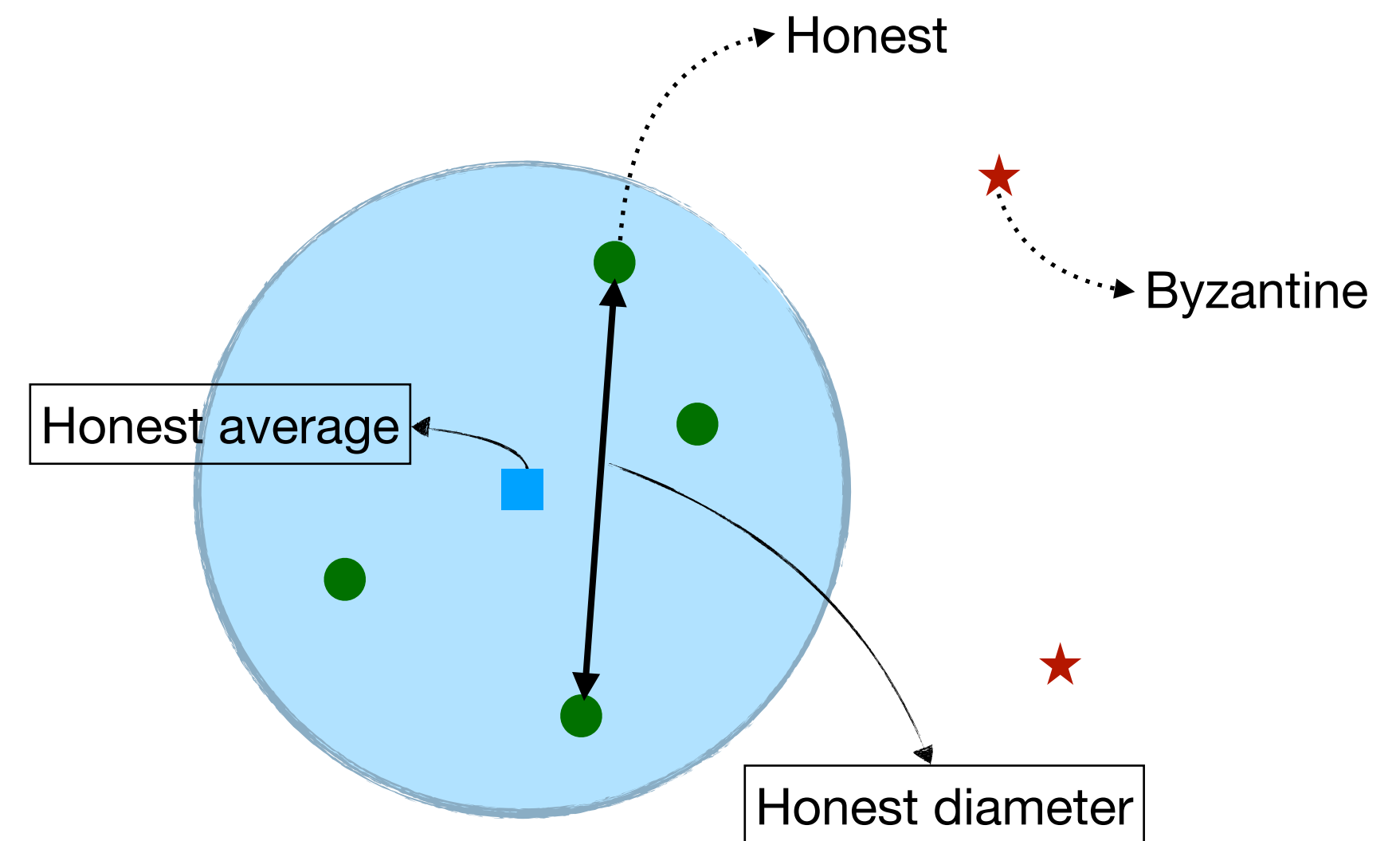
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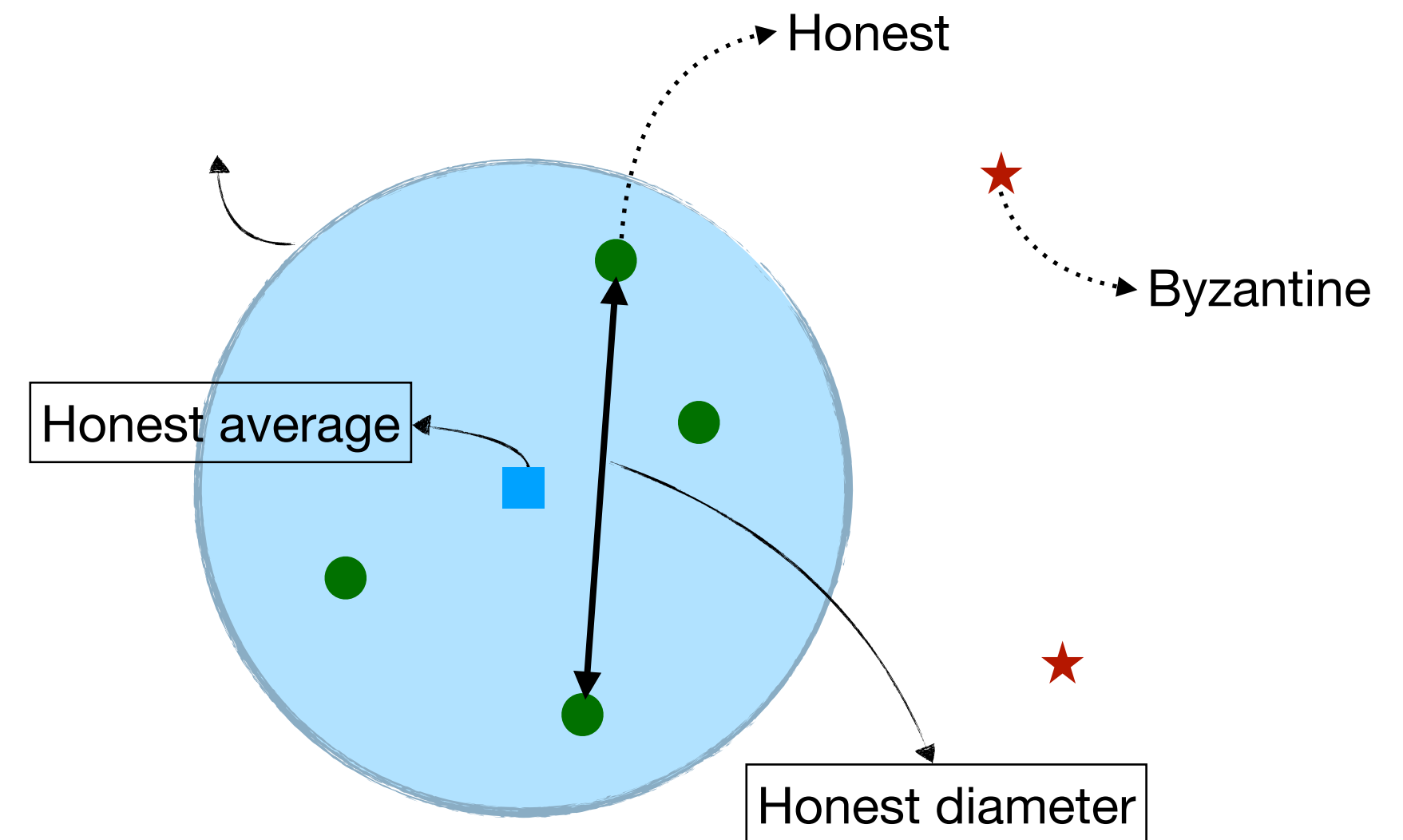
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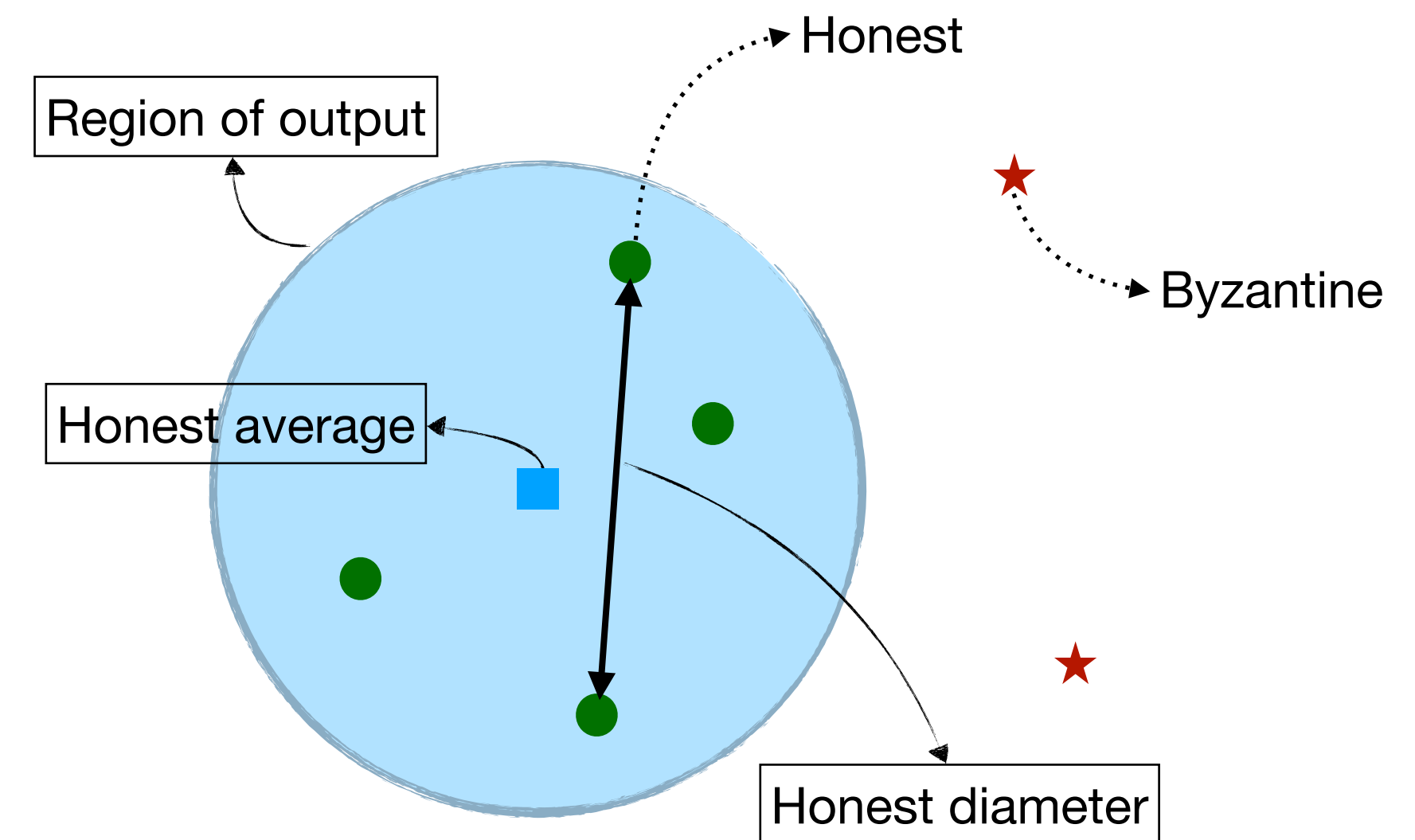
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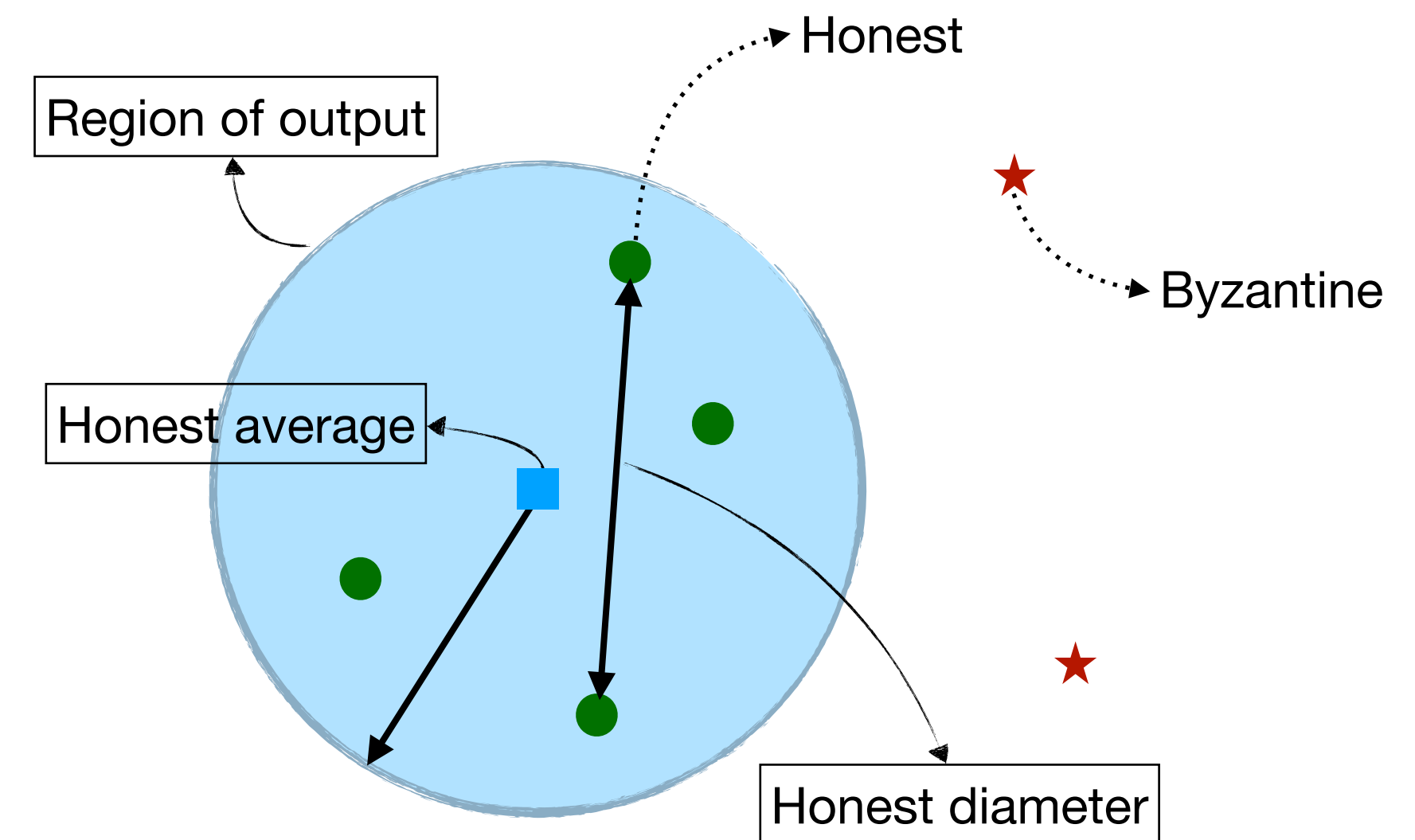
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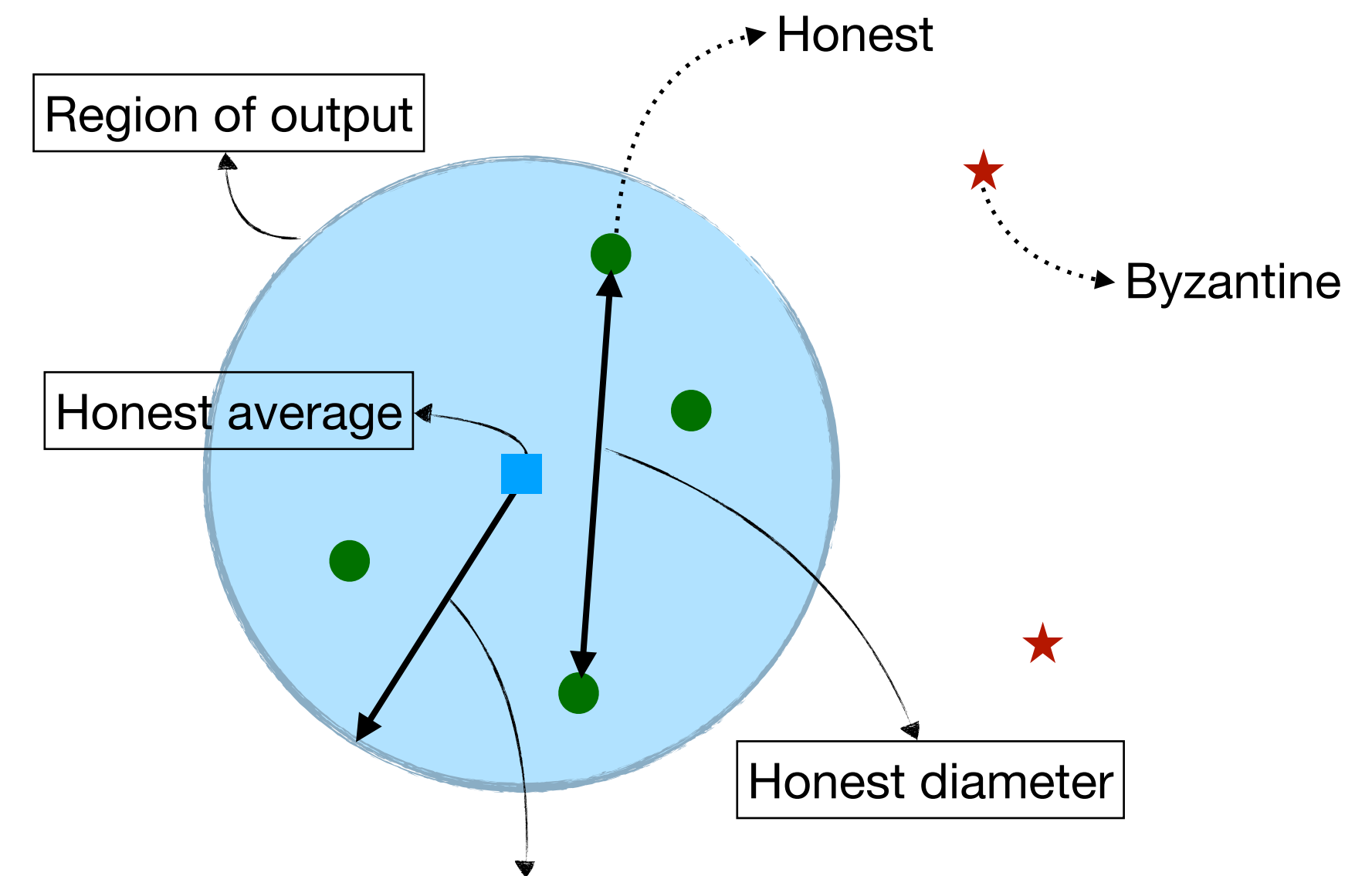
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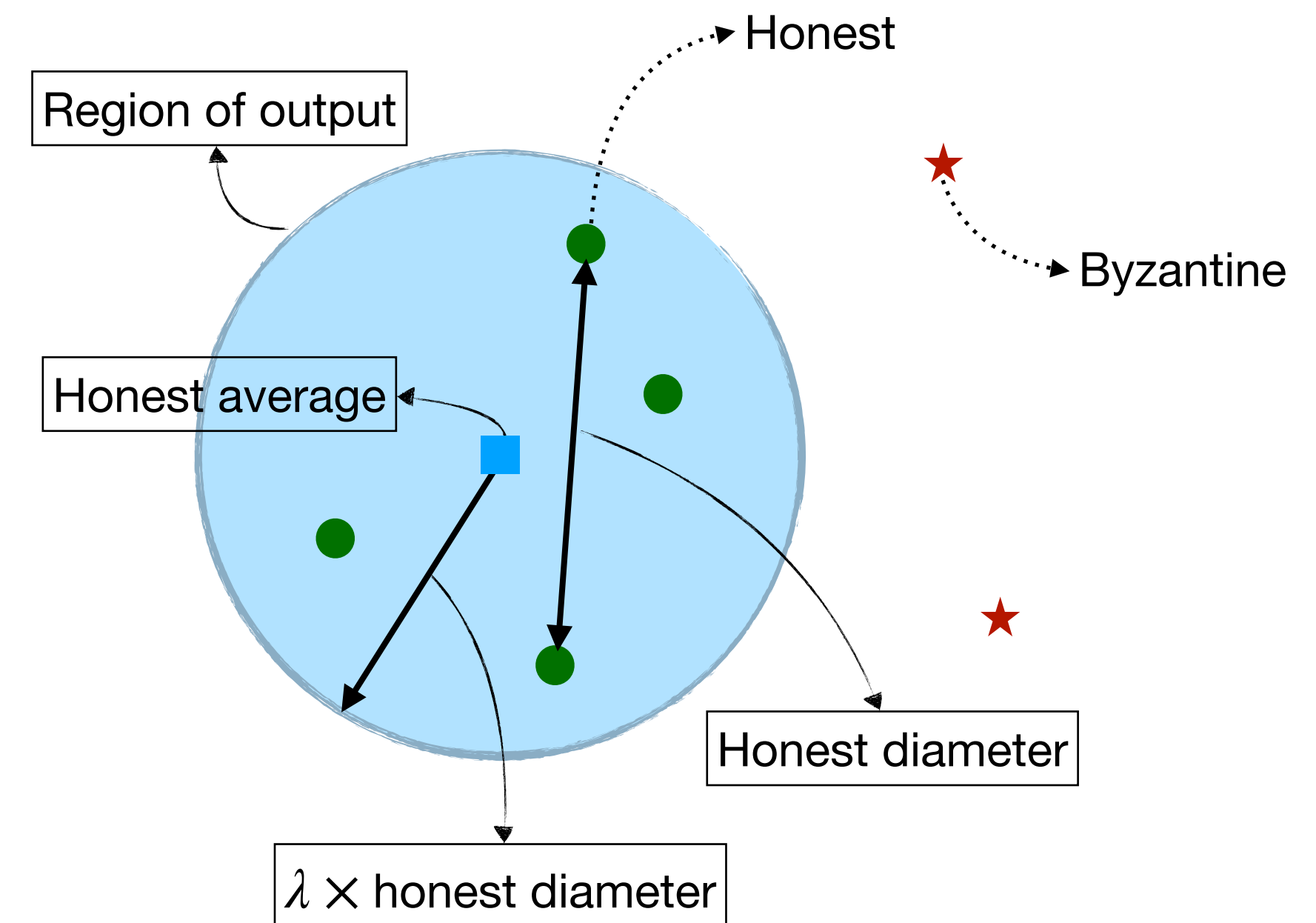
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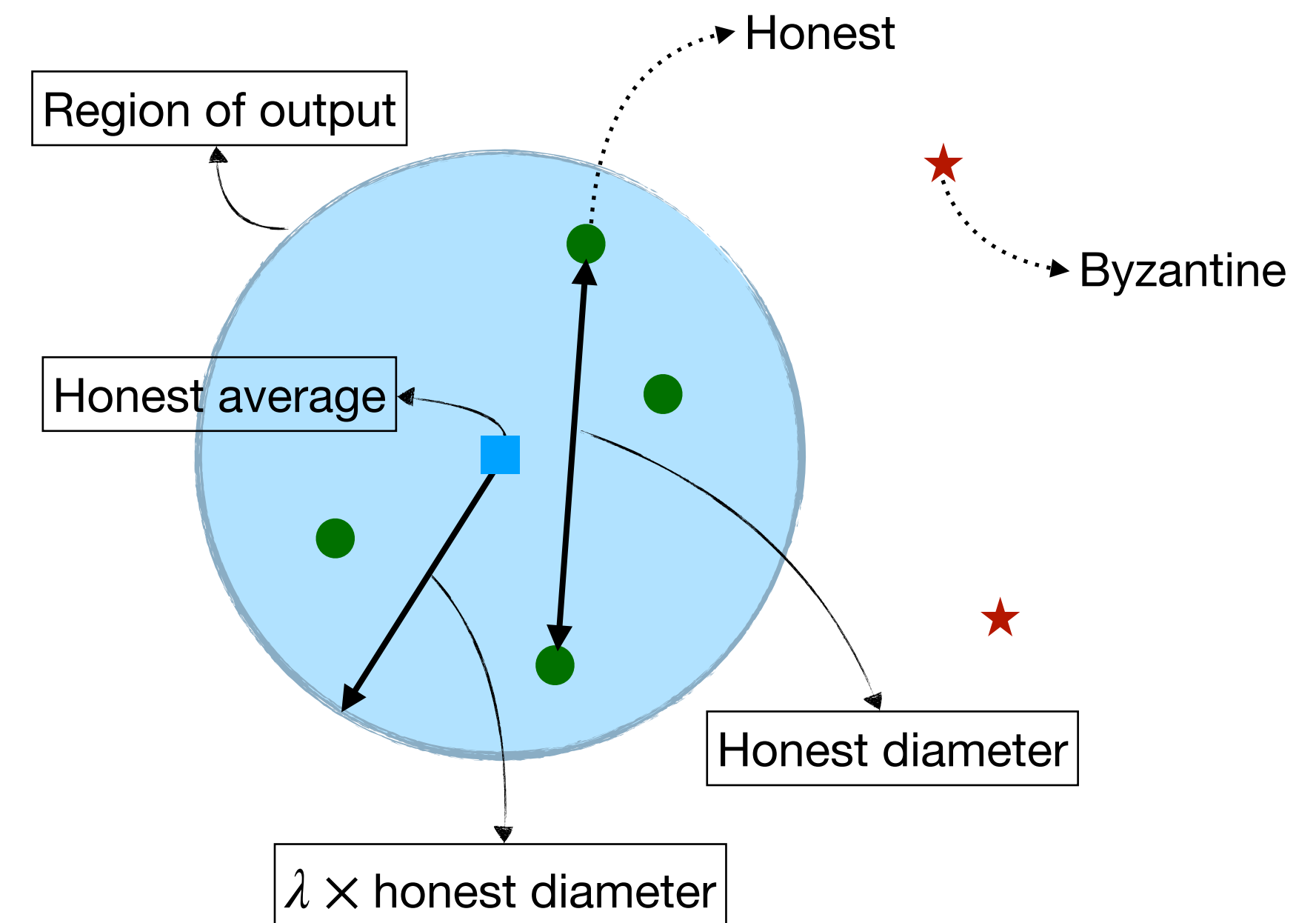
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If all honest values are equal then RESA outputs that value.

Resilient Averaging (RESA)

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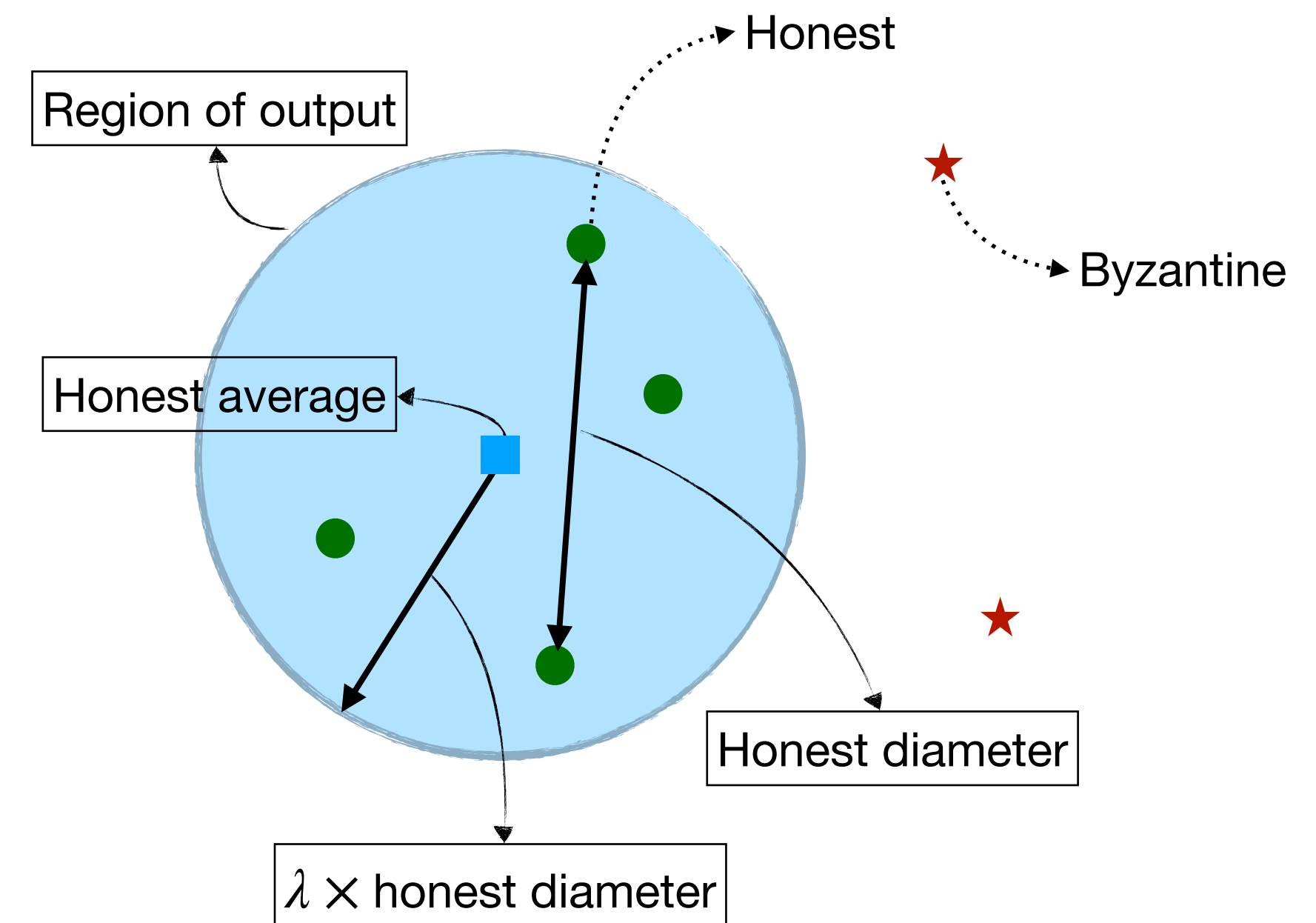
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Resilience coefficient

Sanity check

If all honest values are equal then RESA outputs that value.



Resilience Coefficients of some Aggregation Rules

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Smaller the λ better the Byzantine resilience

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Lower bound: $\lambda \geq \frac{f}{n-f}$

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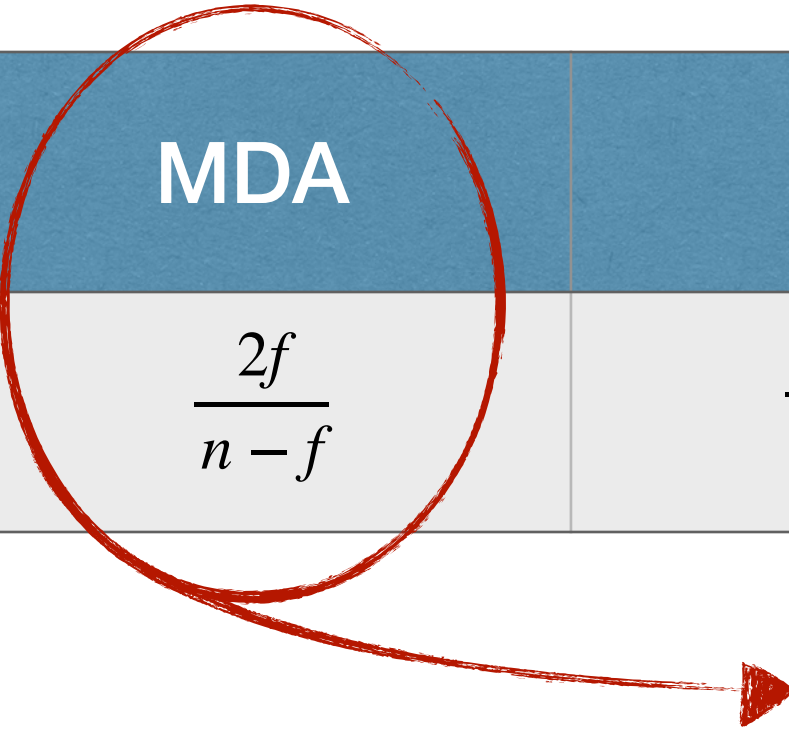
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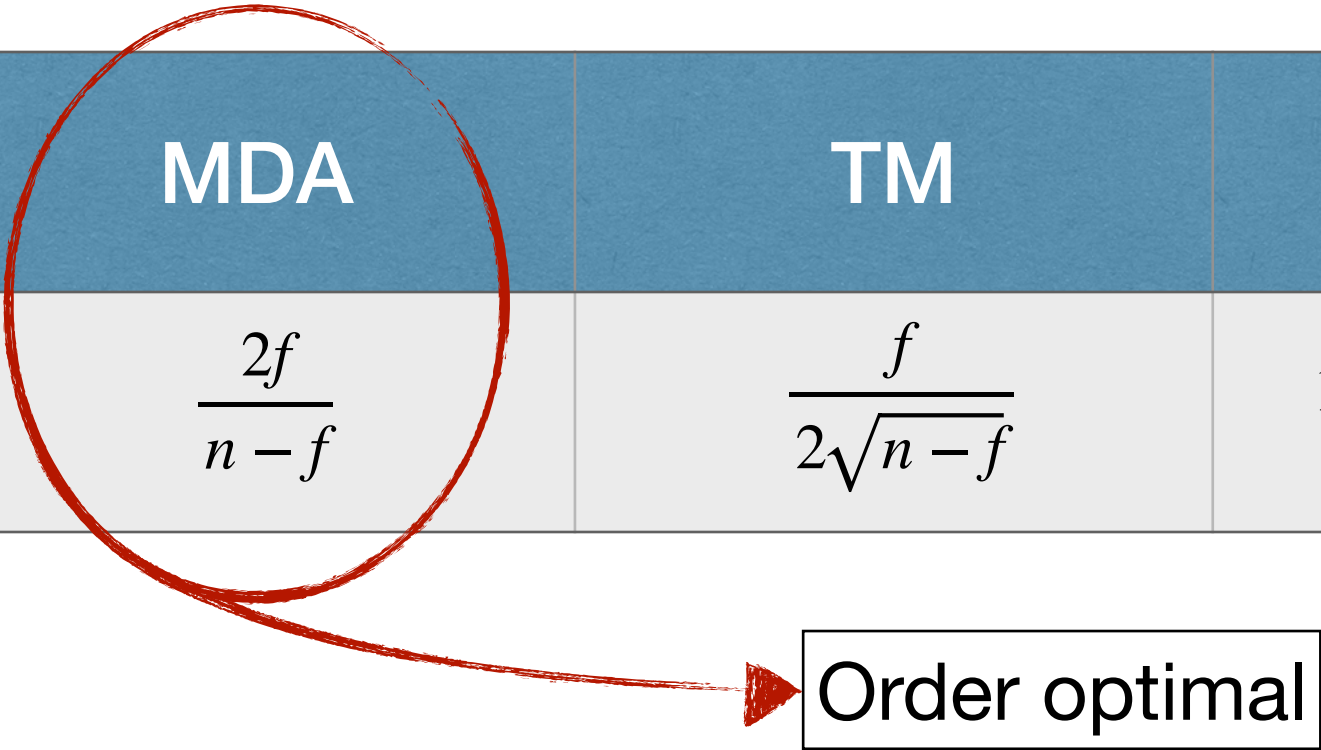


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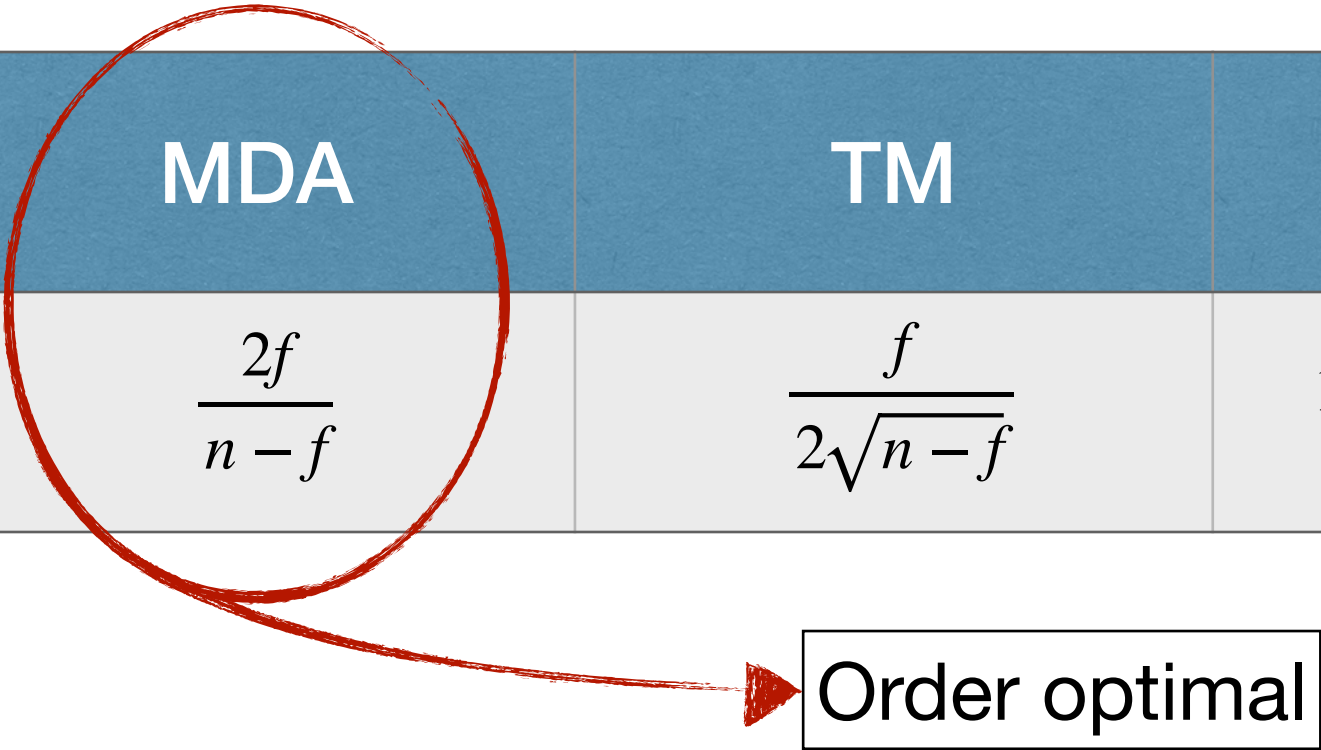


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The values hold for any $f < n/2$

Byzantine Resilience Guarantee

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Server updates: $\theta_{t+1} \leftarrow \theta_t - \gamma_t R_t$

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(f, λ) -**RESA** aggregation rule F + **Momentum** with $\beta = \sqrt{1 - c/T}$

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(f, ϵ) -Resilience

Compares overall efficiency for different aggregation rules

Empirical Evidence

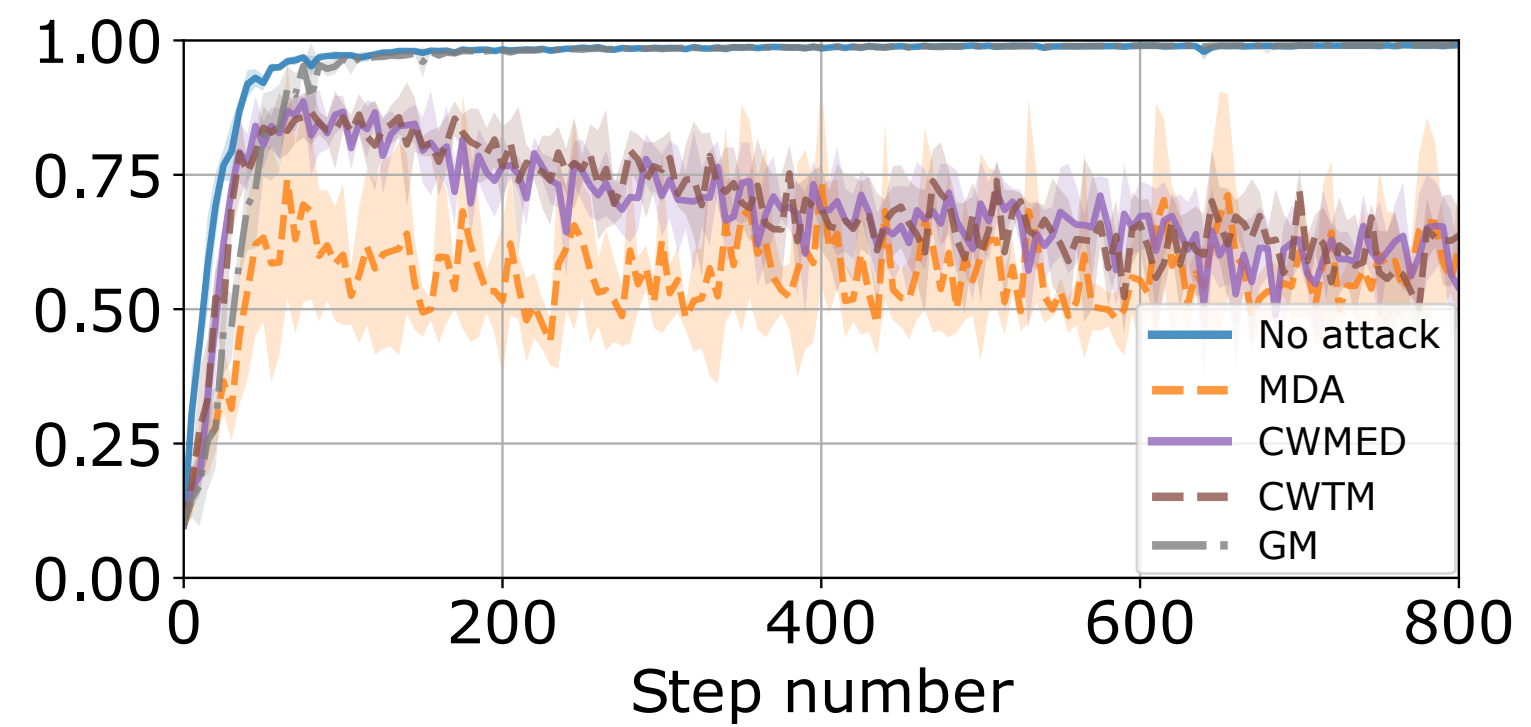
Empirical Evidence

Empirical Evidence

**Without
Momentum**

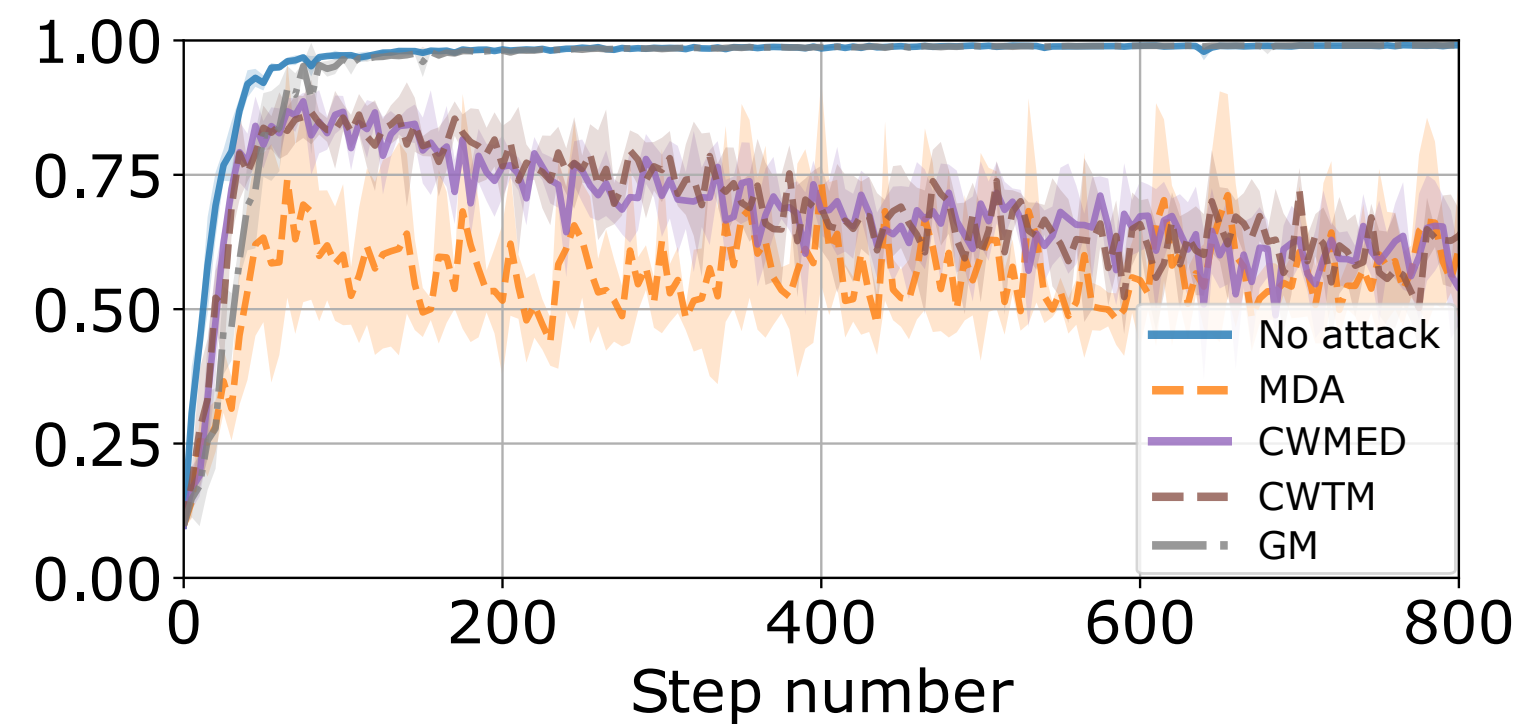
Empirical Evidence

Without Momentum



Empirical Evidence

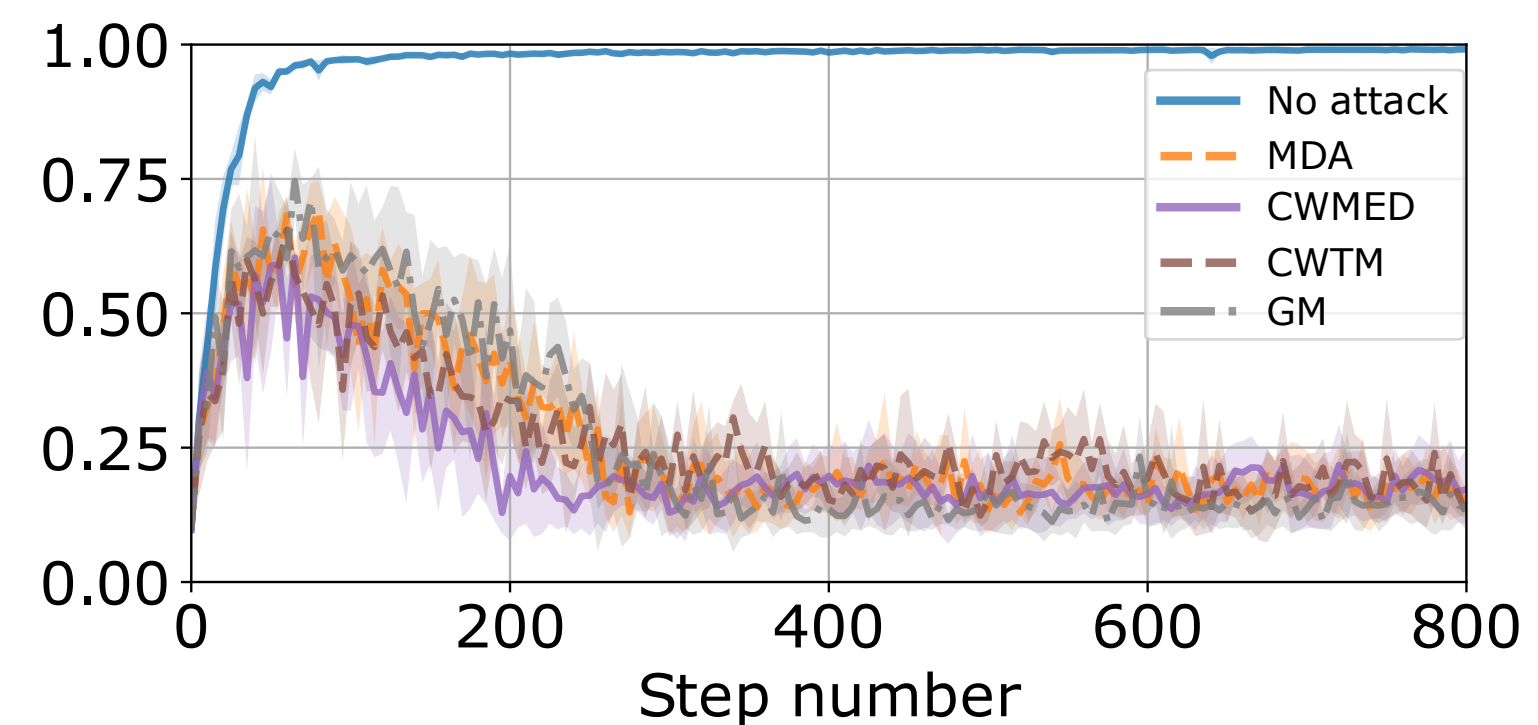
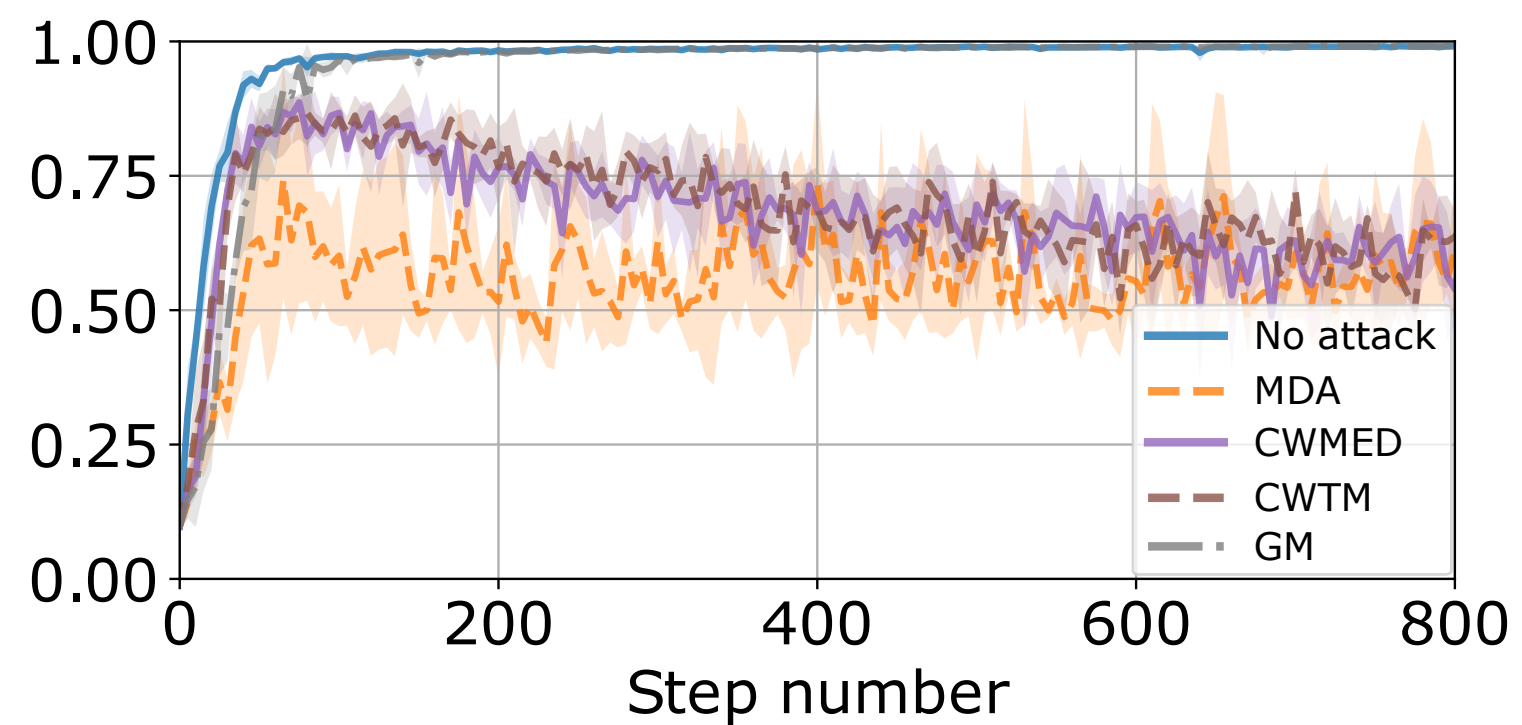
Without Momentum



Label-flipping

Empirical Evidence

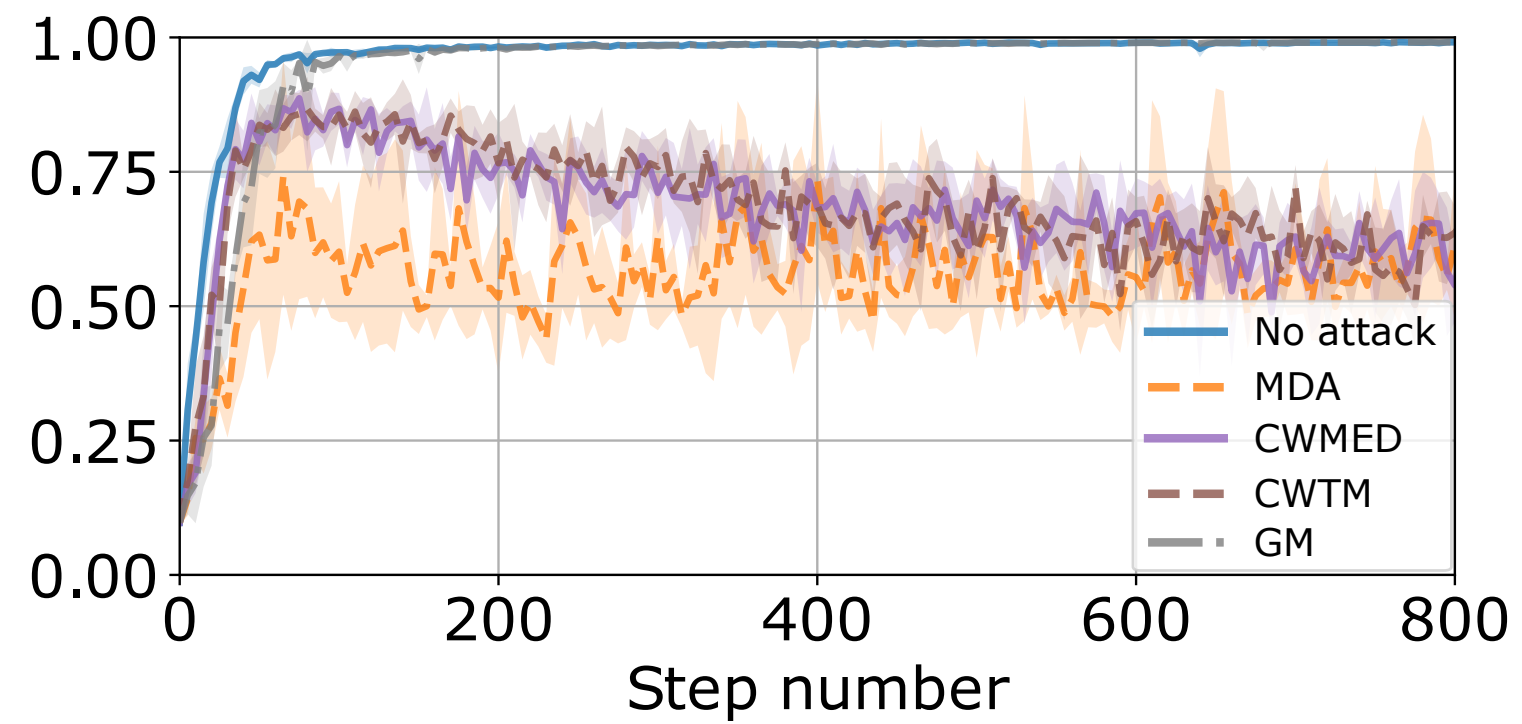
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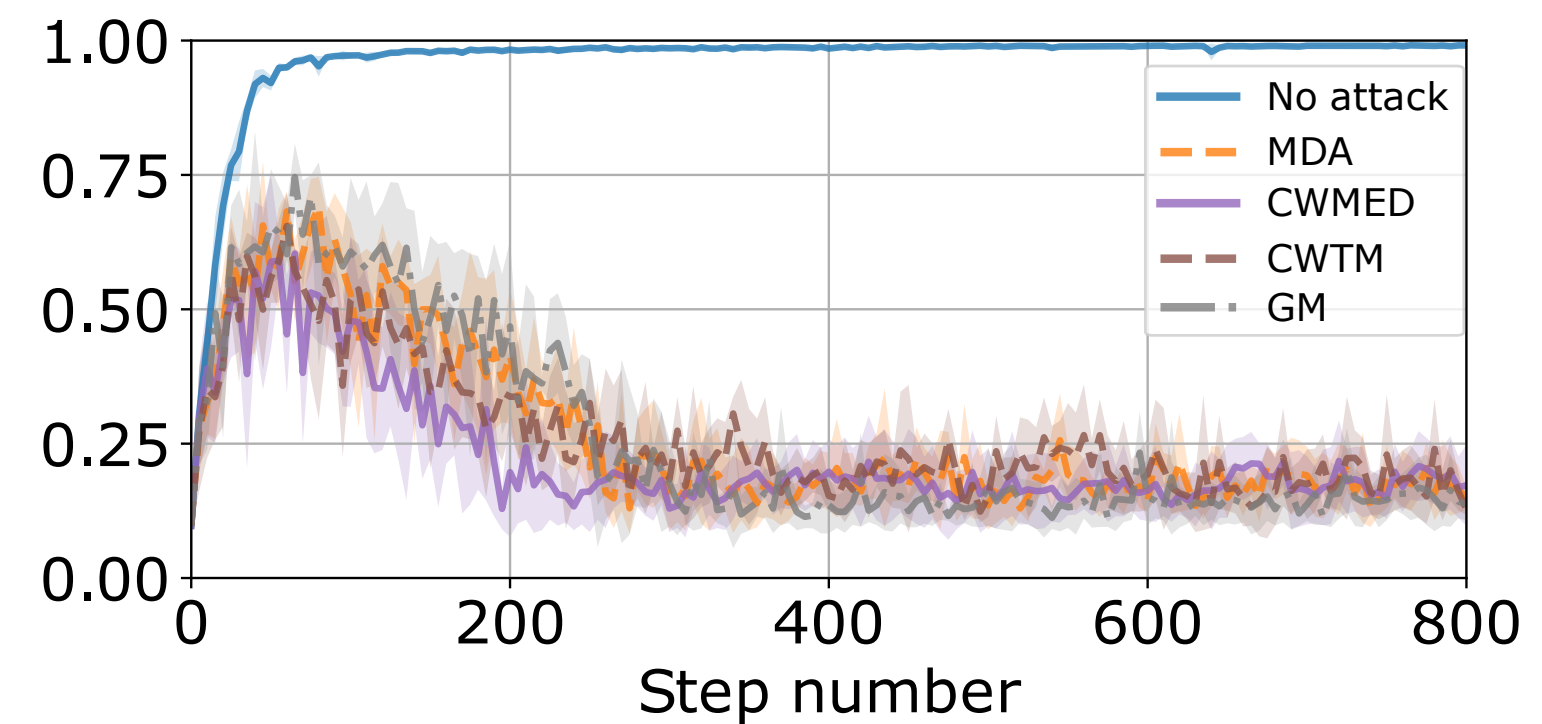
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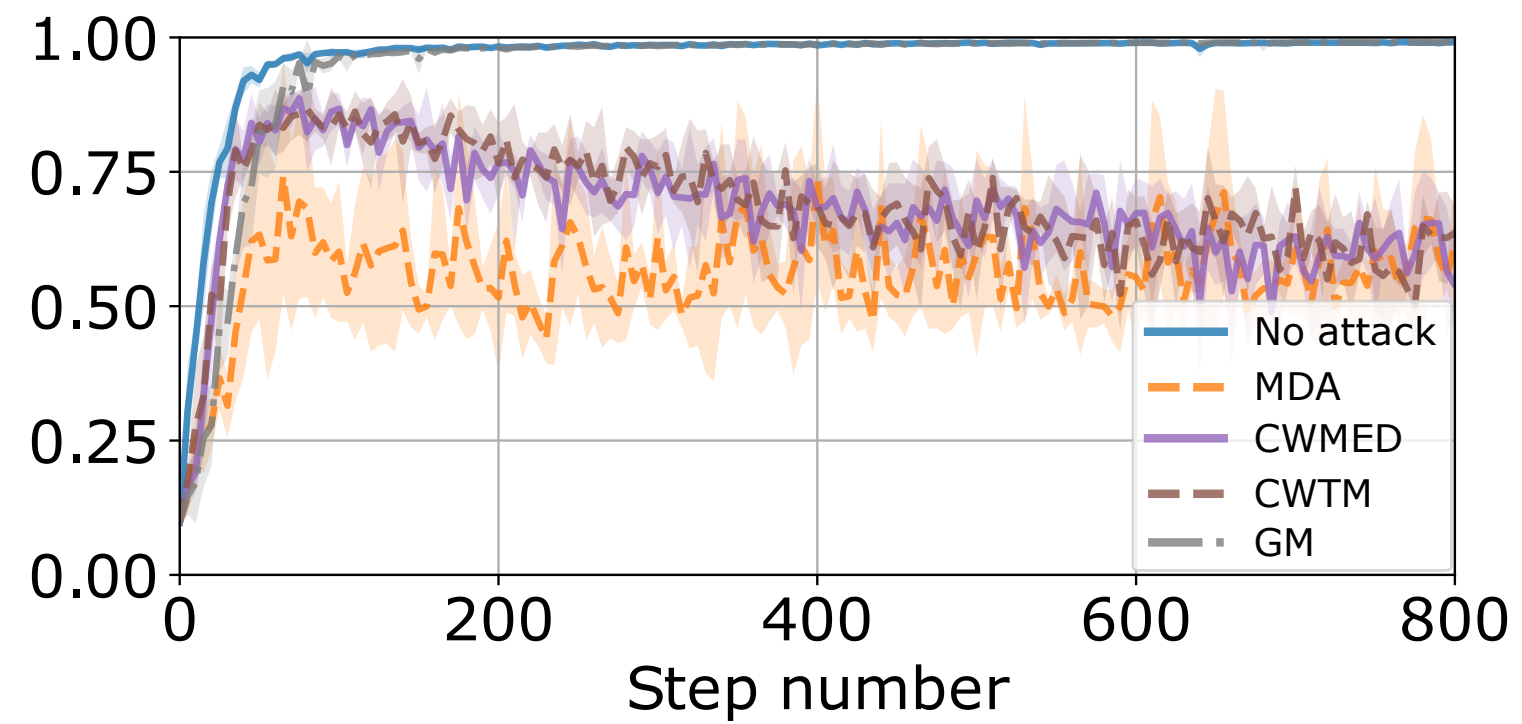
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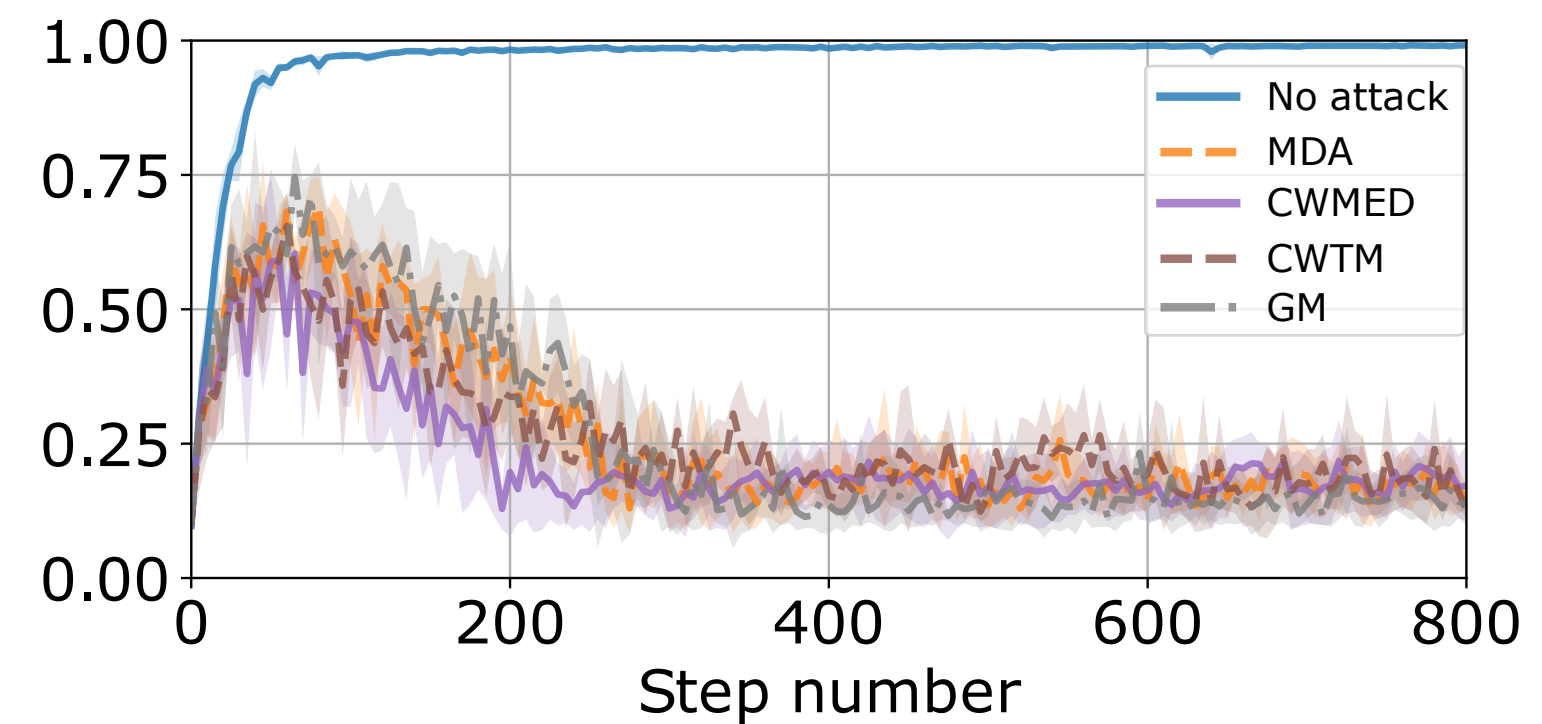
Little is enough (*Baruch et al., 2019*)

Empirical Evidence

Without Momentum



With Momentum

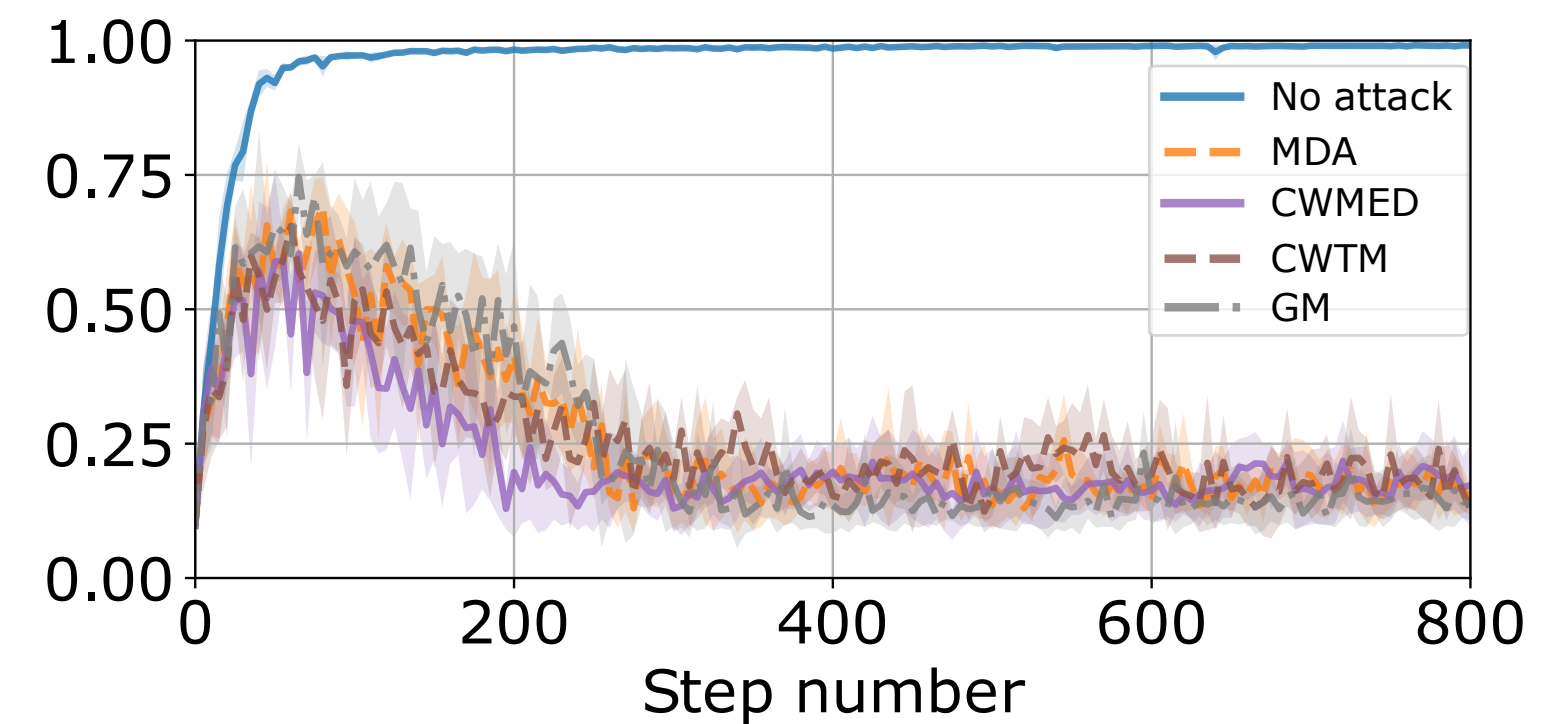
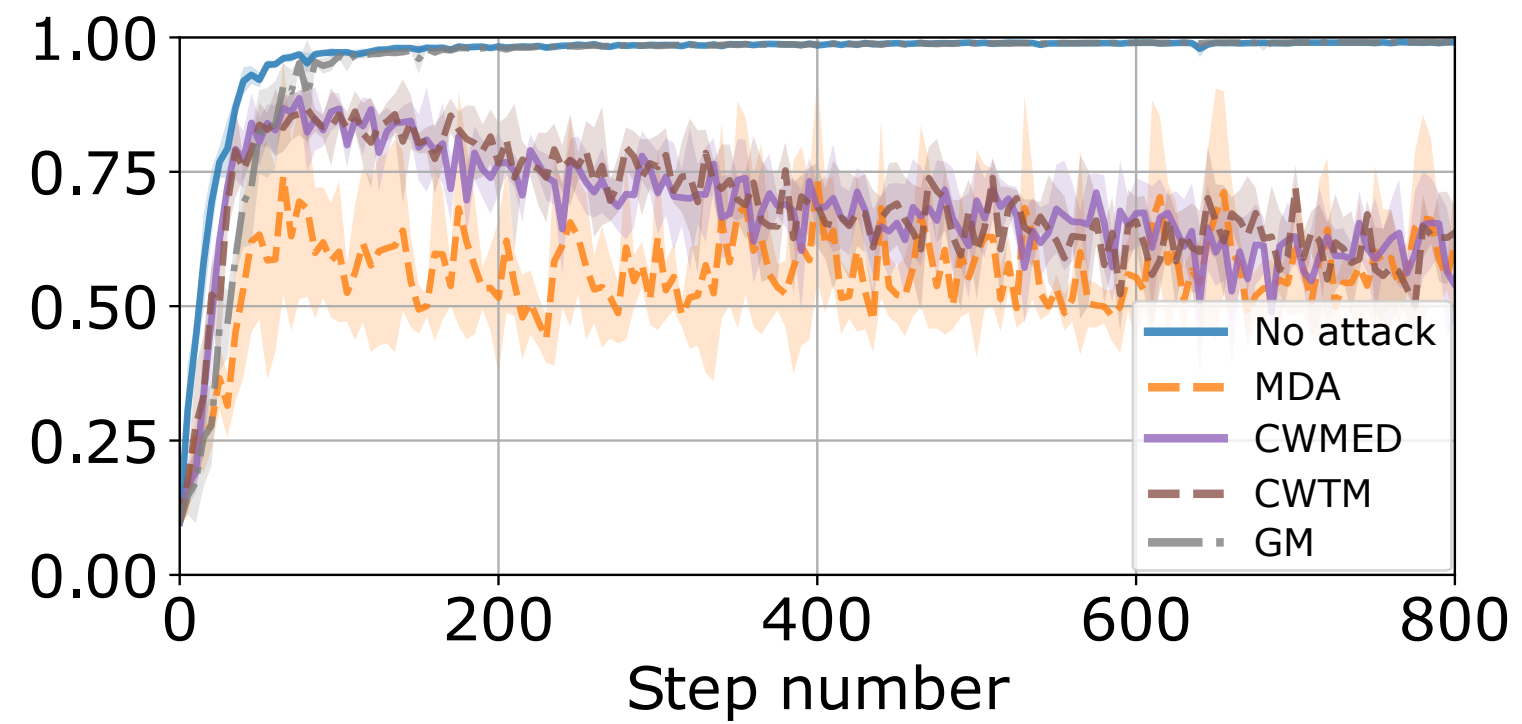


Label-flipping

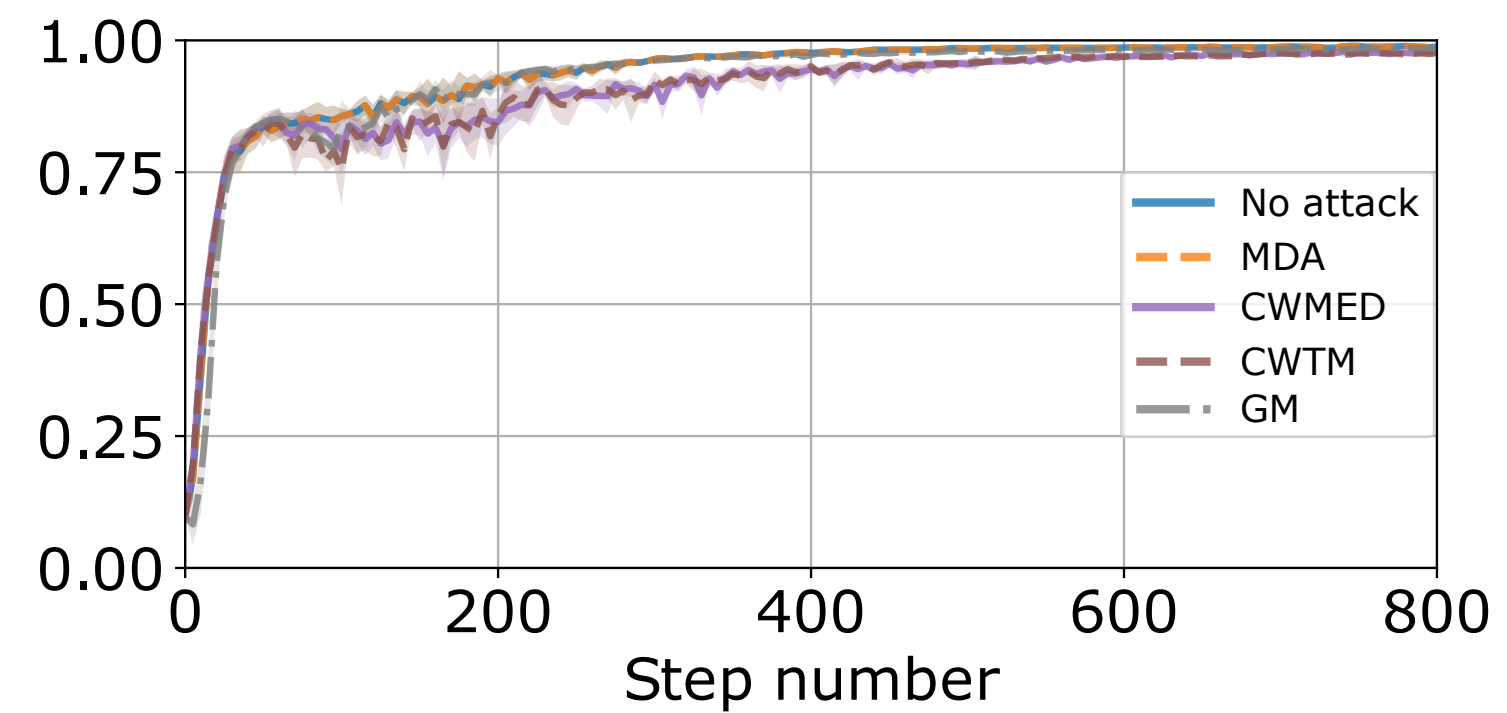
Little is enough (*Baruch et al., 2019*)

Empirical Evidence

Without Momentum



With Momentum

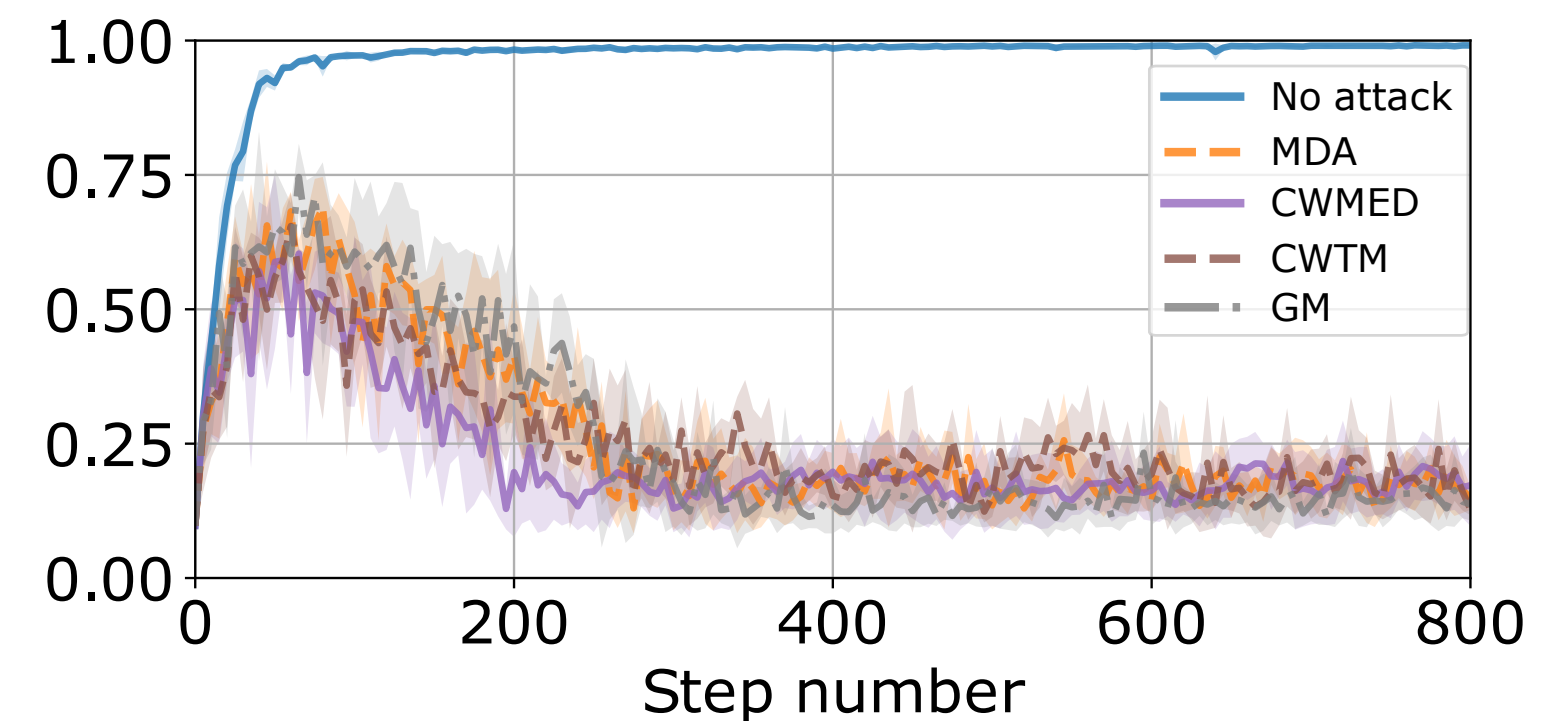
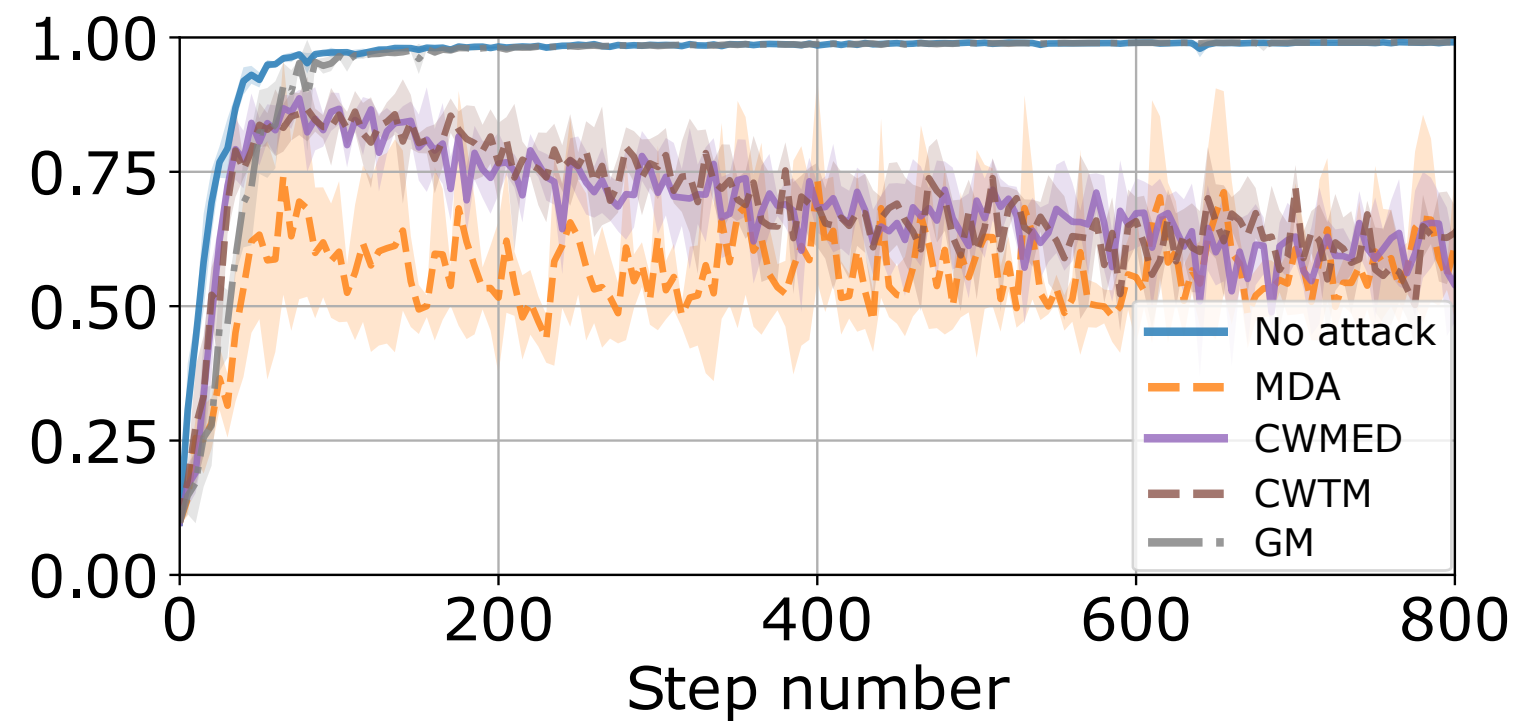


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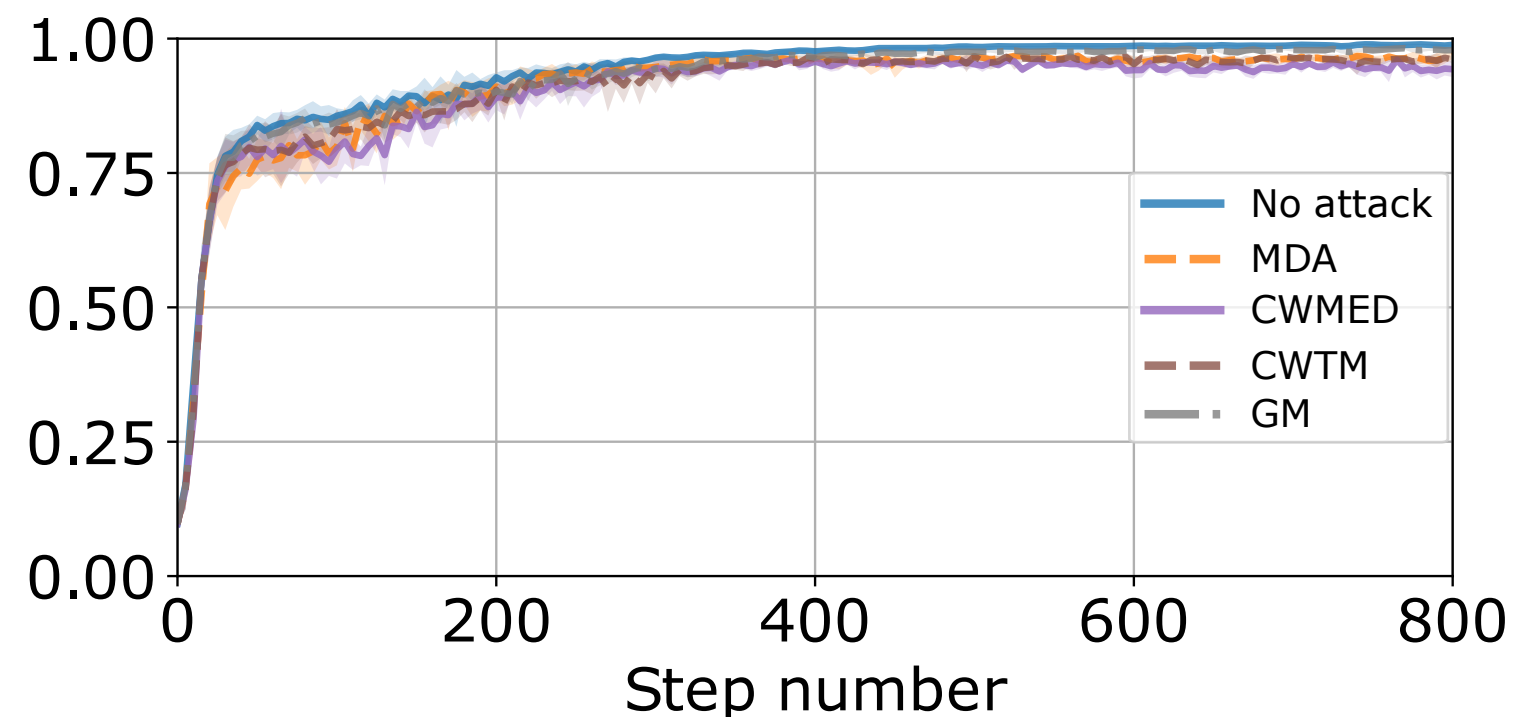
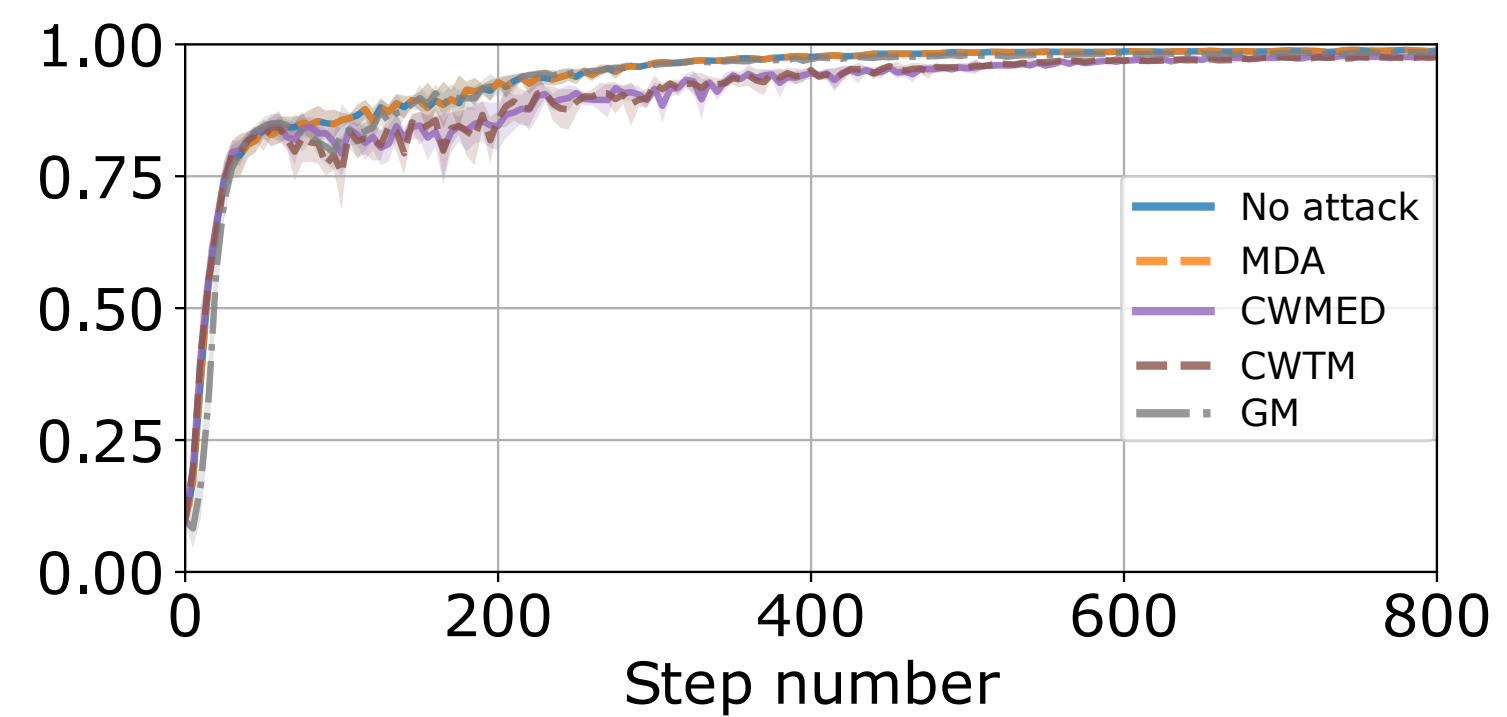
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* MNIST classification task

***Efficiency* + Byzantine Resilience ?**

Efficiency + Byzantine Resilience ?

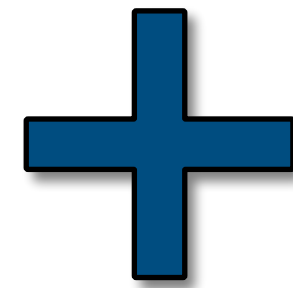
CAN THE SERVER STILL OBTAIN

$$\theta^* \in (\theta ; \nabla Q(\theta) = 0)$$

Efficiency + Byzantine Resilience ?

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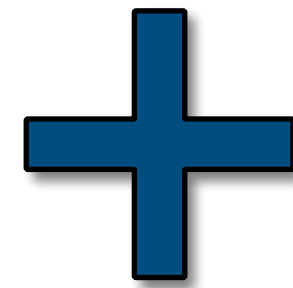
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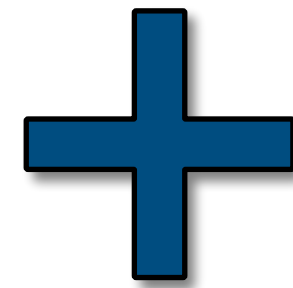


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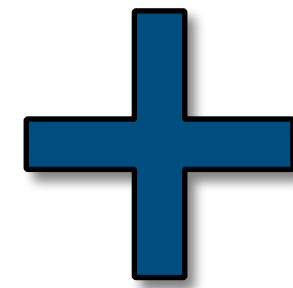
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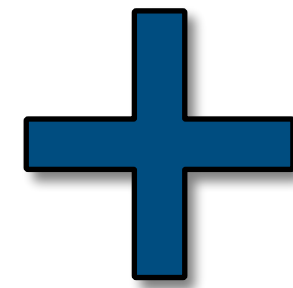
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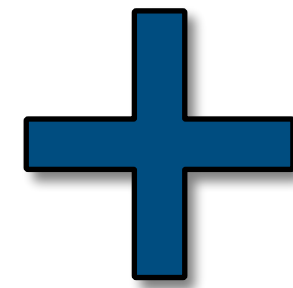
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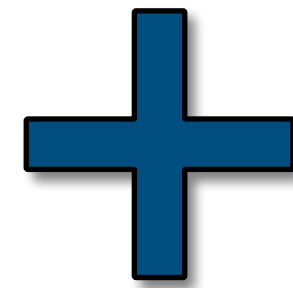
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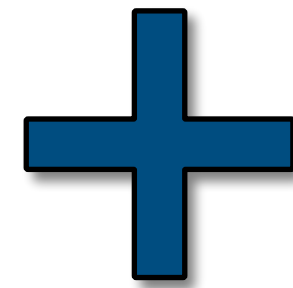
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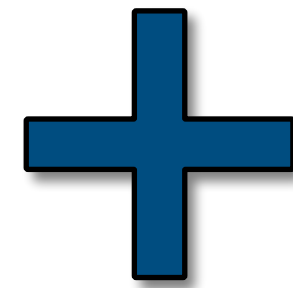
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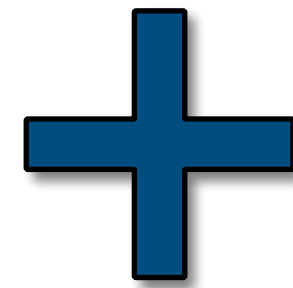
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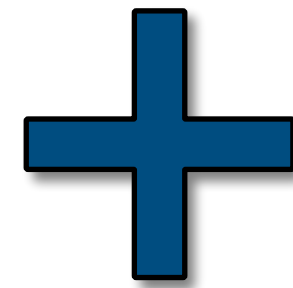
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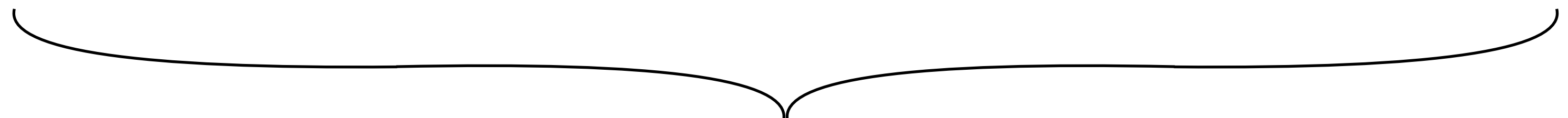
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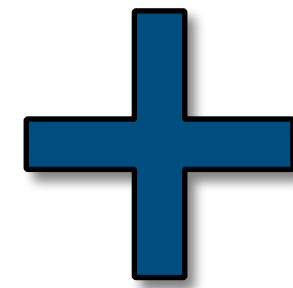
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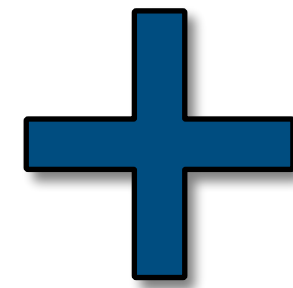
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Median based rules

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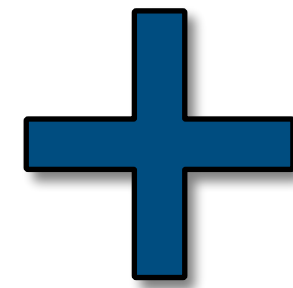
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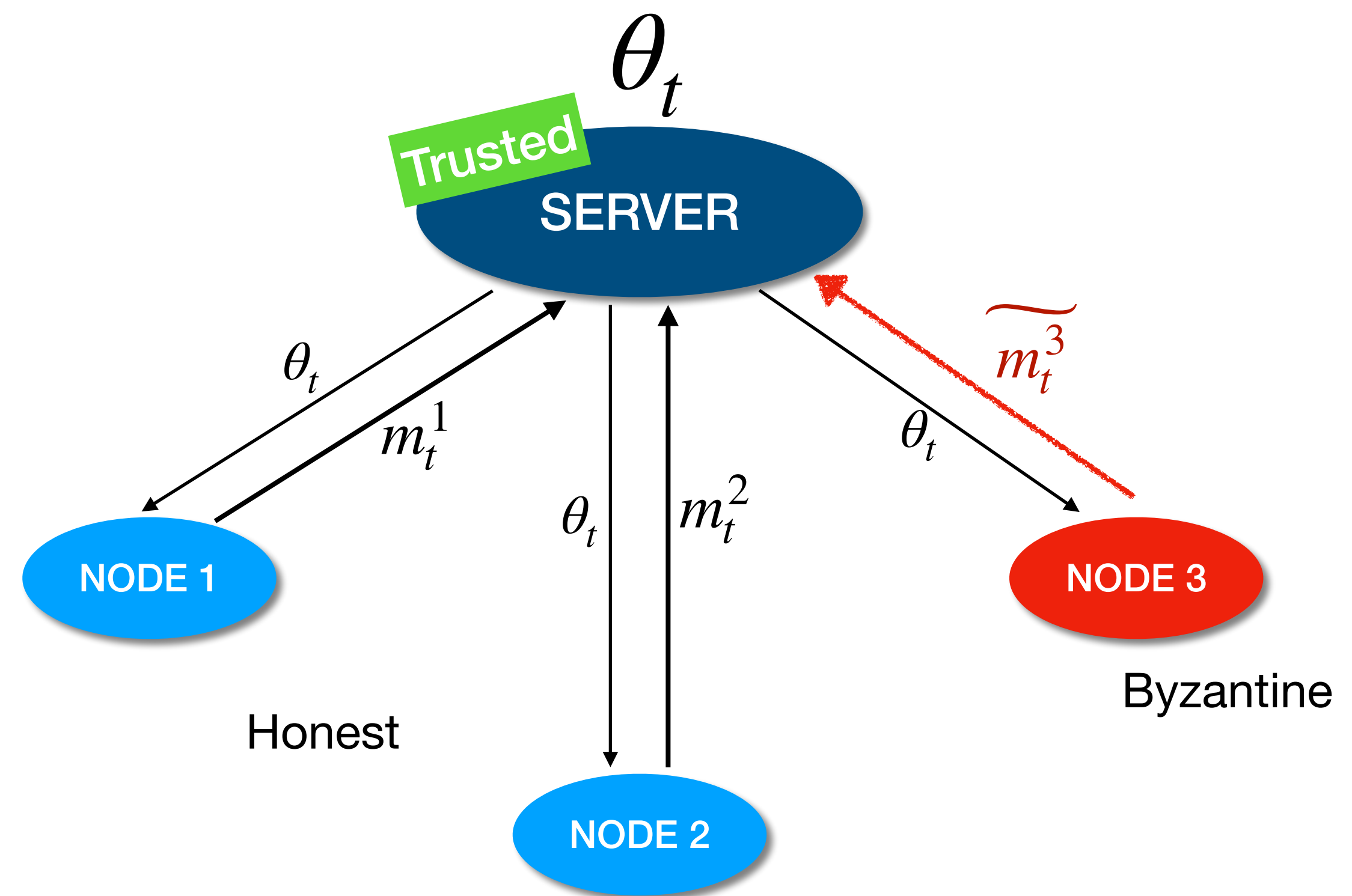
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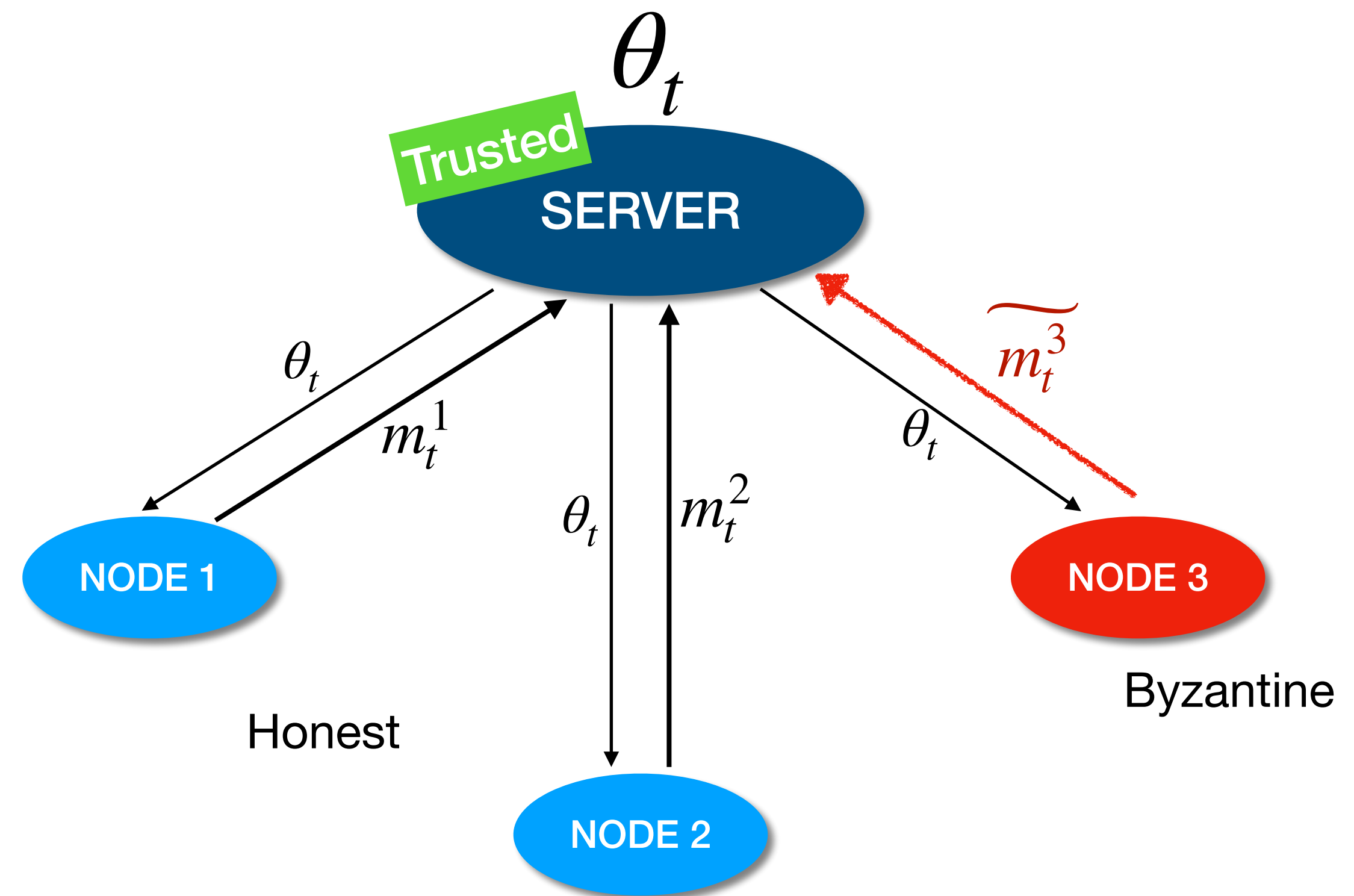
* An extension of Krum, called multi-Krum, uses an averaging component to obtain guarantees comparable to MDA, but is computationally cheaper.

!!Caution!! Momentum may NOT Help Always



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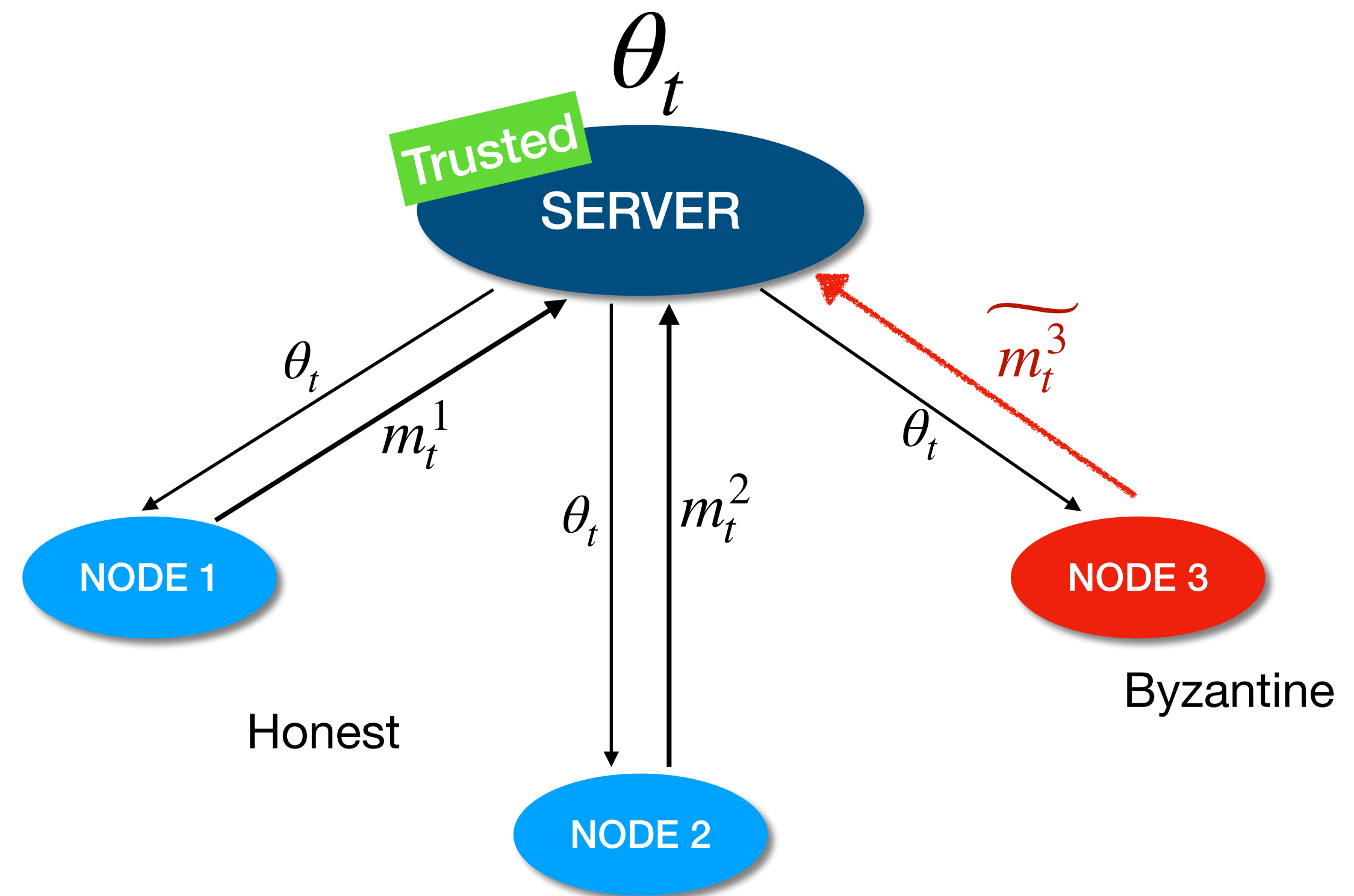
When **data distributions** across nodes are “**very**” different



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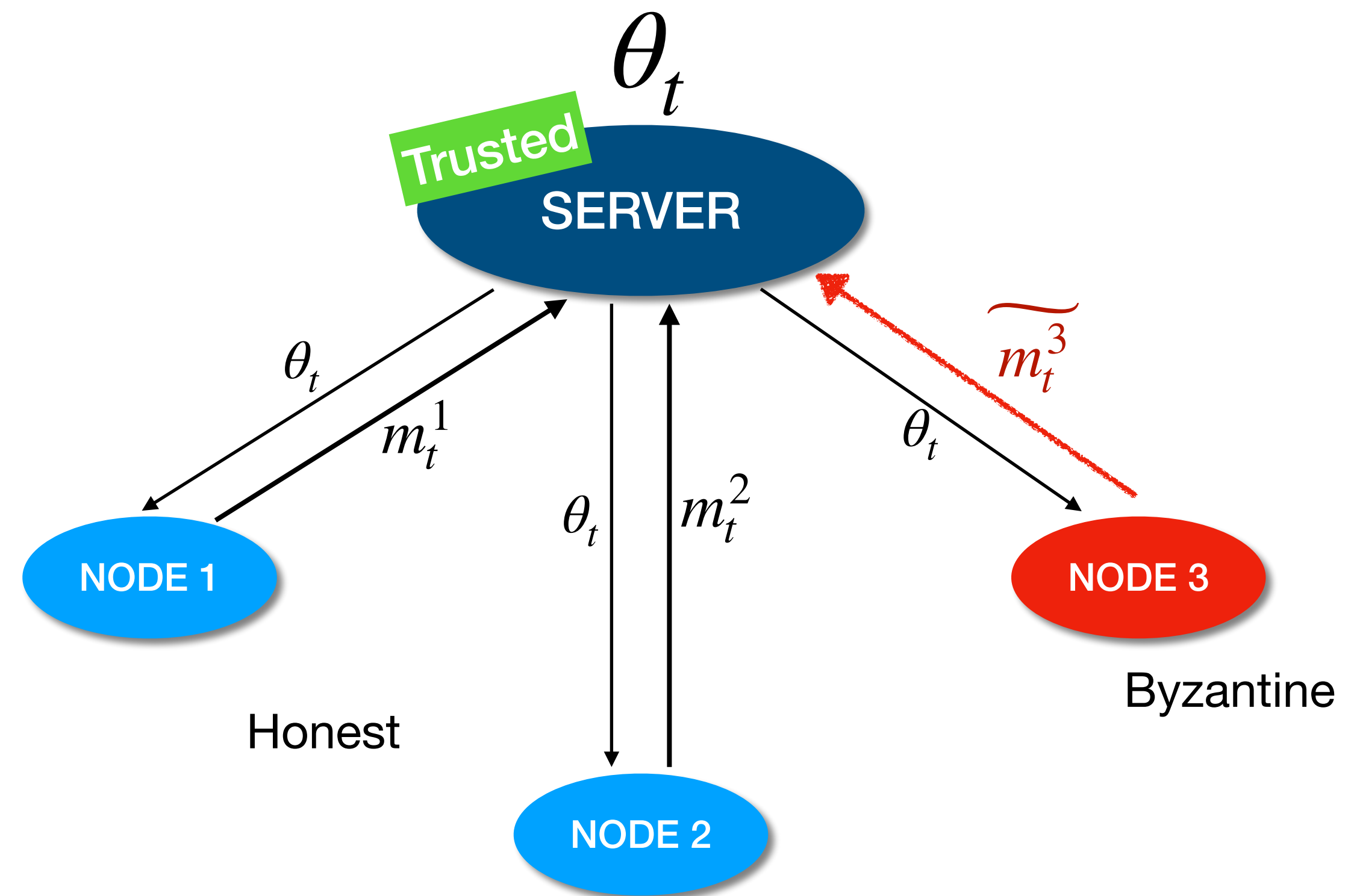


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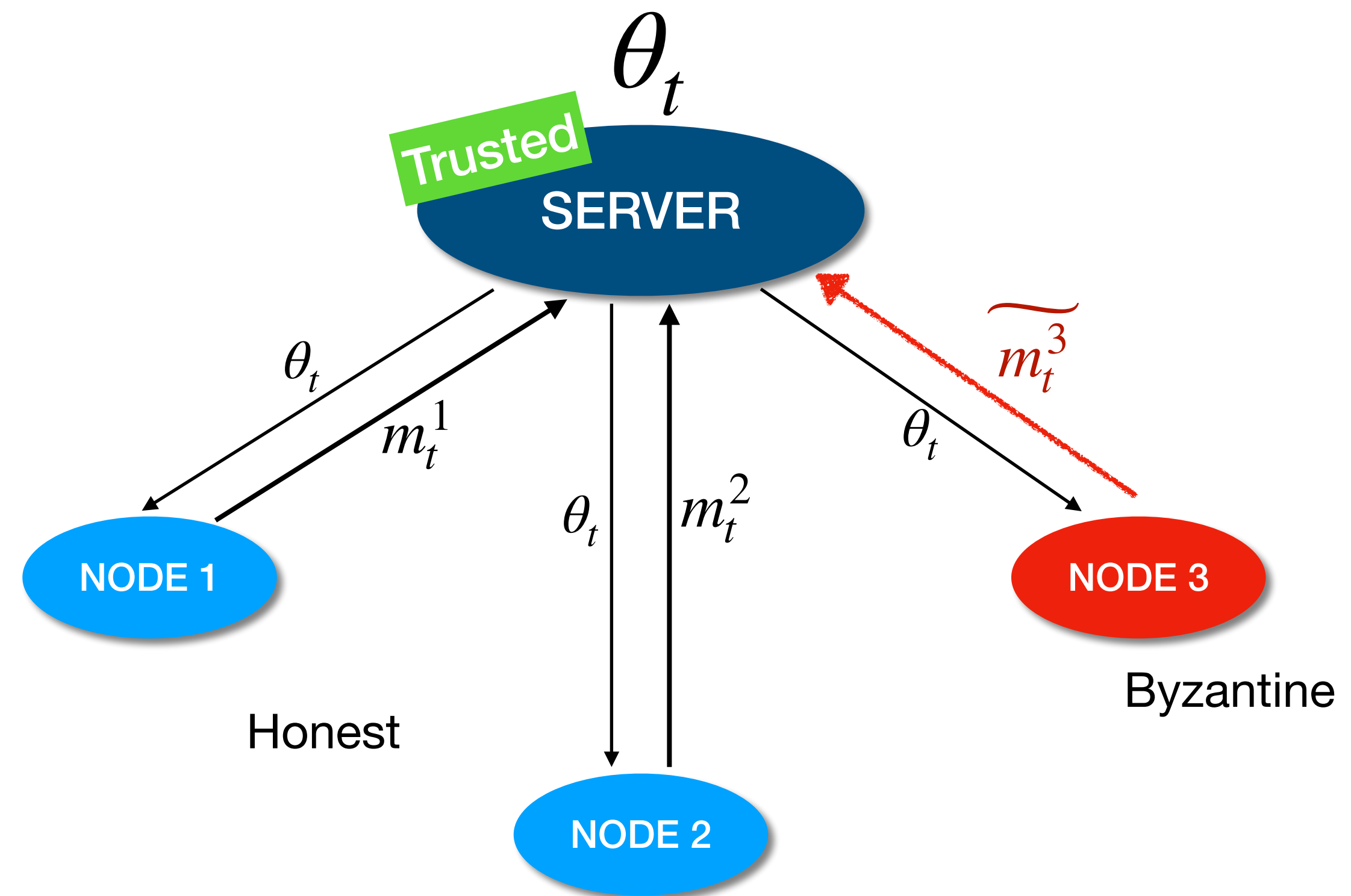


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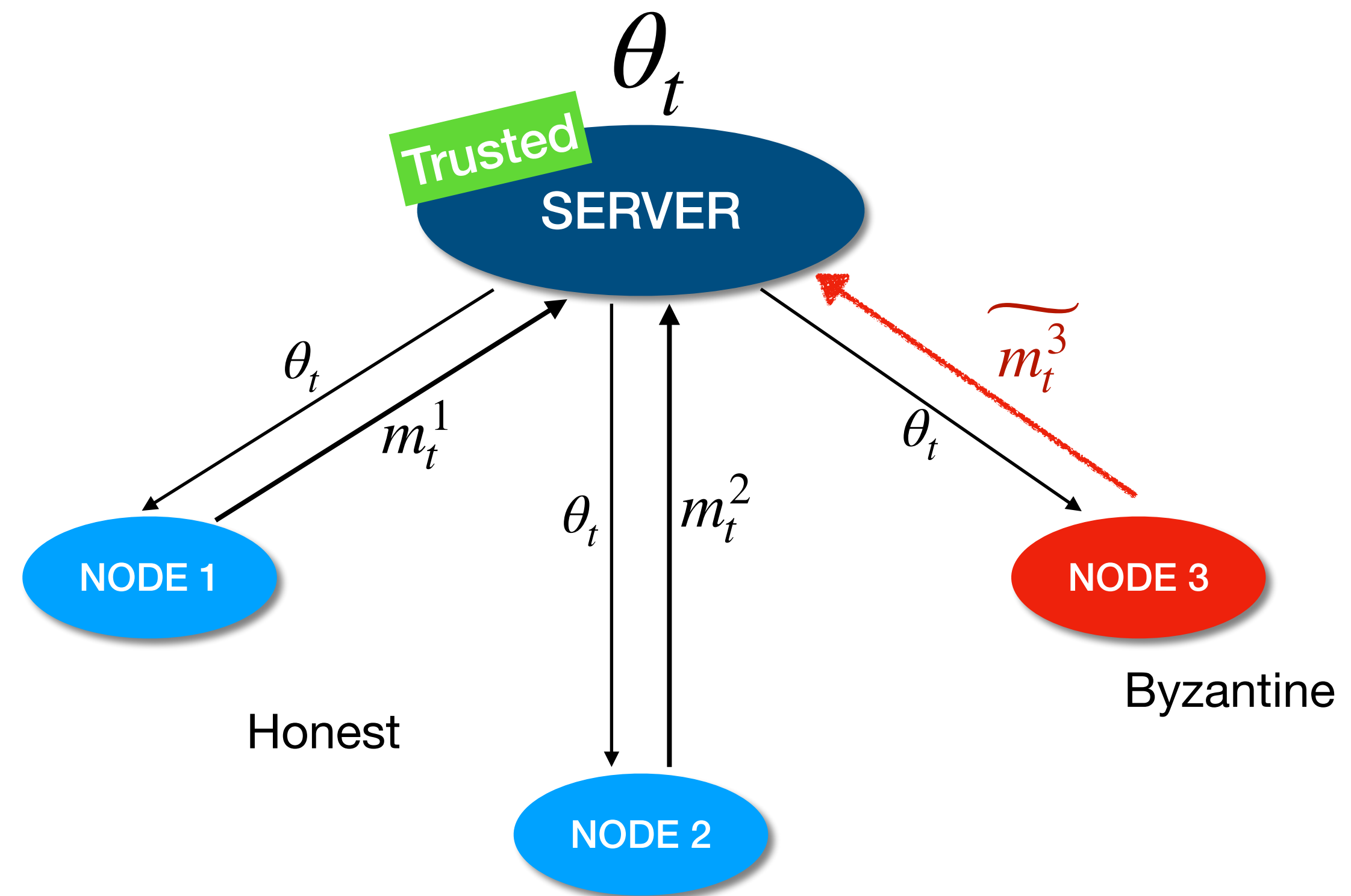
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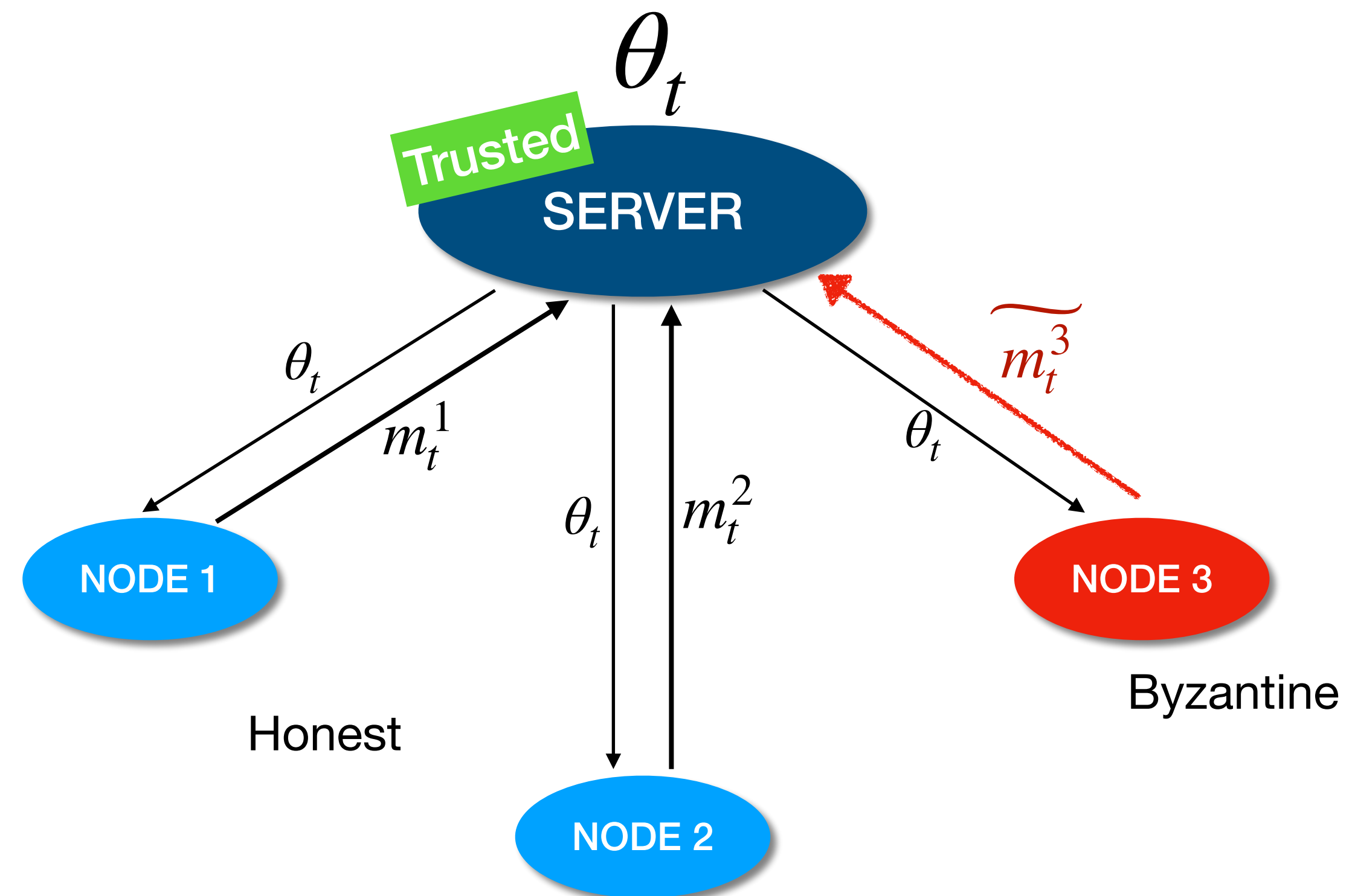
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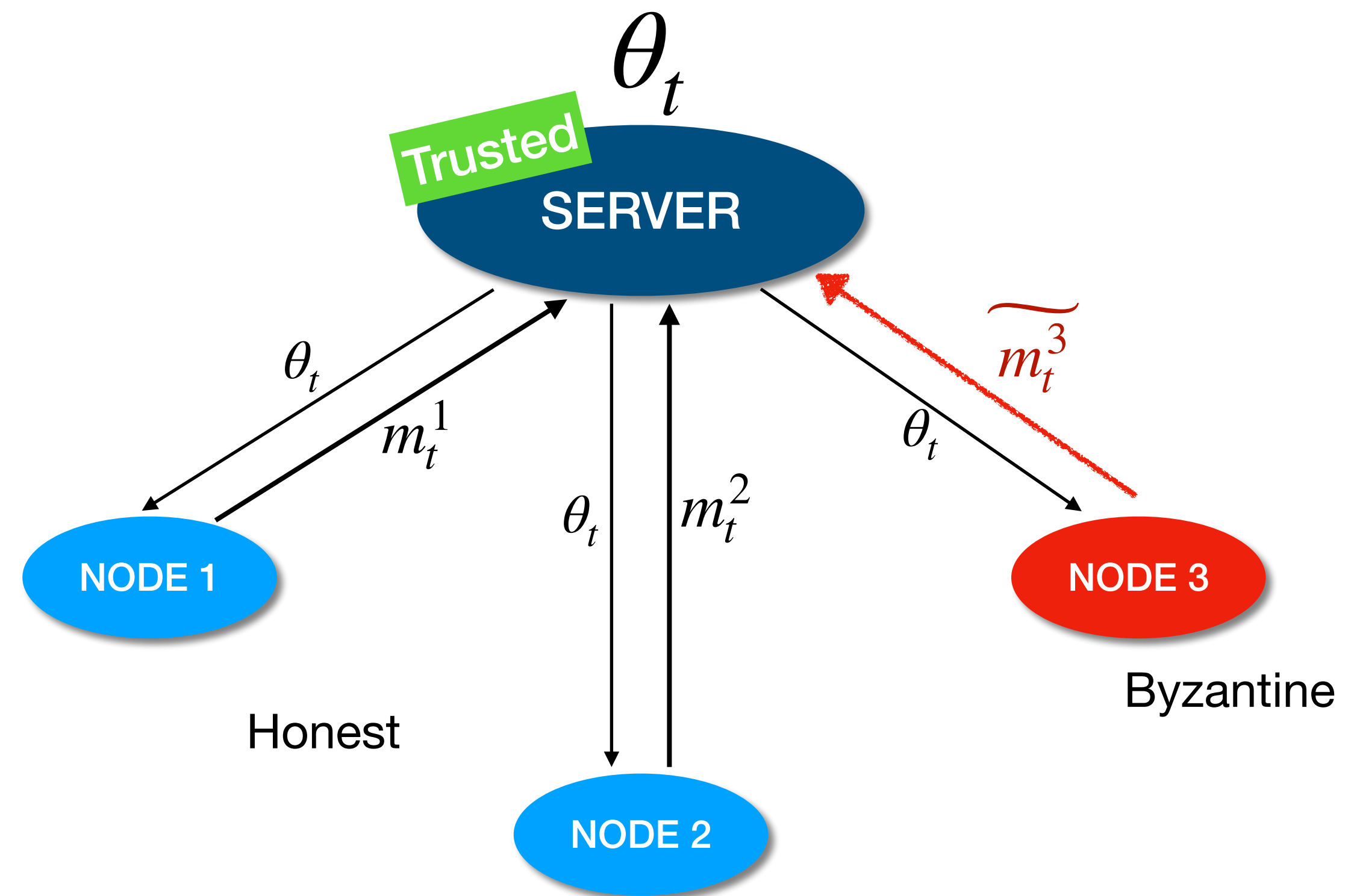
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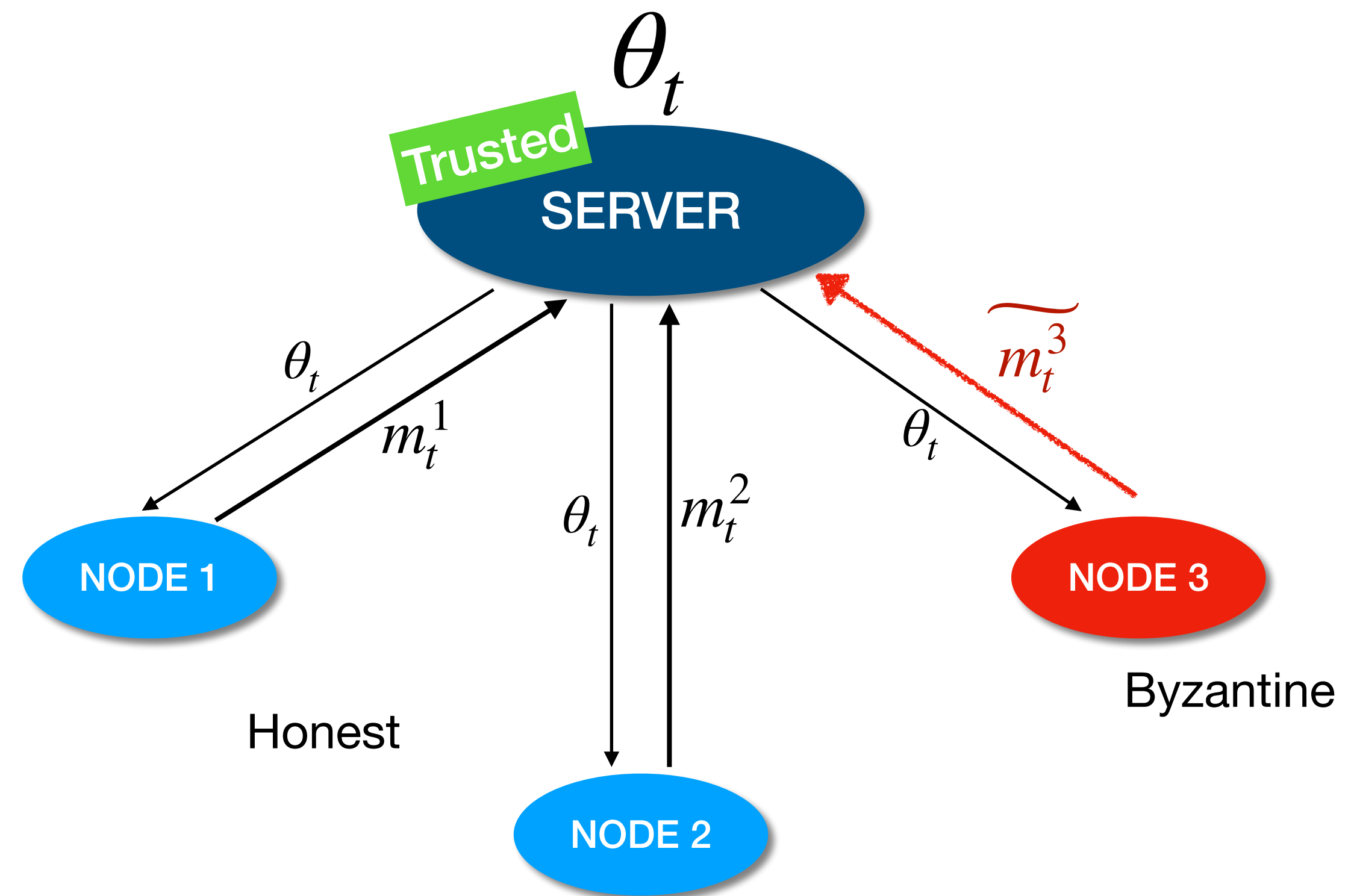
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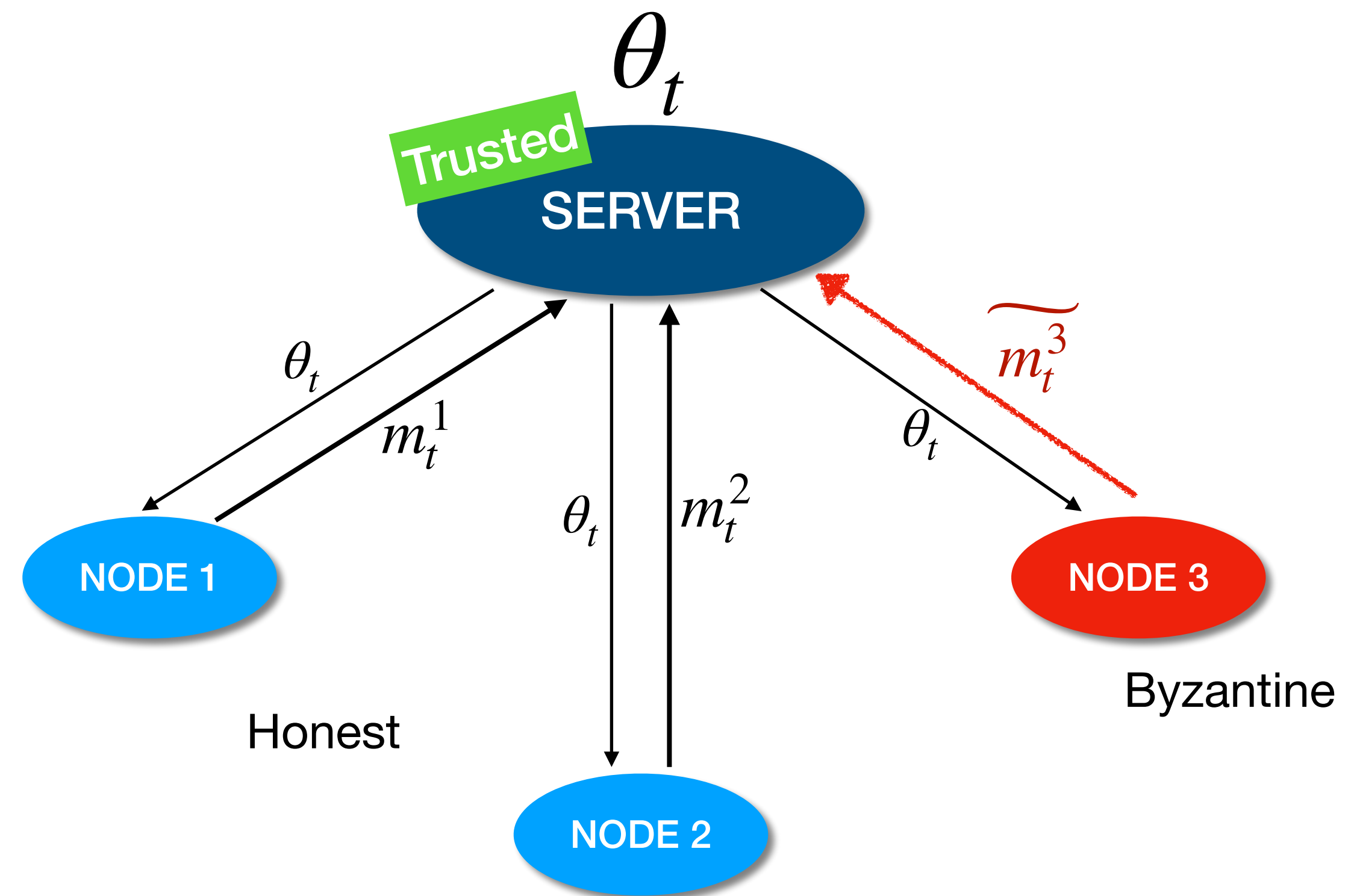
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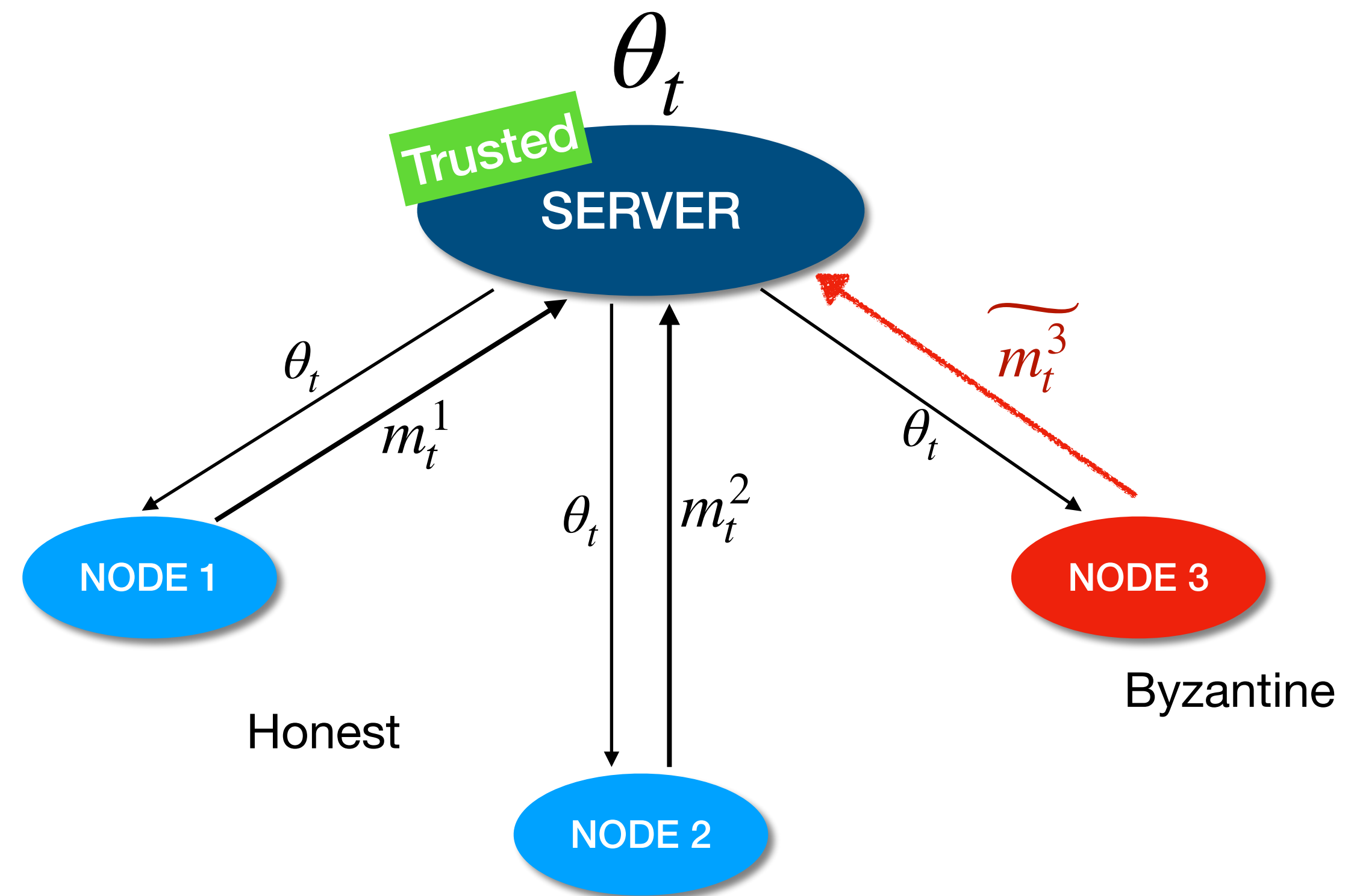
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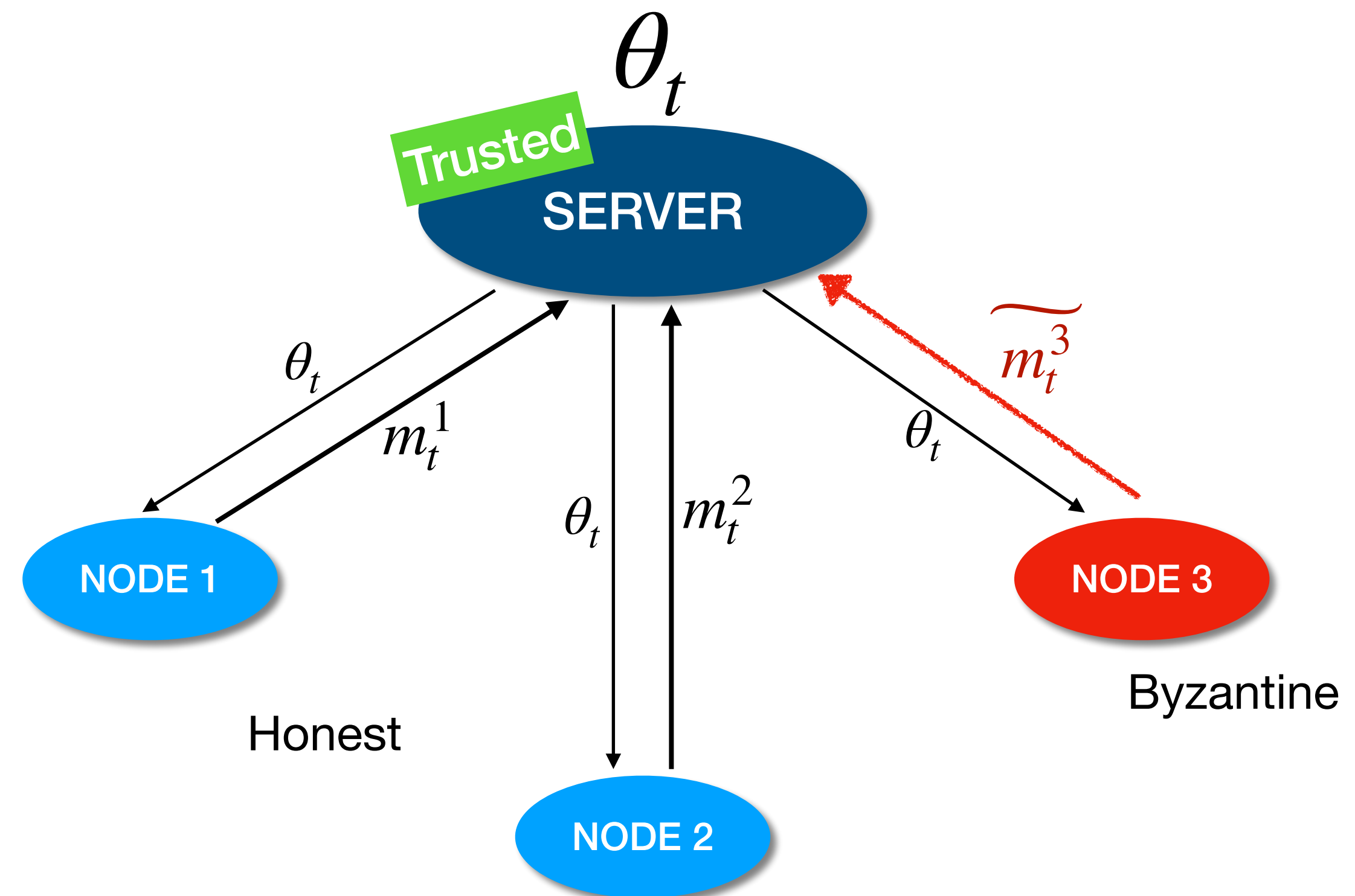
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On the other hand, $\mathbb{E} \left[\|g_t^i - g_t^j\|^2 \right] \leq c_1 \sigma^2 + c_2 \|\nabla Q_i(\theta_k) - \nabla Q_j(\theta_k)\|^2$





What's Next?!



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Study the impact of momentum with **heterogeneity**.



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Does use of local momentum improve **privacy**?

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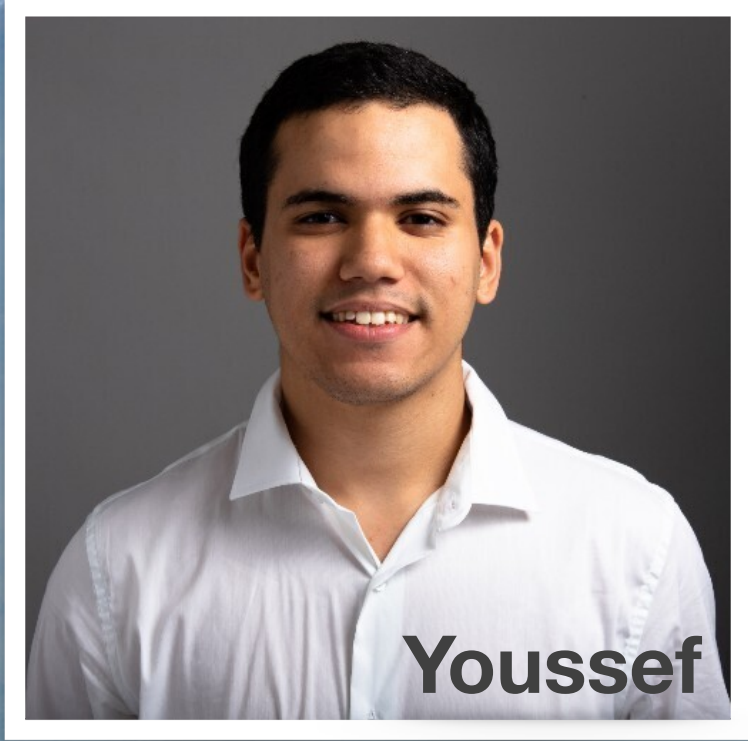
Thanks to ...



John



Sadegh



Youssef



Rafael



Rachid



Lê Nguyễn



Readings

Farhadkhani, Sadegh; Rachid Guerraoui; Nirupam Gupta; Rafael Pinot and John Stephan.
Byzantine Machine Learning Made Easy by Resilient Averaging of Momentums. *ICML 2022.*

El-Mhamdi El-Mahdi; Rachid Guerraoui and Sébastien Rouault.
Distributed momentum for byzantine-resilient learning. *ICLR 2021.*

Karimireddy Sai Praneeth; Lie He and Martin Jaggi.
Learning from history for byzantine robust optimization. *ICML 2021.*

**Momentum for
Byzantine resilience**

Alistarh Dan; Zeyuan Allen-Zhu and Jerry Li.
Byzantine stochastic gradient descent. *NeurIPS 2018.*

El-Mhamdi El-Mahdi; Guerraoui Rachid, and Sébastien Rouault.
The hidden vulnerability of distributed learning in Byzantium. *ICML 2018.*

Chen Yudong; Lili Su and Jiaming Xu.
Distributed statistical machine learning in adversarial settings: Byzantine gradient descent.
Proceedings of the ACM on Measurement and Analysis of Computing Systems 2017.

**Notable prior work
On Byzantine resilience**

Thank You